IDFS Programmers Manual

Version P

Carrie A. Gonzalez

E-MAIL: <u>carrie.gonzalez@swri.org</u>

Southwest Research Institute

28 December 2012

DESCRIPTION OF THE IDFS PROGRAMMERS MANUAL	1
PROGRAMMING EXAMPLES	3
EXAMPLE 1	3
EXAMPLE 2	9
EXAMPLE 3	15
EXAMPLE 4	21
EXAMPLE 5	27
EXAMPLE 6	39
EXAMPLE 7	47
EXAMPLE 8	53
EXAMPLE 9	59
ADJUST_TIME	65
CALC_TIME_RESOLUTION	67
CONVERT_TO_UNITS	71
CREATE_DATA_STRUCTURE	83
CREATE_IDF_DATA_STRUCTURE	85
CREATE_TENSOR_DATA_STRUCTURE	
DESTROY_LAST_IDF_DATA_STRUCTURE	89
DESTROY_LAST_TENSOR_DATA_STRUCTURE	91
EXTRACT_SINGLE_ELEMENT_FROM_IDFS_TENSOR	
FIELDS_TO_KEY	
FILE_OPEN	101
FILE_POS	107
FIRST_IDFS_SENSOR	117
FREE_EXPERIMENT_INFO	121
FREE_VERSION_INFO	123
GET_DATA_KEY	125
GET_VERSION_NUMBER	127
INIT_IDFS	129
NEXT_FILE_START_TIME	131
OVERRIDE_POTENTIAL_POLYNOMIAL	135
READ_DREC	139
READ_DREC_SPIN	147
READ_TENSOR_DATA	153
READ_IDF	
RESET_EXPERIMENT_INFO	161
SELECT_SENSOR	165
START_IMAGE	169
START_OF_SPIN	
TURN_OFF_PITCH_ANGLE_COMPUTATIONS	
TURN_ON_CELESTIAL_POSITION_COMPUTATIONS	
TURN_ON_EULER_ANGLE_COMPUTATIONS	
VALID_IDF_DATA_STRUCTURE	189
VALID_TENSOR_DATA_STRUCTURE	191
BUFFER_BIN_FILL	193

CENTER_AND_BAND_VALUES	197
COLLAPSE_DIMENSIONS	203
FILL_DATA	
FILL_DATA_ENVELOPE	
FILL_DISCONTINUOUS_DATA	227
FILL_MODE_DATA	
FILL_MODE_INFO	
FILL_SENSOR_INFO	
FILL_THETA_MATRIX	
MODE_UNITS_INDEX	
NUMBER_OF_DATA_BINS	
NUMBER_OF_PHI_BINS	
RETURN_CENTER_AND_BAND_PTRS	
RETURN_PHI_PTRS	
SET BIN INFO	
SET_COLLAPSE_INFO	
SET_SCAN_INFO	
SET TIME VALUES	
SPIN DATA	
SPIN DATA PIXEL	
SWEEP DATA	
SWEEP_DISCONTINUOUS_DATA	
SWEEP_MODE_DATA	
UNITS INDEX	
CREATE_SCF_DATA_STRUCTURE	
FREE_SCF_INFO	
INIT SCF.	
LOAD SCF	
READ_SCF	
SCF OPEN	
SCF_OUTPUT_DATA	
SCF POSITION	
SCF_SAMPLE_RATE	
SCF_TERMINATE_SOURCES	
SCF_VERSION_NUMBER	
SCF_ALGORITHM_START	
SCF_BIN_INFO	
SCF_OUTPUT_CENTER_AND_BANDS	
SCF_OUTPUT_DATA_INDEX	
SCF_OUTPUT_SELECT	
SCF_SAMPLE_AVERAGE	
SCF_TIME_AVERAGE	
SCF_TIME_REFERENCE	
LIBBASE_IDFS.H	
RET_CODES.H	409

USER_DEFS.H	421
LIBTREC_IDFS.H	425
SCF_CODES.H	427
SCF_DEFS.H	
SCF_FILE_DEFS.H	433
LIBBASE_SCF.H	435
LIBAVG_SCF.H	437
IDF_DATA	
DIRECTION_COS	445
TRANSFORMATION_INFO	447
SCF DATA	
TENSOR_DATA	453

Revision	Release Date	Changes to Document
A	09/12/2002	 Manual was re-formatted and modifications were made to bring the manual up-to-date with respect to code. Calling sequence changed for set_bin_info () Calling sequence changed for collapse_dimensions () Changes were made to update the error codes returned
		by the SCF modules since tensor manipulation was implemented.
В	01/07/2003	Added the module fill_data_envelope ()
C	10/20/2003	 Calling sequence changed for set_bin_info () and scf_bin_info () since added new variable spacing format 'A' for actual values (no computations)
D	08/23/2004	 Updated SYNPOSIS and EXAMPLES sections for fields_to_key () Updated DESCRIPTION and EXAMPLES sections for init_idfs () and init_scf () to reference dbInitialize () and CfgInit (). Updated ARGUMENTS section for better clarification for set_bin_info () Added the module first_idfs_sensor () Calling sequence changed for collapse_dimensions () Calling sequence changed for return_phi_ptrs () Updated ARGUMENTS, DESCRIPTION and EXAMPLES section for scf_bin_info () Added the module scf_terminate_sources () Updated ret_codes header file (1H)
E	06/16/05	 Table of Contents added Added another example between example 5 and example 6, so renumbered examples 6 - 8 Added 1R modules create_tensor_data_structure (), extract_from_idfs_tensor(), read_drec_spin (), read_tensor_data (), start_of_spin (), start_spin_source_status (), and valid_tensor_data_structure () Added 2R modules spin_data (), spin_data_pixel ()
F	12/15/05	 convert_to_units(), fill_sensor_info (), fill_mode_info(), mode_units_index(), units_index(), set_bin_info(), and set_scan_info() changed the data type for the tbl_oper argument(s) since table operators were expanded from 2-byte to 4-byte values for the additional data buffer capabilities

Revision Log

Revision	Release Date	Changes to Document
F	12/15/05	 Added error codes -438 through -461 to ret_codes.h header file Added definition of MAX_UNITS_BUFFERS to user_defs.h header file, needed for the data buffer capabilities that were added for unit conversion Added write-up for potential_source_status() and modified write-up for idf_data.h since added capability to return spacecraft potential data from read_drec(). Updated status codes for file_open(), file_pos(), read_drec() and read_tensor_data() for error codes associated with spacecraft potential data.
G	06/14/06	• Added / removed error codes from ret_codes.h header file and added to / removed from modules that return these error codes.
H	06/30/06	 Updated file_pos(), free_experiment_info() for tensor_data or idf_data usage for data structure parameter Modified get_data_key() to make references to the include file libdb.h which is needed for the prototype since it was moved out of libbase_idfs.h Updated calling sequence for sweep_data(), sweep_mode_data() and sweep_discontinuous_data() and updated DESCRIPTION section for spacecraft potential data Added spacecraft potential as data type for units_index(), convert_to_units(), and fill_sensor_info() and updated DESCRIPTION section Updated DESCRIPTION section for spacecraft potential data for file_open(), file_pos(), read_drec(), read_drec_spin(), reset_experiment_info(), fill_data(), fill_data_envelope(), fill_discontinuous_data(), fill_mode_data(), spin_data(), and spin_data_pix() Added SCF_TENSOR_VECTOR_SRC error code to scf_output_data() and SCF_codes include file (3H)
Ι	08/17/06	• Added new module override_potential_polynomial () and added new error codes to ret_codes.h header file.
J	12/18/06	 Added new modules turn_off_pitch_angle_computations() and turn_on_euler_angle_computations() for speed issues.

Revision	Release Date	Changes to Document
J	12/18/06	 Updated ret_codes.h, user_defs.h, and idf_data.h header files since added capability to return euler angle data from read_drec(). Modified file_pos(), file_open(), read_drec(), and read_tensor_data() for error codes associated with euler angle data Added modules euler_angle_source_status()
K	09/29/08	 Added clarification to description section for override_potential_polynomial()
L	07/14/09	 Added module create_data_structure() Modified calling sequence for center_and_band_values () Updated ret_codes.h – moved all positive status codes to beginning and added CENTER_CONVERSION, READ_SPIN_DATA_GAP, WRONG_DATA_STRUCTURE and CREATE_DSTR_NOT_FOUND
М	09/24/09	 Added new modules for coordinate system transformations: turn_on_celestial_position_computations(), celestial_position_source_status() Updated ret_codes.h for coordinate system transformations – added TURN_ON_CP_NOT_FOUND, UPDATE_IDF_BAD_CP_DEF, CP_MAIN_DATA_MISSING, CP_STR_MALLOC, CP_DATA_MALLOC, FILE_POS_CP, CP_INFO_IDF_ELE_NOT_FOUND, CP_INFO_IDF_TBL_NUM, CP_INFO_IDF_TBL_NUM, CP_INFO_IDF_CON_NUM, CP_INFO_IDF_CON_NUM, CP_TBL_MALLOC, CP_BAD_SRC, BAD_CP_FORMAT, NO_CP_CONSTANT, RESET_CP_REALLOC, CP_BAD_FRAC, CP_BAD_TIMES, RESET_TINFO_MALLOC Updated user_defs.h to add coordinate system transformation mneumonics Removed unused error codes from ret_codes.h, which include – NUM_CAL_MALLOC, OPEN_EX_MALLOC, LOCATE_EX_MALLOC, and VIDF_OPEN_EX_MALLOC

Revision	Release Date	Changes to Document
M	09/24/09	 Modified error codes returned by file_open(), file_pos(), read_drec(), and read_tensor_data() to reflect codes associated with coordinate system transformation code Modified idf_data structure for coordinate system transformation changes and added write-up for idfs_transformation structure Updated tensor_data structure since out of revision Updated example section in fields_to_key () to utilize SDDAS data types Modified read_drec_spin () since calling sequence was incorrect Updated error codes returned by scf_output_data() and scf_position()
		 Removed some error codes returned by collapse_dimensions() that are no longer applicable Updated calling sequences for spin_data () and spin_data_pixel () - changes were needed in case of coordinate system transformation Updated error codes returned by load_scf ()
Ν	08/31/11	 Updated description section for turn_off_pitch_angle_computations(), turn_on_euler_angle_computations() and turn_on_celestial_position_computations() since must be called BEFORE file_pos(), not read_drec() Updated description section for file_pos () to indicate that data structures have been filled in and can be interrogated upon return and updated error codes Deleted write-ups for start_spin_source_status(), potential_source_status(), euler_angle_source_status() and celestial_position_source_status() since no longer available Changed name from extract_from_idfs_tensor() to extract_single_element_from_idfs_tensor() Moved status codes associated with ancillary data from file_open() to file_pos() since ancillary data is now processed AFTER the main IDFS source has been positioned successfully Updated error codes for read_tensor_data() since data quality flags can now be a tensor as well Updated error codes for collapse_dimensions()

Revision	Release Date	Changes to Document
N	08/31/11	 Removed HDR_FMT_TWO error codes from list of error codes returned by read_drec () since only pertinent to multi-dimensional data Updated SCF_DEFS.H in section 3H Modified data type for cal_len and cset_num elements in idf_data structure in section 1S Modified tensor data structure in section 1S
0	06/04/12	 Added new modules destroy_last_idf_data_structure () and destroy_last_tensor_data_structure () Updated error codes for file_pos() since now need to make sure address of data structure is valid Updated ret_codes.h header file since added these 2 new modules and modified file_pos()
Р	12/28/12	 Updated ret_codes.h for background data – added BKGD_MAIN_DATA_MISSING, BKGD_BAD_SRC, BAD_BKGD_FORMAT, BKGD_TBL_MALLOC, BKGD_MALLOC, BKGD_IDF_DATA_MALLOC, BKGD_IDF_DATA_MALLOC, BKGD_INFO_IDF_ELE_NOT_FOUND, BKGD_INFO_IDF_TBL_NUM, BKGD_INFO_IDF_TBL_NUM, BKGD_INFO_IDF_CON_NUM, BKGD_INFO_IDF_NO_ENTRY, FILE_POS_BKGD, BKGD_BAD_TIMES, RESET_BKGD_REALLOC, BKGD_BAD_FRAC, UPDATE_IDF_BAD_BKGD_DEF, NO_BKGD_CONSTANT Modified error codes returned by file_open(), file_pos(), read_drec() and read_tensor_data() to reflect codes associated with background data Updated user_defs.h and idf_data.h header files since added capability to return background data from read_drec(). Added background as data type for units_index(), convert_to_units(), and fill_sensor_info() and updated DESCRIPTION section Updated DESCRIPTION section for background data for file_open(), file_pos(), read_drec(), read_drec_spin(), reset_experiment_info(), fill_data(), fill_data_envelope(), fill_discontinuous_data(), fill_mode_data(), spin_data(), spin_data_pix(), sweep_data(), sweep_discontinuous_data() and sweep_mode_data()

DESCRIPTION OF THE IDFS PROGRAMMERS MANUAL

The IDFS Programmers Manual describes the set of routines that can be used to access data that is stored in IDFS format and to access the derived data products defined within an SCF file. This manual consists of ten sections entitled 1R, 2R, 3R, 4R, 1H, 2H, 3H, **4H**, **1S** and **3S**. The section entitled **1R** contains a detailed description of the basic set of IDFS data retrieval routines that return data one sample set at a time or one spin at a time. The section entitled **2R** contains a detailed description of the IDFS routines that are used to retrieve data that is time-averaged, sample-averaged, or spin-averaged. Time-averaged data refers to data that is acquired for a specified time interval. Sample-averaged data refers to data that is averaged over a specific number of data samples. Spin-averaged data refers to data that is averaged over a complete spin. The section entitled **3R** contains a detailed description of the basic set of SCF output retrieval routines that return data for each iteration of the SCF algorithm. The section entitled $4\mathbf{R}$ contains a detailed description of the SCF routines that are used to retrieve derived data products that are time-averaged or sample-averaged. Time-averaged SCF data has the same meaning as time-averaged IDFS data. Sample-averaged SCF data refers to data that is averaged over a specific number of iterations of the SCF algorithm.

The sections entitled **1H**, **2H**, **3H** and **4H** contain a description of each of the IDFS/SCF include files. These include files contain the return codes for the IDFS/SCF routines, mnemonics that should be utilized for some of the parameter values to the various routines and the prototypes for the IDFS/SCF routines. The section entitled **1S** contains a detailed description of the data structure which holds the pertinent information returned by the IDFS read routine. The last section, **3S**, contains a detailed description of the data structure which holds the values returned from the execution of the algorithm in the named SCF file.

The SCF software supports post acquisition analysis. The IDFS software supports realtime and post acquisition analysis. The processing for real-time and post acquisition analysis differs somewhat based upon the nature of the data files. In the real-time scenario, the header and data files are incomplete and it is possible to attempt to read from either file prior to the data being received. This will result in a premature end-offile (eof) and the IDFS routine will return the status code EOF_STATUS for a header file read and DREC_EOF_NO_SENSOR or DREC_EOF_SENSOR for a data file read. For real-time processing, if any of the three codes are returned, the processing simply continues, anticipating that the data will eventually be received and processed at a later date. A true end-of-file status is acknowledged by the read_drec routine, returning the status code LOS_STATUS or NEXT_FILE_STATUS, as defined in the description of the read_drec routine. For post analysis acquisition, the IDFS routines may return the code FILL_HEADER, indicating that a dummy or fill header was read from the header file - the header record was never received and placed into the file. Since the data file should be complete, no end-of-file (eof) should be returned for a call to the read routine. If an eof is encountered (zero bytes read from the file), the error code DREC_READ_ERROR is returned. If either of these return codes is encountered in post analysis acquisition, the system should be terminated, indicating a possibly corrupted header or data file. The only end-of-file status acceptable for post analysis acquisition is the status code NEXT_FILE_STATUS or LOS_STATUS. It is also possible that a partial read may take place - that is, the number of bytes read did not match the number of bytes asked for. The IDFS routine will return the status code PARTIAL_READ in a playback scenario and EOF_STATUS in a real-time scenario and will re-position the file pointer at the start of the record in question. For real-time processing, if EOF_STATUS is returned, the processing simply continues, anticipating that the next read will result in a complete record. For post analysis acquisition, if PARTIAL_READ is returned, the system should be terminated, indicating a possibly corrupted header or data file.

All of the IDFS and SCF routines are detailed in depth within this manual. In the **ARGUMENTS** section of the description, a brief explanation of each argument or parameter is given. In some cases, a mnemonic is shown in parentheses for specific values. It is recommended that the user use the mnemonics instead of the specified value for the parameters. These mnemonics are defined in the **user_defs.h** include file for the IDFS routines and in the **SCF_defs.h** include file for the SCF routines. These files are described in sections **1H** and **3H** of the IDFS Programmers Manual. Using the mnemonics increases readability and guards against possible future changes to parameter values.

The IDFS and SCF software is written in the C programming language. In order to ease the task of porting the software to different platforms, the software utilizes typedefs. These typedefs are defined in the **SDDAS_types.h** include file, which can be found in section **1H** of the IDFS Programmers Manual. All IDFS and SCF routines utilize the typedefs for arguments and return values.

PROGRAMMING EXAMPLES

In order to help explain how a programmer would go about developing a program that utilizes the IDFS routines, examples of programs that retrieve and display the data on the screen from the TSS-1 RETE experiment are shown below. These programs illustrate both real-time and post analysis acquisition of data for a single sensor, as well as for all sensors for a given virtual instrument.

EXAMPLE 1

```
#include <stdio.h>
#include <string.h>
#include "ret_codes.h"
#include "user_defs.h"
#include "libCfg.h"
#include "libbase_idfs.h"
#include "libbase_idfs.h"
```

/* This routine processes real-time data for RTLA's sensor 0. */

```
void main (void)
```

```
struct idf_data *EXP_DATA;
SDDAS_FLOAT conv_data[1000];
SDDAS_LONG btime_sec, btime_nano, etime_sec, etime_nano, *tbl_oper;
SDDAS_ULONG data_key;
SDDAS_USHORT version;
register SDDAS_USHORT k;
SDDAS_SHORT rcode, sensor, ret_val;
SDDAS_SHORT btime_yr, btime_day, etime_yr, etime_day;
SDDAS_CHAR extension[3], full_swp = 1, fwd = 1, *tbls_to_apply, num_tbls;
char more_data = 1;
void *idf_data_ptr;
```

btime_yr = -1; btime_day = -1; btime_sec = -1; btime_nano = 0; etime_yr = -1; etime_day = -1;

```
etime sec = -1:
etime nano = 0;
sensor = 0;
strcpy (extension,"");
CfgInit ();
dbInitialize ();
init_idfs ();
/* Retrieve the key that is associated with the project, mission, experiment, instrument */
/* and virtual instrument specified.
                                                           */
ret_val = get_data_key ("TSS", "TSS-1", "RETE", "RETE", "RTLA", &data_key);
if (ret val != ALL OKAY)
{
 printf ("\n Error %d from get_data_key routine.\n", ret_val);
 exit (-1);
}
get version number (&version);
/* Create an instance of the idf data structure.
                                                         */
ret_val = create_idf_data_structure (&idf_data_ptr);
if (ret val != ALL OKAY)
{
 printf ("\n Error %d from create_idf_data_structure routine.\n", ret_val);
 exit (-1);
}
EXP DATA = (struct idf data *) idf data ptr;
/* Open the data files associated with the time period selected for this data set /
                                                         */
                                                         */
/* extension / version combination.
ret_val = file_open (data_key, extension, version, btime_yr, btime_day, btime_sec,
             btime nano, etime yr, etime day, etime sec, etime nano, 0);
if (ret_val != ALL_OKAY)
ł
 printf ("\n Error %d from file_open routine.\n", ret_val);
 exit (-1);
}
```

```
/* Since the routine FILE OPEN sets internal flags to indicate that all sensors are to */
/* be processed, reset the flags to indicate that only sensor 0 is being requested.
                                                 */
ret_val = select_sensor (data_key, extension, version, sensor);
if (ret val != ALL OKAY)
{
 printf ("\n Error %d from select_sensor routine.\n", ret_val);
 exit (-1):
}
*/
/* Retrieve the raw units for the data.
num tbls = 0;
tbls to apply = NULL;
tbl_oper = NULL;
/* Get the data for the requested sensor.
                                                    */
while (more_data)
 /* Find the position in the data file closest to the requested start time for this data set. */
 /* If the file has been positioned correctly, future calls to this routine just return the
                                                   */
 /* ALL OKAY status; otherwise, the routine keeps trying to read from the files and
                                                   */
 /* to position the file pointers (records may not have been written to disk yet).
                                                   */
 ret_val = file_pos (data_key, extension, version, idf_data_ptr, btime_yr, btime_day,
            btime_sec, btime_nano, etime_yr, etime_day, etime_sec, etime_nano);
 if (ret val == LOS STATUS)
 more data = 0;
 else if (ret val == NEXT FILE STATUS)
  /* For realtime processing, btime_sec is set to -1 so that when files are
                                               */
  /* crossed, the routines will position the file at the beginning of that next file.*/
  etime_yr, etime_day, etime_sec, etime_nano);
```

```
if (rcode != ALL_OKAY)
  printf ("\nError %d from reset_experiment_info.\n", rcode);
  exit (-1);
 }
ł
else if (ret_val != ALL_OKAY && ret_val != EOF_STATUS)
 printf ("\n Error %d from file_pos routine.\n", ret_val);
 exit (-1);
}
if (ret_val == ALL_OKAY)
ł
 ret_val = read_drec (data_key, extension, version, idf_data_ptr, sensor, fwd, full_swp);
 if (ret val < 0)
 ł
  printf ("\nError %d from read drec.\n", ret val);
  exit (-1);
 }
 */
 /* The sensor data was found within the time being processed.
 if (ret_val == ALL_OKAY || EXP_DATA->filled_data)
  rcode = convert_to_units (data_key, extension, version, idf_data_ptr,
                     sensor, SENSOR, 0, num_tbls, tbls_to_apply,
                      tbl_oper, conv_data, 0, 0);
  if (rcode != ALL_OKAY)
   ł
    printf ("\nError %d from convert_to_units.\n", rcode);
    exit (-1);
   }
  /* Print the times for the sample being returned.
                                                               */
  printf ("\n\nSENSOR %d's START TIME_MS = %ld", sensor, EXP_DATA->bmilli);
  printf ("\nSENSOR %d's START TIME_NS = %ld", sensor, EXP_DATA->bnano);
  printf ("\nSENSOR %d's END TIME_MS = %ld", sensor, EXP_DATA->emilli);
  printf ("\nSENSOR %d's END TIME_NS = %ld", sensor, EXP_DATA->enano);
```

}

}

```
*/
   /* Print the data, 6 values per row, in exponential format.
   for (k = 0; k < EXP_DATA -> num_sample; ++k)
    {
    if (k % 6 == 0)
     printf ("\n");
    printf ("%10.2e ", conv_data[k]);
    }
   printf ("nn");
   }
  if (ret_val == LOS_STATUS)
   more_data = 0;
  else if (ret_val == NEXT_FILE_STATUS)
   ł
   /* For realtime processing, btime_sec is set to -1 so that when files are
                                                  */
   /* crossed, the routines will position the file at the beginning of that next
                                                  */
   /* file.
                                                  */
   etime_yr, etime_day, etime_sec, etime_nano);
   if (rcode != ALL_OKAY)
    {
     printf ("\nError %d from reset_experiment_info.\n", rcode);
    exit (-1);
    }
   }
  }
free_experiment_info();
```

example 1

EXAMPLE 2

```
#include <stdio.h>
#include <string.h>
#include "ret codes.h"
#include "user defs.h"
#include "libbase idfs.h"
#include "libVIDF.h"
#include "libCfg.h"
#include "libdb.h"
/* This routine processes real-time data for all RTLA sensors. */
void main (void)
ł
 struct idf_data *EXP_DATA;
 register SDDAS USHORT k;
 SDDAS FLOAT conv data[1000];
 SDDAS LONG btime_sec, btime_nano, etime_sec, etime_nano, rval, *tbl_oper;
 SDDAS ULONG data key;
 SDDAS_USHORT version;
 SDDAS SHORT rcode, sensor, ret val, num sensor;
 SDDAS_SHORT btime_yr, btime_day, etime_yr, etime_day;
 SDDAS CHAR extension[3], full swp = 1, fwd = 1, *tbls to apply, num tbls;
 char more data = 1;
 void *idf_data_ptr;
 /* Set the start and stop time (in this case to reflect real-time scenario) and select the */
 /* data file of interest ("" means default file is to be used).
                                                                        */
 btime_yr = -1;
 btime_day = -1;
 btime sec = -1;
 btime nano = 0;
 etime_yr = -1;
 etime_day = -1;
 etime sec = -1;
 etime_nano = 0;
 strcpy (extension,"");
 CfgInit ();
 dbInitialize ();
 init_idfs ();
```

```
/* Retrieve the key that is associated with the project, mission, experiment, instrument */
/* and virtual instrument specified.
                                                     */
ret_val = get_data_key ("TSS", "TSS-1", "RETE", "RETE", "RTLA", &data_key);
if (ret val != ALL OKAY)
{
 printf ("\n Error %d from get_data_key routine.\n", ret_val);
 exit (-1):
}
get version number (&version);
/* Create an instance of the idf_data structure.
ret_val = create_idf_data_structure (&idf_data_ptr);
if (ret_val != ALL_OKAY)
ł
 printf ("\n Error %d from create_idf_data_structure routine.\n", ret_val);
 exit (-1);
EXP_DATA = (struct idf_data *) idf_data_ptr;
*/
/* Open the data files associated with the time period selected for this data set /
                                                    */
/* extension / version combination.
ret_val = file_open (data_key, extension, version, btime_yr, btime_day, btime_sec,
            btime nano, etime yr, etime day, etime sec, etime nano, 0);
if (ret_val != ALL_OKAY)
 printf ("\n Error %d from file_open routine.\n", ret_val);
 exit (-1);
}
*/
/* Find out the number of sensors defined for this virtual instrument.
rval = read_idf (data_key, extension, version, (SDDAS_CHAR *) &num_sensor, _SEN,
```

```
0, 0, 1);
```

```
if (rval < 0)
 printf ("\n Error %ld from read_idf routine.\n", rval);
 exit (-1);
}
*/
/* Retrieve the raw units for the data.
num_tbls = 0;
tbls to apply = NULL;
tbl oper = NULL;
/* Get the data for all sensors.
                                                      */
while (more_data)
 /* Find the position in the data file closest to the requested start time for this data set. */
 /* If the file has been positioned correctly, future calls to this routine just return the
                                                     */
 /* ALL OKAY status; otherwise, the routine keeps trying to read from the files and
                                                     */
 /* to position the file pointers (records may not have been written to disk yet).
                                                     */
 ret_val = file_pos (data_key, extension, version, idf_data_ptr, btime_yr, btime_day,
            btime_sec, btime_nano, etime_yr, etime_day, etime_sec, etime_nano);
 if (ret val == LOS STATUS)
 more_data = 0;
 else if (ret val == NEXT FILE STATUS)
  /* For realtime processing, btime_sec is set to -1 so that when files are
                                                 */
  /* crossed, the routines will position the file at the beginning of that next file. */
  etime yr, etime day, etime sec, etime nano);
  if (rcode != ALL_OKAY)
  ł
   printf ("\nError %d from reset_experiment_info.\n", rcode);
   exit (-1);
  }
```

}

ł

```
else if (ret val != ALL OKAY && ret val != EOF STATUS)
 printf ("\n Error %d from file_pos routine.\n", ret_val);
 exit (-1);
if (ret_val == ALL_OKAY)
 for (sensor = 0; sensor < num_sensor; ++sensor)
  /* Advance to the next data set only if the last sensor is being processed to ensure */
  /* all samples which occur at the same time are processed simultaneously.
                                                         */
  fwd = (sensor == num_sensor - 1) ? 1 : 0;
  ret_val = read_drec (data_key, extension, version, idf_data_ptr, sensor, fwd, full_swp);
  if (ret val < 0)
  {
   printf ("\nError %d from read drec.\n", ret val);
   exit (-1);
   }
  /* The sensor data was found within the time being processed.
                                                         */
  if (ret val == ALL OKAY \parallel EXP DATA->filled data)
   rcode = convert_to_units (data_key, extension, version, idf_data_ptr, sensor,
                     SENSOR, 0, num_tbls, tbls_to_apply, tbl_oper,
                     conv data, (0, 0);
   if (rcode != ALL_OKAY)
    {
    printf ("\nError %d from convert_to_units.\n", rcode);
    exit (-1):
    }
  */
  /* Print the times for the sample being returned.
```

printf ("\n\nSENSOR %d's START TIME_MS = %ld", sensor, EXP_DATA->bmilli); printf ("\nSENSOR %d's START TIME_NS = %ld", sensor, EXP_DATA->bnano); printf ("\nSENSOR %d's END TIME_MS = %ld", sensor, EXP_DATA->emilli);

} }

}

```
printf ("\nSENSOR %d's END TIME_NS = %ld", sensor, EXP_DATA->enano);
     */
     /* Print data values, 6 values per row, in exponential format.
     for (k = 0; k < EXP_DATA -> num_sample; ++k)
     {
      if (k \% 6 == 0)
       printf ("\n");
      printf ("%10.2e ", conv_data[k]);
     }
     printf ("nn");
    }
    if (ret_val == LOS_STATUS)
    more data = 0;
    else if (ret_val == NEXT_FILE_STATUS)
    ł
     */
     /* For realtime processing, blime sec is set to -1 so that when files are
     /* crossed, the routines will position the file at the beginning of that next file. */
     etime_yr, etime_day, etime_sec, etime_nano);
     if (rcode != ALL OKAY)
     {
      printf ("\nError %d from reset_experiment_info.\n", rcode);
      exit (-1);
     }
    }
   }
free_experiment_info();
```

example 2

example 2

EXAMPLE 3

#include <stdio.h>
#include <string.h>
#include "ret_codes.h"
#include "user_defs.h"
#include "libbase_idfs.h"
#include "libCfg.h"
#include "libdb.h"

/* This routine processes playback data for RTLA's sensor 0. */

void main (void)

struct idf_data *EXP_DATA; SDDAS_FLOAT conv_data[1000]; SDDAS_LONG btime_sec, btime_nano, etime_sec, etime_nano, ret_time_sec; SDDAS_LONG ret_time_nano, new_start_sec, new_start_nsec, *tbl_oper; SDDAS_ULONG data_key; SDDAS_USHORT version; register SDDAS_USHORT k; SDDAS_SHORT sensor, ret_val, rcode, new_year, new_day; SDDAS_SHORT sensor, ret_val, rcode, new_year, new_day; SDDAS_SHORT btime_yr, btime_day, etime_yr, etime_day; SDDAS_CHAR extension[3], full_swp = 1, fwd = 1, *tbls_to_apply, num_tbls; char more_data = 1; void *idf_data_ptr;

btime_yr = 1991; btime_day = 93; btime_sec = 81; btime_nano = 0; etime_yr = 1991; etime_day = 93; etime_sec = 1536;

etime_nano = 0;

/* Set the sensor of interest and the data file of interest ("" means default file is to be used).*/

```
sensor = 0;
strcpy (extension,"");
CfgInit ();
dbInitialize ();
init idfs ();
/* Retrieve the key that is associated with the project, mission, experiment, instrument */
/* and virtual instrument specified.
                                                          */
ret val = get data key ("TSS", "TSS-1", "RETE", "RETE", "RTLA", &data key);
if (ret val != ALL OKAY)
{
 printf ("\n Error %d from get_data_key routine.\n", ret_val);
 exit (-1);
}
get version number (&version);
/* Create an instance of the idf_data structure.
                                                         */
ret_val = create_idf_data_structure (&idf_data_ptr);
if (ret val != ALL OKAY)
{
 printf ("\n Error %d from create_idf_data_structure routine.\n", ret_val);
 exit (-1);
EXP DATA = (struct idf data *) idf data ptr;
/* Open the data files associated with the time period selected for this data set /
                                                        */
                                                         */
/* extension/version combination.
ret_val = file_open (data_key, extension, version, btime_yr, btime_day, btime_sec,
             btime nano, etime yr, etime day, etime sec, etime nano, 0);
if (ret_val != ALL_OKAY)
ł
 printf ("\n Error %d from file_open routine.\n", ret_val);
 exit (-1);
}
```

```
/* Since the routine FILE OPEN sets internal flags to indicate that all sensors are to */
/* be processed, reset the flags to indicate that only sensor 0 is being requested.
                                                      */
ret_val = select_sensor (data_key, extension, version, sensor);
if (ret val != ALL OKAY)
{
 printf ("\n Error %d from select_sensor routine.\n", ret_val);
 exit (-1):
}
/* Find the position in the data file closest to the requested start time for this data set.
                                                        */
/* Unlike real-time, if an error is encountered, the system should terminate - no need to */
/* retry in anticipation of incoming data.
                                                        */
ret_val = file_pos (data_key, extension, version, idf_data_ptr, btime_yr, btime_day,
            btime sec, btime nano, etime yr, etime day, etime sec, etime nano);
if (ret_val != ALL_OKAY)
ł
 printf ("\n Error %d from file_pos.\n", ret_val);
 exit (-1);
}
/* Retrieve the raw units for the data.
                                                       */
num_tbls = 0;
tbls to apply = NULL;
tbl oper = NULL;
/* Get the data for the requested sensor. Terminate when the requested end time is reached*/
                                                          */
/* or when no more data files are available for processing.
while (more data)
 ret val = read drec (data key, extension, version, idf data ptr, sensor, fwd, full swp);
 if (ret val < 0)
  printf ("\nError %d from read_drec.\n", ret_val);
```

```
exit (-1);
}
```

```
*/
/* The sensor data was found within the time sample being processed.
if (ret val == ALL OKAY || EXP DATA->filled data)
{
 ret time sec = (EXP DATA - bmilli + (EXP DATA - bnano / 100000)) / 1000;
 ret_time_nano = (EXP_DATA->bmilli % 1000) * 1000000 + EXP_DATA->bnano;
 */
 /* The requested end time has been reached?
 if (EXP_DATA->byear > etime_yr ||
  (EXP_DATA->byear == etime_yr && EXP_DATA->bday > etime_day) ||
  (EXP_DATA->byear == etime_yr && EXP_DATA->bday == etime_day &&
  ret time sec > etime sec) \parallel
  (EXP_DATA->byear == etime_yr && EXP_DATA->bday == etime_day &&
  ret time sec == etime sec && ret time nano > etime nano))
 ł
  more_data = 0;
  break;
 }
 rcode = convert to units (data key, extension, version, idf data ptr, sensor,
                  SENSOR, 0, num_tbls, tbls_to_apply, tbl_oper, conv_data,
                  0.0:
 if (rcode != ALL_OKAY)
  printf ("\nError %d from convert_to_units.\n", rcode);
  exit (-1);
 }
 /* Print the times for the sample being returned.
                                                        */
 printf ("\n\nSENSOR %d's START TIME_MS = %ld", sensor, EXP_DATA->bmilli);
 printf ("\nSENSOR %d's START TIME_NS = %ld", sensor, EXP_DATA->bnano);
 printf ("\nSENSOR %d's END TIME_MS = %ld", sensor, EXP_DATA->emilli);
```

printf ("\nSENSOR %d's END TIME_NS = %ld", sensor, EXP_DATA->enano);

```
*/
 /* Print the data values, 6 values per row, in exponential format.
 for (k = 0; k < EXP_DATA -> num_sample; ++k)
 {
  if (k \% 6 == 0)
   printf ("n");
  printf ("%10.2e ", conv_data[k]);
 }
 printf ("nn");
}
if (ret_val == LOS_STATUS || ret_val == NEXT_FILE_STATUS)
 */
 /* Get the start time to use to get the next data file.
 rcode = next_file_start_time (data_key, extension, version, 0, &new_year,
                      &new_day, &new_start_sec, &new_start_nsec);
 if (rcode != ALL OKAY)
  printf ("\n Error %d from next_file_start_time.\n", rcode);
  exit (-1);
 }
 rcode = reset_experiment_info (data_key, extension, version, new_year,
                        new_day, new_start_sec, new_start_nsec,
                        etime_yr, etime_day, etime_sec, etime_nano);
 if (rcode == NO_DATA)
  more_data = 0;
  break;
 else if (rcode != ALL_OKAY)
  printf ("\n Error %d from reset_experiment_info.\n", rcode);
  exit (-1);
 }
 rcode = file_pos (data_key, extension, version, idf_data_ptr, new_year, new_day,
              new_start_sec, new_start_nsec, etime_yr, etime_day, etime_sec,
```

etime_nano);

```
if (rcode != ALL_OKAY)
{
    printf ("\n Error %d from file_pos.\n", rcode);
    exit (-1);
    }
}
free_experiment_info();
}
```

EXAMPLE 4

```
#include <stdio.h>
#include <string.h>
#include "ret_codes.h"
#include "user_defs.h"
#include "libbase_idfs.h"
#include "libVIDF.h"
#include "libCfg.h"
#include "libdb.h"
```

/* This routine processes playback data for all RTLA sensors. */

void main (void)

{

struct idf_data *EXP_DATA; SDDAS_FLOAT conv_data[1000]; SDDAS_LONG btime_sec, btime_nano, etime_sec, etime_nano, ret_time_sec; SDDAS_LONG ret_time_nano, new_start_sec, new_start_nsec, rval, *tbl_oper; SDDAS_ULONG data_key; SDDAS_USHORT version; register SDDAS_USHORT k; SDDAS_SHORT sensor, ret_val, num_sensor, rcode, new_year, new_day; SDDAS_SHORT btime_yr, btime_day, etime_yr, etime_day; SDDAS_CHAR extension[3], full_swp = 1, fwd = 1, *tbls_to_apply, num_tbls; char more_data = 1; void *idf_data_ptr;

```
btime_yr = 1991;
btime_day = 93;
btime_sec = 81;
btime_nano = 0;
etime_yr = 1991;
etime_day = 93;
etime_sec = 1536;
etime_nano = 0;
```

December 28, 2012

```
strcpy (extension,"");
CfgInit ();
dbInitialize ();
init idfs ();
/* Retrieve the key that is associated with the project, mission, experiment, instrument */
                                                       */
/* and virtual instrument specified.
ret_val = get_data_key ("TSS", "TSS-1", "RETE", "RETE", "RTLA", &data_key);
if (ret val != ALL OKAY)
{
 printf ("\n Error %d from get_data_key routine.\n", ret_val);
 exit (-1);
}
get_version_number (&version);
*/
/* Create an instance of the idf data structure.
ret_val = create_idf_data_structure (&idf_data_ptr);
if (ret_val != ALL_OKAY)
{
 printf ("\n Error %d from create_idf_data_structure routine.\n", ret_val);
 exit (-1);
EXP_DATA = (struct idf_data *) idf_data_ptr;
/* Open the data files associated with the time period selected for this data set /
                                                     */
/* extension / version combination.
                                                     */
ret_val = file_open (data_key, extension, version, btime_yr, btime_day, btime_sec,
            btime_nano, etime_yr, etime_day, etime_sec, etime_nano, 0);
if (ret_val != ALL_OKAY)
{
 printf ("\n Error %d from file open routine.\n", ret val);
 exit (-1);
}
```

```
/* Find the position in the data file closest to the requested start time for this data set. */
```

```
/* Unlike real-time, if an error is encountered, the system should terminate - no need
                                                 */
                                                 */
/* to retry in anticipation of incoming data.
ret_val = file_pos (data_key, extension, version, idf_data_ptr, btime_yr, btime_day,
           btime_sec, btime_nano, etime_yr, etime_day, etime_sec, etime_nano);
if (ret_val != ALL_OKAY)
 {
 printf ("\n Error %d from file_pos.\n", ret_val);
 exit (-1):
 }
*/
/* Find out the number of sensors defined for this virtual instrument.
rval = read_idf (data_key, extension, version, (SDDAS_CHAR *) &num_sensor,
          SEN, 0, 0, 1);
if (rval < 0)
 printf ("\n Error %ld from read_idf routine.\n", rval);
 exit (-1);
 }
/* Retrieve the raw units for the data.
                                                */
num_tbls = 0;
tbls_to_apply = NULL;
tbl_oper = NULL;
*/
/* Get the data for all sensors.
while (more_data)
 {
 for (sensor = 0; sensor < num_sensor; ++sensor)
  /* Advance to the next data set only if the last sensor is being processed to ensure */
  /* all samples which occur at the same time are processed simultaneously.
                                                */
```

```
fwd = (sensor == num_sensor - 1) ? 1 : 0;
ret val = read drec (data key, extension, version, idf data ptr, sensor, fwd,
              full swp);
if (ret val < 0)
{
 printf ("\nError %d from read drec.\n", ret val);
 exit (-1);
}
/* The sensor data was found within the time being processed.
                                                       */
if (ret_val == ALL_OKAY || EXP_DATA->filled_data)
ł
 /* If the time of the sample is past the requested end time, stop processing data. */
 ret_time_sec = (EXP_DATA -> bmilli + (EXP_DATA -> bnano / 100000)) / 1000;
 ret_time_nano = (EXP_DATA->bmilli % 1000) * 1000000 + EXP_DATA->bnano;
 if (EXP_DATA->byear > etime_yr ||
  (EXP_DATA->byear == etime_yr && EXP_DATA->bday > etime_day)
  (EXP_DATA->byear == etime_yr && EXP_DATA->bday == etime_day &&
  ret_time_sec > etime_sec) ||
  (EXP DATA->byear == etime yr && EXP DATA->bday == etime day &&
  ret time sec == etime sec && ret time nano > etime nano))
 {
  more data = 0;
  break;
 }
 rcode = convert_to_units (data_key, extension, version, idf_data_ptr, sensor,
                  SENSOR, 0, num_tbls, tbls_to_apply, tbl_oper,
                  conv data, (0, 0):
 if (rcode != ALL_OKAY)
 ł
   printf ("\nError %d from convert_to_units.\n", rcode);
   exit (-1);
 }
 */
 /* Print the times for the sample being returned.
```

```
printf ("\n\nSENSOR %d's START TIME_MS = %ld", sensor,
      EXP DATA->bmilli);
 printf ("\nSENSOR %d's START TIME_NS = %ld", sensor, EXP_DATA->bnano);
 printf ("\nSENSOR %d's END TIME_MS = %ld", sensor, EXP_DATA->emilli);
 printf ("\nSENSOR %d's END TIME NS = %ld", sensor, EXP DATA->enano);
 */
 /* Print the data, 6 values per row, in exponential format.
 for (k = 0; k < EXP_DATA -> num_sample; ++k)
  if (k \% 6 == 0)
   printf ("\n");
  printf ("%10.2e ", conv_data[k]);
 }
 printf ("nn");
}
if (ret val == LOS STATUS \parallel ret val == NEXT FILE STATUS)
 /* Get the start time to use to get the next data file.
                                                           */
 rcode = next_file_start_time (data_key, extension, version, 0, &new_year,
                       &new_day, &new_start_sec, &new_start_nsec);
 if (rcode != ALL OKAY)
 {
  printf ("\n Error %d from next file start time.\n", rcode);
  exit (-1);
  }
 rcode = reset_experiment_info (data_key, extension, version, new_year,
                         new_day, new_start_sec, new_start_nsec,
                         etime_yr, etime_day, etime_sec, etime_nano);
 if (rcode == NO_DATA)
 ł
   more_data = 0;
   break;
 else if (rcode != ALL OKAY)
  printf ("\n Error %d from reset_experiment_info.\n", rcode);
  exit (-1);
```

This example demonstrates the usage of most of the IDFS routines. The example was coded for real-time, processing all sensors for the virtual instrument in question. The user can refer to the previous coding examples to determine how to change this example to process post-time data or single sensor data only.

#include <stdio.h> #include <string.h> #include "ret codes.h" #include "user defs.h" #include "libtrec idfs.h" #include "libVIDF.h" #include "libCfg.h" #include "libdb.h" /* This routine processes real-time data for all RTLA sensors. */ void main (void) { struct idf_data *EXP_DATA; register SDDAS FLOAT *dptr, *frac; register SDDAS_SHORT loop, i; SDDAS ULONG data key: SDDAS USHORT vnum; SDDAS_FLOAT *ret_data, *ret_frac, sen_min, sen_max, *base_data, *base_frac; SDDAS FLOAT *center ptr, *band low, *band high, actual phi, *data ptr; SDDAS FLOAT start range[6], stop range[6]; SDDAS_LONG btime_sec, btime_nsec, etime_sec, etime_nsec, base_sec, base_nano, base_pix; SDDAS LONG res sec, res nano, *start time sec, *start time nano, offset buf, rval; SDDAS_LONG *end_time_sec, *end_time_nano, *bpix, *epix, offset_unit, tbl_oper[2]; SDDAS SHORT sensor, ret val, accum bin stat, num sensor, *sen numbers; SDDAS_SHORT *num_units, data_block, uind_raw, uind_base, buf_num, sen_units; SDDAS_SHORT num_bands, num_converted, rcode, fill_code, num_sen; SDDAS_SHORT btime_yr, btime_day, etime_yr, etime_day; SDDAS_SHORT *start_yr, *start_day, *end_yr, *end_day; SDDAS CHAR extension[3], data type, hdr change, num tbls, tbls to apply[2]; SDDAS_CHAR *buf_stat, *ret_bin, *bin_stat, *base_bin, last_plot, num_center_band; SDDAS_CHAR dimen_status[6]; char more data = 1, first time = 1; void *idf_data_ptr;

```
/* Set the start and stop time (in this case to reflect real-time scenario) and select the */
/* data file of interest ("" means default file is to be used).
                                                         */
btime vr = -1;
btime day = -1;
btime sec = -1;
btime_nsec = -1;
etime yr = -1;
etime_day = -1;
etime sec = -1;
etime nsec = -1;
strcpy (extension,"");
CfgInit ();
dbInitialize ();
init_idfs ();
/* Retrieve the key that is associated with the project, mission, experiment, instrument */
/* and virtual instrument specified.
                                                          */
ret_val = get_data_key ("TSS", "TSS-1", "RETE", "RETE", "RTLA", &data_key);
if (ret val != ALL OKAY)
 printf ("\n Error %d from get_data_key routine.\n", ret_val);
 exit (-1);
ł
get_version_number (&vnum);
ret val = create idf data structure (&idf data ptr);
if (ret val != ALL OKAY)
{
 printf ("\n Error %d from create_idf_data_structure routine.\n", ret_val);
 exit (-1);
}
EXP DATA = (struct idf data *) idf data ptr;
/* The data will be collapsed over the scan dimension to squash the data over the
                                                         */
                                                         */
/* entire frequency range for this virtual instrument.
```

dimen_status[0] = DIMEN_ON;

```
start_range[0] = 0.16;
stop range[0] = 0.9;
start_range[1] = stop_range[1] = 0.0;
start_range[2] = stop_range[2] = 0.0;
start_range[3] = stop_range[3] = 0.0;
start_range[4] = stop_range[4] = 0.0;
start_range[5] = stop_range[5] = 0.0;
dimen_status[1] = DIMEN_OFF;
dimen_status[2] = DIMEN_OFF;
dimen status[3] = DIMEN OFF;
dimen_status[4] = DIMEN_OFF;
dimen status[5] = DIMEN OFF;
/* Open the data files associated with the time period selected for this data set /
                                                       */
/* extension/version combination.
                                                       */
ret_val = file_open (data_key, extension, vnum, btime_yr, btime_day, btime_sec,
             btime nsec, etime yr, etime day, etime sec, etime nsec, 0);
if (ret_val != ALL_OKAY)
ł
 printf ("\n Error %d from file_open routine.\n", ret_val);
 exit (-1);
}
*/
/* Find out the number of sensors defined for this virtual instrument.
rval = read_idf (data_key, extension, vnum, (SDDAS_CHAR *) &num_sensor, _SEN, 0,
          0, 1);
if (rval < 0)
ł
 printf ("\n Error %ld from read_idf routine.\n", rval);
 exit (-1);
}
*/
/* Get the data for all sensors.
while (more_data)
```

{

```
/* Find the position in the data file closest to the requested start time for this data set.*/
/* If the file has been positioned correctly, future calls to this routine just return the */
/* ALL OKAY status; otherwise, the routine keeps trying to read from the files
                                                    */
/* and to position the file pointers (records may not have been written to disk yet).
                                                   */
rcode = file_pos (data_key, extension, vnum, idf_data_ptr, btime_yr, btime_day,
           btime sec, btime nsec, etime yr, etime day, etime sec, etime nsec);
if (rcode == LOS STATUS)
more data = 0:
else if (rcode == NEXT_FILE_STATUS)
 /* For realtime processing, btime_sec is set to -1 so that when files are crossed, */
 /* the routines will position the file at the beginning of that next file.
                                                  */
 etime_yr, etime_day, etime_sec, etime_nsec);
 if (ret val != ALL OKAY)
  printf ("\nError %d from reset experiment info.\n", ret val);
  exit (-1);
else if (rcode != ALL_OKAY && rcode != EOF_STATUS)
 printf ("\n Error %d from file pos routine.\n", rcode);
 exit (-1);
*/
/* Some items need to be set just once.
if (first time)
ł
 first time = 0;
 /* Set the base reference time, location and duration for the data buffers.
```

ret_val = read_drec (data_key, extension, vnum, idf_data_ptr, 0, 0, 0);

```
if (ret_val < 0)
ł
 printf ("\nError %d from read_drec.\n", ret_val);
 exit (-1);
}
base_sec = EXP_DATA->bmilli / 1000;
base nano = (EXP DATA->bmilli % 1000) * 1000000 + EXP DATA->bnano;
base_pix = 0;
res sec = 9;
res_nano = 21600000;
set time values (vnum, EXP DATA->byear, EXP DATA->bday, base sec,
            base_nano, base_pix, res_sec, res_nano);
/* Select sensor data in raw units for all sensors.
                                                         */
num_tbls = 0;
data_type = SENSOR;
sen_min = VALID_MIN;
sen_max = VALID_MAX;
for (sensor = 0; sensor < num_sensor; ++sensor)
{
 ret_val = fill_sensor_info (data_key, extension, vnum, sensor, sen_min, sen_max, num_tbls,
                    tbls_to_apply, tbl_oper, data_type, 0);
 if (ret val != ALL OKAY)
 {
  printf ("\nError %d from fill sensor info.\n", ret val);
  exit (-1);
  }
}
*/
/* Select sensor data in base units for all sensors.
num_tbls = 2;
tbls_to_apply[0] = 0;
tbls_to_apply[1] = 1;
tbl oper[0] = 0;
tbl_oper[1] = 3;
```

```
for (sensor = 0; sensor < num_sensor; ++sensor)
 ret_val = fill_sensor_info (data_key, extension, vnum, sensor, sen_min, sen_max, num_tbls,
                      tbls_to_apply, tbl_oper, data_type, 0);
 if (ret val != ALL OKAY)
   printf ("\nError %d from fill sensor info.\n", ret val);
  exit (-1);
  }
}
/* Specify that 8 linear center bins from 0.16 to 0.86 (.1 delta) are to be created
                                                                */
/* and missing bins are to be left empty. No need to call SET_SCAN_INFO since*/
/* raw sweep step values are desired for this sweeping instrument. Since
                                                                */
/* num center band is 0, the contents of tbl oper and tbls to apply don't matter. */
num center band = 0;
ret val = set bin info (data key, extension, vnum, VARIABLE SWEEP,
                  0.16, 0.86, 0.1, 8, LIN_SPACING, num_center_band,
                  tbls to apply, tbl oper, num center band,
                  tbls_to_apply, tbl_oper, num_center_band,
                  tbls_to_apply, tbl_oper, 'L', POINT_STORAGE, NO_BIN_FILL);
if (ret_val != ALL_OKAY)
 printf ("\nError %d from set_bin_info.\n", ret_val);
 exit (-1);
}
/* The scan units should be in terms of frequency.
                                                               */
num_tbls = 1;
tbls_to_apply[0] = 0;
tbl_oper[0] = 0:
ret val = set scan info (data key, extension, vnum, num tbls, tbls to apply, tbl oper);
if (ret_val != ALL_OKAY)
ł
 printf ("\nError %d from set_scan_info.\n", ret_val);
 exit (-1);
}
```

```
/* Since all sensors use the same scan range, any valid sensor number can be
                                                               */
 /* passed in as the required argument.
                                                               */
 sensor = 0;
 ret_val = center_and_band_values (data_key, extension, vnum, idf_data_ptr, sensor,
                            1, 1, &center ptr, &band low, &band high,
                            &num_bands, &num_converted);
 if (ret_val != ALL_OKAY && ret_val != CENTER_CONVERSION)
  printf ("\nError %d from center_and_band_values.\n", ret_val);
  exit (-1);
  }
 /* Specify that data will be collapsed for 2 units, but no PHI dimension and do */
 /* not interleave the data.
                                                              */
 ret val = set collapse info (data key, extension, vnum, 2, 360.0, & actual phi, 0);
 if (ret val != ALL OKAY)
  {
  printf ("\nError %d from set_collapse_info.\n", ret_val);
  exit (-1);
  }
}
if (rcode == ALL OKAY)
ł
 fill_code = fill_data (data_key, extension, vnum, idf_data_ptr, &sen_numbers, &ret_data,
                 &ret_frac, &ret_bin, &bpix, &epix, &buf_stat, &num_sen,
                 &num_units, &data_block, &start_yr, &start_day, &start_time_sec,
                 &start_time_nano, &end_yr, &end_day, &end_time_sec,
                 &end_time_nano, &hdr_change, 255);
 if (fill_code != ALL_OKAY && fill_code != LOS_STATUS &&
   fill_code != EOF_STATUS && fill_code != NEXT_FILE_STATUS)
  {
  printf ("\nError %d from fill_data.\n", fill_code);
  exit (-1);
  }
```

```
*/
/* Loop over all defined sensors.
for (sensor = 0; sensor < num sensor; ++sensor)
 */
 /* Loop over sensors processed by the FILL DATA routine.
 for (i = 0; i < num sen; ++i)
  ł
  if (*(\text{sen numbers} + i) == \text{sensor})
   {
    offset_unit = *(num_units + i) * NUM_BUFFERS * data_block;
    base_data = ret_data + offset_unit;
    base_frac = ret_frac + offset_unit;
    base_bin = ret_bin + offset_unit;
    num_tbls = 0;
    ret_val = units_index (data_key, extension, vnum, sensor, sen_min, sen_max,
                     tbls_to_apply, tbl_oper, data_type, 0, &uind_raw,
                     &sen units, num tbls);
    if (ret_val != ALL_OKAY)
    ł
     printf ("\nError %d from units_index.\n", ret_val);
     exit (-1);
    }
    num_tbls = 2;
    tbls_to_apply[0] = 0;
    tbls_to_apply[1] = 1;
    tbl_oper[0] = 0;
    tbl_oper[1] = 3;
    ret_val = units_index (data_key, extension, vnum, sensor, sen_min, sen_max,
                     tbls_to_apply, tbl_oper, data_type, 0, &uind_base,
                     &sen_units, num_tbls);
    if (ret_val != ALL_OKAY)
    {
     printf ("\nError %d from units_index.\n", ret_val);
     exit (-1);
    }
```

```
for (buf_num = 0; buf_num < NUM_BUFFERS; ++buf_num)
 if (*(buf stat + buf num) == BUFFER READY)
 {
   */
   /* Print the raw units data.
   offset_buf = buf_num * sen_units * data_block;
   offset_unit = uind_raw * data_block;
   dptr = base data + offset buf + offset unit;
   frac = base_frac + offset_buf + offset_unit;
   bin stat = base bin + offset buf + offset unit;
   accum_bin_stat = 0;
   for (loop = 0; loop < data_block; ++loop)
    accum_bin_stat += *(bin_stat + loop);
   /* Make sure there is some data in the buffers. Still check bin stat
                                                          */
   /* since frac will be 0.0 if bin_stat = 0. For this data set, it is known
                                                         */
                                                          */
   /* that the sweep values are contiguous.
   if (accum bin stat != 0)
   ł
    printf ("\n\n sensor %d information\n", sensor);
    printf ("\n start_pix = %ld", *(bpix + buf_num));
    printf ("\n end_pix = %ld", *(epix + buf_num));
    for (loop = 0; loop < data_block; ++loop)</pre>
     ł
     if (*(bin_stat + loop) != 0)
      printf ("\n raw data[%d] = %10.2e from freq bin
             %.2f to %.2f",loop,*(dptr+loop) / *(frac+loop),
             (band_low + loop), (band_low + loop + 1));
      else
       printf ("\n raw data[%d] = %10.2e from freq bin
             %.2f to %.2f", loop, *(dptr + loop),
            (band_low + loop), (band_low + loop + 1));
     }
   ł
   */
   /* Print the base units data.
```

```
offset_unit = uind_base * data_block;
      dptr = base data + offset buf + offset unit;
      frac = base_frac + offset_buf + offset_unit;
      bin_stat = base_bin + offset_buf + offset_unit;
      accum bin stat = 0;
      for (loop = 0; loop < data_block; ++loop)
        accum bin stat += *(bin stat + loop);
      if (accum bin stat != 0)
       ł
        printf ("\n\n sensor %d information\n", sensor);
        printf ("\n start_pix = %ld", *(bpix + buf_num));
        printf ("\n end_pix = %ld", *(epix + buf_num));
        for (loop = 0; loop < data_block; ++loop)
        {
         if (*(bin stat + loop) != 0)
          printf ("\n base data[%d] = %10.2e from freq bin
                 %.2f to %.2f",loop,*(dptr+loop) / *(frac+loop),
                 (band_low + loop), (band_low + loop + 1));
         else
          printf ("\n base data[%d] = %10.2e from freq bin
                %.2f to %.2f", loop, *(dptr + loop),
                (band_low + loop), (band_low + loop + 1));
        }
       }
     }
   }
  }
}
/* Collapse the data over the scan dimension.
                                                               */
for (buf_num = 0; buf_num < NUM_BUFFERS; ++buf_num)</pre>
if (*(buf stat + buf num) == BUFFER READY)
 {
  /* Place the data for the current buffer into the matrix used to collapse data
                                                             */
  /* over the theta and/or scan dimensions (no phi, mass or charge dimensions).*/
```

```
ret_val = fill_theta_matrix (data_key, extension, vnum, num_sen,
                      sen numbers, ret data, ret frac,
                      ret_bin, num_units, buf_num, sen_units);
if (ret_val != ALL_OKAY)
ł
 printf ("\nError %d from fill_theta_matrix.\n", ret_val);
 exit (-1);
}
for (sensor = 0; sensor < num sensor; ++sensor)
 /* Collapse over scan dimension for the raw data. The single value will */
 /* be set to -3.4e38 (OUTSIDE MIN) if no data was present in the data */
                                                             */
 /* buffers for the sensor in question.
 ret val = collapse dimensions (data key, extension, vnum, sensor, dimen status,
                           start_range, stop_range, STRAIGHT_AVG, 0,
                           &data_ptr, 0, 1, 2, 0.0, 1, 0, 0, 0, 1, buf_num);
 if (ret_val != ALL_OKAY)
  ł
   printf ("\nError %d from collapse_dimensions.\n", ret_val);
  exit (-1);
  }
 if (*data ptr > OUTSIDE MIN)
  printf ("\n data from collapsing raw units for sensor %d is %10.2e",
         sensor, *data_ptr);
 /* Collapse over scan dimension for the base data. The single value will*/
 /* be set to -3.4e38 (OUTSIDE_MIN) if no data was present in the data */
 /* buffers for the sensor in question.
                                                             */
 last_plot = (sensor == num_sensor - 1) ? 1 : 0;
 ret_val = collapse_dimensions (data_key, extension, vnum, sensor, dimen_status,
                           start_range, stop_range, STRAIGHT_AVG, 0,
                           &data_ptr, 0, 1, 2, 0.0, 1, 0, 1, last_plot, 1, buf_num);
 if (ret_val != ALL_OKAY)
  ł
  printf ("\nError %d from collapse_dimensions.\n", ret_val);
  exit (-1);
  }
```

}

```
if (*data_ptr > OUTSIDE_MIN)
       printf ("\n data from collapsing base units for sensor %d is %10.2e", sensor, *data ptr);
     }
    }
   if (fill_code == LOS_STATUS)
    more data = 0;
   else if (fill code == NEXT FILE STATUS)
   {
    /* For realtime processing, btime_sec is set to -1 so that when files are crossed, */
    /* the routines will position the file at the beginning of that next file. The
                                                              */
    /* mandatory call to file pos can be found at the top of while loop.
                                                              */
    etime_yr, etime_day, etime_sec, etime_nsec);
    if (ret val != ALL OKAY)
     {
     printf ("\nError %d from reset experiment info.\n", ret val);
     exit (-1);
     }
   }
  }
free_experiment_info();
```

All of the routines used within the above program are detailed in depth within sections 1R and 2R of this manual. In all IDFS coding examples provided, the database assignment names for the project, mission, experiment, instrument and virtual instrument are used to determine the data key that is to be used for the data set in question.

This example demonstrates how a spin's worth of data can be acquired and processed.

#include <stdio.h> #include <string.h> #include "ret codes.h" #include "user defs.h" #include "libtrec_idfs.h" #include "libCfg.h" #include "libdb.h" void main (int argc, char **argv) { struct idf_data *EXP_DATA; register SDDAS_FLOAT *dptr, *frac; register SDDAS SHORT loop, i; SDDAS ULONG data key; SDDAS_USHORT vnum; SDDAS FLOAT *ret data, *ret frac, sen min, sen max, *base data, *base frac; SDDAS_FLOAT *center_ptr, *band_low, *band_high; SDDAS DOUBLE frac sec; SDDAS LONG btime sec, etime sec; SDDAS LONG *start time sec, *start time nano, *end time sec, *end time nano; SDDAS_LONG offset_unit, etime_nsec, btime_nsec, tbl_oper[5]; SDDAS_SHORT sensor, ret_val, accum_bin_stat, *sen_numbers, num_sen; SDDAS SHORT *num units, data block, uind raw, sen units; SDDAS SHORT num bands, num converted, fill code, btime yr; SDDAS_SHORT btime_day, etime_yr, etime_day, *start_time_yr, *start_time_day; SDDAS SHORT *end time yr, *end time day, spin sen ctrl; SDDAS_CHAR extension[3], data_type, hdr_change, num_tbls, err_str[200]; SDDAS CHAR *ret bin, *bin stat, *base bin; SDDAS_CHAR tbls_to_apply[5], num_center_band; short hr, min, sec; char more_data = 1, first_time = 1; void *idf_data_ptr; btime yr = 2002; btime_day = 301; btime sec = (19 * 3600) + (30 * 60) + 0; btime_nsec = 0; etime yr = 2002; etime_day = 301; etime_sec = (19 * 3600) + (30 * 60) + 20;

etime_nsec = 0;

```
strcpy (extension,"");
CfgInit();
dbInitialize();
init_idfs ();
/* Retreive the key that is associated with the project, mission, experiment, instrument */
/* and virtual instrument specified.
                                                         */
ret_val = get_data_key ("CLUSTERII", "CLUSTER-2", "PEACE", "3DR", "CP3DRH",
                &data key);
if (ret val != ALL OKAY)
 printf ("\n Error %d from get_data_key routine.\n", ret_val);
 exit (-1);
}
get version number (&vnum);
/* Create one instance of the data structure.
                                                          */
ret_val = create_idf_data_structure (&idf_data_ptr);
if (ret val != ALL OKAY)
 printf ("\n Error %d from create_idf_data_structure routine.\n", ret_val);
 exit (-1);
}
/* Open the data files associated with the time period selected for this data set /
                                                       */
/* extension / version combination.
                                                       */
ret_val = file_open (data_key, extension, vnum, btime_yr, btime_day, btime_sec,
             btime_nsec, etime_yr, etime_day, etime_sec, etime_nsec, 0);
if (ret val != ALL OKAY)
{
 printf ("\n Error %d from file open routine.\n", ret val);
 exit (-1);
}
```

```
/* Find the position in the data file closest to the requested start time for this data set.
                                                     */
/* Unlike real-time, if an error is encountered, the system should terminate - no need
                                                     */
                                                    */
/* to retry in anticipation of incoming data.
ret_val = file_pos (data_key, extension, vnum, idf_data_ptr, btime_yr, btime_day,
           btime sec, btime nsec, etime yr, etime day, etime sec, etime nsec);
if (ret_val != ALL_OKAY)
 printf ("\n Error %d from file_pos routine.\n", ret_val);
 exit (-1);
}
                                    */
spin_sen_ctrl = 0; /* sensor 0 as time controller
ret_val = start_of_spin (data_key, extension, vnum, spin_sen_ctrl, etime_yr, etime_day,
              etime sec, etime nsec);
if (ret val != ALL OKAY)
{
 printf ("\n Error %d from start of spin routine.\n", ret val);
 exit (-1);
}
/* Get the data for all sensors.
                                                      */
EXP DATA = (struct idf data *) idf data ptr;
while (more_data)
 /* Some items need to be set just once.
                                                   */
 if (first time)
  /* Select sensor data for sensor zero.
                                                  */
  first_time = 0;
  num tbls = 0;
  tbls_to_apply[0] = 1;
  tbl_oper[0] = 0;
  data_type = SENSOR;
```

```
sen_min = VALID_MIN;
sen max = VALID MAX;
sensor = spin_sen_ctrl;
ret_val = fill_sensor_info (data_key, extension, vnum, sensor, sen_min, sen_max, num_tbls,
                  tbls to apply, tbl oper, data type, 0);
if (ret val != ALL OKAY)
ł
 printf ("\n Error %d from fill sensor info routine.\n", ret val);
 exit (-1);
}
/* Create the data bins.
                                                        */
num_center_band = 0;
ret_val = set_bin_info (data_key, extension, vnum, VARIABLE_SWEEP, 0.0, 93.0, 1.0,
                93, LIN SPACING, num center band, tbls to apply, tbl oper,
                num_center_band, tbls_to_apply, tbl_oper,
                num center band, tbls to apply, tbl oper,
               'L', POINT_STORAGE, NO_BIN_FILL);
if (ret val != ALL OKAY)
 printf ("\n Error %d from set_bin_info routine.\n", ret_val);
 exit (-1);
}
/* The scan units should be in terms of electron volts.
                                                        */
num tbls = 0;
tbls_to_apply[0] = 0;
tbl_oper[0] = 0;
ret_val = set_scan_info (data_key, extension, vnum, num_tbls, tbls_to_apply, tbl_oper);
if (ret val != ALL OKAY)
{
 printf ("\n Error %d from set scan info routine.\n", ret val);
 exit (-1);
}
/* Since all sensors use the same scan range, any valid sensor number can be
                                                       */
/* passed in as the required argument.
                                                       */
```

```
ret_val = center_and_band_values (data_key, extension, vnum, idf_data_ptr, sensor, 1, 1,
                                &center ptr, &band low, &band high, &num bands,
                                &num converted);
 if (ret_val != ALL_OKAY && ret_val != CENTER_CONVERSION)
  ł
   printf ("\n Error %d from center_and_band_values routine.\n", ret_val);
   exit (-1);
  }
}
fill code = spin_data (data_key, extension, vnum, idf_data_ptr, &sen_numbers,
                  &ret data, &ret frac, &ret bin, &num sen, &num units,
                  &data_block, &start_time_yr, &start_time_day, &start_time_sec,
                  &start time nano, &end time yr, &end time day,
                  &end time sec, &end time nano, &hdr change);
if (fill_code != ALL_OKAY)
{
  printf ("\n Error %d from spin data routine.\n", ret val);
  exit (-1);
}
/* Loop over sensors processed by the SPIN DATA routine.
                                                                    */
for (i = 0; i < num\_sen; ++i)
 if (*(sen_numbers + i) == sensor)
  {
   offset unit = *(num units + i) * data block;
   base_data = ret_data + offset_unit;
   base frac = ret frac + offset unit;
   base_bin = ret_bin + offset_unit;
   num_tbls = 0;
   tbls_to_apply[0] = 1;
   tbl_oper[0] = 0;
   ret val = units index (data key, extension, vnum, sensor, sen min, sen max, tbls to apply,
                       tbl_oper, data_type, 0, &uind_raw, &sen_units, num_tbls);
   if (ret val != ALL OKAY)
    printf ("\n Error %d from units index routine.\n", ret val);
    exit (-1);
    }
```

```
if (fill\_code == ALL\_OKAY)
 {
   */
   /* Print the raw units data.
   offset_unit = uind_raw * data_block;
   dptr = base data + offset unit;
   frac = base_frac + offset_unit;
   bin stat = base bin + offset unit;
   accum_bin_stat = 0;
   for (loop = 0; loop < data_block; ++loop)
    accum_bin_stat += *(bin_stat + loop);
   /* Make sure there is some data in the buffers. Still check
                                                     */
   /* bin stat since frac will be 0.0 if bin stat = 0. For this
                                                     */
   /* data set, it is known that the sweep values are contiguous. */
   if (accum bin stat != 0)
    {
    frac_sec = *start_time_nano / 100000000.0;
    printf ("\nTIME %04d %03d ", *start_time_yr, *start_time_day);
    hr = *start\_time\_sec / 3600;
     sec = *start time sec \% 3600;
    \min = \sec / 60:
     \sec = \sec \% 60;
    printf ("%02d %02d %02d %9.6f", hr, min, sec, frac_sec);
    for (loop = 0; loop < data block; ++loop)
     {
      if (*(bin_stat + loop) != 0)
       printf ("\n%8.3f
                        %3.0f",*(dptr+loop) / *(frac+loop), (float) loop);
      else
                        %3.0f", *(dptr + loop), (float) loop);
       printf ("\n%10.2e
     }
   }
  }
}
```

```
free_experiment_info();
}
```

example 6

This example demonstrates how a programmer would go about developing a program that utilizes the SCF software. The data that is returned is displayed to the screen, but these values could be sent to a file to be used by another program or some other action could be taken once the results were retrieved.

```
#include <stdio.h>
#include <string.h>
#include <stdlib.h>
#include "SCF_defs.h"
#include "SCF file defs.h"
#include "libbase SCF.h"
#include "libCfg.h"
#include "libdb.h"
void main (int argc, char **argv)
 struct scf_data *SCF_DATA;
 register SDDAS LONG i;
 SDDAS_FLOAT *dptr, *stop_loop;
 SDDAS DOUBLE time value;
 SDDAS_LONG btime_sec, etime_sec, ret_time_sec, ret_time_nano;
 SDDAS LONG etime nano, btime nano, num output, *intptr, *dimen;
 SDDAS_USHORT scf_vnum;
 SDDAS_SHORT ret_val, btime_yr, btime_day, etime_yr, etime_day;
 SDDAS CHAR filename[SCF FILENAME];
 char more data = 1;
 void *scf_data_ptr;
 */
 /* Set the time for processing.
 btime_yr = 1992;
 btime_day = 217;
 btime \sec = 32340;
 btime nano = 0;
 etime yr = 1992;
 etime_day = 217;
 etime sec = 32342;
 etime_nano = 0;
```

strcpy (filename, "TMMO_EXAMPLE");

```
CfgInit ();
dbInitialize ():
init_scf ();
*/
/* Open the SCF file and all input data sets.
scf_version_number (&scf_vnum);
ret val = scf open (filename, scf vnum, btime yr, btime day, btime sec, btime nano,
           etime_yr, etime_day, etime_sec, etime_nano);
if (ret val != ALL OKAY)
{
 printf ("\n Error %d from scf_open routine.\n", ret_val);
 exit (-1);
}
/* Position the input data sets at the requested start time.
                                             */
ret val = scf position (filename, scf vnum, btime yr, btime day, btime sec,
             btime_nano, etime_yr, etime_day, etime_sec, etime_nano);
if (ret_val != ALL_OKAY)
{
 printf ("\n Error %d from scf_position routine.\n", ret_val);
 exit (-1);
}
*/
/* Create one instance of the data structure.
ret_val = create_scf_data_structure (filename, scf_vnum, &scf_data_ptr);
if (ret_val != ALL_OKAY)
{
 printf("\n Error %d from create_scf_data_structure routine.\n",ret_val);
 exit (-1);
SCF_DATA = (struct scf_data *) scf_data_ptr;
*/
/* Find the input source with the fastest sample rate.
```

```
time_value = 0.0;
ret_val = scf_sample_rate (filename, scf_vnum, SCF_DELTA_T, time_value,
                   SCF_MEASURE_LAT_TM);
if (ret val != ALL OKAY)
 printf ("\n Error %d from scf_sample_rate routine.\n", ret_val);
 exit (-1);
}
*/
/* Determine the number of output variables being returned.
ret_val = read_scf (filename, scf_vnum, S_NUM_OUTPUT, NOT_USED,
              (SDDAS_CHAR *) &num_output);
if (ret_val != ALL_OKAY)
 printf ("\n Error %d from read_scf routine.\n", ret_val);
 exit (-1);
}
intptr = (SDDAS_LONG *) calloc ((size_t) num_output, sizeof (SDDAS_LONG));
if (intptr == 0)
{
 printf ("\n Error from calloc system call.\n");
 exit (-1);
}
/* Retrieve the "dimensionality" of the output variables.
                                                       */
for (dimen = intptr, i = 0; i < num_output; ++i, ++dimen)
ł
 ret_val = read_scf (filename, scf_vnum, S_OUTPUT_DIMENSION, i,
               (SDDAS_CHAR *) dimen);
 if (ret_val != ALL_OKAY)
 {
  printf ("\n Error %d from read scf routine.\n", ret val);
  exit (-1);
  }
ł
dimen = intptr;
```

```
/* Evaluate the algorithm, retrieving the output until the requested end time has been
                                                   */
                                                   */
/* reached.
while (more_data)
ł
 ret val = scf output data (filename, scf vnum, scf data ptr);
 if (ret_val != ALL_OKAY && ret_val != SCF_TERMINATE)
  printf ("\n Error %d from scf_output_data routine.\n", ret_val);
  exit (-1);
 }
 printf ("\n\nSTART YEAR = %d START DAY = %d", SCF_DATA->byear,
     SCF_DATA->bday);
 printf ("\nSTART TIME_MS = %ld START TIME_NS = %ld", SCF_DATA->bmilli,
     SCF DATA->bnano);
 printf ("\nEND YEAR = %d END DAY = %d", SCF_DATA->eyear, SCF_DATA->eday);
 printf ("\nEND TIME MS = %ld END TIME NS = %ld", SCF DATA->emilli,
     SCF_DATA->enano);
 */
 /* Print the output variables returned.
 for (i = 0; i < SCF_DATA->num_output; ++i)
 ł
  dptr = SCF_DATA->output_data + *(SCF_DATA->output_index + i);
  stop_loop = dptr + *(SCF_DATA->output_length + i);
  */
  /* Print out scalar output only.
  if (*(dimen + i) == 0)
  for (; dptr < stop_loop; ++dptr)</pre>
   printf ("\nOutput Variable %ld = %e", i, *dptr);
 }
 */
 /* Processing must be stopped due to data not being online.
```

```
if (ret_val == SCF_TERMINATE)
  {
  more data = 0;
  break;
  }
 /* End time has been reached? Compare against the end time of the iteration since
                                                                 */
 /* requested end time could fall between the time range processed.
                                                                  */
 ret_time_sec = (SCF_DATA -> emilli + (SCF_DATA -> enano / 1000000)) / 1000;
 ret_time_nano = (SCF_DATA->emilli % 1000) * 1000000 + SCF_DATA->enano;
 if (SCF_DATA->eyear > etime_yr ||
  (SCF_DATA->eyear == etime_yr && SCF_DATA->eday > etime_day) ||
  (SCF_DATA->eyear == etime_yr && SCF_DATA->eday == etime_day &&
   ret time sec > etime sec) \parallel
   (SCF_DATA->eyear == etime_yr && SCF_DATA->eday == etime_day &&
   ret time sec == etime sec && ret time nano > etime nano))
  {
  more data = 0;
  break;
  }
}
free_scf_info ();
exit(0);
```

example 7

This example demonstrates how a programmer would go about developing a program that utilizes the SCF software to return time-averaged data.

```
#include <stdio.h>
#include <string.h>
#include "SCF defs.h"
#include "user_defs.h"
#include "libbase SCF.h"
#include "libavg SCF.h"
#include "libCfg.h"
#include "libdb.h"
void main (int argc, char **argv)
{
 struct scf data *SCF DATA;
 register SDDAS LONG i, loop, buf num;
 register SDDAS_FLOAT *dptr, *frac;
 SDDAS DOUBLE frac sec;
 SDDAS_FLOAT *ret_data, *ret_frac, *base_data, *base_frac;
 SDDAS FLOAT time frac, data min, data max, *center bin, *bin low, *bin high;
 SDDAS_ULONG buf_zero_loc;
 SDDAS LONG stime sec, stime nano, end time sec, end time nano, offset unit;
 SDDAS_LONG btime_sec, btime_nano, etime_sec, etime_nano, offset_buf;
 SDDAS_LONG base_sec, base_nano, res_sec, res_nano, base_pix, output_var;
 SDDAS LONG dependent var, accum bin stat, block size, *bpix, *epix;
 SDDAS_LONG num_output, *output_numbers, *output_size, num_select, output_ind;
 SDDAS_LONG time_msec, num_bands;
 SDDAS USHORT scf vnum;
 SDDAS_SHORT ret_val, btime_yr, btime_day, etime_yr, etime_day, end_time_yr, ret_code;
 SDDAS SHORT base yr, base day, hr, min, sec, stime yr, stime day, end time day;
 SDDAS_CHAR filename[SCF_FILENAME], *ret_bin, *base_bin;
 SDDAS_CHAR *buf_stat, *bin_stat;
 char more data = 1;
 void *scf data ptr;
 /* Set the time for processing.
                                                            */
 btime yr = 1992;
 btime_day = 217;
 btime_sec = 32340;
 btime_nano = 0;
```

```
etime_yr = 1992;
etime day = 217;
etime_sec = 32342;
etime_nano = 0;
strcpy (filename, "TMMO_EXAMPLE");
CfgInit ();
dbInitialize ();
init_scf ();
/* Open the SCF file and all input data sets.
                                               */
scf_version_number (&scf_vnum);
ret_val = scf_open (filename, scf_vnum, btime_yr, btime_day, btime_sec, btime_nano,
             etime_yr, etime_day, etime_sec, etime_nano);
if (ret val != ALL OKAY)
{
 printf ("\n Error %d from scf open routine.\n", ret val);
 exit (-1);
}
/* Position the input data sets at the requested start time.
                                                   */
ret_val = scf_position (filename, scf_vnum, btime_yr, btime_day, btime_sec,
               btime_nano, etime_yr, etime_day, etime_sec, etime_nano);
if (ret_val != ALL_OKAY)
{
 printf ("\n Error %d from scf_position routine.\n", ret_val);
 exit (-1);
}
*/
/* Create one instance of the data structure.
ret_val = create_scf_data_structure (filename, scf_vnum, &scf_data_ptr);
if (ret_val != ALL_OKAY)
{
 printf ("\n Error %d from create_scf_data_structure routine.\n", ret_val);
 exit (-1);
}
```

*/

```
SCF_DATA = (struct scf_data *) scf_data_ptr;
/* Find the input source with the fastest sample rate.
time frac = 0.0;
ret_val = scf_sample_rate (filename, scf_vnum, SCF_DELTA_T, time_frac,
                 SCF_MEASURE_LAT_TM);
if (ret val != ALL OKAY)
{
 printf ("\n Error %d from scf_sample_rate routine.\n", ret_val);
 exit (-1);
}
*/
/* Set the base reference time, location and duration for the data buffers.
ret_val = scf_algorithm_start (filename, scf_vnum, &base_yr, &base_day,
                   &base_sec, &base_nano, &res_sec, &res_nano);
if (ret val < 0)
 printf ("\n Error %d from scf_algorithm_start routine.\n", ret_val);
 exit (-1);
}
base_pix = 0;
scf_time_reference (scf_vnum, base_yr, base_day, base_sec, base_nano,
             base_pix, res_sec, res_nano);
*/
/* Create the data bins for output variable zero.
output_var = 0;
dependent_var = -1;
ret_val = scf_bin_info (filename, scf_vnum, output_var, FIXED_SWEEP,
               0.0, 0.0, 1, LIN_SPACING, dependent_var,
               dependent_var, '', POINT_STORAGE);
if (ret_val != ALL_OKAY)
ł
 printf ("\n Error %d from scf_bin_info routine.\n", ret_val);
 exit (-1);
}
```

```
/* Select output variable zero, which is known to be scalar, so no dependent
                                                       */
                                                       */
/* variable needed.
data_min = VALID_MIN;
data max = VALID MAX;
ret val = scf output select (filename, scf vnum, output var, data min, data max,
                   dependent_var);
if (ret_val != ALL_OKAY)
 printf ("\n Error %d from scf output select routine.\n", ret val);
 exit (-1);
}
/* Evaluate the algorithm, retrieving the output until the requested end time is reached. */
while (more data)
 ret code = scf time average (filename, scf vnum, scf data ptr, &ret data, &ret frac,
                      &ret_bin, &bpix, &epix, &buf_stat, &stime_yr, &stime_day,
                      &stime_sec, &stime_nano, &end_time_yr, &end_time_day,
                      &end_time_sec, &end_time_nano, &num_output,
                      &output_numbers, &output_size);
 if (ret_code != ALL_OKAY && ret_code != SCF_TERMINATE)
 ł
  printf ("\n Error %d from scf_time_average routine.\n", ret_code);
  exit (-1);
  }
 */
 /* Loop over output variables processed by scf_time_average().
 for (i = 0; i < num\_output; ++i)
 ł
  if (*(output_numbers + i) == output_var)
   ret_val = scf_output_center_and_bands (filename, scf_vnum, output_var,
                            &center bin, &bin low, &bin high, &num bands);
   if (ret_val != ALL_OKAY)
     printf ("\n Error %d from scf output center and bands routine.\n", ret val);
```

December 28, 2012

```
exit (-1);
}
ret_val = scf_output_data_index (filename, scf_vnum, output_var, data_min, data_max,
                     dependent_var, &num_select, &output_ind, &buf_zero_loc);
if (ret val != ALL OKAY)
ł
 printf ("\n Error %d from scf_output_data_index routine.\n", ret_val);
 exit (-1);
}
/* Set pointers to the beginning of the first buffer for the selected output variable.*/
base_data = ret_data + buf_zero_loc;
base_frac = ret_frac + buf_zero_loc;
base bin = ret bin + buf zero loc;
block_size = *(output_size + i);
for (buf_num = 0; buf_num < NUM_BUFFERS; ++buf_num)
if (*(buf_stat + buf_num) == BUFFER_READY)
{
  */
  /* Point to the buffer being processed, then point to the definition
  /* being processed.
                                                     */
  offset buf = buf num * num select * block size;
  offset_unit = output_ind * block_size;
  dptr = base_data + offset_buf + offset_unit;
  frac = base frac + offset buf + offset unit;
  bin_stat = base_bin + offset_buf + offset_unit;
  accum_bin_stat = 0;
  for (loop = 0; loop < block_size; ++loop)
   accum_bin_stat += *(bin_stat + loop);
  /* Make sure there is some data in the buffers. For this data, the bins are */
  /* contiguous since FIXED_SWEEP LIN_SPACING was utilized for
                                                      */
                                                      */
  /* scf bin info().
```

}

```
if (accum_bin_stat != 0)
       frac sec = stime nano / 100000000.0;
       hr = stime sec / 3600;
       sec = stime sec \% 3600;
       \min = \sec / 60;
        \sec = \sec \% 60:
        time_msec = stime_sec * 1000 + (stime_nano / 1000000);
        printf ("\nTIME %04d %03d ", stime_yr, stime_day);
       printf ("%02d %02d %02d %9.6f", hr, min, sec, frac sec);
        for (loop = 0; loop < block size; ++loop)
        {
         if (*(bin_stat + loop) != 0)
          printf ("\n%e bin_low = %e bin_high = %e",*(dptr+loop) / *(frac+loop),
                                 *(bin_low + loop), *(bin_low + loop + 1));
         else
          printf ("n\%10.2e bin low = %e bin high = %e", *(dptr + loop),
                          (bin_low + loop), (bin_low + loop + 1));
        }
       }
     }
   }
  }
 /* Processing must terminate due to data not being on-line.
                                                                 */
 if (ret_code == SCF_TERMINATE)
  break:
 /* End time has been reached? Compare against the end time of the iteration since
                                                                 */
                                                                 */
 /* requested end time could fall between the time range processed.
 if (end_time_yr == etime_yr && end_time_day == etime_day && end_time_sec > etime_sec)
  break:
 else if (end_time_yr == etime_yr && end_time_day == etime_day &&
      end time sec == etime sec && end time nano > etime nano)
  break;
free_scf_info ();
exit (0);
```

This example demonstrates how a programmer would go about developing a program that utilizes the SCF software to return sample-averaged data.

```
#include <stdio.h>
#include <string.h>
#include "SCF defs.h"
#include "user_defs.h"
#include "libbase SCF.h"
#include "libavg_SCF.h"
#include "libCfg.h"
#include "libdb.h"
void main (int argc, char **argv)
{
 struct scf data *SCF DATA;
 register SDDAS LONG i, loop;
 register SDDAS_FLOAT *dptr, *frac;
 SDDAS DOUBLE frac sec;
 SDDAS_FLOAT *ret_data, *ret_frac, *base_data, *base_frac;
 SDDAS FLOAT time frac, data min, data max, *center bin, *bin low, *bin high;
 SDDAS_ULONG buf_zero_loc;
 SDDAS LONG stime sec, stime nano, end time sec, end time nano, offset unit;
 SDDAS_LONG btime_sec, btime_nano, etime_sec, etime_nano, time_msec, num_bands;
 SDDAS_LONG dependent_var, accum_bin_stat, block_size, output_var;
 SDDAS LONG num output, *output numbers, *output size, num select, output ind;
 SDDAS USHORT scf vnum;
 SDDAS_SHORT ret_code, ret_val, btime_yr, btime_day, etime_yr, etime_day;
 SDDAS SHORT hr, min, sec, stime yr, stime day, end time yr, end time day;
 SDDAS_CHAR filename[SCF_FILENAME], *ret_bin, *base_bin, *bin_stat;
 char more data = 1:
 void *scf_data_ptr;
 */
 /* Set the time for processing.
 btime_yr = 1992;
 btime day = 217;
 btime_sec = 32340;
 btime nano = 0;
 etime_yr = 1992;
 etime_day = 217;
```

```
etime sec = 32342;
etime nano = 0;
strcpy (filename, "TMMO_EXAMPLE");
CfgInit ():
dbInitialize ();
init_scf ();
/* Open the SCF file and all input data sets.
scf version number (&scf vnum);
ret_val = scf_open (filename, scf_vnum, btime_yr, btime_day, btime_sec, btime_nano,
             etime_yr, etime_day, etime_sec, etime_nano);
if (ret val != ALL OKAY)
{
 printf ("\n Error %d from scf_open routine.\n", ret_val);
 exit (-1);
}
/* Position the input data sets at the requested start time.
                                                   */
ret_val = scf_position (filename, scf_vnum, btime_yr, btime_day, btime_sec,
               btime_nano, etime_yr, etime_day, etime_sec, etime_nano);
if (ret_val != ALL_OKAY)
ł
 printf ("\n Error %d from scf_position routine.\n", ret_val);
 exit (-1);
}
/* Create one instance of the data structure.
                                                           */
ret_val = create_scf_data_structure (filename, scf_vnum, &scf_data_ptr);
if (ret val != ALL OKAY)
{
 printf ("\n Error %d from create scf data structure routine.\n", ret val);
 exit (-1);
}
SCF_DATA = (struct scf_data *) scf_data_ptr;
```

```
*/
/* Find the input source with the fastest sample rate.
time frac = 0.0;
ret_val = scf_sample_rate (filename, scf_vnum, SCF_DELTA_T, time_frac,
                SCF_MEASURE_LAT_TM);
if (ret val != ALL OKAY)
 printf ("\n Error %d from scf_sample_rate routine.\n", ret_val);
 exit (-1):
}
*/
/* Create the data bins for output variable zero.
output_var = 0;
dependent_var = -1;
ret val = scf bin info (filename, scf vnum, output var, FIXED SWEEP,
              0.0, 0.0, 1, LIN_SPACING, dependent_var,
             dependent_var, dependent_var, '', POINT_STORAGE);
if (ret_val != ALL_OKAY)
ł
 printf ("\n Error %d from scf_bin_info routine.\n", ret_val);
 exit (-1);
}
/* Select output variable zero, which is known to be scalar, so no dependent
                                                */
/* variable needed.
                                                */
data_min = VALID_MIN;
data_max = VALID_MAX;
ret_val = scf_output_select (filename, scf_vnum, output_var, data_min, data_max,
                dependent_var);
if (ret_val != ALL_OKAY)
 printf ("\n Error %d from scf output select routine.\n", ret val);
 exit (-1);
}
/* Evaluate the algorithm, averaging two iterations of the algorithm until the requested */
/* end time has been reached.
                                                     */
```

ł

```
while (more_data)
 ret_code = scf_sample_average (filename, scf_vnum, scf_data_ptr, 2, &ret_data, &ret_frac,
                      &ret_bin, &stime_yr, &stime_day, &stime_sec, &stime_nano,
                      &end time yr, &end time day, &end time sec, &end time nano,
                      &num output, &output numbers, &output size);
 if (ret_code != ALL_OKAY && ret_code != SCF_TERMINATE)
  {
  printf ("\n Error %d from scf_sample_average routine.\n", ret_code);
  exit (-1);
  }
 */
 /* Loop over output variables processed by scf sample average().
 for (i = 0; i < num\_output; ++i)
  ł
  if (*(output\_numbers + i) == output var)
    ret_val = scf_output_center_and_bands (filename, scf_vnum, output_var,
                         &center bin, &bin low, &bin high, &num bands);
    if (ret val != ALL OKAY)
     printf ("\n Error %d from scf_output_center_and_bands routine.\n", ret_val);
     exit (-1);
     }
    ret_val = scf_output_data_index (filename, scf_vnum, output_var, data_min, data_max,
                             dependent var, &num select, &output ind,
                             &buf_zero_loc);
    if (ret val != ALL OKAY)
    ł
     printf ("\n Error %d from scf_output_data_index routine.\n", ret_val);
     exit (-1);
     }
    /* Set pointers to the beginning of the data for the selected output variable.
                                                                */
    base data = ret data + buf zero loc;
    base_frac = ret_frac + buf_zero_loc;
    base_bin = ret_bin + buf_zero_loc;
```

block size = $*(output_size + i);$

```
*/
  /* Point to the definition being processed.
  offset_unit = output_ind * block_size;
  dptr = base_data + offset_unit;
  frac = base_frac + offset_unit;
  bin stat = base bin + offset unit;
  accum_bin_stat = 0;
  for (loop = 0; loop < block_size; ++loop)
   accum_bin_stat += *(bin_stat + loop);
  */
  /* Make sure there is some data in the buffer.
  if (accum_bin_stat != 0)
  {
   frac sec = stime nano / 100000000.0;
   hr = stime\_sec / 3600;
   sec = stime sec \% 3600;
   \min = \sec / 60;
   \sec = \sec \% 60:
   printf ("\nTIME %04d %03d ", stime_yr, stime_day);
   printf ("%02d %02d %02d %9.6f", hr, min, sec, frac_sec);
   for (loop = 0; loop < block size; ++loop)
    {
    if (*(bin_stat + loop) != 0)
     printf ("\n%e",*(dptr+loop) / *(frac+loop));
    else
     printf ("\n%10.2e", *(dptr + loop));
    }
   }
 }
*/
/* Processing must terminate due to data not being on-line.
```

```
if (ret_code == SCF_TERMINATE)
break:
```

}

}

ADJUST_TIME

function - adjusts the time components if a year/day boundary has been crossed

SYNOPSIS

#include "libbase_idfs.h"

void adjust_time (SDDAS_SHORT *year, SDDAS_SHORT *day, SDDAS_LONG *time, SDDAS_CHAR time_unit)

ARGUMENTS

year	- the year time component
day	- the day of year time component
time	- the time of day time component
time_unit	- flag which specifies the time unit for the time argument
	1 - the time of day component is specified in seconds
	2 – the time of day component is specified in milliseconds

DESCRIPTION

Adjust_time is the IDFS routine that will correct time components when a day boundary or boundaries have been crossed. Year boundaries and leap years are taken into account during the calculation. If the time values are correct as is, the time values are not modified in any way.

ERRORS

This routine returns no status or error codes.

BUGS

None

EXAMPLES

Correct the time values in case the time of day value represents more than a day's worth of milliseconds. Assume that time values have already been set.

#include "libbase_idfs.h"

SDDAS_SHORT year, day; SDDAS_LONG tod_milli; SDDAS_CHAR time_unit;

time_unit = 2; adjust_time (&year, &day, &tod_milli, time_unit); adjust_time (1R)

CALC_TIME_RESOLUTION

function - returns the maximum temporal resolution allowed by the selected data set

SYNOPSIS

#include "libbase_idfs.h"
#include "ret_codes.h"

n,
ec)

ARGUMENTS

data_key	- unique value which indicates the data set of interest
exten	- two character extension to be added to IDFS file names when
	default files are not to be used, otherwise a null string
version	- IDFS data set identification number which allows for multiple
	openings of the same data set
idf_data_ptr	- pointer to the idf_data structure that is to hold sensor data and
-	pertinent ancillary data for the data set of interest
num_sweeps	- the number of sweeps / spins to use to calculate the maximum
_	temporal resolution
	– negative value indicates spins are to be utilized for the
	calculation
	 positive value indicates sweeps are to be utilized for the
	calculation
res_sec	- the temporal resolution expressed in seconds
res_nsec	- the temporal resolution residual of seconds expressed in
	nanoseconds
calc_time_resolution	- routine status (see TABLE 1)

TABLE 1. Status Codes Returned for CALC_TIME_RESOLUTION

STATUS CODE	EXPLANATION OF STATUS
CALC_TRES_NOT_FOUND	the requested data_key, exten, version combination has no memory allocated
	for processing (user did not call file_open for this combination)
WRONG_HEADER_FORMAT	multi-dimensional IDFS data storage is not supported by this module
ALL_OKAY	routine terminated successfully

DESCRIPTION

Calc_time_resolution is the IDFS routine that determines the maximum temporal resolution associated with the data set of interest, which is referenced through the key value **data_key** which can be created using the **get_data_key** module. The calculated resolution may be modified by specifying the number of sweeps/spins which are to be processed. If the parameter **num_sweeps** is set to indicate that the resolution should be calculated in terms of spins, a check is made to determine if the data set requested returns a spin rate. If

the data set does not return a spin rate, the resolution is calculated in terms of sweeps, not spins. Before this routine can be utilized, a call to the routine **file_open** must be made.

The parameter **version** allows multiple file openings for an IDFS data set. If the data, header and VIDF file for the specified data set need to be opened just once for processing, the same version number should be passed to all IDFS routines. However, for multiple file openings, the version number should be unique and all file manipulations performed by the IDFS routines will use the file descriptors defined for the version number specified. The user should call the **get_version_number** routine to retrieve a unique version number instead of choosing this value themselves. The retrieval of multiple data parameters from a single data source does not constitute the need for multiple version numbers; a single version number will suffice.

The parameter **idf_data_ptr** is a pointer to the structure that is to hold all data pertinent to the data set being processed. The structure is created and the address to this structure is returned when a call to the **create_idf_data_structure** routine is made. The user also has the option of calling the module **create_data_structure**, which determines what type of data structure is needed for the IDFS data set of interest. In most cases, one data structure is sufficient to process any number of distinct data sets. However, if more than one structure is needed, the user may call the **create_idf_data_structure** routine N times to create N instances of the **idf_data** structure. The user must keep track of which pointer to send to the IDFS routines that utilize this structure.

If the **file_open** routine is not to open the default set of IDFS files but a modified set of IDFS files, the two character extension applied to these data files must be supplied to this routine within the string variable **exten**. These files must have the identical name as the IDFS files with the two character identification code appended to the end of the file names (i.e. RTLA19922181432Dxx, RTLA19922181432Hxx, RTLA19922181432Ixx). The files must reside either in the directory specified by the environment variable USER_DATA, which is set by the user, or in the user's home directory if the environment variable USER_DATA is not set. To open the default IDFS data files, **exten** should be set to a null string. The usage of modified data sets is limited to post acquisition data; therefore, it is suggested that the user set **exten** to a null string for real-time scenarios.

ERRORS

All errors within this routine are returned through the status variable. The include file **ret_codes.h**, which includes all possible return values, should be included so that the mnemonics for the return codes can be referenced. The **ret_codes.h** file is described in section 1H of the IDFS Programmers Manual.

SEE ALSO

file_open	1 R
get_data_key	1 R
get_version_number	1R
create_data_structure	1R

create_idf_data_structure	1R
ret_codes	1H
libbase_idfs	1H

BUGS

None

EXAMPLES

Determine the temporal resolution for four sweeps of data from the virtual instrument RTLA, which is part of the RETE instrument/experiment, which is part of the TSS-1 mission, which is identified with the TSS project.

#include "libbase_idfs.h"
#include "ret_codes.h"

SDDAS_ULONG data_key; SDDAS_USHORT vnum; SDDAS_LONG res_sec, res_nsec; SDDAS_SHORT status; void *idf_data_ptr;

```
status = get_data_key ("TSS", "TSS-1", "RETE", "RETE", "RTLA", &data_key);
if (status != ALL_OKAY)
{
    printf ("\n Error %d returned by get_data_key routine.\n", status);
    exit (-1);
    get_version_number (&vnum);
```

```
status = create_idf_data_structure (&idf_data_ptr);
if (status != ALL_OKAY)
{
    printf ("\n Error %d returned by create_idf_data_structure routine.\n", status);
    exit (-1);
}
```

```
status = calc_time_resolution (data_key, "'", vnum, idf_data_ptr, 4,
&res_sec, &res_nsec);
if (status != ALL_OKAY)
```

```
{
    printf ("\n Error %d returned by calc_time_resolution routine.\n", status);
    exit (-1);
}
```

CONVERT_TO_UNITS

function - converts raw data into units by applying the tables and operations specified

SYNOPSIS

#include "libbase_idfs.h"
#include "ret_codes.h"
#include "user_defs.h"

SDDAS_SHORT convert_to_units (SDDAS_ULONG data_key, SDDAS_CHAR *exten,
SDDAS_USHORT version, void *idf_data_ptr,
SDDAS_SHORT sensor, SDDAS_CHAR data_type,
SDDAS_CHAR cal_set, SDDAS_CHAR num_tbls,
SDDAS_CHAR *tbls_to_apply, SDDAS_LONG *tbl_oper,
SDDAS_FLOAT *ret_data, SDDAS_CHAR chk_fill,
SDDAS_LONG fill_value)

ARGUMENTS

GUMENIS	
data_key	- unique value which indicates the data set of interest
exten	- two character extension to be added to IDFS file names when
	default files are not to be used, otherwise a null string
version	- IDFS data set identification number which allows for multiple
	openings of the same data set
idf_data_ptr	- pointer to the idf_data structure that is to hold sensor data and
-	pertinent ancillary data for the data set of interest
sensor	- the sensor identification number if processing sensor, sweep step,
	calibration, data quality, pitch angle, azimuthal angle, or spacecraft
	potential data; otherwise, the instrument status (mode) value of
	interest
data_type	- the type of data being requested
•••	1 - sensor data (SENSOR)
	2 - sweep step data (SWEEP_STEP)
	3 - calibration data (CAL_DATA)
	4 - instrument status or mode data (MODE)
	5 - data quality data (D_QUAL)
	6 - pitch angle data (PITCH_ANGLE)
	7 - start azimuthal angle data (START_AZ_ANGLE)
	8 - stop azimuthal angle data (STOP_AZ_ANGLE)
	9 – spacecraft potential data (SC_POTENTIAL)
	10 – background data (BACKGROUND)
cal_set	- the calibration set from which requested calibration data
	(CAL_DATA) is to be retrieved
	- If calibration data is not being requested, this parameter is
	not utilized and it is suggested that the user pass a value of
	zero for this parameter.
num_tbls	 the number of elements specified in the tbls_to_apply and
	tbl_oper parameters

tbls_to_apply - the tables that are to be applied in order to derive the desired un	
tbl_oper - the operations that are to be applied to the specified tables in or to derive the desired units	der
ret_data - user-defined array which holds the data in the unit requested	
chk_fill - flag indicating if the data is to be checked for fill values. If a f	i 11
value is found within the data and if the chk_fill flag is set to 1	, the
data value will be returned as -3.4e38 (OUTSIDE_MIN) in the	
ret_data array in order to flag the data as a fill value. If the ch	k_fill
flag is set to 0, all data is treated as valid data and is returned as	3
such in the ret_data array. Fill data is only applicable to SENS	SOR
and CAL_DATA data types.	
0 - do not check for fill values	
1 - check for fill values	
fill_value - the fill data value, as specified within the raw telemetry	
convert_to_units - routine status (see TABLE 1)	

TABLE 1. Status Codes Returned for CONVERT_TO_UNITS

STATUS CODE	EXPLANATION OF STATUS
CNVT_NOT_FOUND	the requested data_key, exten, version combination has no memory allocated
	for processing (user did not call file_open for this combination)
CNVT_BAD_DTYPE	invalid data type value
CNVT_BAD_TBL_OPER	the look-up operation is not defined for the combination of the primary and
	intermediate accumulators
CNVT_BAD_TBL_NUM	invalid table number
CNVT_NO_TMP	there is no data in the intermediate accumulator to combine with the primary
	accumulator
CNVT_TMP_MALLOC	no memory for the intermediate accumulator
CONV_CAL_MALLOC	no memory for temporary array that holds the calibration data before it is
	expanded to vector length
CONV_CAL_VECTOR_MISMATCH	one of the tables specified is a function of data that is not dimensioned the
	same size as the requested calibration set
CONV_MODE_BAD_MODE	invalid instrument status (mode) value
CONV_MODE_BAD_TBL_NUM	the table specified is not a mode-dependent table for the mode in question
CONV_MODE_MISMATCH	only tables that apply to mode data are valid
CNVT_NO_ADV	a table operator references an advanced data buffer(s) which does not contain
	any data to use in order to perform the specified operation
CNVT_BAD_BUF_NUM	a table operator specifies a combination function to be performed on
	advanced data buffers and specifies a 2 for the FROM or TO buffer value. A
	value of 2 is reserved and cannot be used.
CNVT_SAME_BUF_NUM	a table operator specifies a combination function to be performed on
	advanced data buffers and specifies the same value for the FROM and TO
	buffer values – the two data buffers values must be different
WRONG_DATA_STRUCTURE	incompatibility between IDFS data set and IDFS data structure used to hold
	the data being returned
ALL_OKAY	routine terminated successfully

DESCRIPTION

Convert_to_units is the IDFS data conversion routine. This routine will convert sensor data, sweep step data, calibration data, instrument status (mode) information, data quality data, pitch angle data, azimuthal angle data, spacecraft potential data and background data to different formats (units) by applying the tables and the table operations in the specified order. It is imperative that a call to the **read_drec** routine be made PRIOR to calling this routine in order to fill the **idf_data** structure. With the exception of mode data, all data types are associated with a specific sensor, which is indicated through the sensor number (**sensor**). The sensor is further identified as being associated with a specific data set. The data set of interest is referenced through the key value **data_key** which can be created using the **get_data_key** module.

There are two data types defined for azimuthal angle data, **START_AZ_ANGLE** and **STOP_AZ_ANGLE**. The start azimuthal angle values are always returned as values between 0 and 360 degrees. However, the stop azimuthal angle values could be negative (if the instrument is spinning in a negative direction) or could be greater than 360 degrees. The stop azimuthal angle values are computed by adding the degrees covered by the accumulation time of each sample to the start azimuthal angle values.

The instrument status (mode) data comes from the header record and is defined for the virtual instrument in question; therefore, the instrument status data is not associated with any particular sensor. When mode data is being requested, the user should set the **sensor** parameter to specify the status value of interest, with the numbering starting at zero.

The units that the data is to be returned in is specified by the user through the parameters **num_tbls**, **tbls_to_apply** and **tbl_oper**. If the user wants raw units, that is, the telemetry data, to be returned, the user should set the **num_tbls** parameter to zero and put a placeholder variable for the **tbls_to_apply** and **tbl_oper** parameters. The raw units for pitch angle and azimuthal angle data is defined as degrees. For other units pertinent to the data set requested, the user must specify the tables and the table operations that are to be applied to calculate the desired unit. The order is implied by the contents of the **tbls_to_apply** array.

The parameter **version** allows multiple file openings for an IDFS data set. If the data, header and VIDF file for the specified data set need to be opened just once for processing, the same version number should be passed to all IDFS routines. However, for multiple file openings, the version number should be unique and all file manipulations performed by the IDFS routines will use the file descriptors defined for the version number specified. The user should call the **get_version_number** routine to retrieve a unique version number instead of choosing this value themselves. The retrieval of multiple data parameters from a single data source does not constitute the need for multiple version numbers; a single version number will suffice.

The parameter **idf_data_ptr** is a pointer to the structure that is to hold all data pertinent to the data set being processed. The structure is created and the address to this structure is

returned when a call to the **create_idf_data_structure** routine is made. The user also has the option of calling the module **create_data_structure**, which determines what type of data structure is needed for the IDFS data set of interest. In most cases, one data structure is sufficient to process any number of distinct data sets. However, if more than one structure is needed, the user may call the **create_idf_data_structure** routine N times to create N instances of the **idf_data** structure. The user must keep track of which pointer to send to the IDFS routines that utilize this structure.

If the **file_open** routine is not to open the default set of IDFS files but a modified set of IDFS files, the two character extension applied to these data files must be supplied to this routine within the string variable **exten**. These files must have the identical name as the IDFS files with the two character identification code appended to the end of the file names (i.e. RTLA19922181432Dxx, RTLA19922181432Hxx, RTLA19922181432Ixx). The files must reside either in the directory specified by the environment variable USER_DATA, which is set by the user, or in the user's home directory if the environment variable USER_DATA is not set. To open the default IDFS data files, **exten** should be set to a null string. The usage of modified data sets is limited to post acquisition data; therefore, it is suggested that the user set **exten** to a null string for real-time scenarios.

The user will need to pass in an array **ret_data** that will be used to return the data in the unit requested. The user has 2 choices as to how to handle the allocation of space for this array. The user can either declare an array of a large size, say 1000, which is of the type **SDDAS_FLOAT** (e.g., SDDAS_FLOAT hold_values[1000]), or the user can use a memory allocation routine to allocate the precise number of bytes needed to hold this information. The number of bytes needed is dependent upon the type of data being requested. The following table illustrates the number of bytes needed for the various data types. The names appearing in bold text represent elements from the **idf_data** structure.

DATA TYPE	NUMBER OF BYTES
SENSOR	sizeof (SDDAS_FLOAT) * num_sample
SWEEP_STEP	<pre>sizeof (SDDAS_FLOAT) * num_swp_steps</pre>
CAL_DATA	sizeof (SDDAS_FLOAT) * num_sample
MODE	sizeof (SDDAS_FLOAT) * 1
D_QUAL	sizeof (SDDAS_FLOAT) * 1
PITCH_ANGLE	sizeof (SDDAS_FLOAT) * num_pitch or
	sizeof (SDDAS_FLOAT) * num_sample
START_AZ_ANGLE	sizeof (SDDAS_FLOAT) * num_angle
STOP_AZ_ANGLE	sizeof (SDDAS_FLOAT) * num_angle
SC_POTENTIAL	sizeof (SDDAS_FLOAT) * num_potential
BACKGROUND	sizeof (SDDAS_FLOAT) * num_background

If pitch angle data is being requested, a check must be made to see if pitch angle data was calculated. If **num_pitch** is equal to zero, no pitch angles were computed. In this case, the user must allocate sizeof (SDDAS_FLOAT) * **num_sample** bytes since this module will return **num_sample** values, all set to -3.4e38 (OUTSIDE_MIN). The same check must be made for spacecraft potential and background data. If **num_potential** is equal to zero, no spacecraft potential values were returned. In this case, the user must allocate sizeof

(SDDAS_FLOAT) * **num_sample** bytes since this module will return **num_sample** values, all set to -3.4e38 (OUTSIDE_MIN). If **num_background** is equal to zero, no background values were returned. In this case, the user must allocate sizeof (SDDAS_FLOAT) * **num_sample** bytes since this module will return **num_sample** values, all set to -3.4e38 (OUTSIDE_MIN). If the user is dynamically allocating the space for the data, it is **imperative** that the user check these length indicators to ensure that enough space is allocated to hold the data. For example, if the previous call to the **read_drec** routine set **num_sample** to 12, the user would have allocated 12 * sizeof (SDDAS_FLOAT) bytes. However, if the next call to the **read_drec** routine sets **num_sample** to 18, the user needs to reallocate the memory to 18 * sizeof (SDDAS_FLOAT) bytes. If the user does not reallocate the memory for the data, the **convert_to_units** routine will attempt to write into memory beyond the data array, which could result in abnormal program termination. It is advised that the user reallocate space only if the number of data elements increases since the memory allocation subroutines can become time and resource consuming if called after every **read drec** call.

ERRORS

All errors within this routine are returned through the status variable. The include file **ret_codes.h**, which includes all possible return values, should be included so that the mnemonics for the return codes can be referenced. The **ret_codes.h** file is described in section 1H of the IDFS Programmers Manual.

SEE ALSO

file_open	1 R
read_drec	1R
get_data_key	1 R
get_version_number	1R
create_data_structure	1 R
create_idf_data_structure	1R
ret_codes	1H
user_defs	1H
libbase_idfs	1H
idf_data	1 S

BUGS

None

EXAMPLES

Convert one sweep of data from sensor 2 in the virtual instrument RTLA, which is part of the RETE instrument/experiment, which is part of the TSS-1 mission, which is identified with the TSS project. Return the sensor data in raw units and do not check for fill data values. Assumption is that no more than 1000 values are returned.

#include "libbase_idfs.h"
#include "ret_codes.h"

```
#include "user_defs.h"
SDDAS_ULONG data_key;
SDDAS USHORT vnum;
SDDAS FLOAT hold values[1000];
SDDAS_LONG *tbl_oper;
SDDAS_SHORT status;
SDDAS CHAR num tbls, *tbls to apply;
void *idf_data_ptr;
num tbls = 0:
tbls_to_apply = NULL;
tbl_oper = NULL;
status = get_data_key ("TSS", "TSS-1", "RETE", "RETE", "RTLA", &data_key);
if (status != ALL_OKAY)
{
  printf ("\n Error %d returned by get_data_key routine.\n", status);
  exit (-1);
}
get version number (&vnum);
status = create_idf_data_structure (&idf_data_ptr);
if (status != ALL OKAY)
{
  printf ("\n Error %d returned by create_idf_data_structure routine.\n", status);
  exit (-1);
}
status = read_drec (data_key, "", vnum, idf_data_ptr, 2, 1, 1);
if (status != ALL_OKAY)
{
  printf ("\n Error %d returned by read_drec routine.\n", status);
  exit (-1);
}
status = convert to units (data key, "", vnum, idf data ptr, 2, SENSOR, 0, num tbls,
                          tbls_to_apply, tbl_oper, hold_values, 0, 0);
if (status != ALL_OKAY)
{
 printf ("\n Error %d returned by convert_to_units routine.\n", status);
```

exit (-1);

}

Convert sensor data, sweep step data, calibration data, data quality data, pitch angle data, azimuthal angle data, spacecraft potential data and background data for sensor 2 in addition to mode data for instrument status value 0 in the virtual instrument RTLA, which is part of

December 28, 2012

the RETE instrument/experiment, which is part of the TSS-1 mission, which is identified with the TSS project. Allocate the data arrays so that no memory waste is encountered.

```
#include "libbase idfs.h"
#include "user defs.h"
#include "ret codes.h"
struct idf data *EXP DATA;
SDDAS_ULONG data_key;
SDDAS USHORT vnum;
SDDAS_FLOAT *data_values, *swp_values, *cal_values, *mode_values, dqual_value;
SDDAS FLOAT *pitch values, *start az values, *stop az value, *potential values;
SDDAS FLOAT *background;
SDDAS LONG offset, *tbl oper;
SDDAS SHORT status;
SDDAS_CHAR cset, *tbls_to_apply, num_tbls;
size t bytes;
void *base sen, *base swp, *base cal, *base mode, *base az, *base pitch;
void *base_potential, *base_background, *idf_data_ptr;
num_tbls = 0;
tbls to apply = NULL;
tbl oper = NULL;
status = get_data_key ("TSS", "TSS-1", "RETE", "RETE", "RTLA", &data_key);
if (status != ALL OKAY)
{
  printf ("\n Error %d returned by get_data_key routine.\n", status);
  exit (-1);
}
get version number (&vnum);
status = create idf data structure (&idf data ptr);
if (status != ALL OKAY)
{
  printf ("\n Error %d returned by create_idf_data_structure routine.\n", status);
  exit (-1);
}
EXP DATA = (struct idf data *) idf data ptr;
status = read_drec (data_key, "", vnum, idf_data_ptr, 2, 1, 1);
if (status != ALL_OKAY)
{
  printf ("\n Error %d returned by read_drec routine.\n", status);
  exit (-1);
}
```

```
bytes = sizeof (SDDAS_FLOAT) * EXP_DATA->num_sample;
if ((base_sen = malloc (bytes)) == NULL)
{
    printf ("\n No memory for array that holds converted sensor data.");
    return (-1);
}
```

/* Return data values in raw units and check for fill values of 255 (raw telemetry value). */

```
data values = (SDDAS FLOAT *) base sen;
status = convert_to_units (data_key, "", vnum, idf_data_ptr, 2, SENSOR, 0, num tbls,
                          tbls to apply, tbl oper, data values, 1, 255);
if (status != ALL OKAY)
ł
  printf ("\n Error %d returned by convert_to_units routine.\n", status);
  exit (-1);
 }
bytes = sizeof (SDDAS_FLOAT) * EXP_DATA->num_swp_steps;
if ((base swp = malloc (bytes)) == NULL)
{
   printf ("\n No memory for array that holds converted sweep data.");
  return (-1);
 }
                                              */
/* Return raw step values.
swp values = (SDDAS_FLOAT *) base_swp;
status = convert_to_units (data_key, "", vnum, idf_data_ptr, 2, SWEEP_STEP, 0,
                          num_tbls, tbls_to_apply, tbl_oper, swp_values, 0, 0);
if (status != ALL_OKAY)
ł
 printf ("\n Error %d returned by convert_to_units routine.\n", status);
 exit (-1);
 }
bytes = sizeof (SDDAS_FLOAT) * EXP_DATA->num_sample;
if ((base cal = malloc (bytes)) == NULL)
{
 printf ("\n No memory for array that holds converted cal. data.");
 return (-1);
 }
```

```
/* Return raw calibration values.
                                                   */
cal values = (SDDAS FLOAT *) base cal;
cset = 1;
status = convert_to_units (data_key, "", vnum, idf_data_ptr, 2, CAL_DATA, cset,
                          num_tbls, tbls_to_apply, tbl_oper, cal_values, 0, 0);
if (status != ALL OKAY)
{
 printf ("\n Error %d returned by convert_to_units routine.\n", status);
 exit (-1);
 }
bytes = size of (SDDAS FLOAT) * 1;
if ((base mode = malloc (bytes)) == NULL)
{
 printf ("\n No memory for array that holds converted mode data.");
 return (-1);
 }
/* Return raw mode values. Notice that for the sensor parameter, */
/* we are passing in a zero, which is the mode of interest.
                                                                */
mode values = (SDDAS FLOAT *) base mode;
status = convert_to_units (data_key, '''', vnum, idf_data_ptr, 0, MODE, 0, num_tbls,
                           tbls_to_apply, tbl_oper, mode_values, 0, 0);
if (status != ALL_OKAY)
 printf ("\n Error %d returned by convert to units routine.\n", status);
 exit (-1);
 }
                                                   */
/* Return data quality values.
status = convert_to_units (data_key, "", vnum, idf_data_ptr, 2, D_QUAL, 0,
                          num_tbls, tbls_to_apply, tbl_oper, &dqual_value, 0, 0);
if (status != ALL OKAY)
{
 printf ("\n Error %d returned by convert to units routine.\n", status);
 exit (-1);
 }
if (EXP DATA->num pitch == 0)
 bytes = sizeof (SDDAS_FLOAT) * EXP_DATA->num_sample;
else
 bytes = sizeof (SDDAS_FLOAT) * EXP_DATA->num_pitch;
```

```
if ((base_pitch = malloc (bytes)) == NULL)
{
    printf ("\n No memory for array that holds pitch angle data.");
    return (-1);
}
```

/* Return pitch angle data values in raw units (by default, degrees). */

```
pitch_values = (SDDAS_FLOAT *) base_pitch;
status = convert_to_units (data_key, '''', vnum, idf_data_ptr, 2, PITCH_ANGLE, 0,
                          num_tbls, tbls_to_apply, tbl_oper, pitch_values, 0, 0);
if (status != ALL OKAY)
{
 printf ("\n Error %d returned by convert to units routine.\n", status);
 exit (-1);
 }
bytes = 2 * sizeof (SDDAS FLOAT) * EXP DATA->num angle;
if ((base_az = malloc (bytes)) == NULL)
ł
 printf ("\n No memory for array that holds azimuthal angle data.");
 return (-1);
 }
/* Return azimuthal angle data values in raw units (by default, degrees).
                                                                      */
/* Cast base_az in setting of stop_az_values since it is a void pointer.
                                                                       */
start az values = (SDDAS FLOAT *) base az;
offset = sizeof (SDDAS_FLOAT) * EXP_DATA->num_angle;
stop_az_values = (SDDAS_FLOAT *) ((SDDAS_CHAR *) base_az + offset);
status = convert to units (data key, "", vnum, idf data ptr, 2, START AZ ANGLE,
                           0, num_tbls, tbls_to_apply, tbl_oper, start_az_values, 0, 0);
if (status != ALL OKAY)
 printf ("\n Error %d returned by convert to units routine.\n", status);
 exit (-1);
 }
status = convert_to_units (data_key, '''', vnum, idf_data_ptr, 2, STOP_AZ_ANGLE, 0,
                          num_tbls, tbls_to_apply, tbl_oper, stop_az_values, 0, 0);
if (status != ALL_OKAY)
 printf ("\n Error %d returned by convert_to_units routine.\n", status);
 exit (-1);
```

```
}
if (EXP DATA->num potential == 0)
 bytes = sizeof (SDDAS_FLOAT) * EXP_DATA->num_sample;
else
 bytes = sizeof (SDDAS_FLOAT) * EXP_DATA->num_potential;
if ((base potential = malloc (bytes)) == NULL)
{
 printf ("\n No memory for array that holds spacecraft potential data.");
 return (-1);
 }
/* Return spacecraft potential data values in raw units. */
potential_values = (SDDAS_FLOAT *) base_potential;
status = convert_to_units (data_key, "", vnum, idf_data_ptr, 2, SC_POTENTIAL, 0,
                          num_tbls, tbls_to_apply, tbl_oper, potential_values, 0, 0);
if (status != ALL OKAY)
{
 printf ("\n Error %d returned by convert to units routine.\n", status);
 exit (-1);
 }
if (EXP DATA->num background == 0)
 bytes = sizeof (SDDAS_FLOAT) * EXP_DATA->num_sample;
else
 bytes = sizeof (SDDAS FLOAT) * EXP DATA->num background;
if ((base background = malloc (bytes)) == NULL)
{
 printf ("\n No memory for array that holds background data.");
 return (-1);
 }
/* Return background data values in raw units. */
background_values = (SDDAS_FLOAT *) base_background;
status = convert_to_units (data_key, "", vnum, idf_data_ptr, 2, BACKGROUND, 0,
                          num_tbls, tbls_to_apply, tbl_oper, background_values, 0,
                          0);
if (status != ALL OKAY)
 printf ("\n Error %d returned by convert to units routine.\n", status);
 exit (-1);
 }
```

CREATE_DATA_STRUCTURE

function - creates an instance of the structure that is needed to hold the data for the data set specified

SYNOPSIS

#include "libbase_idfs.h"
#include "ret_codes.h"

SDDAS_SHORT	create_data_structure (SDDAS_ULONG data_key,
	SDDAS_CHAR *exten,
	SDDAS_USHORT version, void **data_ptr)

ARGUMENTS

-		
	data_key	- unique value which indicates the data set of interest
	exten	- two character extension to be added to IDFS file names when
		default files are not to be used, otherwise a null string
	version	- IDFS data set identification number which allows for multiple
		openings of the same data set
	data_ptr	- pointer to the newly created data structure
	create_data_structure	- routine status (see TABLE 1)

TABLE 1. Status Codes Returned for CREATE_DATA_STRUCTURE

STATUS CODE	EXPLANATION OF STATUS
CREATE_DSTR_NOT_FOUND	the requested data_key, exten, version combination has no memory
	allocated for processing (user did not call file_open for this combination)
	error codes returned by create_idf_data_structure ()
	error codes returned by create_tensor_data_structure ()
ALL_OKAY	the data structure was allocated

DESCRIPTION

Create_data_structure is the IDFS routine that creates the appropriate instance of the data structure that is used by the IDFS software to return sensor data and pertinent ancillary data for the data set of interest. The type of data structure allocated depends upon the IDFS data source being processed – either conventional IDFS data with a dependency based upon a scanning variable (refer to **create_idf_data_structure**) or multi-dimensional tensor IDFS data (refer to **create_tensor_data_structure**). With each call to this module, a new data structure is created and the address of this structure is returned. In order to access the elements within the data structure, the user must explicitly cast the returned void pointer to a pointer of the correct type.

In most cases, one data structure is sufficient to process any number of distinct data sets. However, if more than one structure is needed, the user may call the **create_data_structure** routine N times to create N instances of the data structure. The user must keep track of which pointer to send to the IDFS routines that utilize this structure. The contents of this structure is described in section 1S of the IDFS Programmers Manual.

The address of each data structure that is created is kept and this memory is freed when the **free_experiment_info** routine is called. The user **must not** free the memory themselves since the IDFS software will attempt to free the memory location and the result is uncertain.

ERRORS

All errors within this routine are returned through the status variable. The include file **ret_codes.h**, which includes all possible return values, should be included so that the mnemonics for the return codes can be referenced. The **ret_codes.h** file is described in section 1H of the IDFS Programmers Manual.

SEE ALSO

free_experiment_info	1 R
create_idf_data_structure	1R
create_tensor_data_structure	1R
ret_codes	1H
libbase_idfs	1H
idf_data	1S
tensor_data	1S

BUGS

None

EXAMPLES

Create one instance of the data structure that is needed for the data set specified and return the address in the specified parameter. Assume that the data_key and version number have already been set by the appropriate routines.

#include "libbase_idfs.h"
#include "ret_codes.h"

SDDAS_ULONG data_key; SDDAS_USHORT vnum; SDDAS_SHORT status; void *data_ptr;

```
status = create_data_structure (data_key, '''', vnum, &data_ptr);
if (status != ALL_OKAY)
{
    printf ("\n Error %d returned by create_data_structure routine.\n", status);
    exit (-1);
}
```

CREATE_IDF_DATA_STRUCTURE

function - creates an instance of the **idf_data** structure

SYNOPSIS

#include "libbase_idfs.h"
#include "ret_codes.h"

SDDAS_SHORT create_idf_data_structure (void **idf_data_ptr)

ARGUMENTS

idf_data_ptr - pointer to the newly created idf_data structure create_idf_data_structure - routine status (see TABLE 1)

TABLE 1. Status Codes Returned for CREATE_IDF_DATA_STRUCTURE

STATUS CODE	EXPLANATION OF STATUS
CREATE_DATA_ALL_MALLOC	no memory to hold the address of all allocated idf_data structures
CREATE_DATA_ALL_REALLOC	no memory for expansion of the area that holds the address of all allocated idf_data structures
CREATE_DATA_MALLOC	no memory for the idf_data structure
ALL_OKAY	the idf_data structure was allocated

DESCRIPTION

Create_idf_data_structure is the IDFS routine that creates an instance of the **idf_data** structure that is used by the IDFS software to return sensor data and pertinent ancillary data for the data set of interest. With each call to this module, a new **idf_data** structure is created and the address of this structure is returned. In order to access the elements within the **idf_data** structure, the user must explicitly cast the returned void pointer to a pointer of the type **struct idf_data**.

In most cases, one data structure is sufficient to process any number of distinct data sets. However, if more than one structure is needed, the user may call the **create_idf_data_structure** routine N times to create N instances of the **idf_data** structure. The user must keep track of which pointer to send to the IDFS routines that utilize this structure. The contents of this structure is described in section 1S of the IDFS Programmers Manual.

The address of each **idf_data** structure that is created is kept and this memory is freed when the **free_experiment_info** routine is called. The user **must not** free the memory themselves since the IDFS software will attempt to free the memory location and the result is uncertain.

ERRORS

All errors within this routine are returned through the status variable. The include file **ret_codes.h**, which includes all possible return values, should be included so that the mnemonics for the return codes can be referenced. The **ret_codes.h** file is described in section 1H of the IDFS Programmers Manual.

SEE ALSO

free_experiment_info	1R
ret_codes	1H
libbase_idfs	1H
idf_data	1 S

BUGS

None

EXAMPLES

Create one instance of the **idf_data** structure and return the address in the specified parameter. Cast the returned void pointer so that elements of the **idf_data** structure can be referenced.

#include "libbase_idfs.h"
#include "ret_codes.h"

struct idf_data *EXP_DATA; SDDAS_SHORT status; void *idf_data_ptr;

status = create_idf_data_structure (&idf_data_ptr);

if (status != ALL_OKAY)
{
 printf ("\n Error %d returned by create_idf_data_structure routine.\n", status);
 exit (-1);
}
EXP_DATA = (struct idf_data *) idf_data_ptr;

/* Print the start time. */

printf ("\n START TIME_MS = %d", EXP_DATA->bmilli);

CREATE_TENSOR_DATA_STRUCTURE

function - creates an instance of the tensor_data structure

SYNOPSIS

#include "libbase_idfs.h"
#include "ret_codes.h"

SDDAS_SHORT create_tensor_data_structure (void **tensor_data_ptr)

ARGUMENTS

tensor_data_ptr - pointer to the newly created **tensor_data** structure create_tensor_data_structure - routine status (see TABLE 1)

TABLE 1. Status Codes Returned for CREATE_TENSOR_DATA_STRUCTURE

STATUS CODE	EXPLANATION OF STATUS
CREATE_TENSOR_DATA_ALL_MALLOC	no memory to hold the address of all allocated tensor_data
	structures
CREATE_TENSOR_DATA_ALL_REALLOC	no memory for expansion of the area that holds the address of all
	allocated tensor_data structures
CREATE_TENSOR_DATA_MALLOC	no memory for the tensor_data structure
ALL_OKAY	the tensor_data structure was allocated

DESCRIPTION

Create_tensor_data_structure is the IDFS routine that creates an instance of the **tensor_data** structure that is used by the IDFS software to return sensor data and pertinent ancillary data for the multi-dimensional IDFS data set of interest. With each call to this module, a new **tensor_data** structure is created and the address of this structure is returned. In order to access the elements within the **tensor_data** structure, the user must explicitly cast the returned void pointer to a pointer of the type **struct tensor_data**.

In most cases, one data structure is sufficient to process any number of distinct multidimensional IDFS data sets. However, if more than one structure is needed, the user may call the **create_tensor_data_structure** routine N times to create N instances of the **tensor_data** structure. The user must keep track of which pointer to send to the IDFS routines that utilize this structure. The contents of this structure is described in section 1S of the IDFS Programmers Manual.

The address of each **tensor_data** structure that is created is kept and this memory is freed when the **free_experiment_info** routine is called. The user **must not** free the memory themselves since the IDFS software will attempt to free the memory location and the result is uncertain.

ERRORS

All errors within this routine are returned through the status variable. The include file **ret_codes.h**, which includes all possible return values, should be included so that the mnemonics for the return codes can be referenced. The **ret_codes.h** file is described in section 1H of the IDFS Programmers Manual.

SEE ALSO

free_experiment_info	1R
ret_codes	1H
libbase_idfs	1H
tensor_data	1 S

BUGS

None

EXAMPLES

Create one instance of the **tensor_data** structure and return the address in the specified parameter. Cast the returned void pointer so that elements of the **tensor_data** structure can be referenced.

#include "libbase_idfs.h"
#include "ret_codes.h"

struct tensor_data *TENSOR_DATA; SDDAS_SHORT status; void *tensor_data_ptr;

```
status = create_tensor_data_structure (&tensor_data_ptr);
if (status != ALL_OKAY)
{
    printf ("\n Error %d returned by create_tensor_data_structure routine.\n", status);
    exit (-1);
}
TENSOR_DATA = (struct tensor_data *) tensor_data_ptr;
```

/* Print the start time. */

printf ("\n START TIME_MS = %d", TENSOR_DATA->bmilli);

DESTROY_LAST_IDF_DATA_STRUCTURE

function – free the last instance of the idf_data structure allocated

SYNOPSIS

#include "libbase_idfs.h"
#include "ret_codes.h"

SDDAS_SHORT destroy_last_idf_data_structure ()

ARGUMENTS

destroy_last_idf_data_structure - routine status (see TABLE 1)

TABLE 1. Status Codes Returned for DESTROY_LAST_IDF_DATA_STRUCTURE

STATUS CODE	EXPLANATION OF STATUS
DESTROY_NO_IDF_DATA	there are no idf_data structures to be freed
ALL_OKAY	the last allocated idf_data structure was freed

DESCRIPTION

Destroy_last_idf_data_structure is the IDFS routine that destroys or frees the last instance of the **idf_data** structure that was allocated by the **create_idf_data_structure** routine in order to return sensor data and pertinent ancillary data for the data set of interest. An array of pointers that holds the address of each **idf_data** structure that is created is kept and with each call to this module, the last **idf_data** structure that was allocated is freed. If this module is called more times than the number of allocated structures, an error code is returned to alert the calling routine of this situation.

ERRORS

All errors within this routine are returned through the status variable. The include file **ret_codes.h**, which includes all possible return values, should be included so that the mnemonics for the return codes can be referenced. The **ret_codes.h** file is described in section 1H of the IDFS Programmers Manual.

SEE ALSO

create_idf_data_structure	1R
ret_codes	1H
libbase_idfs	1H
idf_data	1 S

BUGS

None

EXAMPLES

Destroy, or free, the last instance of the **idf_data** structure.

#include "libbase_idfs.h"
#include "ret_codes.h"

SDDAS_SHORT status;

status = destroy_last_idf_data_structure ();

if (status != ALL_OKAY)

{

•

printf ("\n Error %d returned by destroy_last_idf_data_structure routine.\n", status);
exit (-1);

}

DESTROY_LAST_TENSOR_DATA_STRUCTURE

function - free the last instance of the tensor_data structure allocated

SYNOPSIS

#include "libbase_idfs.h"
#include "ret_codes.h"

SDDAS_SHORT destroy_last_tensor_data_structure ()

ARGUMENTS

destroy_last_tensor_data_structure - routine status (see TABLE 1)

TABLE 1. Status Codes Returned for DESTROY_LAST_TENSOR_DATA_STRUCTURE

STATUS CODE	EXPLANATION OF STATUS
DESTROY_NO_TENSOR_DATA	there are no tensor_data structures to be freed
ALL_OKAY	the last allocated tensor_data structure was freed

DESCRIPTION

Destroy_last_tensor_data_structure is the IDFS routine that destroys or frees the last instance of the tensor data structure that was allocated bv the create tensor data structure routine in order to return sensor data and pertinent ancillary data for the multi-dimensional IDFS data set of interest. An array of pointers that holds the address of each tensor data structure that is created is kept and with each call to this module, the last tensor data structure that was allocated is freed. If this module is called more times than the number of allocated structures, an error code is returned to alert the calling routine of this situation.

ERRORS

All errors within this routine are returned through the status variable. The include file **ret_codes.h**, which includes all possible return values, should be included so that the mnemonics for the return codes can be referenced. The **ret_codes.h** file is described in section 1H of the IDFS Programmers Manual.

SEE ALSO

create_tensor_data_structure	1R
ret_codes	1H
libbase_idfs	1H
tensor_data	1 S

BUGS

None

EXAMPLES

Destroy, or free, the last instance of the **tensor_data** structure.

#include "libbase_idfs.h"
#include "ret_codes.h"

SDDAS_SHORT status;

status = destroy_last_tensor_data_structure ();

if (status != ALL_OKAY)

{

•

printf ("\n Error %d returned by destroy_last_tensor_data_structure routine.\n", status); exit (-1);

}

EXTRACT_SINGLE_ELEMENT_FROM_IDFS_TENSOR

function - extracts a single element from the specified IDFS tensor

SYNOPSIS

#include "libbase_idfs.h"
#include "ret_codes.h"

void extract_single_element_from_idfs_tensor (SDDAS_SHORT tensor_rank,
SDDAS_ULONG *tensor_next_dimen, void *tensorA,
SDDAS_ULONG *element_indices, void *ret_ptr,
SDDAS_CHAR long_dtype)

ARGUMENTS

tensor_rank tensor_next_dimen	-	the rank of the tensor being processed pointer to an array of size tensor_rank that holds the number of data values to bypass in order to get to the next index for a given dimension ([0] = first dimension or slowest varying dimension)		
tensorA	-	pointer to the input tensor data		
element_indices	-	pointer to an array of size tensor_rank that holds the indices		
		for each of the dimensions defined so that a single element of the tensor can be indexed		
ret_ptr	-	pointer to the resultant		
long_dtype	-	flag indicating whether the input / return values are integer or		
		floating point		
		0 - values are floating point values		
		1 - values are integer values		

DESCRIPTION

Extract_single_element_from_idfs_tensor is the IDFS routine that is used to extract a single element from the multi-dimensional IDFS data that is returned by the **read_tensor_data** module. The first two arguments, **tensor_rank** and **tensor_next_dimen** can be taken directly from the **tensor_data** structure that is returned by the **read_tensor_data** module. The argument **element_indices** is used to specify the start index location at which the extraction is to take place for each defined dimension for the multi-dimensional data held by the **tensorA** argument.

For the time being, multi-dimensional IDFS data can not be dynamically converted to any other physical unit; therefore, the data must be stored in the physical unit desired when the data set is created. However, the **read_tensor_data** module will return two sets of data within the **tensor_data** structure. One set represents the raw integer values that are stored within the data record and one set represents the floating point values that result when transferring the raw integer values into the data type defined by **d_type** in the VIDF file for the IDFS data set being processed. The two arguments, **tensorA** and **long_dtype**, should be coupled so that the user can extract data from either of these two data sets correctly.

ERRORS

This routine returns no status or error codes.

SEE ALSO

create_data_structure	1R
create_tensor_data_structure	1R
read_tensor_data	1R
libbase_idfs	1H
tensor_data	1S

BUGS

None

EXAMPLES

Extract the data, one element at a time, from the multi-dimensional data returned by the **read_tensor_data** module. It is already known that the data stored in the multi-dimensional IDFS data set is a 2-D tensor.

#include "libbase_idfs.h"
#include "ret_codes.h"
#include "user_defs.h"

```
struct tensor_data *TENSOR_DATA;
register SDDAS_USHORT i, j;
SDDAS_FLOAT conv_data;
SDDAS_ULONG data_key;
SDDAS_USHORT version;
SDDAS_USHORT version;
SDDAS_ULONG element_indices[IDFS_MAX_DIMEN];
SDDAS_LONG data_val;
SDDAS_LONG data_val;
SDDAS_SHORT status, sensor = 0;
SDDAS_CHAR extension[3];
void *tensor_data_ptr, *param;
```

```
status = create_tensor_data_structure (&tensor_data_ptr);
if (status != ALL OKAY)
{
 printf ("\n Error %d returned by create_tensor_data_structure routine.\n", status);
 exit (-1);
}
TENSOR_DATA = (struct tensor_data *) tensor_data_ptr;
status = read_tensor_data (data_key, extension, version, tensor_data_ptr, sensor, 1);
if (status < 0)
{
 printf ("\nError %d from read_tensor_data.\n", status);
 exit (-1);
 }
if (status == ALL OKAY || TENSOR DATA->filled data)
{
 /* Print the raw integer data values, 6 values per row, in exponential format.
                                                                         */
 for (i = 0; i < \text{TENSOR}_DATA \rightarrow \text{tensor}_sizes[0]; ++i)
  {
   for (j = 0; j < TENSOR_DATA -> tensor_sizes[1]; ++j)
   ł
    element indices[0] = i;
    element_indices[1] = j;
    param = &data_val;
    extract single element from idfs tensor (TENSOR DATA->tensor rank,
                           TENSOR DATA->tnext dimen,
                            (void *) TENSOR_DATA->sen_data,
                            &element_indices[0], param, 1);
    if (j == 0)
     printf ("\n");
    printf ("%ld ", data_val);
   }
  }
```

```
*/
/* Print the floating point data values, 6 values per row, in exponential format.
for (i = 0; i < TENSOR_DATA->tensor_sizes[0]; ++i)
 {
  for (j = 0; j < TENSOR_DATA->tensor_sizes[1]; ++j)
  {
   element_indices[0] = i;
   element_indices[1] = j;
   param = &conv_data;
   extract_single_element_from_idfs_tensor (TENSOR_DATA->tensor_rank,
                       TENSOR_DATA->tnext_dimen,
                       (void *) TENSOR_DATA->tdata,
                       &element_indices[0], param, 0);
   if (j == 0)
    printf ("\n");
   printf ("%.4f ", conv_data);
  }
 }
}
```

FIELDS_TO_KEY

function - create a key value which identifies the data set of interest

SYNOPSIS

#include "libbase_idfs.h"
#include "libCfg.h"

void fields_to_key (SDDAS_SHORT *params, SDDAS_ULONG *data_key)

ARGUMENTS

params	-	an array which holds the assigned database numbers for the project,
		mission, experiment, instrument and virtual instrument to be accessed
data_key	-	unique value which indicates the data set being requested

DESCRIPTION

Fields_to_key is the IDFS routine which creates a key that reflects the data set being accessed by utilizing the assigned database numbers for the project, mission, experiment, instrument and virtual instrument of interest. The IDFS routine **get_data_key** performs the same function but works with the assigned database names instead of the assigned database numbers. Most of the IDFS routines utilize key values; therefore, a call to either this routine or to the **get_data_key** routine must be made before any of the other IDFS routines that utilize a key value can be called.

The user selects the data set of interest by specifying a virtual instrument from a specific instrument, which comes from a parent experiment within a mission which is associated with a specific project. All references for these items are through assigned database numbers. The **params** parameter is an array that holds these assigned database numbers in the order specified below:

element 0	project identification number
element 1	mission identification number
element 2	experiment identification number
element 3	instrument identification number
element 4	virtual instrument identification number

ERRORS

This routine returns no status or error codes.

SEE ALSO

get_data_key 1R

BUGS

None

EXAMPLES

Retrieve the data key for the virtual instrument RTLA, which is part of the RETE instrument/experiment, which is part of the TSS-1 mission, which is identified with the TSS project.

```
#include "libbase_idfs.h"
#include "libCfg.h"
extern LinkList Projects;
StrHier Scode;
SDDAS ULONG data key;
SDDAS_SHORT project, mission, exper, inst, vinst, params[5];
Scode = SourceByStr (Projects, "TSS", (SDDAS_CHAR *) 0);
if (Scode == NULL)
{
 printf ("\n Error in calling SourceByStr for project number.\n");
 exit (-1);
}
else
 project = SNUM (Scode);
Scode = SourceByStr (Projects, "TSS", "TSS-1", (SDDAS_CHAR *) 0);
if (Scode == NULL)
{
 printf ("\n Error in calling SourceByStr for mission number.\n");
 exit (-1);
}
else
 mission = SNUM (Scode);
Scode = SourceByStr (Projects, "TSS", "TSS-1", "RETE", (SDDAS_CHAR *) 0);
if (Scode == NULL)
{
 printf ("\n Error in calling SourceByStr for experiment number.\n");
 exit (-1);
}
else
 exper = SNUM (Scode);
Scode = SourceByStr (Projects, "TSS", "TSS-1", "RETE", "RETE", (SDDAS_CHAR *) 0);
if (Scode == NULL)
{
 printf ("\n Error in calling SourceByStr for instrument number.\n");
```

```
exit (-1);
 }
else
 inst = SNUM (Scode);
Scode = SourceByStr (Projects, "TSS", "TSS-1", "RETE", "RETE", "RTLA",
                     (SDDAS_CHAR *) 0);
if (Scode == NULL)
{
 printf ("\n Error in calling SourceByStr for virtual inst. number.\n");
 exit (-1);
 }
else
 vinst = SNUM (Scode);
params[0] = project;
params[1] = mission;
params[2] = exper;
params[3] = inst;
params[4] = vinst;
fields_to_key (params, &data_key);
```

In the coding example provided, the database assignment numbers for the project, mission, experiment, instrument and virtual instrument are retrieved through calls to the modules **SourceByStr** and **SNUM**. A detailed description of these modules can be found in the IDFS Configuration Definition Document.

FILE_OPEN

function - open IDFS files (data, header and VIDF) for the time period requested

SYNOPSIS

#include "libbase_idfs.h"
#include "ret_codes.h"

SDDAS_SHORT file_open (SDDAS_ULONG data_key, SDDAS_CHAR *exter	1,
SDDAS_USHORT version, SDDAS_SHORT btime	_yr,
SDDAS_SHORT btime_day, SDDAS_LONG btime	_sec,
SDDAS_LONG btime_nano, SDDAS_SHORT etim	e_yr,
SDDAS_SHORT etime_day, SDDAS_LONG etime	_sec,
SDDAS_LONG etime_nano, SDDAS_CHAR mode	_data)

ARGUMENTS

data_key	- uniqu	e value which indicates the data set of interest			
exten	- two c	haracter extension to be added to IDFS file names when			
	defau	It files are not to be used, otherwise a null string			
version	- IDFS	data set identification number which allows for multiple			
	openi	ngs of the same data set			
btime_yr	- begin	ning year for data being requested			
btime_day	- begin	ning day of year for data being requested			
btime_sec	- begin	ning time of day in seconds for data being requested			
btime_nano	- begin	beginning time of day residual in nanoseconds			
etime_yr	- endin	g year for data being requested			
etime_day	- endin	g day of year for data being requested			
etime_sec	- endin	g time of day in seconds for data being requested			
etime_nano	- endin	g time of day residual in nanoseconds			
mode_data	- flag i	ndicating if instrument status (mode) data will be requested			
	for th	is data set			
	0	- instrument status data will not be requested for this data set			
	1	- instrument status data will be requested for this data set			
file_open	- routin	ne status (see TABLE 1)			
btime_yr btime_day btime_sec btime_nano etime_yr etime_day etime_sec etime_nano mode_data	 openi begin begin begin begin endin endin endin endin flag i for th 0 1 	ngs of the same data set ning year for data being requested ning day of year for data being requested ning time of day in seconds for data being requested ning time of day residual in nanoseconds g year for data being requested g day of year for data being requested g time of day in seconds for data being requested g time of day residual in nanoseconds ndicating if instrument status (mode) data will be requested is data set - instrument status data will not be requested for this data set - instrument status data will be requested for this data set			

STATUS CODE	EXPLANATION OF STATUS		
NO_DATA	there is no data available for the requested time period (playback scenario)		
OPEN_PTR_MALLOC	no memory for IDFS location pointers		
OPEN_EX_REALLOC	no memory for experiment definition structure expansion		
ALL_FLAG_MALLOC	no memory for sensor flags		
RTIME_NO HEADER	header file could not be opened (real-time scenario)		
RTIME_NO_DATA	data file could not be opened (real-time scenario)		
PBACK_NO_HEADER	header file could not be opened (playback scenario)		
PBACK_NO_DATA	data file could not be opened (playback scenario)		
ONCE_IDF_ELE_NOT_FOUND	the data item being requested was not found in the VIDF file		

TABLE 1. Status Codes Returned for FILE_OPEN

STATUS CODE	EXPLANATION OF STATUS
ONCE_IDF_MANY_BYTES	the number of elements being requested is more than the number of
	elements available for the selected field
ONCE_IDF_TBL_NUM	the table being requested exceeds the number of defined tables
ONCE_IDF_CON_NUM	the constant being requested exceeds the number of defined constants
ONCE_IDF_NO_ENTRY	the field being requested is not defined
ONCE_BAD_HEADER_FMT	invalid header record format value
ONCE_BAD_TENSOR_RANK	invalid rank value for multi-dimensional IDFS data
ONCE_BAD_TENSOR_LENGTHS	invalid dimension length value for multi-dimensional IDFS data
ONCE_CTARGET_MALLOC	no memory for cal_target VIDF values
ONCE_CLEN_MALLOC	no memory for cal_wlen VIDF values
ONCE_CSCOPE_MALLOC	no memory for cal_scope VIDF values
CAL_DATA_MALLOC	no memory for calibration information
ONCE_DATA_MALLOC	no memory for data record information
ONCE_TBL_INFO_MALLOC	no memory for structures which hold non-array table specific information
ONCE_D_TYPE_MALLOC	no memory for d_type VIDF values
ONCE_TDW_LEN_MALLOC	no memory for tdw_len VIDF values
ONCE_SPIN_OFF_MALLOC	no memory for spin_time_off VIDF values
ONCE_SEN_STAT_MALLOC	no memory for sen_status VIDF values
ONCE_CDTYPE_MALLOC	no memory for cal_d_type VIDF values
ONCE_BAD_NUM_TBLS	num_tbls can not be set to any value other than 0 for multi-dimensional
	IDFS data
ONCE_BAD_CAL_TARGET	cal_target can not be set to any value other than 0 for multi-dimensional
	IDFS data
ONCE_BAD_MAX_NSS	max_nss can not be set to any value other than 1 for multi-dimensional
	IDFS data
ONCE_BAD_SMP_ID	smp_id must be set to 3 for multi-dimensional IDFS data
ONCE_BAD_DA_METHOD	da_method must be set to 0 for multi-dimensional IDFS data
ONCE_BAD_SWP_LEN	swp_len must be set to 1 for multi-dimensional IDFS data
ONCE_BAD_SEN_MODE	sen_mode must be set to either 3 or 7 for multi-dimensional IDFS data
NUM_CAL_REALLOC	no memory for expansion of calibration array
UPDATE_IDF_ELE_NOT_FOUND	the data item being requested was not found in the VIDF file
UPDATE_IDF_MANY_BYTES	the number of elements being requested is more than the number of
	elements available for the selected field
UPDATE_IDF_TBL_NUM	the table being requested exceeds the number of defined tables
UPDATE_IDF_CON_NUM	the constant being requested exceeds the number of defined constants
UPDATE_IDF_NO_ENTRY	the field being requested is not defined
UPDATE_IDF_NO_FILL	a fill value must be specified for multi-dimensional IDFS data
UPDATE_IDF_BAD_PA_DEF	pitch angle can not be specified for multi-dimensional IDFS data
UPDATE_IDF_BAD_POT_DEF	spacecraft potential data can not be specified for multi-dimensional IDFS
	data
UPDATE_IDF_BAD_SPIN_DEF	start of spin data source can not be specified for multi-dimensional IDFS
	data
UPDATE_IDF_BAD_PMI_DEF	euler angle can not be specified for multi-dimensional IDFS data
UPDATE_IDF_BAD_CP_DEF	celestial position angles can not be specified for multi-dimensional IDFS
	data
UPDATE_IDF_BAD_BKGD_DEF	background data can not be specified for multi-dimensional IDFS data
ASCII_AFTER_SENSOR	all ASCII and mode-dependent tables must be defined after all other tables
	are defined in the VIDF
CONST_ANG_MALLOC	no memory for angle offset values
CONST_TEMP_MALLOC	no memory for temporary working area
CONST_IDF_ELE_NOT_FOUND	the data item being requested was not found in the VIDF file

STATUS CODE	EXPLANATION OF STATUS
CONST_IDF_NO_ENTRY	the field being requested is not defined
CONST_IDF_TBL_NUM	the table being requested exceeds the number of defined tables
CONST_IDF_CON_NUM	the constant being requested exceeds the number of defined constants
CONST_IDF_MANY_BYTES	the number of elements being requested is more than the number of
	elements available for the selected field
	error codes returned by get_data_key ()
	error codes returned by ReadVIDF ()
ALL_OKAY	all IDFS files opened

In addition to the status codes listed above, other error/status codes may be returned in the case of a database request. The user is referred to the webpage <u>http://cluster/libdbSQL.html</u> for an explanation of the interface to the database which is used by the IDFS data access software. The write-up for the modules dbIDFSGetRealTimeFile and dbIDFSGetFile are pertinent to the **file_open** module.

DESCRIPTION

File_open is the IDFS file open routine. The data set of interest is referenced through the key value **data_key** which can be created using the **get_data_key** module. The files that are opened, the header, data, and VIDF file, are dependent on the data set (**data_key**), file name extension (**exten**) and the time range specified. The maximum number of files that can be opened at one time is a system dependent value. For example, with SunOS, the maximum number of open file descriptors is set at 256. This value can be modified; however, system performance may be degraded as this value is increased.

The parameter **version** allows multiple file openings for an IDFS data set. If the data, header and VIDF file for the specified data set need to be opened just once for processing, the same version number should be passed to all IDFS routines. However, for multiple file openings, the version number should be unique and all file manipulations performed by the IDFS routines will use the file descriptors defined for the version number specified. In either case, the specified IDFS data set will only be opened once for each unique parameter set. If additional calls are made to this routine with the same parameter set, the module simply returns the **ALL_OKAY** status code. The user should call the **get_version_number** routine to retrieve a unique version number instead of choosing this value themselves. The retrieval of multiple data parameters from a single data source does not constitute the need for multiple version numbers; a single version number will suffice.

The appropriate files are searched for within the current on-line database for the data set designated. The database returns both the file name and a status code. The database contains information about the satellite data on the local machine. The contents of the database entries include the file name referencing the header file, data file or the VIDF file. For playback data, the contents of the database entries also include the name of the primary and/or secondary media names along with their respective data sizes and offsets on the media. These entries are indexed by increasing universal time to expedite data searching. If the files do exist on the local machine, the files are opened and the file descriptors are saved in an internally defined structure for later use by the other IDFS routines. If the files do not exist on the local machine, the appropriate error code is returned.

This routine opens the first set of files within the time span over which data is to be processed. For a real-time scenario, there is only one set of files for the time span being processed. In post acquisition analysis, if there is more than one file set within the requested time interval, the remaining files will be opened and processed after the currently opened files are processed.

If the **file_open** routine is not to open the default set of IDFS files but a modified set of IDFS files, the two character extension applied to these data files must be supplied to this routine within the string variable **exten**. These files must have the identical name as the IDFS files with the two character identification code appended to the end of the file names (i.e. RTLA19922181432Dxx, RTLA19922181432Hxx, RTLA19922181432Ixx). The files must reside either in the directory specified by the environment variable USER_DATA, which is set by the user, or in the user's home directory if the environment variable USER_DATA is not set. To open the default IDFS data files, **exten** should be set to a null string. The usage of modified data sets is limited to post acquisition data; therefore, it is suggested that the user set **exten** to a null string for real-time scenarios.

Once the files have been opened successfully, the VIDF is loaded into memory. Selected information from the VIDF file is retrieved and stored in an internally defined structure. The fields selected are those pieces of information that are to be used by the other IDFS routines. After the necessary elements have been read from the VIDF file, internal flags are set to indicate that all sensors associated with the data set are to be processed and memory to hold various information concerning each sensor is to be allocated by the routine **file_pos**. If only a few of the sensors associated with the data set are to be processed, these can be selected by the use of the routine **select_sensor**, which will reset the internal flags such that only the necessary sensors will be processed and have space allocated.

ERRORS

All errors within this routine are returned through the status variable. The include file **ret_codes.h**, which includes all possible return values, should be included so that the mnemonics for the return codes can be referenced. The **ret_codes.h** file is described in section 1H of the IDFS Programmers Manual.

SEE ALSO

file_pos	1R
select_sensor	1R
get_data_key	1R
get_version_number	1R
ret_codes	1H
libbase_idfs	1H

BUGS

None

EXAMPLES

Open the real-time files associated with the virtual instrument RTLA, which is part of the RETE instrument/experiment, which is part of the TSS-1 mission, which is identified with the TSS project. In the calling sequence, indicate that instrument status data is not to be requested for the data set in question.

#include "libbase_idfs.h"
#include "ret_codes.h"

```
SDDAS_ULONG data_key;
SDDAS_USHORT vnum;
SDDAS_SHORT status;
status = get_data_key ("TSS", "TSS-1", "RETE", "RETE", "RTLA", &data_key);
```

```
if (status != ALL_OKAY)
```

```
{
```

```
printf ("\n Error %d returned by get_data_key routine.\n", status);
exit (-1);
```

```
exit (-
```

get_version_number (&vnum);

```
status = file_open (data_key, "", vnum, -1, -1, -1, 0, -1, -1, -1, 0, 0);
if (status != ALL_OKAY)
{
    printf ("\n Error %d returned by file_open routine.\n", status);
    exit (-1);
}
```

The RTLA default data set was modified to remove all counts less than 2. This new data set resides in the user's home directory and has the 2 character extension L2 appended to the IDFS file names. In the calling sequence, indicate that instrument status data is to be requested for the data set in question. To open this data set:

```
#include "libbase_idfs.h"
#include "ret_codes.h"
SDDAS_ULONG data_key;
SDDAS_USHORT vnum;
SDDAS_SHORT status;
status = get_data_key ("TSS", "TSS-1", "RETE", "RETE", "RTLA", &data_key);
if (status != ALL_OKAY)
{
    printf ("\n Error %d returned by get_data_key routine.\n", status);
    exit (-1);
}
```

get_version_number (&vnum);

```
status = file_open (data_key, "L2", vnum, -1, -1, -1, 0, -1, -1, 0, 1);
if (status != ALL_OKAY)
{
    printf ("\n Error %d returned by file_open routine.\n", status);
    exit (-1);
}
```

FILE_POS

function - allocates memory for necessary idfs data structures and positions the file pointers at the requested time in the files

SYNOPSIS

#include "libbase_idfs.h"
#include "ret_codes.h"

SDDAS_SHORT	file_pos (SDDAS_ULONG data_key, SDDAS_CHAR *exten,
	SDDAS_USHORT version, void *data_ptr,
	SDDAS_SHORT btime_yr, SDDAS_SHORT btime_day,
	SDDAS_LONG btime_sec, SDDAS_LONG btime_nano,
	SDDAS_SHORT etime_yr, SDDAS_SHORT etime_day,
	SDDAS_LONG etime_sec, SDDAS_LONG etime_nano)

ARGUMENTS

data_key exten	-	unique value which indicates the data set of interest two character extension to be added to IDFS file names when default files are not to be used, otherwise a null string
version	-	IDFS data set identification number which allows for multiple openings of the same data set
data_ptr	-	pointer to the data structure that is to hold sensor data and pertinent ancillary data for the data set of interest (either idf_data or tensor_data)
btime_yr	-	beginning year for data being requested
btime_day	-	beginning day of year for data being requested
btime_sec	-	beginning time of day in seconds for data being requested
btime_nano	-	beginning time of day residual in nanoseconds
etime_yr	-	ending year for data being requested
etime_day	-	ending day of year for data being requested
etime_sec	-	ending time of day in seconds for data being requested
etime_nano	-	ending time of day residual in nanoseconds
file_pos	-	routine status (see TABLE 1)

TABLE 1.	Status	Codes	Returned	for	FILE_POS
----------	--------	-------	----------	-----	----------

STATUS CODE	EXPLANATION OF STATUS		
POS_NOT_FOUND	the requested data_key, exten, version combination has no memory		
	allocated for processing (user did not call file_open for this		
	combination)		
POS_DATA_READ_ERROR	read error on data file		
SCOM_TBL_MALLOC	no memory for table offset value for sensors being processed		
SCOM_PTR_MALLOC	no memory for pointers to the memory allocated to hold table offset		
	values		
SCOM_INDEX_MALLOC	no memory for sensor index array		
SCOM_SEN_PTR_MALLOC	no memory for array of structures which hold sensor-specific		
	information		

STATUS CODE	EXPLANATION OF STATUS
SEN_IDF_ELE_NOT_FOUND	the data item being requested was not found in the VIDF file
SEN_IDF_NO_ENTRY	the field being requested is not defined
SEN_IDF_MANY_BYTES	the number of elements being requested is more than the number of
	elements available for the selected field
SEN_IDF_TBL_NUM	the table being requested exceeds the number of defined tables
SEN_IDF_CON_NUM	the constant being requested exceeds the number of defined constants
CCOM_MATCH_MALLOC	no memory for temporary array used for determining the number of
	sensor table combinations
CCOM_VAL_MALLOC	no memory for base offset and comparison offset values
CRIT_ACT_MALLOC	no memory for critical action information
TBL_MISC_MALLOC	no memory to hold table information for all integer tables
TBL_IDF_ELE_NOT_FOUND	the data item being requested was not found in the VIDF file
TBL_IDF_MANY_BYTES	the number of elements being requested is more than the number of
	elements available for the selected field
TBL_IDF_TBL_NUM	the table being requested exceeds the number of defined tables
TBL_IDF_CON_NUM	the constant being requested exceeds the number of defined constants
TBL_IDF_NO_ENTRY	the field being requested is not defined
TBL_VAR_NOT_RAW	the table can only be a function of raw data since the table format
	specifies an expanded loop-up table
TBL_VAR_NOT_CAL	the table can only be a function of a calibration set since the table type
	is a sweep-length dependent table and the table format specifies an
	expanded look-up table
TBL_MALLOC	no memory to hold values for all integer tables
GET_ACTION_MALLOC	no memory for array that holds the actions for critical status bytes
CRIT_IDF_ELE_NOT_FOUND	the data item being requested was not found in the VIDF file
CRIT_IDF_MANY_BYTES	the number of elements being requested is more than the number of
	elements available for the selected field
CRIT_IDF_TBL_NUM	the table being requested exceeds the number of defined tables
CRIT_IDF_CON_NUM	the constant being requested exceeds the number of defined constants
CRIT_IDF_NO_ENTRY	the field being requested is not defined
MODE_PTR_MALLOC	no memory for array of structures which hold mode-specific
	information
MODE_TBL_MISC_MALLOC	no memory to hold table information for all integer mode-dependent
MODE THE WE HE NOT FOUND	tables
MODE_TBL_IDF_ELE_NOT_FOUND	the data item being requested was not found in the VIDF file
MODE_TBL_IDF_MANY_BYTES	the number of elements being requested is more than the number of
MODE TRUDE TRUDY	elements available for the selected field
MODE_TBL_IDF_TBL_NUM	the table being requested exceeds the number of defined tables
MODE_TBL_IDF_CON_NUM	the constant being requested exceeds the number of defined constants
MODE_TBL_IDF_NO_ENTRY	the field being requested is not defined
MODE_TBL_VAR_NOT_RAW	the table can only be a function of raw data since the table format
MODE TRI MAR NOT CAL	specifies an expanded loop-up table
MODE_TBL_VAR_NOT_CAL	the table can only be a function of a calibration set since the table type
	is sweep-length dependent table and the table format specifies an
MODE TRI MALLOC	expanded look-up table
MODE_TBL_MALLOC	no memory to hold values for all integer mode-dependent tables
MODE_TBL_SZ_IDF_ELE_NOT_FOUND	the data item being requested was not found in the VIDF file
MODE_TBL_SZ_IDF_MANY_BYTES	the number of elements being requested is more than the number of
MODE THE SZ IDE THE NUM	elements available for the selected field
MODE_TBL_SZ_IDF_TBL_NUM	the table being requested exceeds the number of defined tables
MODE_TBL_SZ_IDF_CON_NUM	the constant being requested exceeds the number of defined constants
MODE_TBL_SZ_IDF_NO_ENTRY	the field being requested is not defined

STATUS CODE	EXPLANATION OF STATUS
ALLOC_HDR_READ_ERROR	read error on header file
ALLOC_HDR_MALLOC	no memory for header record information
ALLOC_HDR_REALLOC	no memory for header information expansion (header increased in size)
SWEEP_TIME_MALLOC	no memory for time of sample values
TIME_OFF_MALLOC	no memory for time offset values for individual sensors
EXP_IDF_ELE_NOT_FOUND	the data item being requested was not found in the VIDF file
EXP_IDF_MANY_BYTES	the number of elements being requested is more than the number of
	elements available for the selected field
EXP_IDF_TBL_NUM	the table being requested exceeds the number of defined tables
EXP_IDF_CON_NUM	the constant being requested exceeds the number of defined constants
EXP_IDF_NO_ENTRY	the field being requested is not defined
TIMING_MALLOC	no memory for structures that hold timing information for pixel location
 PBACK_LOS	an LOS indicator record was encountered when trying to find the record
	containing the requested start time (playback scenario only) - user is
	advised to change the start time to either a previous or later time period
PBACK_NEXT_FILE	a NEXT_FILE indicator record was encountered when trying to find the
	record containing the requested start time (playback scenario only) -
	user is advised to change the start time to either a previous or later time
	period
POS_HDR_READ_ERROR	read error on header file
POS_HDR_MALLOC	no memory for header record information
POS_HDR_REALLOC	no memory for header information expansion (header increased in size)
FILE_POS_DATA_GAP	the time range requested lies within a gap found within the data file
FILE_POS_MODE	error encountered when positioning file descriptors for instrument status
	(mode) data
FILE_POS_PA	error encountered while trying to position the pitch angle IDFS data set
FILE_POS_SPIN	error encountered while trying to position the start of spin data source
FILE_POS_POT	error encountered while trying to position the spacecraft potential IDFS
	data set
FILE_POS_EULER	error encountered while trying to position the euler angle IDFS data set
FILE_POS_CP	error encountered while trying to position the celestial position angle
	IDFS data set
FILE_POS_BKGD	error encountered while trying to position the background IDFS data set
RHDR_READ_ERROR	read error on header file
RHDR_HDR_MALLOC	no memory for header information
RHDR_HDR_REALLOC	no memory for header information expansion
PITCH_MALLOC	no memory for structure that holds pitch angle information
PINFO_IDF_ELE_NOT_FOUND	the data item being requested was not found in the VIDF file
PINFO_IDF_MANY_BYTES	the number of element being requested is more than the number of
	elements available for the selected field
PINFO_IDF_TBL_NUM	the table being requested exceeds the number of defined tables
PINFO_IDF_CON_NUM	the constant being requested exceeds the number of defined constants
PINFO_IDF_NO_ENTRY	the field being requested is not defined
PA_UNIT_MALLOC	no memory for normal vector definition for pitch angle data
PA_DATA_MALLOC	no memory for data and normalization factors for pitch angle data
PA_TBL_MALLOC	no memory for table number / table operation information for pitch
	angle data
PA_UNIT_NORMAL	definition of the normal vector for the pitch angle data is incomplete
NO_PA_CONSTANT	the pitch angle constants are not defined in the VIDF file
PA_BAD_SRC	the IDFS data source for the pitch angle data is not a scalar instrument
BAD_PA_FORMAT	the format specification field for the pitch angle data is invalid
SPIN_SRC_MALLOC	no memory for structure that holds start of spin data source info

STATUS CODE	EXPLANATION OF STATUS
SPIN_SRC_BAD_SRC	the start of spin data source is non-scalar
SPIN_SINFO_IDF_ELE_NOT_FOUND	the data item being requested was not found in the VIDF file
SPIN_SINFO_IDF_MANY_BYTES	the number of element being requested is more than the number of
	elements available for the selected field
SPIN_SINFO_IDF_TBL_NUM	the table being requested exceeds the number of defined tables
SPIN_SINFO_IDF_CON_NUM	the constant being requested exceeds the number of defined constants
SPIN_SINFO_IDF_NO_ENTRY	the field being requested is not defined
POT_INFO_IDF_ELE_NOT_FOUND	the data item being requested was not found in the VIDF file
POT_INFO_IDF_MANY_BYTES	the number of element being requested is more than the number of
DOT INFO INF TRUNING	elements available for the selected field
POT_INFO_IDF_TBL_NUM	the table being requested exceeds the number of defined tables
POT_INFO_IDF_CON_NUM	the constant being requested exceeds the number of defined constants
POT_INFO_IDF_NO_ENTRY	the field being requested is not defined
POT_TBL_MALLOC	no memory for table number / table operation information for spacecraft potential data
POT_BAD_SRC	the IDFS data source for the spacecraft potential data is not a scalar
	instrument
BAD_SCPOT_FORMAT	the format specification field for the spacecraft potential data is invalid
POT_MALLOC	no memory for structure that holds spacecraft potential information
POT_DATA_MALLOC	no memory for data and normalization factors for spacecraft potential
	data
EULER_INFO_IDF_ELE_NOT_FOUND	the data item being requested was not found in the VIDF file
EULER_INFO_IDF_MANY_BYTES	the number of element being requested is more than the number of
	elements available for the selected field
EULER_INFO_IDF_TBL_NUM	the table being requested exceeds the number of defined tables
EULER_INFO_IDF_CON_NUM	the constant being requested exceeds the number of defined constants
EULER_INFO_IDF_NO_ENTRY	the field being requested is not defined
EULER_MALLOC	no memory for structure that holds euler angle information
EULER_AXIS_MALLOC	no memory euler angles and euler rotation axis information
EULER_IDF_DATA_MALLOC	no memory for array of pointers for the idf_data structures needed to
	hold the euler angle data read from the specified IDFS data source
EULER_BAD_SRC	the IDFS data source for the euler angle data is not a scalar instrument
EULER_TBL_MALLOC	no memory for table number / table operation information for euler
	angle data
BAD_EULER_FORMAT	the format specification field for the euler angle data is invalid
LESS_EULER_CONSTANT_ANGLES	the number of euler angle constants defined in the VIDF file is less than
	the number of euler angles defined in the VIDF file
LESS_EULER_CONSTANT_AXIS	the number of euler rotation axis constants defined in the VIDF file is
MORE EULER CONSTANT ANGLES	less than the number of euler angles defined in the VIDF file
MORE_EULER_CONSTAINT_ANGLES	the number of euler angle constants defined in the VIDF file is more than the number of euler angles defined in the VIDF file
MORE_EULER_CONSTANT_AXIS	the number of culer rotation axis constants defined in the VIDF file is
	more than the number of euler angles defined in the VIDF file
TOO_MANY_EULER	this data set defines more euler angles than the IDFS system can handle
CP_INFO_IDF_ELE_NOT_FOUND	the data item being requested was not found in the VIDF file
CP_INFO_IDF_MANY_BYTES	the number of element being requested is more than the number of
	elements available for the selected field
CP_INFO_IDF_TBL_NUM	the table being requested exceeds the number of defined tables
CP_INFO_IDF_CON_NUM	the constant being requested exceeds the number of defined constants
CP_INFO_IDF_NO_ENTRY	the field being requested is not defined
CP_TBL_MALLOC	no memory for table number / table operation information for celestial
	position angle data

STATUS CODE	EXPLANATION OF STATUS
NO_CP_CONSTANT	the celestial position angle constants are not defined in the VIDF file
CP_STR_MALLOC	no memory for structure that holds celestial position angle information
CP_DATA_MALLOC	no memory for data and normalization factors for celestial position
	angle data
CP_BAD_SRC	the IDFS data source for the celestial position angle data is not a scalar
	instrument
NO_BKGD_CONSTANT	the background constants are not defined in the VIDF file
BKGD_TBL_MALLOC	no memory for table number / table operation information for
	background data
BKGD_BAD_SRC	the IDFS data source for the background data is not a scalar instrument
BKGD_MALLOC	no memory for structure that holds background information
BKGD_DATA_MALLOC	no memory for data and normalization factors for background data
BKGD_IDF_DATA_MALLOC	no memory for array of pointers for the idf_data structures needed to
	hold the background data read from the specified IDFS data source
BKGD_INFO_IDF_ELE_NOT_FOUND	the data item being requested was not found in the VIDF file
BKGD_INFO_IDF_MANY_BYTES	the number of element being requested is more than the number of
	elements available for the selected field
BKGD_INFO_IDF_TBL_NUM	the table being requested exceeds the number of defined tables
BKGD_INFO_IDF_CON_NUM	the constant being requested exceeds the number of defined constants
BKGD_INFO_IDF_NO_ENTRY	the field being requested is not defined
FILE_POS_INVALID_DATA	the data structure passed as an argument is not a valid data structure to
	use - may have been previously freed
	Error codes returned by read_drec ()
	Error codes returned by ReadVIDF ()
ALL_OKAY	routine terminated successfully

DESCRIPTION

File_pos is the IDFS data positioning routine. The data set of interest is referenced through the key value data_key which can be created using the get_data_key module. This routine uses the currently opened files for the requested data set and sets the current data pointer to the data sample or sweep whose beginning time is closest to the requested start time. If btime_sec is equal to the value -1, the file position is set at the beginning of the current real-time data file. If btime_sec is set equal to the value -2, the file position is set to the present location within the current real-time data file. If the beginning time indicates post acquisition analysis, calls are made to the routine read_drec in order to position the data pointer as close to the requested start time as possible, using the btime_nano time component to get to the closest nanosecond, and the data structure is filled in and ready for access upon return from file_pos ().

Once the data set of interest has been successfully positioned, any ancillary data sources that are defined are also opened and positioned. If the data set of interest contains pitch angle information within the VIDF file, an attempt is made to open the IDFS data set that contains the magnetic field elements to be used in the pitch angle calculations and to set the data pointer for the pitch angle IDFS data set to the data sample or sweep whose beginning time is closest to the time at which the data set of interest has been positioned. If the data set of interest contains spacecraft potential information within the VIDF file, an attempt is made to open the IDFS data set that contains the spacecraft potential data values and to set the data pointer for the spacecraft potential IDFS data set to the data sample or sweep whose

beginning time is closest to the time at which the data set of interest has been positioned. If the data set of interest contains start of spin information within the VIDF file, an attempt is made to open the IDFS data set that contains the time for each spin period and to set the data pointer for the start of spin IDFS data set to the data sample or sweep whose beginning time is closest to the time at which the data set of interest has been positioned. If the data set of interest contains euler angle information within the VIDF file, an attempt is made to open the IDFS data set that contains the euler angle and euler rotation axis information used in the euler angle calculations and to set the data pointer for the euler angle IDFS data set to the data sample or sweep whose beginning time is closest to the time at which the data set of interest has been positioned. If the data set of interest contains celestial position angle information within the VIDF file, an attempt is made to open the IDFS data set that contains the celestial position angle data (declination angle and right ascension angle) and to set the data pointer for the celestial position IDFS data set to the data sample or sweep whose beginning time is closest to the time at which the data set of interest has been positioned. If the data set of interest contains background information within the VIDF file, an attempt is made to open the IDFS data set that contains the background data values and to set the data pointer for the background IDFS data set to the data sample or sweep whose beginning time is closest to the time at which the data set of interest has been positioned.

Data positioning is performed only once for each unique parameter set. If additional calls are made to this routine with the same parameter set, the module simply returns the **ALL_OKAY** status code, with the exception being after a call to the module **reset_experiment_info**, which closes the existing IDFS data set and opens the next IDFS data set to be processed. It is imperative that a call to the **file_pos** routine be made immediately after a successful return from the **reset_experiment_info** module in order for the IDFS software to process the next IDFS data set correctly. Before the first call to the **file_pos** routine can be made, a call to the routine **file_open** with the identical **data_key**, **exten** and **version** parameters must have been made to obtain a set of file descriptors for the appropriate VIDF, header and data files.

The parameter **version** allows multiple file openings for an IDFS data set. If the data, header and VIDF file for the specified data set need to be opened just once for processing, the same version number should be passed to all IDFS routines. However, for multiple file openings, the version number should be unique and all file manipulations performed by the IDFS routines will use the file descriptors defined for the version number specified. The user should call the **get_version_number** routine to retrieve a unique version number instead of choosing this value themselves. The retrieval of multiple data parameters from a single data source does not constitute the need for multiple version numbers; a single version number will suffice.

The parameter **data_ptr** is a pointer to the data structure that is to hold all data pertinent to the data set being processed. The data structure that is utilized is either an instance of the **idf_data** structure or the **tensor_data** structure. The data structure is created and the address to this structure is returned when a call to the **create_idf_data_structure** or **create_tensor_data_structure** routine is made. The user also has the option of calling the module **create_data_structure**, which determines what type of data structure is needed for

the IDFS data set of interest. In most cases, one data structure is sufficient to process any number of distinct data sets. However, if more than one structure is needed, the user may call the **create_idf_data_structure** or **create_tensor_data_structure** routine N times to create N instances of the **idf_data** or **tensor_data** structure. The user must keep track of which pointer to send to the IDFS routines that utilize this structure.

File_pos is also the IDFS routine that allocates memory blocks which are used to hold and return information utilized by the IDFS routines. Memory is allocated to hold both the header and data record information. Whereas the size of the data records stay fixed, the size of the header records may change. File_pos allocates space based upon the size of the header record associated with the data record read. Memory expansion for the header information is handled by the read_drec routine. Memory is also allocated to hold information relevant to the application of the data calibration sets, to hold sensor time offset values and to hold full sweep values. The memory pointers for all of these elements are stored within an internally defined structure that is identified with a specific data set.

File_pos also allocates space to hold the calibration data and the instrument mode flags that are returned by the **read_drec** routine. If the currently assigned memory block is determined to be insufficient in size (too small), the memory block is dynamically expanded. The pointers to the two memory blocks are held in the **idf_data** structure. This data structure is described in section 1S of the IDFS Programmers Manual.

The last task of this routine is to allocate memory for structure(s) that hold the table values and critical status information for the sensors being processed. The memory pointer for this array of structures is stored within an internally defined structure that is identified with a specific data set. This routine assumes that the requested sensors have already been selected through the routine **select_sensor**. If the routine **select_sensor** is not called, all sensors are selected by the routine **file_open**.

If the **file_open** routine is not to open the default set of IDFS files but a modified set of IDFS files, the two character extension applied to these data files must be supplied to this routine within the string variable **exten**. These files must have the identical name as the IDFS files with the two character identification code appended to the end of the file names (i.e. RTLA19922181432Dxx, RTLA19922181432Hxx, RTLA19922181432Ixx). The files must reside either in the directory specified by the environment variable USER_DATA, which is set by the user, or in the user's home directory if the environment variable USER_DATA is not set. To open the default IDFS data files, **exten** should be set to a null string. The usage of modified data sets is limited to post acquisition data; therefore, it is suggested that the user set **exten** to a null string for real-time scenarios.

ERRORS

All errors within this routine are returned through the status variable. The include file **ret_codes.h**, which includes all possible return values, should be included so that the mnemonics for the return codes can be referenced. The **ret_codes.h** file is described in section 1H of the IDFS Programmers Manual.

SEE ALSO

reset_experiment_info	1 R
file_open	1 R
read_drec	1 R
select_sensor	1 R
get_data_key	1 R
get_version_number	1 R
create_data_structure	1 R
create_idf_data_structure	1 R
create_tensor_data_structure	1 R
libbase_idfs	1H
ret_codes	1H
idf_data	1 S
tensor_data	1 S

BUGS

None

EXAMPLES

Position the real-time IDFS data files associated with the virtual instrument RTLA, which is part of the RETE instrument/experiment, at the beginning of the data file. The RETE instrument/experiment is part of the TSS-1 mission, which is identified with the TSS project.

#include "libbase_idfs.h"
#include "ret_codes.h"

```
SDDAS_ULONG data_key;
SDDAS_USHORT vnum;
SDDAS_SHORT status;
void *idf_data_ptr;
```

```
status = get_data_key ("TSS", "TSS-1", "RETE", "RETE", "RTLA", &data_key);
if (status != ALL_OKAY)
{
    printf ("\n Error %d returned by get_data_key routine.\n", status);
    exit (-1);
    get_version_number (&vnum);
status = create_idf_data_structure (&idf_data_ptr);
if (status != ALL_OKAY)
    {
    printf ("\n Error %d returned by create_idf_data_structure routine.\n", status);
    exit (-1);
    }
```

```
status = file_open (data_key, "", vnum, -1, -1, -1, 0, -1, -1, 0, 0);
if (status != ALL_OKAY)
{
    printf ("\n Error %d returned by file_open routine.\n", status);
    exit (-1);
}
```

```
status = file_pos (data_key, '''', vnum, idf_data_ptr, -1, -1, -1, 0, -1, -1, 0);
```

```
if (status != ALL_OKAY)
{
    printf ("\n Error %d returned by file_pos routine.\n", status);
    exit (-1);
}
```

file_pos (1R)

FIRST_IDFS_SENSOR

function – returns the first IDFS sensor that is defined within the sensor set for the current data record

SYNOPSIS

#include "libbase_idfs.h"
#include "ret_codes.h"

SDDAS_SHORT	first_idfs_sensor (SDDAS_ULONG data_key, SDDAS_CHAR *exten,
	SDDAS_USHORT version, SDDAS_SHORT *sensor_num)

ARGUMENTS

data_key	-	unique value which indicates the data set of interest
exten	-	two character extension to be added to IDFS file names when
		default files are not to be used, otherwise a null string
version	-	IDFS data set identification number which allows for multiple
		openings of the same data set
sensor_num	-	sensor identification number
first_idfs_sensor	-	routine status (see TABLE 1)

TABLE 1. Status Codes Returned for FIRST_IDFS_SENSOR

STATUS CODE	EXPLANATION OF STATUS
FIRST_SEN_NOT_FOUND	the requested data_key, exten, version combination has no memory allocated
	for processing (user did not call file_open for this combination)
ALL_OKAY	routine terminated successfully

DESCRIPTION

First_idfs_sensor is the IDFS routine that will return the sensor identification number for the first sensor that is defined within the sensor set of the current data record. The data set of interest is referenced through the key value **data_key** which can be created using the **get_data_key** module. This module is helpful when processing instrument status (mode) data. Although the instrument status data is not sensor-specific, that is, the data pertain to all sensors within the sensor set, the instrument status data is acquired using the IDFS read routine **read_drec** and **read_drec** requires a sensor identification number as one of its arguments.

The parameter **version** allows multiple file openings for an IDFS data set. If the data, header and VIDF file for the specified data set need to be opened just once for processing, the same version number should be passed to all IDFS routines. However, for multiple file openings, the version number should be unique and all file manipulations performed by the IDFS routines will use the file descriptors defined for the version number specified. The user should call the **get_version_number** routine to retrieve a unique version number instead of choosing this value themselves. The retrieval of multiple data parameters from a single data source does not constitute the need for multiple version numbers; a single version number will suffice.

If the **file_open** routine is not to open the default set of IDFS files but a modified set of IDFS files, the two character extension applied to these data files must be supplied to this routine within the string variable **exten**. These files must have the identical name as the IDFS files with the two character identification code appended to the end of the file names (i.e. RTLA19922181432Dxx, RTLA19922181432Hxx, RTLA19922181432Ixx). The files must reside either in the directory specified by the environment variable USER_DATA, which is set by the user, or in the user's home directory if the environment variable USER_DATA is not set. To open the default IDFS data files, **exten** should be set to a null string. The usage of modified data sets is limited to post acquisition data; therefore, it is suggested that the user set **exten** to a null string for real-time scenarios.

ERRORS

All errors within this routine are returned through the status variable. The include file **ret_codes.h**, which includes all possible return values, should be included so that the mnemonics for the return codes can be referenced. The **ret_codes.h** file is described in section 1H of the IDFS Programmers Manual.

SEE ALSO

file_open	1 R
read_drec	1 R
get_data_key	1 R
get_version_number	1R
libbase_idfs	1H
ret_codes	1H

BUGS

None

EXAMPLES

Retrieve the sensor identification number for the first sensor that is defined within the sensor set of the current data record.

#include "libbase_idfs.h"
#include "ret_codes.h"

SDDAS_ULONG data_key; SDDAS_USHORT vnum; SDDAS_SHORT status, sensor_number;

```
status = get_data_key ("TSS", "TSS-1", "RETE", "RETE", "RTLA", &data_key);
if (status != ALL_OKAY)
{
    printf ("\n Error %d returned by get_data_key routine.\n", status);
    exit (-1);
    get_version_number (&vnum);
```

```
status = first_idfs_sensor (data_key, "", vnum, &sensor_number);
if (status != ALL_OKAY)
{
    printf ("\n Error %d returned by first_idfs_sensor routine.\n", status);
    exit (-1);
}
```

FREE_EXPERIMENT_INFO

function - frees all the memory allocated by the IDFS routines

SYNOPSIS

#include "libbase_idfs.h"

void free_experiment_info (void)

ARGUMENTS

No arguments for this routine

DESCRIPTION

Free_experiment_info is the IDFS routine that frees all memory that has been allocated by the IDFS routines. The computer operating system normally takes care of freeing any memory before terminating the program; however, for a clean exit, the user should call this module before exiting from the program. In addition, the user may call this module if a total restart of the IDFS software is desired without restarting the program. In the case of a total restart, the user is advised to call the module **init_idfs** before any other IDFS routine since the **free_experiment_info** routine merely frees allocated memory; it does not reinitialize variables used by the IDFS software.

If any **idf_data** structures were created using the **create_idf_data_structure** or **create_data_structure** routine, **free_experiment_info** will free the memory associated with elements contained in the **idf_data** structure and the data structure itself. The user **must not** free the memory since the IDFS software will also attempt to free the memory.

If any **tensor_data** structures were created using the **create_tensor_data_structure** or **create_data_structure** routine, **free_experiment_info** will free the memory associated with elements contained in the **tensor_data** structure and the data structure itself. The user **must not** free the memory since the IDFS software will also attempt to free the memory.

ERRORS

This routine returns no status or error codes.

SEE ALSO

init_idfs	1 R
create_data_structure	1 R
create_idf_data_structure	1 R
create_tensor_data_structure	1 R
libbase_idfs	1H

BUGS

None

EXAMPLES

The usage of this routine is quite simple since no parameters are needed:

#include "libbase_idfs.h"

free_experiment_info ();

FREE_VERSION_INFO

function - frees the memory allocated by the IDFS routines for the specified version number

SYNOPSIS

#include "libbase_idfs.h"

_

void free_version_info (SDDAS_USHORT version)

ARGUMENTS

version

IDFS data set identification number which allows for multiple openings of the same data set

DESCRIPTION

Free_version_info is the IDFS routine that frees all memory that has been allocated by the IDFS routines for the specified version number. The computer operating system normally takes care of freeing any memory before terminating the program; however, for a clean exit, the user should call this module before exiting from the program. If the user desires a total restart of the IDFS software without restarting the program, the user **should not** use this module but should use the **free_experiment_info** module.

The parameter **version** allows multiple file openings for an IDFS data set. If the data, header and VIDF file for the specified data set need to be opened just once for processing, the same version number should be passed to all IDFS routines. However, for multiple file openings, the version number should be unique and all file manipulations performed by the IDFS routines will use the file descriptors defined for the version number specified. The user should call the **get_version_number** routine to retrieve a unique version number instead of choosing this value themselves. The retrieval of multiple data parameters from a single data source does not constitute the need for multiple version numbers; a single version number will suffice.

ERRORS

This routine returns no status or error codes.

SEE ALSO

free_experiment_info	1 R
get_version_number	1R
libbase_idfs	1H

BUGS

None

EXAMPLE

Free the memory allocated by the IDFS software for the specified version number. Assume this value has been previously set by the **get_version_number** routine.

#include "libbase_idfs.h"

SDDAS_USHORT vnum;

free_version_info (vnum);

GET_DATA_KEY

function - create a key value which identifies the data set of interest

SYNOPSIS

#include "libdb.h"
#include "ret_codes.h"

SDDAS_SHORT get_data_key (SDDAS_CHAR *pstr, SDDAS_CHAR *mstr,
SDDAS_CHAR *estr, SDDAS_CHAR *istr,
SDDAS_CHAR *vstr, SDDAS_ULONG *data_key)

ARGUMENTS

pstr	-	the assigned database name for the project to be accessed
mstr	-	the assigned database name for the mission to be accessed
estr	-	the assigned database name for the experiment to be accessed
istr	-	the assigned database name for the instrument to be accessed
vstr	-	the assigned database name for the virtual instrument to be accessed
data_key	-	unique value which indicates the data set being requested
get_data_key	-	routine status (see TABLE 1)

TABLE 1. Status Codes Returned for GET_DATA_KEY

STATUS CODE	EXPLANATION OF STATUS
DKEY_PROJECT	invalid project name
DKEY_MISSION	invalid mission name
DKEY_EXPERIMENT	invalid experiment name
DKEY_INSTRUMENT	invalid instrument name
DKEY_VINST	invalid virtual instrument name
ALL_OKAY	routine terminated successfully

DESCRIPTION

Get_data_key is the IDFS routine which creates a key that reflects the data set being accessed by utilizing the assigned database names for the project, mission, experiment, instrument and virtual instrument of interest. The IDFS routine **fields_to_key** performs the same function but works with the assigned database numbers instead of the assigned database names. Most of the IDFS routines utilize key values; therefore, a call to either this routine or to the **fields_to_key** routine must be made before any of the other IDFS routines that utilize a key value can be called.

The user selects the data set of interest by specifying the name of a virtual instrument from a specific instrument, which comes from a parent experiment within a mission which is associated with a specific project. All references for these items are through assigned database names. Since the IDFS data access software must interface with the database, the user must include the file **libdb.h** in their code when the **get_data_key** module is called.

ERRORS

All errors within this routine are returned through the status variable. The include file **ret_codes.h**, which includes all possible return values, should be included so that the mnemonics for the return codes can be referenced. The **ret_codes.h** file is described in section 1H of the IDFS Programmers Manual.

SEE ALSO

fields_to_key	1R
ret_codes	1H

BUGS

None

EXAMPLES

Retrieve the data key for the virtual instrument RTLA, which is part of the RETE instrument/experiment, which is part of the TSS-1 mission, which is identified with the TSS project.

#include "libdb.h"
#include "ret_codes.h"

SDDAS_ULONG data_key; SDDAS_SHORT ret_val;

```
ret_val = get_data_key ("TSS", "TSS-1", "RETE", "RETE", "RTLA", &data_key);
if (ret_val != ALL_OKAY)
{
    printf ("\n Error %d returned by get_data_key routine.\n", ret_val);
    exit (-1);
```

}

GET_VERSION_NUMBER

function - returns a unique IDFS data set identification number

SYNOPSIS

#include "libbase_idfs.h"

void get_version_number (SDDAS_USHORT *version)

ARGUMENTS

version

IDFS data set identification number which allows for multiple openings of the same data set

DESCRIPTION

Get_version_number is the IDFS routine that returns a unique IDFS data set identification number that is to be used as a parameter to the other IDFS routines. This parameter allows multiple file openings for an IDFS data set. For multiple file openings of the same IDFS data set, the version number must be unique and all file manipulations performed by the IDFS routines will use the file descriptors defined for the version number specified. If the user is opening many different IDFS data sets, but just opening each data set once, the user may pass the same version number for each of the different IDFS data sets. For example, if the user is going to process RTLA and RTLB data, one version number is sufficient. The user should call the get_version_number routine to be guaranteed a unique version number.

ERRORS

This routine returns no status or error codes.

BUGS

None

EXAMPLES

Retrieve a unique version number to be used by the IDFS routines.

#include "libbase_idfs.h"

SDDAS_USHORT vnum;

get_version_number (&vnum);

INIT_IDFS

function - initializes the system for processing IDFS information

SYNOPSIS

#include "libbase_idfs.h"

void init_idfs (void)

ARGUMENTS

No arguments for this routine

DESCRIPTION

Init_idfs is the IDFS routine that initializes the system to allow processing of the information contained in the IDFS files. A call **must** be made to this routine before any of the other IDFS routines documented in this manual can be utilized.

Since the IDFS data access software must interface with the database, calls must be made to the **dbInitialize** and **CfgInit** modules when the **init_idfs** module is called. The user is referred to the webpages <u>http://cluster/libdbSQL.html</u> and <u>http://cluster/libCfg.html</u> for an explanation of these routines.

ERRORS

This routine returns no status or error codes.

BUGS

None

EXAMPLES

The usage of this routine is quite simple since no parameters are needed:

#include "libbase_idfs.h"

CfgInit (); dbInitialize (); init_idfs (); init_idfs (1R)

NEXT_FILE_START_TIME

function - returns the time that is to be used to retrieve the next data file

SYNOPSIS

#include "libbase_idfs.h"
#include "ret_codes.h"

SDDAS_SHORT	next_file_start_time (SDDAS_ULONG data_key,
	SDDAS_CHAR *exten, SDDAS_USHORT version,
	SDDAS_CHAR mode_data, SDDAS_SHORT *start_yr,
	SDDAS_SHORT *start_day, SDDAS_LONG *start_sec,

SDDAS_LONG *start_nano)

ARGUMENTS

data_key	-	unique value which indicates the data set of interest
exten	-	two character extension to be added to IDFS file names
		when default files are not to be used, otherwise a null string
version	-	IDFS data set identification number which allows for multiple
		openings of the same data set
mode_data	-	flag indicating if the time for instrument status (mode) data is
		being requested
		0 - the time for instrument status data is not being
		requested
		1 - the time for instrument status data is being
		requested
start_yr	-	year for retrieval of next data file
start_day	-	day of year for retrieval of next data file
start_sec	-	time of day in seconds for retrieval of next data file
start_nano	-	time of day residual in nanoseconds
next_file_start_time	-	routine status (see TABLE 1)

TABLE 1. Status Codes Returned for NEXT_FILE_START_TIME

STATUS CODE	EXPLANATION OF STATUS
NEXT_FILE_TIME_NOT_FOUND	the requested data_key, exten, version combination has no memory allocated
	for processing (user did not call file_open for this combination)
NEXT_FILE_TIME_FILE_OPEN	the user did not request mode data processing when file_open was called
NEXT_FILE_TIME_INFO_DUP	the requested data_key, exten, version combination has no memory allocated
	for the instrument status information
ALL_OKAY	routine terminated successfully

DESCRIPTION

Next_file_start_time is the IDFS routine that will return the start time that will trigger the retrieval of the next data file to be processed. The data set of interest is referenced through the key value **data_key** which can be created using the **get_data_key** module. This routine should be called only in the case of a playback database request. When the return code from the **read_drec**, **read_tensor_data**, **start_image**, **fill_data**, **fill_discontinuous_data**,

fill_mode_data, **sweep_data**, **sweep_discontinuous_data**, **sweep_mode_data** or **file_pos** routine indicates that the end of the current data file has been reached (LOS_STATUS or NEXT_FILE_STATUS), the **next_file_start_time** module should be called and the time values returned should be sent to the **reset_experiment_info** routine.

The parameter **version** allows multiple file openings for an IDFS data set. If the data, header and VIDF file for the specified data set need to be opened just once for processing, the same version number should be passed to all IDFS routines. However, for multiple file openings, the version number should be unique and all file manipulations performed by the IDFS routines will use the file descriptors defined for the version number specified. The user should call the **get_version_number** routine to retrieve a unique version number instead of choosing this value themselves. The retrieval of multiple data parameters from a single data source does not constitute the need for multiple version numbers; a single version number will suffice.

If the **file_open** routine is not to open the default set of IDFS files but a modified set of IDFS files, the two character extension applied to these data files must be supplied to this routine within the string variable **exten**. These files must have the identical name as the IDFS files with the two character identification code appended to the end of the file names (i.e. RTLA19922181432Dxx, RTLA19922181432Hxx, RTLA19922181432Ixx). The files must reside either in the directory specified by the environment variable USER_DATA, which is set by the user, or in the user's home directory if the environment variable USER_DATA is not set. To open the default IDFS data files, **exten** should be set to a null string. The usage of modified data sets is limited to post acquisition data; therefore, it is suggested that the user set **exten** to a null string for real-time scenarios.

ERRORS

All errors within this routine are returned through the status variable. The include file **ret_codes.h**, which includes all possible return values, should be included so that the mnemonics for the return codes can be referenced. The **ret_codes.h** file is described in section 1H of the IDFS Programmers Manual.

SEE ALSO

file_open	1 R
reset_experiment_info	1 R
get_version_number	1 R
get_data_key	1 R
file_pos	1 R
read_drec	1 R
read_tensor_data	1 R
start_image	1 R
fill_data	2R
fill_discontinuous_data	2R
fill_mode_data	2R
sweep_data	2R
sweep_discontinuous_data	2R

sweep_mode_data	2R
ret_codes	1H
libbase_idfs	1H

BUGS

None

EXAMPLES

Determine the start time to be used to retrieve the next data file for the virtual instrument RTLA, which is part of the RETE instrument/experiment, which is part of the TSS-1 mission, which is identified with the TSS project. In the calling sequence, indicate that the time for instrument status data is not being requested for the data set in question.

#include "libbase_idfs.h"
#include "ret_codes.h"

SDDAS_ULONG data_key; SDDAS_USHORT vnum; SDDAS_LONG start_sec, start_nsec; SDDAS_SHORT status, start_yr, start_day;

```
status = get_data_key ("TSS", "TSS-1", "RETE", "RETE", "RTLA", &data_key);
if (status != ALL_OKAY)
{
    printf ("\n Error %d returned by get_data_key routine.\n", status);
    exit (-1);
    get version number (&vnum);
```

OVERRIDE_POTENTIAL_POLYNOMIAL

function – overrides the slope and intercept values defined for the first order polynomial that is used to adjust the spacecraft potential data used by the specified data set

SYNOPSIS

#include "libbase_idfs.h"
#include "ret_codes.h"

SDDAS_SHORT override_potential_polynomial (SDDAS_ULONG data_key,				
SDDAS_CHAR *exten, SDDAS_USHORT version,				
	SDDAS_	FLOAT slope, SDDAS_FLOAT intercept)		
ARGUMENTS				
data_key	-	unique value which indicates the data set of interest		
exten	-	two character extension to be added to IDFS		
version	-	file names when default files are not to be used, otherwise a null string IDFS data set identification number which		
		allows for multiple openings of the same data		
1		set		
slope	-	new slope value to be used in the polynomial equation		
intercept	-	new intercept value to be used in the polynomial equation		
override_potential_polynomial	-	routine status (see TABLE 1)		

TABLE 1. Status Codes Returned for **OVERRIDE_POTENTIAL_POLYNOMIAL**

STATUS CODE	EXPLANATION OF STATUS
OVERRIDE_NOT_FOUND	the requested data_key, exten, version combination has no memory
	allocated for processing (user did not call file_open for this combination)
OVERRIDE_NO_POT	there is no spacecraft potential data defined for this data set
OVERRIDE_NO_POT_TBLS	there are no tables defined for this data set which are a function of
	spacecraft potential data $(tbl_var = 3)$
OVERRIDE_TOO_MANY_POT_TBLS	there is more than one table defined for this data set which is a function of
	spacecraft potential data $(tbl_var = 3)$
OVERRIDE_TBL_FMT_MALLOC	no memory for the table format (tbl_fmt) values
OVERRIDE_BAD_TBL_FMT_VALUE	the table format values do not specify a first order polynomial
	error codes returned by ReadVIDF ()
ALL_OKAY	routine terminated successfully

DESCRIPTION

Override_potential_polynomial is the IDFS routine that can be used to override the coefficients of the polynomial equation that is used to modify the spacecraft potential data before it is used to convert the science data and / or scan data for the selected data set into scientific units. The original polynomial equation is defined within a table in the VIDF file

for the data set specified. This table must have the **tbl_var** value set to 3, indicating that the table is a function of spacecraft potential data. The data set of interest is referenced through the key value **data_key** which can be created using the **get_data_key** module. This routine **must** be called after the routine **file_open** and before the routine **file_pos** if this routine is to be utilized properly. If this routine is called multiple times with the identical **data_key**, **exten** and **version** parameters, the slope and intercept values from the last call will be saved and utilized.

The parameter **version** allows multiple file openings for an IDFS data set. If the data, header and VIDF file for the specified data set need to be opened just once for processing, the same version number should be passed to all IDFS routines. However, for multiple file openings, the version number should be unique and all file manipulations performed by the IDFS routines will use the file descriptors defined for the version number specified. The user should call the **get_version_number** routine to retrieve a unique version number instead of choosing this value themselves. The retrieval of multiple data parameters from a single data source does not constitute the need for multiple version numbers; a single version number will suffice.

If the **file_open** routine is not to open the default set of IDFS files but a modified set of IDFS files, the two character extension applied to these data files must be supplied to this routine within the string variable **exten**. These files must have the identical name as the IDFS files with the two character identification code appended to the end of the file names (i.e. RTLA19922181432Dxx, RTLA19922181432Hxx, RTLA19922181432Ixx). The files must reside either in the directory specified by the environment variable USER_DATA, which is set by the user, or in the user's home directory if the environment variable USER_DATA is not set. To open the default IDFS data files, **exten** should be set to a null string. The usage of modified data sets is limited to post acquisition data; therefore, it is suggested that the user set **exten** to a null string for real-time scenarios.

ERRORS

All errors within this routine are returned through the status variable. The include file **ret_codes.h**, which includes all possible return values, should be included so that the mnemonics for the return codes can be referenced. The **ret_codes.h** file is described in section 1H of the IDFS Programmers Manual.

SEE ALSO

file_pos	1R
file_open	1R
get_data_key	1R
get_version_number	1R
ret_codes	1H
libbase_idfs	1H
convert_to_units	1R

BUGS

None

EXAMPLES

Modify the polynomial coefficients associated with the spacecraft potential data for the virtual instrument CPXP1L, which is part of the 3DX1 instrument, which is part of the PEACE experiment, which is part of the CLUSTER-1 mission, which is identified with the CLUSTERII project.

#include "libbase_idfs.h"
#include "ret_codes.h"

```
SDDAS FLOAT slope, intercept;
SDDAS_ULONG data_key:
SDDAS LONG blime sec, blime nano, elime sec, elime nano;
SDDAS USHORT vnum;
SDDAS SHORT status;
status = get_data_key ("CLUSTERII", "CLUSTER-1", "PEACE", "3DX1", "CPXP1L",
                     &data_key);
if (status != ALL OKAY)
{
 printf ("\n Error %d returned by get data key routine.\n", status);
 exit (-1);
}
get version number (&vnum);
btime_sec = (19 * 3600) + (50 * 60) + 0;
btime nano = 0;
etime sec = (19 * 3600) + (51 * 60) + 0;
etime nano = 0;
status = file_open (data_key, "", vnum, 2002, 7, btime_sec, btime_nano, 2002, 7,
                  etime sec, etime nano, 0);
if (status != ALL_OKAY)
ł
 printf ("\n Error %d from file_open routine.\n", status);
 exit (-1);
}
slope = 1.0;
intercept = 1.5;
status = override_potential_polynomial (data_key, "", vnum, slope, intercept);
if (status != ALL OKAY)
{
 printf ("\n Error %d from override potential polynomial routine.\n", status);
 exit (-1);
}
```

READ_DREC

function - read data from an IDFS file and return the data in raw units (telemetry level) in the specified **idf_data** structure

SYNOPSIS

#include "libbase_idfs.h"
#include "ret_codes.h"

SDDAS_SHORT read_drec (SDDAS_ULONG data_key, SDDAS_CHA	AR *exten,
SDDAS_USHORT version, void *idf_data	_ptr,
SDDAS_SHORT sen, SDDAS_CHAR fwc	l,
SDDAS_CHAR full_swp)	

ARGUMENTS

data_key	-	unique value which indicates the data set of interest			
exten	-	two character extension to be added to IDFS file names when default			
		files are not to be used, otherwise a null string			
version	-	IDFS data set identification number which allows for multiple			
		openings of the same data set			
idf_data_ptr	-	pointer to the idf_data structure that is to hold sensor data			
Ĩ		and pertinent ancillary data for the data set of interest			
sen	-	sensor identification number			
fwd	-	next time sample			
		0 - do not advance to the next time sample			
		after obtaining data			
		1 - advance to the next time sample after			
		obtaining data			
full_swp	-	data return length (this option applicable only if the sensor			
- 1		is associated with a scalar data set)			
		0 - return a single data value			
		1 - return n_sample data values			
read_drec	_	routine status (see TABLE 1)			
reaa_aree					

TABLE 1.	Status	Codes	Returned	for READ	DREC
----------	--------	-------	----------	-----------------	-------------

STATUS CODE	EXPLANATION OF STATUS
DREC_NOT_FOUND	the requested data_key, exten, version combination has no memory
	allocated for processing (user did not call file_open for this combination)
DREC_NO_FILES	data and header files have not been opened
DREC_READ_ERROR	read error on data file
PARTIAL_READ	the number of bytes read from the file being accessed did not match the
	number of bytes requested. This code is returned only for the playback
	scenario. The code EOF_STATUS is returned for the real-time scenario.
DREC_HDR_READ_ERROR	read error on header file
DREC_HDR_MALLOC	no memory for header record information
DREC_HDR_REALLOC	no memory for header information expansion (header increased in size)

STATUS CODE	EXPLANATION OF STATUS
RESET_DATA_MALLOC	no memory for sensor data array in the idf_data structure
RESET_DATA_REALLOC	no memory for sensor data array expansion in the idf_data structure
RESET_EULER_REALLOC	no memory for euler angle array expansion in the idf_data structure
RESET_ANGLE_REALLOC	no memory for azimuthal sample angle array expansion in the idf_data
	structure
RESET_PITCH_MALLOC	no memory for pitch angle array in the idf_data structure
RESET_PITCH_REALLOC	no memory for pitch angle array expansion in the idf_data structure
RESET_DCOS_MALLOC	no memory for direction cosine structure
RESET_DCOS_VAL_MALLOC	no memory for direction cosine values
RESET_DCOS_VAL_REALLOC	no memory for expansion of direction cosine values
RESET_MODE_REALLOC	no memory for expansion of instrument mode flags array
ALLOC_EV_REALLOC	no memory for sweep array expansion in the idf_data structure
RESET_CSET_MALLOC	no memory for calibration set size array in the idf_data structure
CRIT_TBL_NOT_FOUND	the table requested was not found amongst the sensor tables
PA_BAD_TIMES	the end time of the sample is less than the start time of the sample for pitch
	angle data
UPDATE_IDF_ELE_NOT_FOUND	the data item being requested was not found in the VIDF file
UPDATE_IDF_MANY_BYTES	the number of elements being requested is more than the number of
	elements available for the selected field
UPDATE_IDF_TBL_NUM	the table being requested exceeds the number of defined tables
UPDATE_IDF_CON_NUM	the constant being requested exceeds the number of defined constants
UPDATE_IDF_NO_ENTRY	the field being requested is not defined
WRONG_HEADER_FORMAT	multi-dimensional IDFS data storage is not supported by this module
CREATE_TBL_MALLOC	no memory for table values (tbl) when the table is expanded using the
	coefficients from the VIDF file
CREATE_IDF_NO_ENTRY	the field being requested is not defined
CREATE_IDF_ELE_NOT_FOUND	the data item being requested was not found in the VIDF file
CREATE_IDF_TBL_NUM	the table being requested exceeds the number of defined tables
CREATE_IDF_MANY_BYTES	the number of elements being requested is more than the number of
	elements available for the selected field
CREATE_IDF_CON_NUM	the constant being requested exceeds the number of defined constants
CREATE_BAD_TBL_OFFSET	invalid tbl_off value encountered
READ_IN_MALLOC	no memory for table values (tbl) read straight from the VIDF file
READ_IN_IDF_ELE_NOT_FOUND	the data item being requested was not found in the VIDF file
READ_IN_IDF_MANY_BYTES	the number of elements being requested is more than the number of
	elements available for the selected field
READ_IN_IDF_TBL_NUM	the table being requested exceeds the number of defined tables
READ_IN_IDF_CON_NUM	the constant being requested exceeds the number of defined constants
READ_IN_IDF_NO_ENTRY	the field being requested is not defined
READ_IN_BAD_TBL_OFFSET	invalid tbl_off value encountered
NEW_SCALE_MALLOC	no memory to hold the scale factors to be applied to the table values
NEW_IDF_ELE_NOT_FOUND	the data item being requested was not found in the VIDF file
NEW_IDF_MANY_BYTES	the number of elements being requested is more than the number of
	elements available for the selected field
NEW_IDF_TBL_NUM	the table being requested exceeds the number of defined tables
NEW_IDF_CON_NUM	the constant being requested exceeds the number of defined constants
NEW_IDF_NO_ENTRY	the field being requested is not defined
FILL_HEADER	the header record read is a fill header, indicating that the header record has
	not been received by the workstation at the time of the read from the file.
	This code is returned only for the playback scenario. The code
	EOF_STATUS is returned for the real-time scenario.
PA_BAD_FRAC	invalid normalization factor calculated for pitch angle data

STATUS CODE	EXPLANATION OF STATUS
PA_BAD_SRC	the IDFS data source for the pitch angle data is not a scalar instrument
BAD_PA_FORMAT	the format specification field for the pitch angle data is invalid
NEW_BAD_TBL_OFFSET	invalid tbl_off value encountered
CHK_DATA_NOT_FOUND	an error was encountered when trying to access the structure that holds
	information pertinent to one of the IDFS data sets being processed
NUM_CAL_REALLOC	no memory for expansion of calibration array
HDR_FMT_ONE_MALLOC	no memory for elements pertinent to original idfs definition
POT_BAD_FRAC	invalid normalization factor calculated for spacecraft potential data
POT_BAD_SRC	the IDFS data source for the spacecraft potential data is not a scalar instrument
BAD_SCPOT_FORMAT	the format specification field for the spacecraft potential data is invalid
POT_BAD_TIMES	the end time of the sample is less than the start time of the sample for
	spacecraft potential data
RESET_POT_REALLOC	no memory for spacecraft potential array expansion in the idf_data
	structure
EULER_BAD_SRC	the IDFS data source for the euler angle data is not a scalar instrument
EULER_BAD_TIMES	the end time of the sample is less than the start time of the sample for euler
	angle data
EULER_BAD_FRAC	invalid normalization factor calculated for euler angle data
BAD_EULER_FORMAT	the format specification field for the euler angle data is invalid
LESS_EULER_CONSTANT_ANGLES	the number of euler angle constants defined in the VIDF file is less than
	the number of euler angles defined in the VIDF file
LESS_EULER_CONSTANT_AXIS	the number of euler rotation axis constants defined in the VIDF file is less
	than the number of euler angles defined in the VIDF file
MORE_EULER_CONSTANT_ANGLES	the number of euler angle constants defined in the VIDF file is more than
	the number of euler angles defined in the VIDF file
MORE_EULER_CONSTANT_AXIS	the number of euler rotation axis constants defined in the VIDF file is
	more than the number of euler angles defined in the VIDF file
CP_BAD_TIMES	the end time of the sample is less than the start time of the sample for
	celestial position angle data
BAD_CP_FORMAT	the format specification field for the celestial position angle data is invalid
CP_BAD_FRAC	invalid normalization factor calculated for celestial position angle data
CP_BAD_SRC	the IDFS data source for the celestial position angle data is not a scalar
DESET OF DEALLOC	instrument
RESET_CP_REALLOC	no memory for celestial position angle array expansion in the idf_data
BKGD_BAD_FRAC	structure invalid normalization factor calculated for background data
BKGD_BAD_TIMES	the end time of the sample is less than the start time of the sample for
BROD_BAD_TIMES	background data
BAD BKGD FORMAT	the format specification field for the background data is invalid
RESET_BKGD_REALLOC	no memory for background array expansion in the idf_data structure
RESET_TINFO_MALLOC	no memory for structure that holds coordinate transformation data in the
	idf_data structure
WRONG_DATA_STRUCTURE	incompatibility between IDFS data set and IDFS data structure used to
	hold the data being returned
DREC_EOF_NO_SENSOR	no data found for the requested sensor – eof on forward (real-time scenario
	only)
DREC_EOF_SENSOR	data found for the requested sensor – eof on forward (real-time scenario
	only)
DREC_NO_SENSOR	no data found for the requested sensor
EOF_STATUS	eof encountered on file being accessed (real-time scenario only)
LOS_STATUS	loss of signal encountered
DREC_NO_SENSOR EOF_STATUS	data found for the requested sensor – eof on forward (real-time scenario only) no data found for the requested sensor eof encountered on file being accessed (real-time scenario only)

STATUS CODE	EXPLANATION OF STATUS
NEXT_FILE_STATUS	the end of the current data file being processed has been reached
	Error codes returned by file_pos ()
	Error codes returned by reset_experiment_info ()
	Error codes returned by convert_to_units ()
ALL_OKAY	data for requested sensor is returned

DESCRIPTION

Read_drec is the IDFS data read routine, returning data for a single sensor. The sensor is indicated through the sensor number (**sen**). The data set of interest is referenced through the key value **data_key** which can be created using the **get_data_key** module. The routine returns not only the data for the sensor but also most of the pertinent ancillary data concerning the state of the virtual instrument including time, instrument status (mode) values, all applicable correction and calibration data, sweep step values, azimuthal angle values, pitch angle values, spacecraft potential values and background values where applicable. All data is returned in raw units (telemetry format). To convert the data into the unit desired, the user should utilize the **convert_to_units** routine, which is explained in section 1R of the IDFS Programmers Manual.

In cases where pitch angle data is needed. the routine not turn off pitch angle computations may be called in order to save time performing unnecessary pitch angle computations. By default, euler angle information, if pertinent to the data set of interest, is not returned from the read_drec module unless the routine turn on euler angle computations has been called. In addition, celestial position angle information, if pertinent to the data set of interest, is not returned from the read drec module unless the routine turn on celestial position computations has been called.

The returned data is placed in the **idf_data** structure that is referenced by the argument **idf_data_ptr**. The argument **idf_data_ptr** is a pointer to the structure that is to hold all data pertinent to the data set being processed. The structure is created and the address to this structure is returned when a call to the **create_idf_data_structure** routine is made. The user also has the option of calling the module **create_data_structure**, which determines what type of data structure is needed for the IDFS data set of interest. In most cases, one data structure is sufficient to process any number of distinct data sets. However, if more than one structure is needed, the user may call the **create_idf_data_structure** routine N times to create N instances of the **idf_data** structure. The user must keep track of which pointer to send to the IDFS routines that utilize this structure. The contents of this structure is described in section 1S of the IDFS Programmers Manual.

The parameter **version** allows multiple file openings for an IDFS data set. If the data, header and VIDF file for the specified data set need to be opened just once for processing, the same version number should be passed to all IDFS routines. However, for multiple file openings, the version number should be unique and all file manipulations performed by the IDFS routines will use the file descriptors defined for the version number specified. The user should call the **get_version_number** routine to retrieve a unique version number instead of choosing this value themselves. The retrieval of multiple data parameters from a

single data source does not constitute the need for multiple version numbers; a single version number will suffice.

If the sensor returns scalar data, the number of data points returned in a given call can be changed through the variable **full_swp**. If **full_swp** is 0, the data is returned one sample at a time. If **full_swp** is 1, then all of the data, from the current data value through the end of the sensor set, are returned. With the exception of the first call to the **read_rec** routine, if **full_swp** is always set to 1 for a scalar sensor, the number of samples returned at each call is **n_sample**, which is defined in the header record. The number of samples returned at the first call depends on the initial position of the data pointer. The number of data values returned is always indicated in the **idf_data** structure.

After the data has been read, the current data pointer will be either be advanced to the next set of data values or remain at the current set of data values, depending upon the value of the variable **fwd**. For sweeping data, the pointer is advanced to the next full sweep with each forward. When used with scalar values, the pointer is advanced to the next value or to the next sensor set depending on whether the current value of **full_swp** is 0 or 1, respectively. By keeping the pointer at the same sensor set, repeated calls using the same virtual instrument but different sensors can be made, ensuring that all of the data returned was taken at the same time. Since the data is placed into the data arrays **before** the current data pointer is advanced, the user should check the status of the element **filled_data** within the **idf_data** structure if any status code other than **ALL_OKAY** is returned. This flag value will indicate if the data arrays have been filled and this data should be processed before further action is taken in accordance with the status code returned.

If the **file_open** routine is not to open the default set of IDFS files but a modified set of IDFS files, the two character extension applied to these data files must be supplied to this routine within the string variable **exten**. These files must have the identical name as the IDFS files with the two character identification code appended to the end of the file names (i.e. RTLA19922181432Dxx, RTLA19922181432Hxx, RTLA19922181432Ixx). The files must reside either in the directory specified by the environment variable USER_DATA, which is set by the user, or in the user's home directory if the environment variable USER_DATA is not set. To open the default IDFS data files, **exten** should be set to a null string. The usage of modified data sets is limited to post acquisition data; therefore, it is suggested that the user set **exten** to a null string for real-time scenarios.

There are two sets of time values returned by the **read_drec** routine. Within the **idf_data** structure, there are the elements **byear**, **bday**, **bmilli**, **bnano**, **eyear**, **eday**, **emilli** and **enano**. These time elements are associated with the requested sensor. The instrument status (mode) values are not sensor-specific, that is, they pertain to all sensors within the sensor set. Therefore, the time span encompassed by the instrument status values is specified in the elements **mode_byear**, **mode_bday**, **mode_bmilli**, **mode_bnano**, **mode_eyear**, **mode_eday**, **mode_emilli** and **mode_enano** within the idf_data structure.

ERRORS

All errors within this routine are returned through the status variable. The include file **ret_codes.h**, which includes all possible return values, should be included so that the mnemonics for the return codes can be referenced. The **ret_codes.h** file is described in section 1H of the IDFS Programmers Manual.

SEE ALSO

reset_experiment_info	1R
file_pos	1R
convert_to_units	1R
create_data_structure	1R
create_idf_data_structure	1R
get_data_key	1R
get_version_number	1R
turn_off_pitch_angle_computations	1R
turn_on_euler_angle_computations	1R
turn_on_celestial_position_computations	1 R
ret_codes	1H
libbase_idfs	1H
idf_data	1 S

BUGS

None

EXAMPLES

Obtain one sweep of data from sensor 2 in the virtual instrument RTLA, which is part of the RETE instrument/experiment, which is part of the TSS-1 mission, which is identified with the TSS project. Since this is a sweeping instrument, the **full_swp** variable is set to 1 (can not retrieve part of a sweep). The pointer is moved to the next full sweep in the data array after the data is obtained. The data is returned in the **idf_data** structure referenced by the pointer **idf_data_ptr**.

```
#include "libbase_idfs.h"
#include "ret_codes.h"
SDDAS_ULONG data_key;
SDDAS_USHORT vnum;
SDDAS_SHORT status;
void *idf_data_ptr;
status = get_data_key ("TSS", "TSS-1", "RETE", "RETE", "RTLA", &data_key);
if (status != ALL_OKAY)
{
    printf ("\n Error %d returned by get_data_key routine.\n", status);
    exit (-1);
    get_version_number (&vnum);
```

```
status = create_idf_data_structure (&idf_data_ptr);
if (status != ALL_OKAY)
{
    printf ("\n Error %d returned by create_idf_data_structure routine.\n", status);
    exit (-1);
}
status = read_drec (data_key, '''', vnum, idf_data_ptr, 2, 1, 1);
if (status != ALL_OKAY)
{
    printf ("\n Error %d returned by read_drec routine.\n", status);
    exit (-1);
}
```

read_drec (1R)

READ_DREC_SPIN

function - read data from an IDFS file and return data for a complete spin in raw units (telemetry level) for the sensor requested

SYNOPSIS

#include "libbase_idfs.h"
#include "ret_codes.h"

SDDAS_SHORT read_drec_spin (SDDAS_ULONG data_key, SDDAS_CHAR *exten,
SDDAS_USHORT version, SDDAS_SHORT sen,
SDDAS_USHORT *start_ele, SDDAS_FLOAT *start_frac,
SDDAS_USHORT *stop_ele, SDDAS_FLOAT *stop_frac,
SDDAS_LONG *num_sweeps, void ***data_ptrs)

ARGUMENTS

data_key	-	unique value which indicates the data set of interest
exten	-	two character extension to be added to IDFS file names when default files are not to be used, otherwise a null string
version	-	IDFS data set identification number which allows for multiple openings of the same data set
sen	-	sensor identification number
start_ele	-	element number within the sweep where the spin starts
start_frac	-	percentage of data that is to be included for the element
		within the sweep where the spin starts
stop_ele	-	element number within the sweep where the spin stops
stop_frac	-	percentage of data that is to be included for the element within the sweep where the spin stops
num_sweeps	_	the number of sweeps processed for the spin
data_ptrs	-	array of pointers to the idf_data structure(s) that hold sensor
		data and pertinent ancillary data for the data set of interest for each sweep processed for the spin
read_drec_spin	-	routine status (see TABLE 1)

TABLE 1. Status Codes Returned for READ_DREC_SPIN

STATUS CODE	EXPLANATION OF STATUS
READ_SPIN_NOT_FOUND	the requested data_key, exten, version combination has no memory
	allocated for processing (user did not call file_open for this combination)
READ_SPIN_NO_START	user did not call start_of_spin for this combination before calling this
	module
READ_SPIN_SENSOR_NOT_FOUND	the requested data_key, exten, version combination for one of the sensors
	being processed has no memory allocated for processing
READ_SPIN_DSRC_READ	error reading next record from spin data source to get next spin period
READ_SPIN_DSRC_BACK_SPIN	the next spin period went backwards in time
START_ELE_BAD_SENSOR	the sensor being requested is an invalid sensor number
START_ELE_SPIN_NO_SENSOR	the sensor being requested was not selected as a sensor to be processed for
	the data set in question (user did not call select_sensor for this combination)

STATUS CODE	EXPLANATION OF STATUS	
WRONG_HEADER_FORMAT	multi-dimensional IDFS data storage is not supported by this module	
READ_SPIN_ALL_REALLOC	no memory for expansion of the array of pointers to the idf_data structures	
	that are allocated to hold the data for each sweep within the spin	
READ_SPIN_PARTIAL	a partial spin is being returned since there is no further data available past	
	this point in the spin	
WRONG_DATA_STRUCTURE	incompatibility between IDFS data set and IDFS data structure used to hold	
	the data being returned	
	Error codes returned by read_drec ()	
	Error codes returned by next_file_start_time ()	
	Error codes returned by reset_experiment_info ()	
	Error codes returned by file_pos ()	
	Error codes returned by create_idf_data_structure ()	
READ_SPIN_DATA_GAP	a partial spin is being returned since a data gap was encountered while	
	acquiring the current spin	
READ_SPIN_TERMINATE	processing must be terminated since data for start of spin data source is no	
	longer available – partial spin is returned	
ALL_OKAY	data for requested sensor is returned	

DESCRIPTION

Read_drec_spin is the IDFS data read routine that returns a full spin of data for a single sensor. The sensor is indicated through the sensor number (**sen**). The data set of interest is referenced through the key value **data_key** which can be created using the **get_data_key** module. **Read_drec_spin** make use of the **read_drec** routine and therefore, returns not only the data for the sensor but also most of the pertinent ancillary data concerning the state of the virtual instrument including time, instrument status (mode) values, all applicable correction and calibration data, sweep step values, azimuthal angle values, pitch angle values, spacecraft potential values and background values where applicable.

The argument **data_ptrs** is an array of pointers to the collection of **idf_data** structures that hold all data pertinent to the spin being processed. There is basically one **idf_data** structure allocated for each sweep within the spin. The total number of sweeps contained within the spin being processed is returned in the argument **num_sweeps**. The structures are created as the need for another **idf_data** structure is encountered and the address to the newly created structure is added to the array of pointers referenced by the **data_ptrs** argument. These data structures are re-used as successive spins are processed; therefore, the user must extract all data that is returned prior to the next call to the **read_drec_spin** routine. The contents of the **idf_data** structure is described in section 1S of the IDFS Programmers Manual. All data is returned in raw units (telemetry format). To convert the data into the unit desired, the user should utilize the **convert_to_units** routine, which is explained in section 1R of the IDFS Programmers Manual.

The parameter **version** allows multiple file openings for an IDFS data set. If the data, header and VIDF file for the specified data set need to be opened just once for processing, the same version number should be passed to all IDFS routines. However, for multiple file openings, the version number should be unique and all file manipulations performed by the IDFS routines will use the file descriptors defined for the version number specified. The user should call the **get_version_number** routine to retrieve a unique version number

instead of choosing this value themselves. The retrieval of multiple data parameters from a single data source does not constitute the need for multiple version numbers; a single version number will suffice.

If the **file_open** routine is not to open the default set of IDFS files but a modified set of IDFS files, the two character extension applied to these data files must be supplied to this routine within the string variable **exten**. These files must have the identical name as the IDFS files with the two character identification code appended to the end of the file names (i.e. RTLA19922181432Dxx, RTLA19922181432Hxx, RTLA19922181432Ixx). The files must reside either in the directory specified by the environment variable USER_DATA, which is set by the user, or in the user's home directory if the environment variable USER_DATA is not set. To open the default IDFS data files, **exten** should be set to a null string. The usage of modified data sets is limited to post acquisition data; therefore, it is suggested that the user set **exten** to a null string for real-time scenarios.

For sweeping data, the start of each spin period does not always correlate with the first element of the sweep. The **start_ele** argument returns the element number at which the spin begins for the first sweep returned for the spin being processed. Likewise, the **stop_ele** argument returns the element number at which the spin ends for the last sweep returned for the spin being processed.

Within the IDFS paradigm, there are two methods utilized to determine the start of spin for an IDFS data source. The first method is referred to as the angular method since the start of spin is flagged as the point at which the azimuthal angle crosses over at 0 degrees, taking into account some tolerance factor. The second method allows the time of each spin to be explicitly defined and is specified by defining an IDFS data source that is to be used to determine the spin periods within the VIDF for the data set of interest. When the second method is utilized, the arguments **start_frac** and **stop_frac** will return values between 0.0 and 1.0, indicating the percentage of data that is to be included for the elements within the sweep where the spin starts (**start_ele**) and stops (**stop_ele**). This percentage is calculated based upon the start / stop time for the spin period and the start / stop time for the first and last sweep processed. When the angular method is utilized, the arguments **start_frac** and **stop_frac** will be set at 1.0 since the angle value pertains to the entire duration of the step. The user does not need to concern themselves with which method is utilized and it is up to their discretion whether they wish to utilize the contents of these two arguments when processing the data returned by the **read_drec_spin** module.

Unlike the **read_drec** and **read_tensor_data** modules, the **read_drec_spin** module automatically handles the acquisition of the next data file when the end of the current data file has been reached. This action is performed since this module tries to retrieve a full spin of data, not just a single sweep of data. Since the acquisition is automatically performed, there is no need for the user to call the **reset_experiment_info** module within their code.

ERRORS

All errors within this routine are returned through the status variable. The include file **ret_codes.h**, which includes all possible return values, should be included so that the

mnemonics for the return codes can be referenced. The **ret_codes.h** file is described in section 1H of the IDFS Programmers Manual.

SEE ALSO

1 R
1R
1H
1H
1S

BUGS

None

EXAMPLES

Obtain one spin of data from sensor 0 in the virtual instrument CP3DRH, which is part of the 3DR instrument, which is part of the PEACE experiment, which is part of the CLUSTER-2 mission, which is identified with the CLUSTERII project.

#include "libbase_idfs.h"
#include "ret_codes.h"

```
struct idf data *EXP DATA;
register SDDAS USHORT k;
register SDDAS_LONG swp_num;
SDDAS ULONG data key;
SDDAS_LONG num_sweeps, last_sweep, *tbl_oper;
SDDAS FLOAT conv data[1000], start frac, stop frac;
SDDAS_USHORT vnum, start_ele, stop_ele, start_index, stop_index;
SDDAS_SHORT status, rcode;
SDDAS_CHAR *tbls_to_apply, num_tbls;
void **data_arrays, *idf_data_ptr;
status = get_data_key ("CLUSTERII", "CLUSTER-2", "PEACE", "3DR", "CP3DRH",
                    &data_key);
if (status != ALL_OKAY)
{
 printf ("\n Error %d returned by get_data_key routine.\n", status);
 exit (-1);
}
get_version_number (&vnum);
```

```
/*
  Retrieve the raw units for the data.
                                                       * /
num tbls = 0;
tbls_to_apply = NULL;
tbl_oper = NULL;
status = read_drec_spin (data_key, '''', vnum, 0, &start_ele, &start_frac, &stop_ele,
                 &stop frac, &num sweeps, &data arrays);
*/
/* Process the spin.
if (status == ALL_OKAY || status == READ_SPIN_TERMINATE ||
 status == READ_SPIN_PARTIAL || status == READ_SPIN_DATA_GAP)
ł
  last_sweep = num_sweeps - 1;
  for (swp_num = 0; swp_num < num_sweeps; ++swp_num)
  {
   /* Print the times for the sample being returned.
                                                       */
   idf_data_ptr = *(data_arrays + swp_num);
   EXP_DATA = (struct idf_data *) idf_data_ptr;
   printf ("\nSTART TIME YEAR = %4d START TIME DAY = %03d
         START TIME_MS = %ld START TIME_NS = %ld",
         EXP_DATA->byear, EXP_DATA->bday, EXP_DATA->bmilli,
         EXP DATA->bnano);
   printf ("\nEND_TIME YEAR = %4d END_TIME DAY = %03d
         END TIME MS = \% ld END TIME NS = \% ld ",
         EXP_DATA->eyear, EXP_DATA->eday, EXP_DATA->emilli,
         EXP DATA->enano);
   rcode = convert_to_units (data_key, "", vnum, idf_data_ptr, 0, SENSOR, 0,
                    num_tbls, tbls_to_apply, tbl_oper, conv_data, 0, 0);
   if (rcode != ALL_OKAY)
    printf ("\nError %d from convert to units.\n", rcode);
    exit (-1);
    ł
```

}

}

```
if (swp_num == 0)
 {
  start_index = start_ele;
  stop_index = EXP_DATA->num_sample;
  conv_data[start_ele] *= start_frac;
 }
else if (swp_num == last_sweep)
 {
  start_index = 0;
  stop_index = stop_ele;
  conv_data[stop_ele] *= stop_frac;
 }
else
 {
  start_index = 0;
  stop_index = EXP_DATA->num_sample;
 }
*/
/* Print data values, 6 values per row, in exponential format.
for (k = start_index; k < stop_index; ++k)
 {
   if (k \% 6 == 0)
    printf ("\n");
   printf ("%.6f ", conv_data[k]);
 }
printf ("\n\n");
```

READ_TENSOR_DATA

function - read data from a multi-dimensional IDFS data set and return the data in raw units (telemetry level) in the specified **tensor_data** structure

SYNOPSIS

#include "libbase_idfs.h"
#include "ret_codes.h"

SDDAS_SHORT read_tensor_data (SDDAS_ULONG data_key, SDDAS_CHAR *exten,
SDDAS_USHORT version, void *tensor_data_ptr,
SDDAS_SHORT sen, SDDAS_CHAR fwd)

ARGUMENTS

data_key	-	unique value which indicates the multi-dimensional IDFS		
		data set of interest		
exten	-	two character extension to be added to IDFS file names when		
		default files are not to be used, otherwise a null string		
version	-	IDFS data set identification number which allows for multiple		
		openings of the same data set		
tensor_data_ptr	_	pointer to the tensor_data structure that is to hold sensor data		
		and pertinent ancillary data for the data set of interest		
sen	-	sensor identification number		
fwd	-	next time sample		
		0 - do not advance to the next time sample after obtaining data		
		0		
		1 - advance to the next time sample after		
		obtaining data		
read_tensor_data	-	routine status (see TABLE 1)		

TABLE 1. Status Codes Returned for **READ_TENSOR_DATA**

STATUS CODE	EXPLANATION OF STATUS
TENSOR_NOT_FOUND	the requested data_key, exten, version combination has no memory
	allocated for processing (user did not call file_open for this combination)
WRONG_HEADER_FORMAT	this module should only be called for single-valued multi-dimensional
	IDFS data
TENSOR_NO_FILES	data and header files have not been opened
TENSOR_READ_ERROR	read error on data file for multi-dimensional IDFS data
PARTIAL_READ	the number of bytes read from the file being accessed did not match the
	number of bytes requested. This code is returned only for the playback
	scenario. The code EOF_STATUS is returned for the real-time scenario.
FILL_HEADER	the header record read is a fill header, indicating that the header record has
	not been received by the workstation at the time of the read from the file.
	This code is returned only for the playback scenario. The code
	EOF_STATUS is returned for the real-time scenario.
TENSOR_HDR_READ_ERROR	read error on header file for multi-dimensional IDFS data
TENSOR_HDR_MALLOC	no memory for header record information for multi-dimensional IDFS data

TENSOR_HDR_KEALLOC no memory for header information expansion for multi-dimensional IDFS data (header increased in size) TENSOR_DATA_MALLOC no memory for sensor data array in the tensor_data structure TENSOR_MODE_MALLOC no memory for instrument mode flags array returned in the tensor_data structure TENSOR_MODE_REALLOC no memory for instrument mode flags array TENSOR_DATA_TDW_LEN only byte-oriented multi-dimensional IDFS data can be defined UPDATE_IDF_NO_FILL a fill value must be specified for multi-dimensional IDFS data UPDATE_IDF_BAD_PADEF pitch angle can not be specified for multi-dimensional IDFS data UPDATE_IDF_BAD_PADEF start of spin data source can not be specified for multi-dimensional IDFS data UPDATE_IDF_BAD_PMI_DEF start of spin data source can not be specified for multi-dimensional IDFS data UPDATE_IDF_BAD_PMI_DEF celestial position angles can not be specified for multi-dimensional IDFS data UPDATE_IDF_BAD_CP_DEF celestial position angles can not be specified for multi-dimensional IDFS data UPDATE_IDF_MANN_BYTES the duata item being requested was not found in the VIDF file UPDATE_IDF_NO_NUM the constant being requested exceeds the number of defined tables UPDATE_IDF_NO_VNM the constant being requested exceeds the number of defined tables UPDATE_IDF_N	STATUS CODE	EXPLANATION OF STATUS	
TENSOR_DATA_MALLOC no memory for sensor data array in the tensor_data structure TENSOR_DATA_REALLOC no memory for sensor data array expansion in the tensor_data structure TENSOR_MODE_MALLOC no memory for sensor data array expansion in the tensor_data structure TENSOR_MODE_REALLOC no memory for expansion of instrument mode flags array TENSOR_DATA_TDW_LEN only byte-oriented multi-dimensional IDFS data UPDATE_IDF_BAD_PA_DEF pitch angle can not be specified for multi-dimensional IDFS data UPDATE_IDF_BAD_PA_DEF spacecraft potential data can not be specified for multi-dimensional IDFS data UPDATE_IDF_BAD_PMI_DEF start of spin data source can not be specified for multi-dimensional IDFS data UPDATE_IDF_BAD_PMI_DEF euler angle can not be specified for multi-dimensional IDFS data UPDATE_IDF_BAD_CP_DEF celestial position angles can not be specified for multi-dimensional IDFS data UPDATE_IDF_ELE_NOT_FOUND the data item being requested was not found in the VIDF file UPDATE_IDF_MANY_BYTES the number of elements being requested sceeds the number of defined constants UPDATE_IDF_NO_NUM the table being requested exceeds the number of defined constants UPDATE_IDF_NO_NUM the table being requested exceeds the number of defined constants UPDATE_IDF_NO_NUM the consta	TENSOR_HDR_REALLOC	no memory for header information expansion for multi-dimensional IDFS	
TENSOR_DATA_REALLOC no memory for sensor data array expansion in the tensor_data structure TENSOR_MODE_MALLOC no memory for instrument mode flags array returned in the tensor_data structure TENSOR_MODE_REALLOC no memory for expansion of instrument mode flags array TENSOR_DATA_TDW_LEN only byte-oriented multi-dimensional IDFS data can be defined UPDATE_IDF_BAD_POT_DEF spaccarfa potential data can not be specified for multi-dimensional IDFS data UPDATE_IDF_BAD_POT_DEF start of spin data source can not be specified for multi-dimensional IDFS data UPDATE_IDF_BAD_SPIN_DEF start of spin data source can not be specified for multi-dimensional IDFS data UPDATE_IDF_BAD_BKG_DEF background data can not be specified for multi-dimensional IDFS data UPDATE_IDF_BAD_RAD_YBTS celestial position angles can not be specified for multi-dimensional IDFS data UPDATE_IDF_MANY_BYTES the number of elements being requested is more than the number of elements valiable for the selected field UPDATE_IDF_NO_NNUM the constant being requested exceeds the number of defined constants UPDATE_IDF_NO_ENTRY the field being requested seceds the number of defined constants UPDATE_IDF_NO_QALLOC no memory for expansion of data quality values in the tensor_data structure TENSOR_DQUAL_REALLOC no memory for elements pertinent to multi-dimensi			
TENSOR_MODE_MALLOC no memory for instrument mode flags array returned in the tensor_data structure TENSOR_MODE_REALLOC no memory for expansion of instrument mode flags array TENSOR_DATA_TDW_LEN only byte-oriented multi-dimensional IDFS data can be defined UPDATE_IDF_BAD_PA_DEF pitch angle can not be specified for multi-dimensional IDFS data UPDATE_IDF_BAD_PA_DEF spacecraft potential data can not be specified for multi-dimensional IDFS data UPDATE_IDF_BAD_PMI_DEF cale can not be specified for multi-dimensional IDFS data UPDATE_IDF_BAD_PMI_DEF cale can not be specified for multi-dimensional IDFS data UPDATE_IDF_BAD_CP_DEF calestial position angles can not be specified for multi-dimensional IDFS data UPDATE_IDF_BAD_CP_DEF calestial position angles can not be specified for multi-dimensional IDFS data UPDATE_IDF_BAD_CP_DEF calestial position angles can not be specified for multi-dimensional IDFS data UPDATE_IDF_BAN_WP the data item being requested was not found in the VIDF file UPDATE_IDF_MON_WN the canstant being requested stee number of defined tables UPDATE_IDF_TBL_NUM the table being requested exceeds the number of defined constants UPDATE_IDF_NO_ENTRY the field being requested exceeds the number of defined constants UPDATE_IDF_MO_LEXANT_XANCON no memory for cata quality tensor does not match t	TENSOR_DATA_MALLOC	no memory for sensor data array in the tensor_data structure	
structure TENSOR_MODE_REALLOC no memory for expansion of instrument mode flags array TENSOR_DATA_TDW_LEN only byte-oriented multi-dimensional IDFS data can be defined UPDATE_IDF_NO_FILL a fill value must be specified for multi-dimensional IDFS data UPDATE_IDF_BAD_PA_DEF pitch angle can not be specified for multi-dimensional IDFS data UPDATE_IDF_BAD_PAD_DEF start of spin data source can not be specified for multi-dimensional IDFS data UPDATE_IDF_BAD_BKGD_DEF euler angle can not be specified for multi-dimensional IDFS data UPDATE_IDF_BAD_BKGD_DEF euler angle can not be specified for multi-dimensional IDFS data UPDATE_IDF_BAD_BKGD_DEF celestial position angles can not be specified for multi-dimensional IDFS data UPDATE_IDF_BAD_BKGD_DEF celestial position angles can not be specified for multi-dimensional IDFS data UPDATE_IDF_BAD_BKGD_DEF celestial position angles can not be specified for multi-dimensional IDFS data UPDATE_IDF_MANY_BYTES the number of elements being requested was not found in the VIDF file UPDATE_IDF_MO_NUM the table being requested is not defined UPDATE_IDF_NO_ENTRY the field being requested is not defined UPDATE_IDF_NO_ENTRY the field elexing requested is not defined HDR_FMT_TWO_MALLOC no memory	TENSOR_DATA_REALLOC	no memory for sensor data array expansion in the tensor_data structure	
TENSOR_MODE_REALLOC no memory for expansion of instrument mode flags array TENSOR_DATA_TDW_LEN only byte-oriented multi-dimensional IDFS data can be defined UPDATE_IDF_NO_FILL a fill value must be specified for multi-dimensional IDFS data UPDATE_IDF_BAD_PA_DEF pitch angle can not be specified for multi-dimensional IDFS data UPDATE_IDF_BAD_POT_DEF start of spin data source can not be specified for multi-dimensional IDFS data UPDATE_IDF_BAD_PMI_DEF euler angle can not be specified for multi-dimensional IDFS data UPDATE_IDF_BAD_PMI_DEF celestial position angles can not be specified for multi-dimensional IDFS data UPDATE_IDF_BAD_CP_DEF celestial position angles can not be specified for multi-dimensional IDFS data UPDATE_IDF_ELE_NOT_FOUND the data item being requested was not found in the VIDF file UPDATE_IDF_TBL_NUM the table being requested exceeds the number of defined tables UPDATE_IDF_ON_ENTRY the field being requested is not defined tables UPDATE_IDF_ON_OALLOC no memory for elements pertinent to multi-dimensional IDFS definition HDR_FMT_TWO_DQUAL the field being requested sensor does not match the size of the multi-dimensional IDFS data structure TENSOR_DQUAL_MALLOC no memory for critical action information LESS_EULER_CONSTANT_ANGLES the number of euler angles defined in the VIDF file	TENSOR_MODE_MALLOC	no memory for instrument mode flags array returned in the tensor_data	
TENSOR_DATA_TDW_LEN only byte-oriented multi-dimensional IDFS data can be defined UPDATE_IDF_NO_FILL a fill value must be specified for multi-dimensional IDFS data UPDATE_IDF_BAD_PA_DEF pitch angle can not be specified for multi-dimensional IDFS data UPDATE_IDF_BAD_SPIN_DEF start of spin data source can not be specified for multi-dimensional IDFS data UPDATE_IDF_BAD_MI_DEF euler angle can not be specified for multi-dimensional IDFS data UPDATE_IDF_BAD_RKGD_DEF background data can not be specified for multi-dimensional IDFS data UPDATE_IDF_BAD_RKGD_DEF celestial position angles can not be specified for multi-dimensional IDFS data UPDATE_IDF_BAD_RKGD_DEF celestial position angles can not be specified for multi-dimensional IDFS data UPDATE_IDF_BAD_NATY_BYTES the number of elements being requested was not found in the VIDF file UPDATE_IDF_TBL_NUM the constant being requested exceeds the number of defined constants UPDATE_IDF_NO_ENTRY the field being requested exceeds the number of defined constants UPDATE_IDF_NO_DQUAL the size of the data quality tensor does not match the size of the multi-dimensional IDFS data set TENSOR_DQUAL_MALLOC no memory for cat quality values in the tensor_data structure TENSOR_DQUAL_REALLOC no memory for cat quality values in the tensor_data structure TENSOR_DQUAL_REALLOC <td< td=""><td></td><td>structure</td></td<>		structure	
UPDATE_IDF_BAD_PA_DEF a fill value must be specified for multi-dimensional IDFS data UPDATE_IDF_BAD_PA_DEF pitch angle can not be specified for multi-dimensional IDFS data UPDATE_IDF_BAD_POT_DEF spacceraft potential data can not be specified for multi-dimensional IDFS data UPDATE_IDF_BAD_PMI_DEF start of spin data source can not be specified for multi-dimensional IDFS data UPDATE_IDF_BAD_PMI_DEF celer angle can not be specified for multi-dimensional IDFS data UPDATE_IDF_BAD_CP_DEF celestial position angles can not be specified for multi-dimensional IDFS data UPDATE_IDF_BAD_CP_DEF celestial position angles can not be specified for multi-dimensional IDFS data UPDATE_IDF_BAD_PT_OUND the data item being requested was not found in the VIDF file UPDATE_IDF_MANY_BYTES the number of elements being requested is more than the number of elements available for the selected field UPDATE_IDF_ON_NUM the constant being requested exceeds the number of defined constants UPDATE_IDF_MO_ENTRY the field being requested exceeds the number of defined constants UPDATE_IDF_MO_DALLOC no memory for data quality tensor does not match the size of the multi-dimensional IDFS data set TENSOR_DQUAL_KEALLOC no memory for centical action information LESS_EULER_CONSTANT_ANGLES the number of euler angles defined in the VIDF file is less than the number of euler angles defined in	TENSOR_MODE_REALLOC	no memory for expansion of instrument mode flags array	
UPDATE_IDF_BAD_PA_DEF pitch angle can not be specified for multi-dimensional IDFS data UPDATE_IDF_BAD_POT_DEF spacecraft potential data can not be specified for multi-dimensional IDFS data UPDATE_IDF_BAD_SPIN_DEF start of spin data source can not be specified for multi-dimensional IDFS data UPDATE_IDF_BAD_PMI_DEF euler angle can not be specified for multi-dimensional IDFS data UPDATE_IDF_BAD_CP_DEF euler angle can not be specified for multi-dimensional IDFS data UPDATE_IDF_BAD_CP_DEF celestial position angles can not be specified for multi-dimensional IDFS data UPDATE_IDF_ELE_NOT_FOUND the data item being requested was not found in the VIDF file UPDATE_IDF_TBL_NUM the table being requested field UPDATE_IDF_TON_MUM the constant being requested exceeds the number of defined tables UPDATE_IDF_NO_ENTRY the field being requested exceeds the number of defined constants UPDATE_IDF_NO_ALLOC no memory for elements pertinent to multi-dimensional IDFS definition HDR_FMT_TWO_DQUAL the size of the data quality tensor does not match the size of the multi-dimensional IDFS data set TENSOR_DQUAL_MALLOC no memory for chata quality values returned in the tensor_data structure TENSOR_DQUAL_REALLOC no memory for critical action information LESS_EULER_CONSTANT_ANGLES <t< td=""><td>TENSOR_DATA_TDW_LEN</td><td></td></t<>	TENSOR_DATA_TDW_LEN		
UPDATE_IDF_BAD_POT_DEF spacecraft potential data can not be specified for multi-dimensional IDFS data UPDATE_IDF_BAD_SPIN_DEF start of spin data source can not be specified for multi-dimensional IDFS data UPDATE_IDF_BAD_MI_DEF euler angle can not be specified for multi-dimensional IDFS data UPDATE_IDF_BAD_CP_DEF background data can not be specified for multi-dimensional IDFS data UPDATE_IDF_BAD_CP_DEF celestial position angles can not be specified for multi-dimensional IDFS data UPDATE_IDF_ELE_NOT_FOUND the data item being requested was not found in the VIDF file UPDATE_IDF_TBL_NUM the data item being requested is more than the number of elements available for the selected field UPDATE_IDF_NO_ENTRY the field being requested exceeds the number of defined constants UPDATE_IDF_NO_ENTRY the field being requested avceeds the number of defined constants UPDATE_TWO_DQUAL the size of the data quality tensor does not match the size of the multi-dimensional IDFS data set TENSOR_DQUAL_MALLOC no memory for critical action information LESS_EULER_CONSTANT_ANGLES the number of euler angles defined in the VIDF file is less than the number of euler angles defined in the VIDF file MORE_EULER_CONSTANT_ANGLES the number of euler angles defined in the VIDF file MORE_EULER_CONSTANT_ANGLES the number of euler angles de	UPDATE_IDF_NO_FILL	a fill value must be specified for multi-dimensional IDFS data	
dataUPDATE_IDF_BAD_SPIN_DEFstart of spin data source can not be specified for multi-dimensional IDFS dataUPDATE_IDF_BAD_PMI_DEFeuler angle can not be specified for multi-dimensional IDFS dataUPDATE_IDF_BAD_CP_DEFbackground data can not be specified for multi-dimensional IDFS dataUPDATE_IDF_ELE_NOT_FOUNDthe data item being requested was not found in the VIDF fileUPDATE_IDF_TBL_NUMthe data item being requested is more than the number of elements available for the selected fieldUPDATE_IDF_NO_ENTYthe field being requested exceeds the number of defined tablesUPDATE_IDF_NO_ENTYthe field being requested exceeds the number of defined constantsUPDATE_IDF_NO_ENTYthe field being requested exceeds the number of defined constantsUPDATE_IDF_NO_ENTYthe field being requested is not definedHDR_FMT_TWO_MAILOCno memory for elements pertinent to multi-dimensional IDFS definitionHDR_FMT_TWO_QUALno memory for data quality values returned in the tensor_datatrensor_DQUAL_REALLOCno memory for data quality values in the tensor_datatressthe number of euler angles constants defined in the VIDF fileLESS_EULER_CONSTANT_ANGLESthe number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_ANGLESthe number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_ANGLESthe number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_ANGLESthe number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_ANGLESthe number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_ANGLESthe number	UPDATE_IDF_BAD_PA_DEF	pitch angle can not be specified for multi-dimensional IDFS data	
UPDATE_IDF_BAD_SPIN_DEF start of spin data source can not be specified for multi-dimensional IDFS data UPDATE_IDF_BAD_PMI_DEF euler angle can not be specified for multi-dimensional IDFS data UPDATE_IDF_BAD_CP_DEF background data can not be specified for multi-dimensional IDFS data UPDATE_IDF_BAD_CP_DEF celestial position angles can not be specified for multi-dimensional IDFS data UPDATE_IDF_ELE_NOT_FOUND the data item being requested was not found in the VIDF file UPDATE_IDF_TBL_NUM the table being requested caceds the number of defined tables UPDATE_IDF_ON_ENTRY the field being requested exceeds the number of defined constants UPDATE_IDF_MO_ENTRY the field being requested exceeds the number of defined constants UPDATE_IDF_OQ_DUAL the size of the data quality tensor does not match the size of the multi-dimensional IDFS data set TENSOR_DQUAL_REALLOC no memory for celenants defined in the VIDF file is less than the number of euler angles constants defined in the VIDF file is less than the number of euler angles defined in the VIDF file is less than the number of euler angles defined in the VIDF file MORE_EULER_CONSTANT_ANGLES the number of euler angles defined in the VIDF file MORE_EULER_CONSTANT_ANGLES the number of euler angles defined in the VIDF file MORE_EULER_CONSTANT_ANGLES the number of euler angles defined in the VIDF file	UPDATE_IDF_BAD_POT_DEF	spacecraft potential data can not be specified for multi-dimensional IDFS	
dataUPDATE_IDF_BAD_PMI_DEFculer angle can not be specified for multi-dimensional IDFS dataUPDATE_IDF_BAD_RKGD_DEFbackground data can not be specified for multi-dimensional IDFS dataUPDATE_IDF_BAD_CP_DEFcelestial position angles can not be specified for multi-dimensional IDFS dataUPDATE_IDF_ELE_NOT_FOUNDthe data item being requested was not found in the VIDF fileUPDATE_IDF_MANY_BYTESthe number of elements being requested is more than the number of elements available for the selected fieldUPDATE_IDF_TBL_NUMthe table being requested exceeds the number of defined tablesUPDATE_IDF_NO_ENTRYthe field being requested exceeds the number of defined constantsUPDATE_IDF_NO_ENTRYthe field being requested is not definedHDR_FMT_TWO_MALLOCno memory for elements pertinent to multi-dimensional IDFS definitionHDR_FMT_TWO_DQUALno memory for data quality values returned in the tensor_data structureTENSOR_DQUAL_MALLOCno memory for critical action informationLESS_EULER_CONSTANT_ANGLESthe number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_ANGLESthe number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_ANGLESthe number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_ANGLESthe number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_ANGLESthe number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_ANGLESthe number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_ANGLESthe number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_AXIS<			
UPDATE_IDF_BAD_PMI_DEF euler angle can not be specified for multi-dimensional IDFS data UPDATE_IDF_BAD_BKGD_DEF background data can not be specified for multi-dimensional IDFS data UPDATE_IDF_BAD_CP_DEF celestial position angles can not be specified for multi-dimensional IDFS data UPDATE_IDF_ELE_NOT_FOUND the data item being requested was not found in the VIDF file UPDATE_IDF_TBL_NOT_FOUND the data item being requested is more than the number of elements being requested is more than the number of elements being requested sceeds the number of defined tables UPDATE_IDF_TBL_NUM the table being requested exceeds the number of defined constants UPDATE_IDF_NO_ENTRY the field being requested exceeds the number of defined constants UPDATE_IDF_NO_ENTRY the size of the data quality tensor does not match the size of the multi-dimensional IDFS data set TENSOR_DQUAL_MALLOC no memory for clata set structure CRIT_ACT_MALLOC no memory for critical action information tensor_data structure LESS_EULER_CONSTANT_ANGLES the number of euler angles defined in the VIDF file is structure MORE_EULER_CONSTANT_ANGLES the number of euler angles defined in the VIDF file is less than the number of euler angles defined in the VIDF file is structure used to hold the data being requested sensor MORE_EULER_CONSTANT_AXIS	UPDATE_IDF_BAD_SPIN_DEF	start of spin data source can not be specified for multi-dimensional IDFS	
UPDATE_IDF_BAD_BKGD_DEF background data can not be specified for multi-dimensional IDFS data UPDATE_IDF_BAD_CP_DEF celestial position angles can not be specified for multi-dimensional IDFS data UPDATE_IDF_LEL_NOT_FOUND the data item being requested was not found in the VIDF file UPDATE_IDF_TBL_NUM the table being requested is more than the number of elements available for the selected field UPDATE_IDF_TBL_NUM the table being requested exceeds the number of defined constants UPDATE_IDF_NO_ENTRY the field being requested exceeds the number of defined constants UPDATE_IDF_NO_ENTRY the field being requested is not defined HDR_FMT_TWO_MALLOC no memory for elements pertinent to multi-dimensional IDFS data structure TENSOR_DQUAL_MALLOC no memory for expansion of data quality values in the tensor_data structure TENSOR_DQUAL_REALLOC no memory for critical action information LESS_EULER_CONSTANT_ANGLES the number of culer angle constants defined in the VIDF file is less than the number of euler angles defined in the VIDF file MORE_EULER_CONSTANT_AXIS the number of euler angles defined in the VIDF file is more than the number of euler angles defined in the VIDF file MORE_EULER_CONSTANT_AXIS the number of euler angles defined in the VIDF file is more than the number of euler angles defined in the VIDF file MORE_EULER_CONSTAN			
UPDATE_IDF_BAD_CP_DEF celestial position angles can not be specified for multi-dimensional IDFS data UPDATE_IDF_ELE_NOT_FOUND the data item being requested was not found in the VIDF file UPDATE_IDF_MANY_BYTES the number of elements being requested is more than the number of elements available for the selected field UPDATE_IDF_TBL_NUM the table being requested exceeds the number of defined tables UPDATE_IDF_NO_ENTRY the field being requested exceeds the number of defined constants UPDATE_IDF_NO_ENTRY the field being requested is not defined HDR_FMT_TWO_MALLOC no memory for elements pertinent to multi-dimensional IDFS definition HDR_FMT_TWO_DQUAL the size of the data quality values returned in the tensor_data structure TENSOR_DQUAL_MALLOC no memory for expansion of data quality values in the tensor_data structure CRIT_ACT_MALLOC no memory for critical action information LESS_EULER_CONSTANT_ANGLES the number of euler angles defined in the VIDF file MORE_EULER_CONSTANT_AXIS the number of euler angles defined in the VIDF file is less than the number of euler angles defined in the VIDF file MORE_EULER_CONSTANT_AXIS the number of euler angles defined in the VIDF file is more than the number of euler angles defined in the VIDF file MORE_EULER_CONSTANT_AXIS the number of euler angles defined in the VI			
dataUPDATE_IDF_ELE_NOT_FOUNDthe data item being requested was not found in the VIDF fileUPDATE_IDF_MANY_BYTESthe number of elements being requested is more than the number of elements available for the selected fieldUPDATE_IDF_TBL_NUMthe table being requested exceeds the number of defined tablesUPDATE_IDF_TON_ENTRYthe field being requested exceeds the number of defined constantsUPDATE_IDF_NO_ENTRYthe field being requested is not definedHDR_FMT_TWO_MALLOCno memory for elements pertinent to multi-dimensional IDFS definitionHDR_FMT_TWO_DQUALthe size of the data quality values returned in the tensor_data structureTENSOR_DQUAL_MALLOCno memory for expansion of data quality values in the tensor_dataCRIT_ACT_MALLOCno memory for critical action informationLESS_EULER_CONSTANT_ANGLESthe number of euler angle constants defined in the VIDF fileLESS_EULER_CONSTANT_ANGLESthe number of euler angles defined in the VIDF file is less than the number of euler angles defined in the VIDF file is more than the number of euler angles defined in the VIDF file is more than the number of euler angles defined in the VIDF file is more than the number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_AXISthe number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_AXISthe number of euler angles defined in the VIDF file is more than the number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_AXISthe number of euler angles defined in the VIDF file is more than the number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_AXISthe number of euler angles defined in the			
UPDATE_IDF_ELE_NOT_FOUND the data item being requested was not found in the VIDF file UPDATE_IDF_MANY_BYTES the number of elements being requested is more than the number of elements available for the selected field UPDATE_IDF_TBL_NUM the table being requested exceeds the number of defined tables UPDATE_IDF_CON_NUM the constant being requested exceeds the number of defined constants UPDATE_IDF_NO_ENTRY the field being requested is not defined HDR_FMT_TWO_MALLOC no memory for elements pertinent to multi-dimensional IDFS definition HDR_FMT_TWO_DQUAL the size of the data quality values returned in the tensor_data structure TENSOR_DQUAL_MALLOC no memory for expansion of data quality values in the tensor_data structure TENSOR_DQUAL_REALLOC no memory for cluer angle constants defined in the VIDF file is less than the number of euler angles defined in the VIDF file LESS_EULER_CONSTANT_ANGLES the number of euler angles defined in the VIDF file is less than the number of euler angles defined in the VIDF file is more than the number of euler angles defined in the VIDF file MORE_EULER_CONSTANT_ANGLES the number of euler angles defined in the VIDF file MORE_EULER_CONSTANT_ANGLES the number of euler angles defined in the VIDF file MORE_EULER_CONSTANT_ANGLES the number of euler angles defined in the VIDF file MORE_EULER_CONSTANT_ANGLES the number of euler	UPDATE_IDF_BAD_CP_DEF		
UPDATE_IDF_MANY_BYTES the number of elements being requested is more than the number of elements available for the selected field UPDATE_IDF_TBL_NUM the table being requested exceeds the number of defined tables UPDATE_IDF_CON_NUM the constant being requested exceeds the number of defined constants UPDATE_IDF_NO_ENTRY the field being requested is not defined HDR_FMT_TWO_MALLOC no memory for elements pertinent to multi-dimensional IDFS definition HDR_FMT_TWO_DQUAL the size of the data quality reasor does not match the size of the multi-dimensional IDFS data set TENSOR_DQUAL_MALLOC no memory for expansion of data quality values in the tensor_data structure CRIT_ACT_MALLOC no memory for critical action information LESS_EULER_CONSTANT_ANGLES the number of euler angle constants defined in the VIDF file LESS_EULER_CONSTANT_ANGLES the number of euler angles defined in the VIDF file MORE_EULER_CONSTANT_ANGLES the number of euler angles defined in the VIDF file MORE_EULER_CONSTANT_ANGLES the number of euler angles defined in the VIDF file MORE_EULER_CONSTANT_ANGLES the number of euler angles defined in the VIDF file MORE_EULER_CONSTANT_AXIS the number of euler angles defined in the VIDF file MORE_EULER_CONSTANT_AXIS the number of euler angles defined in the VIDF file M			
elements available for the selected fieldUPDATE_IDF_TBL_NUMthe table being requested exceeds the number of defined tablesUPDATE_IDF_CON_NUMthe constant being requested exceeds the number of defined constantsUPDATE_IDF_NO_ENTRYthe field being requested is not definedHDR_FMT_TWO_MALLOCno memory for elements pertinent to multi-dimensional IDFS definitionHDR_FMT_TWO_DQUALthe size of the data quality tensor does not match the size of the multi-dimensional IDFS data setTENSOR_DQUAL_MALLOCno memory for data quality values returned in the tensor_data structureTENSOR_DQUAL_REALLOCno memory for expansion of data quality values in the tensor_data structureCRIT_ACT_MALLOCno memory for critical action informationLESS_EULER_CONSTANT_ANGLESthe number of euler angle constants defined in the VIDF file is less than the number of euler angles defined in the VIDF fileLESS_EULER_CONSTANT_ANGLESthe number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_ANGLESthe number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_ANGLESthe number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_ANGLESthe number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_AXISthe number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_AXISthe number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_AXISthe number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_AXISthe number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_AXISthe number of euler angles defined in the VIDF file<			
UPDATE_IDF_TBL_NUMthe table being requested exceeds the number of defined tablesUPDATE_IDF_CON_NUMthe constant being requested exceeds the number of defined constantsUPDATE_IDF_NO_ENTRYthe field being requested is not definedHDR_FMT_TWO_MALLOCno memory for elements pertinent to multi-dimensional IDFS definitionHDR_FMT_TWO_DQUALthe size of the data quality tensor does not match the size of the multi-dimensional IDFS data setTENSOR_DQUAL_MALLOCno memory for data quality values returned in the tensor_data structureTENSOR_DQUAL_REALLOCno memory for critical action informationthe size of the query of euler angles constants defined in the VIDF file is less than the number of euler angles defined in the VIDF fileLESS_EULER_CONSTANT_ANGLESthe number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_ANGLESthe number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_AXISthe number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_AXISthe number of euler angles defined in the VIDF fileWRONG_DATA_STRUCTUREincompatibility between IDFS data set and IDFS data structure used to hold the data being returnedTENSOR_EOF_NO_SENSORno data found for the requested sensorTENSOR_EOF_SENSORno data found for the requested sensor – eof on forward (real-time scenario only)	UPDATE_IDF_MANY_BYTES		
UPDATE_IDF_CON_NUMthe constant being requested exceeds the number of defined constantsUPDATE_IDF_NO_ENTRYthe field being requested is not definedHDR_FMT_TWO_MALLOCno memory for elements pertinent to multi-dimensional IDFS definitionHDR_FMT_TWO_DQUALthe size of the data quality tensor does not match the size of the multi-dimensional IDFS data setTENSOR_DQUAL_MALLOCno memory for data quality values returned in the tensor_data structureTENSOR_DQUAL_REALLOCno memory for critical action informationLESS_EULER_CONSTANT_ANGLESthe number of euler angles constants defined in the VIDF file is less than the number of euler angles defined in the VIDF fileLESS_EULER_CONSTANT_AXISthe number of euler angles constants defined in the VIDF file is more than the number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_AXISthe number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_AXISthe number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_AXISthe number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_AXISthe number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_AXISthe number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_AXISincompatibility between IDFS data set and IDFS data structure used to hold the data being returnedTENSOR_NO_SENSORno data found for the requested sensorTENSOR_EOF_NO_SENSORno multi-dimensional IDFS data found for the requested sensor - eof on forward (real-time scenario only)TENSOR_EOF_SENSORmulti-dimensional IDFS data found for the requested sensor - eof on forward (real-time scenario o			
UPDATE_IDF_NO_ENTRYthe field being requested is not definedHDR_FMT_TWO_MALLOCno memory for elements pertinent to multi-dimensional IDFS definitionHDR_FMT_TWO_DQUALthe size of the data quality tensor does not match the size of the multi-dimensional IDFS data setTENSOR_DQUAL_MALLOCno memory for data quality values returned in the tensor_data structureTENSOR_DQUAL_REALLOCno memory for critical action informationCRIT_ACT_MALLOCno memory for critical action informationLESS_EULER_CONSTANT_ANGLESthe number of euler angles defined in the VIDF fileLESS_EULER_CONSTANT_ANGLESthe number of euler rotation axis constants defined in the VIDF file is lessMORE_EULER_CONSTANT_ANGLESthe number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_ANGLESthe number of euler angles defined in the VIDF file is lessMORE_EULER_CONSTANT_ANGLESthe number of euler angles defined in the VIDF file is lessMORE_EULER_CONSTANT_ANGLESthe number of euler angles defined in the VIDF file is in orre than the number of euler angles defined in the VIDF file isMORE_EULER_CONSTANT_ANGLESthe number of euler angles defined in the VIDF file isMORE_EULER_CONSTANT_AXISthe number of euler notation axis constants defined in the VIDF file isMORG_DATA_STRUCTUREincompatibility between IDFS data set and IDFS data structure used to hold the data being returnedTENSOR_NO_SENSORno data found for the requested sensor – eof on forward (real-time scenario only)TENSOR_EOF_SENSORno duat found for the requested sensor – eof on forward (real-time scenario only)			
HDR_FMT_TWO_MALLOCno memory for elements pertinent to multi-dimensional IDFS definitionHDR_FMT_TWO_DQUALthe size of the data quality tensor does not match the size of the multi-dimensional IDFS data setTENSOR_DQUAL_MALLOCno memory for data quality values returned in the tensor_data structureTENSOR_DQUAL_REALLOCno memory for expansion of data quality values in the tensor_dataCRIT_ACT_MALLOCno memory for critical action informationLESS_EULER_CONSTANT_ANGLESthe number of euler angle constants defined in the VIDF fileLESS_EULER_CONSTANT_AXISthe number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_ANGLESthe number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_AXISthe number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_AXISthe number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_AXISthe number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_AXISthe number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_AXISthe number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_AXISthe number of euler angles defined in the VIDF fileMONG_DATA_STRUCTUREincompatibility between IDFS data set and IDFS data structure used to hold the data being returnedTENSOR_EOF_NO_SENSORno data found for the requested sensor – eof on forward (real-time scenario only)TENSOR_EOF_SENSORmulti-dimensional IDFS data found for the requested sensor – eof on forward (real-time scenario only)			
HDR_FMT_TWO_DQUALthe size of the data quality tensor does not match the size of the multi- dimensional IDFS data setTENSOR_DQUAL_MALLOCno memory for data quality values returned in the tensor_data structureTENSOR_DQUAL_REALLOCno memory for expansion of data quality values in the tensor_data structureCRIT_ACT_MALLOCno memory for critical action informationLESS_EULER_CONSTANT_ANGLESthe number of euler angles constants defined in the VIDF fileLESS_EULER_CONSTANT_ANGLESthe number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_ANGLESthe number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_AXISthe number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_AXISthe number of euler rotation axis constants defined in the VIDF fileMORE_EULER_CONSTANT_AXISthe number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_AXISthe number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_AXISthe number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_AXISthe number of euler angles defined in the VIDF fileMORG_DATA_STRUCTUREincompatibility between IDFS data set and IDFS data structure used to hold the data being returnedTENSOR_NO_SENSORno data found for the requested sensor - eof on forward (real-time scenario only)TENSOR_EOF_SENSORmulti-dimensional IDFS data found for the requested sensor - eof on forward (real-time scenario only)			
dimensional IDFS data setTENSOR_DQUAL_MALLOCno memory for data quality values returned in the tensor_data structureTENSOR_DQUAL_REALLOCno memory for expansion of data quality values in the tensor_data structureCRIT_ACT_MALLOCno memory for critical action informationLESS_EULER_CONSTANT_ANGLESthe number of euler angle constants defined in the VIDF file is less than the number of euler angles defined in the VIDF fileLESS_EULER_CONSTANT_AXISthe number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_ANGLESthe number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_ANGLESthe number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_ANGLESthe number of euler angles defined in the VIDF file is more than the number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_ANGLESthe number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_AXISthe number of euler angles defined in the VIDF file is more than the number of euler angles defined in the VIDF fileWRONG_DATA_STRUCTUREincompatibility between IDFS data set and IDFS data structure used to hold the data being returnedTENSOR_EOF_NO_SENSORno data found for the requested sensor - eof on forward (real-time scenario only)TENSOR_EOF_SENSORmulti-dimensional IDFS data found for the requested sensor - eof on forward (real-time scenario only)			
TENSOR_DQUAL_MALLOCno memory for data quality values returned in the tensor_data structureTENSOR_DQUAL_REALLOCno memory for expansion of data quality values in the tensor_data structureCRIT_ACT_MALLOCno memory for critical action informationLESS_EULER_CONSTANT_ANGLESthe number of euler angle constants defined in the VIDF file is less than the number of euler angles defined in the VIDF fileLESS_EULER_CONSTANT_AXISthe number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_ANGLESthe number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_ANGLESthe number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_ANGLESthe number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_ANGLESthe number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_ANGLESthe number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_ANGLESthe number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_AXISthe number of euler rotation axis constants defined in the VIDF fileMORE_DATA_STRUCTUREincompatibility between IDFS data set and IDFS data structure used to hold the data being returnedTENSOR_NO_SENSORno data found for the requested sensorTENSOR_EOF_NO_SENSORmoulti-dimensional IDFS data found for the requested sensor – eof on forward (real-time scenario only)TENSOR_EOF_SENSORmulti-dimensional IDFS data found for the requested sensor – eof on forward (real-time scenario only)	HDR_FMT_TWO_DQUAL		
TENSOR_DQUAL_REALLOCno memory for expansion of data quality values in the tensor_data structureCRIT_ACT_MALLOCno memory for critical action informationLESS_EULER_CONSTANT_ANGLESthe number of euler angle constants defined in the VIDF file is less than the number of euler angles defined in the VIDF fileLESS_EULER_CONSTANT_AXISthe number of euler rotation axis constants defined in the VIDF fileMORE_EULER_CONSTANT_ANGLESthe number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_ANGLESthe number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_ANGLESthe number of euler angles defined in the VIDF file is more than the number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_ANGLESthe number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_AXISthe number of euler rotation axis constants defined in the VIDF fileMORE_EULER_CONSTANT_AXISthe number of euler rotation axis constants defined in the VIDF fileMORE_EULER_CONSTANT_AXISthe number of euler rotation axis constants defined in the VIDF fileMORE_EULER_CONSTANT_AXISthe number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_AXISno data found for the requested sensorTENSOR_NO_SENSORno data found for the requested sensorTENSOR_EOF_NO_SENSORno multi-dimensional IDFS data found for the requested sensor – eof on forward (real-time scenario only)TENSOR_EOF_SENSORmulti-dimensional IDFS data found for the requested sensor – eof on forward (real-time scenario only)			
structureCRIT_ACT_MALLOCno memory for critical action informationLESS_EULER_CONSTANT_ANGLESthe number of euler angle constants defined in the VIDF file is less than the number of euler angles defined in the VIDF fileLESS_EULER_CONSTANT_AXISthe number of euler rotation axis constants defined in the VIDF fileMORE_EULER_CONSTANT_ANGLESthe number of euler angles defined in the VIDF file is more than the number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_ANGLESthe number of euler angle constants defined in the VIDF fileMORE_EULER_CONSTANT_AXISthe number of euler angles defined in the VIDF fileMORE_DATA_STRUCTUREincompatibility between IDFS data set and IDFS data structure used to hold the data being returnedTENSOR_NO_SENSORno data found for the requested sensor – eof on forward (real-time scenario only)TENSOR_EOF_SENSORmulti-dimensional IDFS data found for the requested sensor – eof on forward (real-time scenario only)			
CRIT_ACT_MALLOCno memory for critical action informationLESS_EULER_CONSTANT_ANGLESthe number of euler angle constants defined in the VIDF file is less than the number of euler angles defined in the VIDF fileLESS_EULER_CONSTANT_AXISthe number of euler rotation axis constants defined in the VIDF fileMORE_EULER_CONSTANT_ANGLESthe number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_ANGLESthe number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_AXISthe number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_AXISthe number of euler rotation axis constants defined in the VIDF fileMORE_DATA_STRUCTUREincompatibility between IDFS data set and IDFS data structure used to hold the data being returnedTENSOR_NO_SENSORno data found for the requested sensorTENSOR_EOF_NO_SENSORno multi-dimensional IDFS data found for the requested sensor – eof on forward (real-time scenario only)TENSOR_EOF_SENSORmulti-dimensional IDFS data found for the requested sensor – eof on forward (real-time scenario only)	TENSOR_DQUAL_REALLOC		
LESS_EULER_CONSTANT_ANGLESthe number of euler angle constants defined in the VIDF file is less than the number of euler angles defined in the VIDF fileLESS_EULER_CONSTANT_AXISthe number of euler rotation axis constants defined in the VIDF fileMORE_EULER_CONSTANT_ANGLESthe number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_ANGLESthe number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_AXISthe number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_AXISthe number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_AXISthe number of euler rotation axis constants defined in the VIDF fileMORE_DATA_STRUCTUREincompatibility between IDFS data set and IDFS data structure used to hold the data being returnedTENSOR_NO_SENSORno data found for the requested sensorTENSOR_EOF_NO_SENSORno multi-dimensional IDFS data found for the requested sensor – eof on forward (real-time scenario only)TENSOR_EOF_SENSORmulti-dimensional IDFS data found for the requested sensor – eof on forward (real-time scenario only)			
Image: constant of euler angles defined in the VIDF fileLESS_EULER_CONSTANT_AXISthe number of euler rotation axis constants defined in the VIDF file is less than the number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_ANGLESthe number of euler angle constants defined in the VIDF file is more than the number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_AXISthe number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_AXISthe number of euler rotation axis constants defined in the VIDF file is more than the number of euler angles defined in the VIDF fileWRONG_DATA_STRUCTUREincompatibility between IDFS data set and IDFS data structure used to hold the data being returnedTENSOR_NO_SENSORno data found for the requested sensor forward (real-time scenario only)TENSOR_EOF_SENSORmulti-dimensional IDFS data found for the requested sensor – eof on forward (real-time scenario only)			
LESS_EULER_CONSTANT_AXISthe number of euler rotation axis constants defined in the VIDF file is less than the number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_ANGLESthe number of euler angle constants defined in the VIDF file is more than the number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_AXISthe number of euler rotation axis constants defined in the VIDF fileMORE_EULER_CONSTANT_AXISthe number of euler rotation axis constants defined in the VIDF fileMORE_DATA_STRUCTUREincompatibility between IDFS data set and IDFS data structure used to hold the data being returnedTENSOR_NO_SENSORno data found for the requested sensor forward (real-time scenario only)TENSOR_EOF_SENSORmulti-dimensional IDFS data found for the requested sensor – eof on forward (real-time scenario only)	LESS_EULER_CONSTAINT_ANGLES		
Image: Constraint of the number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_ANGLESthe number of euler angle constants defined in the VIDF file is more than the number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_AXISthe number of euler rotation axis constants defined in the VIDF file is more than the number of euler angles defined in the VIDF fileWRONG_DATA_STRUCTUREincompatibility between IDFS data set and IDFS data structure used to hold the data being returnedTENSOR_NO_SENSORno data found for the requested sensor forward (real-time scenario only)TENSOR_EOF_SENSORmulti-dimensional IDFS data found for the requested sensor – eof on forward (real-time scenario only)	LESS ELLED CONSTANT AVIS		
MORE_EULER_CONSTANT_ANGLESthe number of euler angle constants defined in the VIDF file is more than the number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_AXISthe number of euler rotation axis constants defined in the VIDF file is more than the number of euler angles defined in the VIDF fileWRONG_DATA_STRUCTUREincompatibility between IDFS data set and IDFS data structure used to hold the data being returnedTENSOR_NO_SENSORno data found for the requested sensorTENSOR_EOF_NO_SENSORno multi-dimensional IDFS data found for the requested sensor – eof on forward (real-time scenario only)TENSOR_EOF_SENSORmulti-dimensional IDFS data found for the requested sensor – eof on forward (real-time scenario only)	LESS_EULER_CONSTAINT_AAIS		
the number of euler angles defined in the VIDF fileMORE_EULER_CONSTANT_AXISthe number of euler rotation axis constants defined in the VIDF file is more than the number of euler angles defined in the VIDF fileWRONG_DATA_STRUCTUREincompatibility between IDFS data set and IDFS data structure used to hold the data being returnedTENSOR_NO_SENSORno data found for the requested sensorTENSOR_EOF_NO_SENSORno multi-dimensional IDFS data found for the requested sensor – eof on forward (real-time scenario only)TENSOR_EOF_SENSORmulti-dimensional IDFS data found for the requested sensor – eof on forward (real-time scenario only)	MODE ELLER CONSTANT ANGLES		
MORE_EULER_CONSTANT_AXISthe number of euler rotation axis constants defined in the VIDF file is more than the number of euler angles defined in the VIDF fileWRONG_DATA_STRUCTUREincompatibility between IDFS data set and IDFS data structure used to hold the data being returnedTENSOR_NO_SENSORno data found for the requested sensorTENSOR_EOF_NO_SENSORno multi-dimensional IDFS data found for the requested sensor – eof on forward (real-time scenario only)TENSOR_EOF_SENSORmulti-dimensional IDFS data found for the requested sensor – eof on forward (real-time scenario only)	MORE_EULER_CONSTANT_ANGLES		
more than the number of euler angles defined in the VIDF fileWRONG_DATA_STRUCTUREincompatibility between IDFS data set and IDFS data structure used to hold the data being returnedTENSOR_NO_SENSORno data found for the requested sensorTENSOR_EOF_NO_SENSORno multi-dimensional IDFS data found for the requested sensor – eof on forward (real-time scenario only)TENSOR_EOF_SENSORmulti-dimensional IDFS data found for the requested sensor – eof on forward (real-time scenario only)	MORE EULER CONSTANT AXIS		
WRONG_DATA_STRUCTURE incompatibility between IDFS data set and IDFS data structure used to hold the data being returned TENSOR_NO_SENSOR no data found for the requested sensor TENSOR_EOF_NO_SENSOR no multi-dimensional IDFS data found for the requested sensor – eof on forward (real-time scenario only) TENSOR_EOF_SENSOR multi-dimensional IDFS data found for the requested sensor – eof on forward (real-time scenario only)			
hold the data being returned TENSOR_NO_SENSOR no data found for the requested sensor TENSOR_EOF_NO_SENSOR no multi-dimensional IDFS data found for the requested sensor – eof on forward (real-time scenario only) TENSOR_EOF_SENSOR multi-dimensional IDFS data found for the requested sensor – eof on forward (real-time scenario only)	WRONG DATA STRUCTURE		
TENSOR_NO_SENSOR no data found for the requested sensor TENSOR_EOF_NO_SENSOR no multi-dimensional IDFS data found for the requested sensor – eof on forward (real-time scenario only) TENSOR_EOF_SENSOR multi-dimensional IDFS data found for the requested sensor – eof on forward (real-time scenario only)			
TENSOR_EOF_NO_SENSOR no multi-dimensional IDFS data found for the requested sensor – eof on forward (real-time scenario only) TENSOR_EOF_SENSOR multi-dimensional IDFS data found for the requested sensor – eof on forward (real-time scenario only)	TENSOR NO SENSOR		
forward (real-time scenario only) TENSOR_EOF_SENSOR multi-dimensional IDFS data found for the requested sensor – eof on forward (real-time scenario only)			
TENSOR_EOF_SENSOR multi-dimensional IDFS data found for the requested sensor – eof on forward (real-time scenario only)			
forward (real-time scenario only)	TENSOR_EOF_SENSOR		
	NEXT_FILE_STATUS		
LOS_STATUS loss of signal encountered			
EOF_STATUS eof encountered on file being accessed (real-time scenario only)			
ALL_OKAY single-valued multi-dimensional IDFS data for requested sensor is			
returned		•	

DESCRIPTION

Read_tensor_data is the multi-dimensional IDFS data read routine used to retrieve singlevalued tensor data for a single sensor. The sensor is indicated through the sensor number (sen). The multi-dimensional IDFS data set of interest is referenced through the key value data_key which can be created using the get_data_key module. The routine returns not only the single-valued multi-dimensional IDFS data for the sensor but also most of the pertinent ancillary data concerning the state of the virtual instrument including time and instrument status (mode) values where applicable. For the time being, multi-dimensional IDFS data can not be dynamically converted to any other physical unit; therefore, the data must be stored in the physical unit desired when the data set is created. However, the read_tensor_data module will return two sets of data within the tensor_data structure. One set represents the raw integer values that are stored within the data record and one set represents the floating point values that result when transferring the raw integer values into the data type defined by d_type in the VIDF file for the IDFS data set being processed.

The returned data is placed in the **tensor_data** structure that is referenced by the argument **tensor_data_ptr**. The argument **tensor_data_ptr** is a pointer to the structure that is to hold all data pertinent to the data set being processed. The structure is created and the address to this structure is returned when a call to the **create_tensor_data_structure**, which determines what type of data structure is needed for the IDFS data set of interest. In most cases, one data structure is sufficient to process any number of distinct single-valued multi-dimensional IDFS data sets. However, if more than one structure is needed, the user may call the **create_tensor_data_structure** routine N times to create N instances of the **tensor_data** structure. The user must keep track of which pointer to send to the IDFS routines that utilize this structure. The contents of this structure is described in section 1S of the IDFS Programmers Manual.

The parameter **version** allows multiple file openings for an IDFS data set. If the data, header and VIDF file for the specified data set need to be opened just once for processing, the same version number should be passed to all IDFS routines. However, for multiple file openings, the version number should be unique and all file manipulations performed by the IDFS routines will use the file descriptors defined for the version number specified. The user should call the **get_version_number** routine to retrieve a unique version number instead of choosing this value themselves. The retrieval of multiple data parameters from a single data source does not constitute the need for multiple version numbers; a single version number will suffice.

If the **file_open** routine is not to open the default set of IDFS files but a modified set of IDFS files, the two character extension applied to these data files must be supplied to this routine within the string variable **exten**. These files must have the identical name as the IDFS files with the two character identification code appended to the end of the file names (i.e. RTLA19922181432Dxx, RTLA19922181432Hxx, RTLA19922181432Ixx). The files must reside either in the directory specified by the environment variable USER_DATA, which is set by the user, or in the user's home directory if the environment variable

USER_DATA is not set. To open the default IDFS data files, **exten** should be set to a null string. The usage of modified data sets is limited to post acquisition data; therefore, it is suggested that the user set **exten** to a null string for real-time scenarios.

After the data has been read, the current data pointer will be either be advanced to the next set of data values or remain at the current set of data values, depending upon the value of the variable **fwd**. By keeping the pointer at the current set of data values, repeated calls using the same virtual instrument but different sensors can be made, ensuring that all of the data returned was taken at the same time. Since the data is placed into the data arrays **before** the current data pointer is advanced, the user should check the status of the element **filled_data** within the **tensor_data** structure if any status code other than **ALL_OKAY** is returned. This flag value will indicate if the data arrays have been filled and this data should be processed before further action is taken in accordance with the status code returned.

There are two sets of time values returned by the **read_tensor_data** routine. Within the **tensor_data** structure, there are the elements **byear**, **bday**, **bmilli**, **bnano**, **eyear**, **eday**, **emilli** and **enano**. These time elements are associated with the data for the requested sensor. The instrument status (mode) values are not sensor-specific, that is, they pertain to all sensors within the data record being processed. Therefore, the time span encompassed by the instrument status values is specified in the elements **mode_byear**, **mode_bday**, **mode_bmilli**, **mode_bnano**, **mode_eyear**, **mode_eday**, **mode_emilli** and **mode_enano** within the **tensor_data** structure.

ERRORS

All errors within this routine are returned through the status variable. The include file **ret_codes.h**, which includes all possible return values, should be included so that the mnemonics for the return codes can be referenced. The **ret_codes.h** file is described in section 1H of the IDFS Programmers Manual.

SEE ALSO

file_open	1R
get_data_key	1R
get_version_number	1R
create_data_structure	1R
create_tensor_data_structure	1R
reset_experiment_info	1R
ret_codes	1H
libbase_idfs	1H
tensor_data	1S

BUGS

None

EXAMPLES

Obtain multi-dimensional IDFS data for sensor 0 from the virtual instrument NPD1BM16, which is part of the NPD instrument, which is part of the ASPERA-3 experiment, which is part of the Mars_Express mission, which is identified with the MARS project. The pointer is moved to the next time sample in the data array after the data is obtained. The data is returned in the **tensor_data** structure referenced by the pointer **tensor_data_ptr**.

```
#include "libbase idfs.h"
#include "ret codes.h"
SDDAS_ULONG data_key;
SDDAS USHORT vnum;
SDDAS_SHORT status;
void *tensor_data_ptr;
status = get_data_key ("MARS", "Mars_Express", "ASPERA-3", "NPD", "NPD1BM16",
                      &data_key);
if (status != ALL OKAY)
{
 printf ("\n Error %d returned by get_data_key routine.\n", status);
 exit (-1);
 ł
get_version_number (&vnum);
status = create tensor data structure (&tensor data ptr);
if (status != ALL OKAY)
{
 printf ("\n Error %d returned by create tensor data structure routine.\n", status);
 exit (-1);
 }
status = read_tensor_data (data_key, "", vnum, tensor_data_ptr, 0, 1);
if (status != ALL OKAY)
{
 printf ("\n Error %d returned by read_tensor_data routine.\n", status);
 exit (-1);
 }
```

READ_IDF

function - retrieve information from the VIDF file for the specified IDFS data set

DESCRIPTION

This module has been moved into a separately maintained library. The user is referred to the webpage <u>http://cluster/libVIDF.html</u> for an explanation of the interface to this module. The IDFS data access software makes use of both the **read_idf** and **ReadVIDF** modules. The examples provided at the beginning of this manual make use of only the **read_idf** module.

read_idf (1R)

RESET_EXPERIMENT_INFO

function - closes the current data files and opens the next set of data files to be processed

SYNOPSIS

#include "libbase_idfs.h"
#include "ret_codes.h"

SDDAS_SHORT	reset_experiment_	_info (SDDAS_	_ULONG data_key,

SDDAS_CHAR *exten, SDDAS_USHORT version,
SDDAS_SHORT btime_yr, SDDAS_SHORT btime_day,
SDDAS_LONG btime_sec, SDDAS_LONG btime_nano,
SDDAS_SHORT etime_yr, SDDAS_SHORT etime_day,
SDDAS_LONG etime_sec, SDDAS_LONG etime_nano)

ARGUMENTS

data_key	-	unique value which indicates the data set of interest
exten	-	two character extension to be added to IDFS file
		names when default files are not to be used, otherwise
		a null string
version	-	IDFS data set identification number which allows for
		multiple openings of the same data set
btime_yr	-	beginning year for data being requested
btime_day	-	beginning day of year for data being requested
btime_sec	-	beginning time of day in seconds for data being
		requested
btime_nano	-	beginning time of day residual in nanoseconds
etime_yr	-	ending year for data being requested
etime_day	-	ending day of year for data being requested
etime_sec	-	ending time of day in seconds for data being requested
etime_nano	-	ending time of day residual in nanoseconds
reset_experiment_info	_	routine status (see TABLE 1)
reset_enperment_me		

TABLE 1. Status Codes Returned for RESET_EXPERIMENT_INFO

STATUS CODE	EXPLANATION OF STATUS
RESET_NOT_FOUND	the requested data_key, exten, version combination has no memory allocated
	for processing (user did not call file_open for this combination)
	Error codes returned by file_open ()
ALL_OKAY	all data files opened

In addition to the status codes listed above, other error/status codes may be returned in the case of a database request. The user is referred to the webpage <u>http://cluster/libdbSQL.html</u> for an explanation of the interface to the database which is used by the IDFS data access software. The write-up for the modules dbIDFSGetRealTimeFile and dbIDFSGetFile are pertinent to the **reset_experiment_info** routine.

DESCRIPTION

Reset experiment info is the IDFS routine that may be used when the end of the current data file has been reached and the return code from the read drec, read tensor data, fill discontinuous data, start image, fill data. fill mode data. sweep data, sweep discontinuous data, sweep mode data or file pos routine indicates that more data files need to be processed (NEXT FILE STATUS). The data set of interest is referenced through the key value **data_key** which can be created using the **get_data_key** This routine closes the currently opened files for the requested data set module. (data_key), file name extension (exten) and IDFS data set identification number (version), memory arrays that were allocated based upon VIDF information are freed and the next set of data files are opened. If the data set of interest contains pitch angle information, the IDFS data access software will automatically take care of data file management for the pitch angle IDFS data set. The IDFS data access software performs the same tasks when the data set of interest contains spacecraft potential information, background information and / or start of spin information.

The parameter **version** allows multiple file openings for an IDFS data set. If the data, header and VIDF file for the specified data set need to be opened just once for processing, the same version number should be passed to all IDFS routines. However, for multiple file openings, the version number should be unique and all file manipulations performed by the IDFS routines will use the file descriptors defined for the version number specified. The user should call the **get_version_number** routine to retrieve a unique version number instead of choosing this value themselves. The retrieval of multiple data parameters from a single data source does not constitute the need for multiple version numbers; a single version number will suffice.

The beginning time that is passed to this routine is dependent upon whether playback or real-time processing is desired. If real-time data files are being utilized, the value for **btime_sec** should be set to -1 so that the file positioning routine **file_pos** will position the file pointer at the beginning of the new real-time data file. If playback data files are being utilized, the routine **next_file_start_time** should be called to retrieve the start time that will trigger the retrieval of the next data file to be processed. The time values that are passed into this routine are used to make an internal call to the **file_open** routine in order to retrieve the next set of data files. It is imperative that a call to the **file_pos** routine be made immediately after a successful return from the **reset_experiment_info** module in order for the IDFS software to process the next IDFS data set correctly.

If the **file_open** routine is not to open the default set of IDFS files but a modified set of IDFS files, the two character extension applied to these data files must be supplied to this routine within the string variable **exten**. These files must have the identical name as the IDFS files with the two character identification code appended to the end of the file names (i.e. RTLA19922181432Dxx, RTLA19922181432Hxx, RTLA19922181432Ixx). The files must reside either in the directory specified by the environment variable USER_DATA, which is set by the user, or in the user's home directory if the environment variable USER_DATA is not set. To open the default IDFS data files, **exten** should be set to a null

string. The usage of modified data sets is limited to post acquisition data; therefore, it is suggested that the user set **exten** to a null string for real-time scenarios.

ERRORS

All errors within this routine are returned through the status variable. The include file **ret_codes.h**, which includes all possible return values, should be included so that the mnemonics for the return codes can be referenced. The **ret_codes.h** file is described in section 1H of the IDFS Programmers Manual.

SEE ALSO

file_open	1 R
file_pos	1R
read_drec	1 R
read_tensor_data	1R
start_image	1 R
fill_data	2R
fill_mode_data	2R
fill_discontinuous_data	2R
sweep_data	2R
sweep_mode_data	2R
sweep_discontinuous_data	2R
next_file_start_time	1 R
get_data_key	1 R
get_version_number	1 R
ret_codes	1H
libbase_idfs	1H
idf_data	1 S
tensor_data	1 S

BUGS

None

EXAMPLES

The end of the current playback data file has been reached and more data exists for the virtual instrument RTLA, which is part of the RETE instrument/experiment, which is part of the TSS-1 mission, which is identified with the TSS project. Retrieve the next set of data files. External variables are utilized to illustrate that the user-requested end time is set before this code is executed.

#include "libbase_idfs.h"
#include "ret_codes.h"

extern SDDAS_SHORT etime_yr, etime_day; extern SDDAS_LONG etime_sec, etime_nano;

```
SDDAS_ULONG data_key;
SDDAS USHORT vnum;
SDDAS_LONG btime_sec, btime_nano;
SDDAS_SHORT status, btime_yr, btime_day;
status = get_data_key ("TSS", "TSS-1", "RETE", "RETE", "RTLA", &data_key);
if (status != ALL_OKAY)
{
 printf ("\n Error %d returned by get_data_key routine.\n", status);
 exit (-1);
 }
get version number (&vnum);
status = next_file_start_time (data_key, "", vnum, 0, &btime_yr, &btime_day,
                           &btime sec, &btime nano);
if (status != ALL_OKAY)
ł
 printf ("\n Error %d returned by next file start time routine.\n", status);
 exit (-1);
 }
```



```
if (status != ALL_OKAY)
{
    printf ("\n Error %d returned by reset_experiment_info routine.\n", status);
    exit (-1);
}
```

SELECT_SENSOR

function - indicate which sensors are to be processed for the data set specified

SYNOPSIS

#include "libbase_idfs.h"
#include "ret_codes.h"

SDDAS_SHORT	select_sensor (SDDAS_ULONG data_key, SDDAS_CHAR *exten,
	SDDAS_USHORT version, SDDAS_SHORT sensor)

ARGUMENTS

data_key	-	unique value which indicates the data set of interest
exten	-	two character extension to be added to IDFS file names when
		default files are not to be used, otherwise a null string
version	-	IDFS data set identification number which allows for multiple
		openings of the same data set
sensor	-	sensor identification number
select_sensor	-	routine status (see TABLE 1)

TABLE 1. Status Codes Returned for SELECT_SENSOR

STATUS CODE	EXPLANATION OF STATUS
SEL_SEN_NOT_FOUND	the requested data_key, exten, version combination has no memory allocated
	for processing (user did not call file_open for this combination)
ALL_OKAY	routine terminated successfully

DESCRIPTION

Select_sensor is the IDFS sensor selection routine. The data set of interest is referenced through the key value data_key which can be created using the get_data_key module. This routine does not have to be utilized by the programmer since the routine file_open sets the internal flags to indicate that all sensors associated with the data set are to be processed and memory to hold information concerning each sensor is to be allocated by the routine file_pos. However, in order to conserve space and to avoid unnecessary processing of sensors which are not going be utilized by the programmer, this routine may be called once for each desired sensor. When this routine is called, the internal flags are reset such that only the requested sensors will be processed and have space allocated. This routine must be called before the routine file_pos if this routine is to be utilized properly.

The parameter **version** allows multiple file openings for an IDFS data set. If the data, header and VIDF file for the specified data set need to be opened just once for processing, the same version number should be passed to all IDFS routines. However, for multiple file openings, the version number should be unique and all file manipulations performed by the IDFS routines will use the file descriptors defined for the version number specified. The user should call the **get_version_number** routine to retrieve a unique version number instead of choosing this value themselves. The retrieval of multiple data parameters from a

single data source does not constitute the need for multiple version numbers; a single version number will suffice.

If the **file_open** routine is not to open the default set of IDFS files but a modified set of IDFS files, the two character extension applied to these data files must be supplied to this routine within the string variable **exten**. These files must have the identical name as the IDFS files with the two character identification code appended to the end of the file names (i.e. RTLA19922181432Dxx, RTLA19922181432Hxx, RTLA19922181432Ixx). The files must reside either in the directory specified by the environment variable USER_DATA, which is set by the user, or in the user's home directory if the environment variable USER_DATA is not set. To open the default IDFS data files, **exten** should be set to a null string. The usage of modified data sets is limited to post acquisition data; therefore, it is suggested that the user set **exten** to a null string for real-time scenarios.

Within the IDFS paradigm, an instrument may be classified as a vector instrument or as a scalar instrument when dealing with data that is not stored in multi-dimensional IDFS format. A vector instrument is an instrument whose sensors represent multi-value data sets as opposed to a scalar instrument whose sensors represent a set of singular data values. If the data set to be processed is a vector instrument, the user **should not** call this routine if the **center_and_band_values** routine is to be utilized. If this routine is called, erroneous center sweep and/or band width values may be computed.

ERRORS

All errors within this routine are returned through the status variable. The include file **ret_codes.h**, which includes all possible return values, should be included so that the mnemonics for the return codes can be referenced. The **ret_codes.h** file is described in section 1H of the IDFS Programmers Manual.

SEE ALSO

file_pos	1 R
file_open	1 R
get_data_key	1 R
get_version_number	1 R
center_and_band_values	2R
ret_codes	1H
libbase_idfs	1H

BUGS

None

EXAMPLES

The RTLA virtual instrument, which is part of the RETE instrument/experiment, has 5 sensors associated with it, referenced as sensors 0, 1, 2, 3, and 4. The RETE instrument/experiment is part of the TSS-1 mission, which is identified with the TSS project. Select sensors 0 and 3 to be the only two sensors to be processed and to have space allocated.

```
#include "libbase_idfs.h"
#include "ret codes.h"
SDDAS_ULONG data_key;
SDDAS_USHORT vnum;
SDDAS_SHORT status;
status = get_data_key ("TSS", "TSS-1", "RETE", "RETE", "RTLA", &data_key);
if (status != ALL_OKAY)
{
 printf ("\n Error %d returned by get_data_key routine.\n", status);
 exit (-1);
 }
get_version_number (&vnum);
status = select_sensor (data_key, '''', vnum, 0);
if (status != ALL_OKAY)
{
 printf ("\n Error %d returned by select_sensor routine.\n", status);
 exit (-1);
 }
status = select_sensor (data_key, "", vnum, 3);
if (status != ALL_OKAY)
{
 printf ("\n Error %d returned by select_sensor routine.\n", status);
 exit (-1);
 }
```

START_IMAGE

function - positions the file pointers at the beginning of an image

SYNOPSIS

#include "libbase_idfs.h"
#include "ret_codes.h"

SDDAS_SHORT	start_image (SDDAS_ULONG data_key, SDDAS_CHAR *exten,
	SDDAS_USHORT version, void *idf_data_ptr)

ARGUMENTS

• -·-==		
data_key	-	unique value which indicates the data set of interest
exten	-	two character extension to be added to IDFS file names when
		default files are not to be used, otherwise a null string
version	-	IDFS data set identification number which allows for multiple
		openings of the same data set
idf_data_ptr	-	pointer to the idf_data structure that is to hold sensor
		data and pertinent ancillary data for the data set of interest
start_image	-	routine status (see TABLE 1)

TABLE 1. Status Code Returned for **START_IMAGE**

STATUS CODE	EXPLANATION OF STATUS
IMAGE_NOT_FOUND	the requested data_key, exten, version combination has no memory allocated for
	processing (user did not call file_open for this combination)
IMAGE_READ_ERROR	read error on data or header file
IMAGE_HDR_MALLOC	no memory for header record information
IMAGE_HDR_REALLOC	no memory for header information expansion (header increased in size)
WRONG_DATA_STRUCTURE	incompatibility between IDFS data set and IDFS data structure used to hold the
	data being returned
	Error codes returned by read_drec ()
ALL_OKAY	routine terminated successfully

DESCRIPTION

Start_image is the IDFS routine that positions the file descriptors at the start of an image. The data set of interest is referenced through the key value **data_key** which can be created using the **get_data_key** module. In order to store an image within the IDFS paradigm, at least one calibration set must be defined, calibration set 0, to hold the scan line number and this is a single quantity (one value, not an array of values). Second, the scan line value must increase from sensor set to sensor set within a single data record. This routine uses the currently opened files for the requested data set and sets the current data pointer to the data sample or sweep whose scan line calibration value is set to zero. This routine must be called **AFTER** a call to the **file_pos** routine has been made since the **file_pos** routine sets the data pointer to the data sample or sweep whose beginning time is closest to that requested by the user. The **start_image** routine assumes that the **file_pos** routine has been already been called. Data positioning is performed only once for each unique parameter set. If additional calls are made to this routine with the same parameter set, the module simply

returns the **ALL_OKAY** status code, with the exception being after a call to the module **reset_experiment_info**, which closes the existing IDFS data set and opens the next IDFS data set to be processed.

The parameter **version** allows multiple file openings for an IDFS data set. If the data, header and VIDF file for the specified data set need to be opened just once for processing, the same version number should be passed to all IDFS routines. However, for multiple file openings, the version number should be unique and all file manipulations performed by the IDFS routines will use the file descriptors defined for the version number specified. The user should call the **get_version_number** routine to retrieve a unique version number instead of choosing this value themselves. The retrieval of multiple data parameters from a single data source does not constitute the need for multiple version numbers; a single version number will suffice.

The parameter **idf_data_ptr** is a pointer to the structure that is to hold all data pertinent to the data set being processed. The structure is created and the address to this structure is returned when a call to the **create_idf_data_structure** routine is made. The user also has the option of calling the module **create_data_structure**, which determines what type of data structure is needed for the IDFS data set of interest. In most cases, one data structure is sufficient to process any number of distinct data sets. However, if more than one structure is needed, the user may call the **create_idf_data_structure** routine N times to create N instances of the **idf_data** structure. The user must keep track of which pointer to send to the IDFS routines that utilize this structure.

If the **file_open** routine is not to open the default set of IDFS files but a modified set of IDFS files, the two character extension applied to these data files must be supplied to this routine within the string variable **exten**. These files must have the identical name as the IDFS files with the two character identification code appended to the end of the file names (i.e. RTLA19922181432Dxx, RTLA19922181432Hxx, RTLA19922181432Ixx). The files must reside either in the directory specified by the environment variable USER_DATA, which is set by the user, or in the user's home directory if the environment variable USER_DATA is not set. To open the default IDFS data files, **exten** should be set to a null string. The usage of modified data sets is limited to post acquisition data; therefore, it is suggested that the user set **exten** to a null string for real-time scenarios.

ERRORS

All errors within this routine are returned through the status variable. The include file **ret_codes.h**, which includes all possible return values, should be included so that the mnemonics for the return codes can be referenced. The **ret_codes.h** file is described in section 1H of the IDFS Programmers Manual.

SEE ALSO

file_open	1R
file_pos	1R
read_drec	1R
reset_experiment_info	1R

get_data_key	1R
get_version_number	1R
create_data_structure	1R
create_idf_data_structure	1 R
ret_codes	1H
libbase_idfs	1H

BUGS

None

EXAMPLES

Position the default IDFS data files associated with the virtual instrument SAIA, which is part of the SAI instrument/experiment, at the beginning of the data file and at the start of the image. The SAI instrument/experiment is part of the DE-1 mission, which is identified with the DE (Dynamics Explorer) project.

```
#include "libbase_idfs.h"
#include "ret_codes.h"
```

```
SDDAS_ULONG data_key;
SDDAS_USHORT vnum;
SDDAS_SHORT status;
void *idf_data_ptr;
```

```
status = get_data_key ("DE", "DE-1", "SAI", "SAI", "SAIA", &data_key); if (status != ALL_OKAY)
```

```
{
    printf ("\n Error %d returned by get_data_key routine.\n", status);
    exit (-1);
```

```
}
get_version_number (&vnum);
```

```
status = create_idf_data_structure (&idf_data_ptr);
if (status != ALL_OKAY)
{
    printf ("\n Error %d returned by create_idf_data_structure routine.\n
```

```
printf ("\n Error %d returned by create_idf_data_structure routine.\n", status);
exit (-1);
}
```

```
status = file_pos (data_key, "", vnum, idf_data_ptr, -1, -1, -1, 0, -1, -1, 0);
if (status != ALL_OKAY)
{
    printf ("\n Error %d returned by file_pos routine.\n", status);
    exit (-1);
}
```

```
status = start_image (data_key, "", vnum, idf_data_ptr);
if (status != ALL_OKAY)
{
    printf ("\n Error %d returned by start_image routine.\n", status);
    exit (-1);
}
```

START_OF_SPIN

function - positions the file pointers at the beginning of a spin

SYNOPSIS

#include "libbase_idfs.h"
#include "ret_codes.h"

SDDAS_SHORT	start_of_spin (SDDAS_ULONG data_key, SDDAS_CHAR *exten,
	SDDAS_USHORT version, SDDAS_SHORT ctrl_sen,
	SDDAS_SHORT etime_yr, SDDAS_SHORT etime_day,
	SDDAS_LONG etime_sec, SDDAS_LONG etime_nano)

ARGUMENTS

data_key	-	unique value which indicates the data set of interest
exten	-	two character extension to be added to IDFS file names when
		default files are not to be used, otherwise a null string
version	-	IDFS data set identification number which allows for multiple
		openings of the same data set
ctrl_sen	-	sensor which serves as the controller for timing relating to
		full spins
etime_yr	-	ending year for data being requested
etime_day	-	ending day of year for data being requested
etime_sec	-	ending time of day in seconds for data being requested
etime_nano	-	ending time of day residual in nanoseconds
start_of_spin	-	routine status (see TABLE 1)

TABLE 1. Status Code Returned for START_OF_SPIN

STATUS CODE	EXPLANATION OF STATUS
START_SPIN_NOT_FOUND	the requested data_key, exten, version combination has no memory allocated for
	processing (user did not call file_open for this combination)
START_SPIN_NO_POS	user did not call file_pos for this combination before calling this module
WRONG_HEADER_FORMAT	multi-dimensional IDFS data storage is not supported by this module
START_SPIN_NO_SPIN	the requested data set does not spin
START_SPIN_MALLOC	no memory for structures which hold start of spin information for each sensor
START_SPIN_ALL_MALLOC	no memory for array of pointers to the idf_data structures that are allocated to hold
	the data for each sweep within the spin
START_SPIN_ETIME	user-requested end time was reached and the start of spin was not found
START_SPIN_TIME_MALLOC	no memory for time of sample values for spin determination
WRONG_DATA_STRUCTURE	incompatibility between IDFS data set and IDFS data structure used to hold the
	data being returned
	Error codes returned by create_idf_data_structure ()
	Error codes returned by file_open ()
	Error codes returned by file_pos ()
	Error codes returned by read_drec ()
	Error codes returned by next_file_start_time ()
	Error codes returned by reset_experiment_info ()
ALL_OKAY	routine terminated successfully

DESCRIPTION

Start_of_spin is the IDFS routine that positions the file descriptors at the start of a spin. The data set of interest is referenced through the key value **data_key** which can be created using the **get_data_key** module. The start of spin can be determined in one of two ways: (1) use the azimuthal angle values (default method) or (2) use the spin periods defined by the IDFS data source that was specified as the start of spin source in the VIDF file for the data set of interest. If there was a problem encountered for the start of spin IDFS source on the initial call to the **file_open** module for the data set of interest, the start of spin method will be reverted back to the angular method. Both methods require that the **start_of_spin** module be called **AFTER** a call to the **file_pos** routine has been made since the **file_pos** routine sets the data pointer to the data sample or sweep whose beginning time is closest to that requested by the user, including any start of spin IDFS source that may be defined.

For the angular method, this routine uses the currently opened files for the requested data set and sets the current data pointer to the data sample or element within the sweep whose azimuthal angles indicate the start of a new spin has been reached (angle = 0.0). The start of spin is found for each individual IDFS sensor that is to be processed for the data set specified (refer to the **select_sensor** routine). This is necessary since the computation for the azimuthal angles is based upon time and each IDFS sensor could potentially start at a different time within the same sweep being retrieved from the IDFS data record.

For the start of spin source definition method, this routine uses the currently opened files for the requested data set and sets the current data pointer to the data sample or element within the sweep whose time period lies within the spin period that is closest to the user requested start time. The start of spin is found for each individual IDFS sensor that is to be processed for the data set specified (refer to the **select_sensor** routine). This is necessary since each IDFS sensor could potentially start at a different time within the same sweep being retrieved from the IDFS data record.

In preparation for the usage of spin-averaged data which is returned by the modules defined in section 2R, the parameter **ctrl_sen** is utilized. Spin-averaged data refers to data that is averaged over a complete spin. For the angular method, the parameter **ctrl_sen** defines the sensor that will dictate the time interval for each spin that is processed by the spinaveraging software. This is necessary since each IDFS sensor could potentially start at a different time within the same sweep being retrieved from the IDFS data record; therefore, one sensor has to control the time period that is reflective of each spin. For the start of spin source definition method, the parameter **ctrl_sen** is ignored; instead, the sensor that is defined in the StartOfSpin structure within the VIDF file is used. If the modules defined in section 2R are not going to be utilized, the user is advised to set this parameter to zero.

The parameter **version** allows multiple file openings for an IDFS data set. If the data, header and VIDF file for the specified data set need to be opened just once for processing, the same version number should be passed to all IDFS routines. However, for multiple file openings, the version number should be unique and all file manipulations performed by the IDFS routines will use the file descriptors defined for the version number specified. The user should call the **get_version_number** routine to retrieve a unique version number

December 28, 2012

instead of choosing this value themselves. The retrieval of multiple data parameters from a single data source does not constitute the need for multiple version numbers; a single version number will suffice.

If the **file_open** routine is not to open the default set of IDFS files but a modified set of IDFS files, the two character extension applied to these data files must be supplied to this routine within the string variable **exten**. These files must have the identical name as the IDFS files with the two character identification code appended to the end of the file names (i.e. RTLA19922181432Dxx, RTLA19922181432Hxx, RTLA19922181432Ixx). The files must reside either in the directory specified by the environment variable USER_DATA, which is set by the user, or in the user's home directory if the environment variable USER_DATA is not set. To open the default IDFS data files, **exten** should be set to a null string. The usage of modified data sets is limited to post acquisition data; therefore, it is suggested that the user set **exten** to a null string for real-time scenarios.

ERRORS

All errors within this routine are returned through the status variable. The include file **ret_codes.h**, which includes all possible return values, should be included so that the mnemonics for the return codes can be referenced. The **ret_codes.h** file is described in section 1H of the IDFS Programmers Manual.

SEE ALSO

file_open	1 R
file_pos	1 R
read_drec	1 R
select_sensor	1 R
get_data_key	1 R
get_version_number	1 R
create_idf_data_structure	1 R
next_file_start_time	1 R
reset_experiment_info	1 R
spin_data	2R
spin_data_pixel	2R
ret_codes	1H
libbase_idfs	1H

BUGS

None

EXAMPLES

Position the default IDFS data files associated with the virtual instrument RTLA, which is part of the RETE instrument/experiment, which is part of the TSS-1 mission, which is identified with the TSS project, at the start of the spin that is closest to the user-requested start time specified in the prior call to **file_open** () and **file_pos** () modules.

```
#include "libbase_idfs.h"
#include "ret_codes.h"
SDDAS_ULONG data_key;
SDDAS_LONG etime_sec, etime_nsec;
SDDAS_USHORT vnum;
SDDAS_SHORT status, etime_yr, etime_day;
void *idf_data_ptr;
status = get_data_key ("TSS", "TSS-1", "RETE", "RETE", "RTLA", &data_key);
if (status != ALL_OKAY)
{
 printf ("\n Error %d returned by get_data_key routine.\n", status);
 exit (-1);
 }
get_version_number (&vnum);
etime yr = 1992;
etime_day = 217;
etime sec = 32342;
etime_nsec = 0;
.
status = start_of_spin (data_key, '''', vnum, 0, etime_yr, etime_day, etime_sec,
                      etime_nsec);
if (status != ALL_OKAY)
{
 printf ("\n Error %d returned by start_of_spin routine.\n", status);
 exit (-1);
 }
```

TURN_OFF_PITCH_ANGLE_COMPUTATIONS

function – disables the computation of pitch angles for the specified IDFS data set

SYNOPSIS

#include "libbase_idfs.h"
#include "ret_codes.h"

SDDAS_SHORT turn_off_pitch_angle_computations (SDDAS_ULONG data_key, SDDAS_CHAR *exten, SDDAS_USHORT version)

ARGUMENTS		
data_key	-	unique value which indicates the data set of interest
exten	-	two character extension to be added to IDFS file names when default files are not to be used, otherwise a null string
version		IDFS data set identification number which allows for multiple openings of the same data set
turn_off_pitch_angle_computations	-	routine status (see TABLE 1)

TABLE 1. Status Codes Returned for TURN_OFF_PITCH_ANGLE_COMPUTATIONS

STATUS CODE	EXPLANATION OF STATUS
TURN_OFF_PA_NOT_FOUND	the requested data_key, exten, version combination has no memory
	allocated for processing (user did not call file_open for this combination)
ALL_OKAY	routine terminated successfully

DESCRIPTION

Turn_off_pitch_angle_computations is the routine that disables the computation of the pitch angle data for the data set of interest. This routine was developed in order to speed up the **read_drec** routine since there are times when pitch angle data is not needed by the application accessing the IDFS data. The default scenario for the IDFS data access software is to compute and return pitch angle data, if available, for the data set of interest. If the data set of interest does not return pitch angle data, this routine has no effect. The data set of interest is referenced through the key value **data_key** which can be created using the **get_data_key** module. If this module is utilized, it must be called after the **file_open** routine has been called and before the **file_pos** routine is called.

The parameter **version** allows multiple file openings for an IDFS data set. If the data, header and VIDF file for the specified data set need to be opened just once for processing, the same version number should be passed to all IDFS routines. However, for multiple file openings, the version number should be unique and all file manipulations performed by the IDFS routines will use the file descriptors defined for the version number specified. The user should call the **get_version_number** routine to retrieve a unique version number instead of choosing this value themselves. The retrieval of multiple data parameters from a

single data source does not constitute the need for multiple version numbers; a single version number will suffice.

If the **file_open** routine is not to open the default set of IDFS files but a modified set of IDFS files, the two character extension applied to these data files must be supplied to this routine within the string variable **exten**. These files must have the identical name as the IDFS files with the two character identification code appended to the end of the file names (i.e. RTLA19922181432Dxx, RTLA19922181432Hxx, RTLA19922181432Ixx). The files must reside either in the directory specified by the environment variable USER_DATA, which is set by the user, or in the user's home directory if the environment variable USER_DATA is not set. To open the default IDFS data files, **exten** should be set to a null string. The usage of modified data sets is limited to post acquisition data; therefore, it is suggested that the user set **exten** to a null string for real-time scenarios.

ERRORS

All errors within this routine are returned through the status variable. The include file **ret_codes.h**, which includes all possible return values, should be included so that the mnemonics for the return codes can be referenced. The **ret_codes.h** file is described in section 1H of the IDFS Programmers Manual.

SEE ALSO

file_open	1R
file_pos	1R
read_drec	1 R
get_data_key	1 R
get_version_number	1R
ret_codes	1H
libbase_idfs	1H

BUGS

None

EXAMPLES

Turn off the pitch angle computations for the virtual instrument CP3DRH, which is part of the 3DR instrument, which is part of the PEACE experiment, which is part of the CLUSTER-2 mission, which is identified with the CLUSTERII project.

#include "libbase_idfs.h"
#include "ret_codes.h"

SDDAS_ULONG data_key; SDDAS_USHORT vnum; SDDAS_SHORT status;

```
status = get_data_key ("CLUSTERII", "CLUSTER-2", "PEACE", "3DR", "CP3DRH",
                      &data key);
if (status != ALL_OKAY)
{
 printf ("\n Error %d returned by get_data_key routine.\n", status);
 exit (-1);
}
get version number (&vnum);
status = file_open (data_key, "", vnum, -1, -1, -1, 0, -1, -1, 0, 0);
if (status != ALL_OKAY)
{
 printf ("\n Error %d returned by file_open routine.\n", status);
 exit (-1);
 }
status = turn_off_pitch_angle_computations (data_key, "", vnum);
if (status != ALL OKAY)
{
 printf ("\n Error %d returned by turn_off_pitch_angle_computations routine.\n", status);
```

```
exit (-1);
}
```

TURN_ON_CELESTIAL_POSITION_COMPUTATIONS

function – enables the computation of celestial position angles for the specified IDFS data set

SYNOPSIS

#include "libbase_idfs.h"
#include "ret_codes.h"

SDDAS_SHORT turn_on_celestial_position_computations (SDDAS_ULONG data_key, SDDAS_CHAR *exten, SDDAS_USHORT version)

ARGUMENTS	
data_key	- unique value which indicates the data set of
	interest
exten	- two character extension to be added to IDFS
	file names when default files are not to be used,
	otherwise a null string
version	- IDFS data set identification number which
	allows for multiple openings of the same data set
turn_on_celestial_	position_computations - routine status (see TABLE 1)

TABLE 1. Status Codes Returned for TURN_ON_CELESTIAL_POSITION_COMPUTATIONS

STATUS CODE	EXPLANATION OF STATUS
TURN_ON_CP_NOT_FOUND	the requested data_key, exten, version combination has no memory
	allocated for processing (user did not call file_open for this combination)
ALL_OKAY	routine terminated successfully

DESCRIPTION

Turn_on_celestial_position_computations is the routine that enables the computation and return of the celestial position angle data for the data set of interest. This routine was developed in order to control the ancillary data computations performed by the **read_drec** routine since there are few times when celestial position angle data is needed by the application accessing the IDFS data. The default scenario for the IDFS data access software is to suppress the computation of celestial position angle data, if available, for the data set of interest. The data set of interest is referenced through the key value **data_key** which can be created using the **get_data_key** module. If this module is utilized, it must be called after the **file_open** routine has been called and before the **file_pos** routine is called.

The parameter **version** allows multiple file openings for an IDFS data set. If the data, header and VIDF file for the specified data set need to be opened just once for processing, the same version number should be passed to all IDFS routines. However, for multiple file openings, the version number should be unique and all file manipulations performed by the IDFS routines will use the file descriptors defined for the version number specified. The user should call the **get_version_number** routine to retrieve a unique version number

instead of choosing this value themselves. The retrieval of multiple data parameters from a single data source does not constitute the need for multiple version numbers; a single version number will suffice.

If the **file_open** routine is not to open the default set of IDFS files but a modified set of IDFS files, the two character extension applied to these data files must be supplied to this routine within the string variable **exten**. These files must have the identical name as the IDFS files with the two character identification code appended to the end of the file names (i.e. RTLA19922181432Dxx, RTLA19922181432Hxx, RTLA19922181432Ixx). The files must reside either in the directory specified by the environment variable USER_DATA, which is set by the user, or in the user's home directory if the environment variable USER_DATA is not set. To open the default IDFS data files, **exten** should be set to a null string. The usage of modified data sets is limited to post acquisition data; therefore, it is suggested that the user set **exten** to a null string for real-time scenarios.

ERRORS

All errors within this routine are returned through the status variable. The include file **ret_codes.h**, which includes all possible return values, should be included so that the mnemonics for the return codes can be referenced. The **ret_codes.h** file is described in section 1H of the IDFS Programmers Manual.

SEE ALSO

file_open	1R
file_pos	1 R
read_drec	1 R
get_data_key	1 R
get_version_number	1 R
ret_codes	1H
libbase_idfs	1H

BUGS

None

EXAMPLES

Turn on the celestial position angle computations for the virtual instrument CP3DRH, which is part of the 3DR instrument, which is part of the PEACE experiment, which is part of the CLUSTER-2 mission, which is identified with the CLUSTERII project.

#include "libbase_idfs.h"
#include "ret_codes.h"

SDDAS_ULONG data_key; SDDAS_USHORT vnum; SDDAS_SHORT status;

```
status = get_data_key ("CLUSTERII", "CLUSTER-2", "PEACE", "3DR", "CP3DRH",
                      &data key);
if (status != ALL_OKAY)
ł
 printf ("\n Error %d returned by get_data_key routine.\n", status);
 exit (-1);
 }
get version number (&vnum);
status = file_open (data_key, "", vnum, -1, -1, -1, 0, -1, -1, 0, 0);
if (status != ALL_OKAY)
{
 printf ("\n Error %d returned by file_open routine.\n", status);
 exit (-1);
 }
status = turn_on_celestial_position_computations (data_key, "", vnum);
if (status != ALL OKAY)
{
```

}

December 28, 2012

TURN_ON_EULER_ANGLE_COMPUTATIONS

function - enables the computation of euler angles for the specified IDFS data set

SYNOPSIS

#include "libbase_idfs.h"
#include "ret_codes.h"

SDDAS_SHORT turn_on_euler_angle_computations (SDDAS_ULONG data_key, SDDAS_CHAR *exten, SDDAS_USHORT version)

ARGUMENTS		
data_key	-	unique value which indicates the data set of interest
exten	-	two character extension to be added to IDFS file names when default files are not to be used, otherwise a null string
version		IDFS data set identification number which allows for multiple openings of the same data set
turn_on_euler_angle_computations	-	routine status (see TABLE 1)

TABLE 1. Status Codes Returned for TURN_ON_EULER_ANGLE_COMPUTATIONS

STATUS CODE	EXPLANATION OF STATUS
TURN_ON_EA_NOT_FOUND	the requested data_key, exten, version combination has no memory
	allocated for processing (user did not call file_open for this combination)
ALL_OKAY	routine terminated successfully

DESCRIPTION

Turn_on_euler_angle_computations is the routine that enables the computation and return of the euler angle data for the data set of interest. This routine was developed in order to control the ancillary data computations performed by the **read_drec** routine since there are few times when euler angle data is needed by the application accessing the IDFS data. The default scenario for the IDFS data access software is to suppress the computation of euler angle data, if available, for the data set of interest. The data set of interest is referenced through the key value **data_key** which can be created using the **get_data_key** module. If this module is utilized, it must be called after the **file_open** routine has been called and before the **file_pos** routine is called.

The parameter **version** allows multiple file openings for an IDFS data set. If the data, header and VIDF file for the specified data set need to be opened just once for processing, the same version number should be passed to all IDFS routines. However, for multiple file openings, the version number should be unique and all file manipulations performed by the IDFS routines will use the file descriptors defined for the version number specified. The user should call the **get_version_number** routine to retrieve a unique version number instead of choosing this value themselves. The retrieval of multiple data parameters from a

single data source does not constitute the need for multiple version numbers; a single version number will suffice.

If the **file_open** routine is not to open the default set of IDFS files but a modified set of IDFS files, the two character extension applied to these data files must be supplied to this routine within the string variable **exten**. These files must have the identical name as the IDFS files with the two character identification code appended to the end of the file names (i.e. RTLA19922181432Dxx, RTLA19922181432Hxx, RTLA19922181432Ixx). The files must reside either in the directory specified by the environment variable USER_DATA, which is set by the user, or in the user's home directory if the environment variable USER_DATA is not set. To open the default IDFS data files, **exten** should be set to a null string. The usage of modified data sets is limited to post acquisition data; therefore, it is suggested that the user set **exten** to a null string for real-time scenarios.

ERRORS

All errors within this routine are returned through the status variable. The include file **ret_codes.h**, which includes all possible return values, should be included so that the mnemonics for the return codes can be referenced. The **ret_codes.h** file is described in section 1H of the IDFS Programmers Manual.

SEE ALSO

file_open	1R
file_pos	1R
read_drec	1R
get_data_key	1R
get_version_number	1R
ret_codes	1H
libbase_idfs	1H

BUGS

None

EXAMPLES

Turn on the euler angle computations for the virtual instrument CP3DRH, which is part of the 3DR instrument, which is part of the PEACE experiment, which is part of the CLUSTER-2 mission, which is identified with the CLUSTERII project.

#include "libbase_idfs.h"
#include "ret_codes.h"

SDDAS_ULONG data_key; SDDAS_USHORT vnum; SDDAS_SHORT status;

```
status = get_data_key ("CLUSTERII", "CLUSTER-2", "PEACE", "3DR", "CP3DRH",
                      &data key);
if (status != ALL_OKAY)
{
 printf ("\n Error %d returned by get_data_key routine.\n", status);
 exit (-1);
}
get version number (&vnum);
status = file_open (data_key, "", vnum, -1, -1, -1, 0, -1, -1, 0, 0);
if (status != ALL_OKAY)
{
 printf ("\n Error %d returned by file_open routine.\n", status);
 exit (-1);
 }
status = turn_on_euler_angle_computations (data_key, '''', vnum);
if (status != ALL OKAY)
{
 printf ("\n Error %d returned by turn on euler angle computations routine.\n", status);
 exit (-1);
```

}

December 28, 2012

VALID_IDF_DATA_STRUCTURE

function - indicates if the specified idf_data structure is an active data structure

SYNOPSIS

#include "libbase_idfs.h"

SDDAS_BOOL valid_idf_data_structure (void *idf_data_ptr)

ARGUMENTS

```
idf_data_ptr - pointer to the idf_data structure that is to hold sensor
data and pertinent ancillary data for the data set of interest
```

DESCRIPTION

Valid_idf_data_structure is the IDFS routine that can be called to verify that the address of the data structure **idf_data** is a valid and active address. In other words, the memory associated with the address has not been freed. While it is not usually necessary to utilize this module when processing IDFS data, there are some cases where it was necessary when SCF data is being processed. The module will return a Boolean value to indicate whether the address for the **idf_data** structure is "active" at this time (sTrue) or "inactive" at this time (sFalse).

ERRORS

This routine returns no error codes.

SEE ALSO

create_data_structure	1R
create_idf_data_structure	1R
idf data	1 S

BUGS

None

EXAMPLES

Determine if the memory address for the **idf_data** structure is an active memory location. If it is not, allocate a new **idf_data** structure for usage. This code segment assumes that the module **create_idf_data_structure** or **create_data_structure** has been previously called.

#include "libbase_idfs.h"

SDDAS_SHORT status; SDDAS_BOOL valid_address; void *idf_data_ptr;

valid_address = valid_idf_data_structure (idf_data_ptr);

```
if (!valid_address)
{
    status = create_idf_data_structure (&idf_data_ptr);
    if (status != ALL_OKAY)
    {
        printf ("\n Error %d returned by create_idf_data_structure routine.\n", status);
        exit (-1);
    }
}
```

VALID_TENSOR_DATA_STRUCTURE

function - indicates if the specified tensor_data structure is an active data structure

SYNOPSIS

#include "libbase_idfs.h"

SDDAS_BOOL valid_tensor_data_structure (void *tensor_data_ptr)

ARGUMENTS

```
tensor_data_ptr - pointer to the tensor_data structure that is to hold sensor
data and pertinent ancillary data for the data set of interest
```

DESCRIPTION

Valid_tensor_data_structure is the IDFS routine that can be called to verify that the address of the data structure tensor_data is a valid and active address. In other words, the memory associated with the address has not been freed. While it is not usually necessary to utilize this module when processing IDFS data, there are some cases where it was necessary when SCF data is being processed. The module will return a Boolean value to indicate whether the address for the tensor_data structure is "active" at this time (sTrue) or "inactive" at this time (sFalse).

ERRORS

This routine returns no error codes.

SEE ALSO

create_data_structure	1 R
create_tensor_data_structure	1 R
tensor data	1 S

BUGS

None

EXAMPLES

Determine if the memory address for the **tensor_data** structure is an active memory location. If it is not, allocate a new **tensor_data** structure for usage. This code segment assumes that the module **create_tensor_data_structure** or **create_data_structure** has been previously called.

#include "libbase_idfs.h"

SDDAS_SHORT status; SDDAS_BOOL valid_address; void *tensor_data_ptr;

valid_address = valid_tensor_data_structure (tensor_data_ptr);

```
if (!valid_address)
{
    status = create_tensor_data_structure (&tensor_data_ptr);
    if (status != ALL_OKAY)
    {
        printf ("\n Error %d returned by create_tensor_data_structure routine.\n", status);
        exit (-1);
    }
}
```

BUFFER_BIN_FILL

function - fills in the missing bin elements for the data buffer being referenced

SYNOPSIS

#include "libtrec_idfs.h"
#include "ret_codes.h"

SDDAS_SHORT	buffer_bin_fill (SDDAS_ULONG data_key, SDDAS_CHAR *exten,
	SDDAS_USHORT version, SDDAS_FLOAT *data_ptr,
	SDDAS_CHAR *bin_stat, SDDAS_SHORT block_size,
	SDDAS_LONG need_filled, SDDAS_CHAR bin_project)

ARGUMENTS

data_key	-	unique value which indicates the data set of interest
exten	-	two character extension to be added to IDFS file names when default files are not to be used, otherwise a null string
version	-	IDFS data set identification number which allows for multiple openings of the same data set
data_ptr	-	pointer to the data buffer being processed
bin_stat	-	pointer to status flags which are associated with each data bin returned
		0 - no data has been placed into the data bin being processed
		 data has been placed into the data bin being processed
block_size	-	the number of data values returned in a single data buffer
need_filled	-	the number of filled bins needed in order to fill in the missing data bins
bin_project	-	flag indicating if the data is to be projected into empty bins
		beyond the first or last data bin which contains data
		0 - do not project the data
		1 - project the data
buffer_bin_fill	-	routine status (see TABLE 1)

TABLE 1. Status Codes Returned for BUFFER_BIN_FILL

STATUS CODE	EXPLANATION OF STATUS
BUF_BIN_NOT_FOUND	the requested data_key, exten, version combination has no memory allocated for processing (user did not call file_open for this combination)
BUF_BIN_MALLOC	no memory for temporary internal array
ALL_OKAY	routine terminated successfully

DESCRIPTION

Buffer_bin_fill is the IDFS routine which fills any missing bins in the data buffers that are returned by the IDFS routines that return time-averaged data (**fill_data** and **fill_discontinuous_data**), sample-averaged data (**sweep_data** and

sweep_discontinuous_data) or spin-averaged data (**spin_data** and **spin_data_pixel**). The user should process only those buffers that are flagged with the status value BUFFER_READY. The data set of interest is referenced through the key value **data_key** which can be created using the **get_data_key** module. This module **can not** be used in conjunction with the **fill_mode_data** and **sweep_mode_data** modules since this module is concerned with sensor-specific data.

The parameter **version** allows multiple file openings for an IDFS data set. If the data, header and VIDF file for the specified data set need to be opened just once for processing, the same version number should be passed to all IDFS routines. However, for multiple file openings, the version number should be unique and all file manipulations performed by the IDFS routines will use the file descriptors defined for the version number specified. The user should call the **get_version_number** routine to retrieve a unique version number instead of choosing this value themselves. The retrieval of multiple data parameters from a single data source does not constitute the need for multiple version numbers; a single version number will suffice.

If the **file_open** routine is not to open the default set of IDFS files but a modified set of IDFS files, the two character extension applied to these data files must be supplied to this routine within the string variable **exten**. These files must have the identical name as the IDFS files with the two character identification code appended to the end of the file names (i.e. RTLA19922181432Dxx, RTLA19922181432Hxx, RTLA19922181432Ixx). The files must reside either in the directory specified by the environment variable USER_DATA, which is set by the user, or in the user's home directory if the environment variable USER_DATA is not set. To open the default IDFS data files, **exten** should be set to a null string. The usage of modified data sets is limited to post acquisition data; therefore, it is suggested that the user set **exten** to a null string for real-time scenarios.

The empty data bins will be filled in according to the method selected in the call to the **set_bin_info** module, with the exception of a least squares fit. The least squares fit method, if selected, is replaced by a constant column row approach, with a minimum of 3 data points needed before the fill in can be accomplished. This replacement is necessary since the least squares fit method is valid for 2-D fits only and this routine works with 1-D data. If the user selected NO_BIN_FILL, the data bins are left as is, with any unfilled bins left unfilled. If the user selected any other fill method, that fill method is used to fill in the missing data bins. If the user is collapsing the data over any data dimension, there is no need to call this module. The missing data bins will be handled by the call to the **collapse_dimensions** module.

ERRORS

All errors within this routine are returned through the status variable. The include file **ret_codes.h**, which includes all possible return values, should be included so that the mnemonics for the return codes can be referenced. The **ret_codes.h** file is described in section 1H of the IDFS Programmers Manual.

December 28, 2012

SEE ALSO file_open

me_open	11
fill_data	2R
fill_discontinuous_data	2R
sweep_data	2R
sweep_discontinuous_data	2R
spin_data	2R
spin_data_pixel	2R
collapse_dimensions	2R
set_bin_info	2R
get_data_key	1R
get_version_number	1R
ret_codes	1H
libtrec_idfs	2H

BUGS

None

EXAMPLES

Assume that the **fill_data** module has been called and that **data_ptr** has been set to point to a data buffer that has been flagged as BUFFER_READY and **bin_stat** has been set to point to the corresponding status flags for the data buffer in question. The variable **data_block** is returned by the module **fill_data**. Use a minimum of three data points to fill in the missing bins and do not project the data past the first and last data bins actually found. The data set selected is from the virtual instrument RTLA, which is part of the RETE instrument/experiment, which is part of the TSS-1 mission, which is identified with the TSS project.

1 **R**

```
#include "libtrec_idfs.h"
#include "ret_codes.h"
```

SDDAS_ULONG data_key; SDDAS_USHORT vnum; SDDAS_SHORT status, data_block; SDDAS_FLOAT *data_ptr; SDDAS_CHAR *bin_stat;

```
status = get_data_key ("TSS", "TSS-1", "RETE", "RETE", "RTLA", &data_key);
if (status != ALL_OKAY)
{
    printf ("\n Error %d returned by get_data_key routine.\n", status);
    exit (-1);
    }
get_version_number (&vnum);
```

```
status = buffer_bin_fill (data_key, '''', vnum, data_ptr, bin_stat, data_block, 3, 0);
```

```
if (status != ALL_OKAY)
{
    printf ("\n Error %d returned by buffer_bin_fill routine.\n", status);
    exit (-1);
}
```

CENTER_AND_BAND_VALUES

function - creates the center sweep and/or band width values associated with the data bins

SYNOPSIS

#include "libtrec_idfs.h"
#include "ret_codes.h"

SDDAS_SHORT center_and_band_values (SDDAS_ULONG data_key,
SDDAS_CHAR *exten, SDDAS_USHORT version,
void *idf_data_ptr, SDDAS_SHORT sensor,
SDDAS_CHAR ret_center, SDDAS_CHAR ret_band,
SDDAS_FLOAT **center_ptr, SDDAS_FLOAT **low_ptr,
SDDAS_FLOAT **high_ptr, SDDAS_SHORT *num_bins,
SDDAS_SHORT *num_converted)

ARGUMENTS

data_key exten	-	unique value which indicates the data set of interest two character extension to be added to IDFS file names when default files are not to be used, otherwise a null string
version	-	IDFS data set identification number which allows for multiple openings of the same data set
idf_data_ptr	-	pointer to the idf_data structure that is to hold sensor data and pertinent ancillary data for the data set of interest
sensor	_	sensor identification number
ret_center	-	flag indicating if the center sweep values are to be returned
		 0 - do not return the center sweep value 1 - calculate and return the pointer to the center sweep values
ret_band	-	flag indicating if the band width values for the sweep are to be returned
		0 - do not return the band width values for the sweep
		1 - calculate and return the pointer(s) to the band width values for the sweep
center_ptr	-	pointer to the location that holds the center sweep values
low_ptr	-	pointer to the location that holds the lower bands for non-contiguous bands or all band widths for contiguous bands
high_ptr	-	pointer to the location that holds the upper bands for non-contiguous bands
num_bins	-	the number of values returned

num_converted	-	the number of values that were converted to the
		desired scientific scan unit
center_and_band_values	-	routine status (see TABLE 1)

TABLE 1. Status Codes Returned for CENTER_AND_BAND_VALUES

STATUS CODE	EXPLANATION OF STATUS
CENTER_NOT_FOUND	the requested data_key, exten, version combination has no memory allocated for
	processing (user did not call file_open for this combination)
BPTR_NOT_FOUND	the data binning information has not been allocated (user did not call set_bin_info
	for this combination)
CENTER_NO_SENSOR	the requested sensor is not being processed (user did not call select_sensor for this
	combination)
BAND_MALLOC	no memory for banded sweep values
CENTER_MALLOC	no memory for center sweep values
CENTER_TMP_MALLOC	no memory for temporary scratch space
CALC_CENTER_DREC	an error was returned by read_drec () for fixed sweep binning
ALLOC_EV_REALLOC	no memory for sweep array expansion in the idf_data structure
BAD_VFMT	bad format character for variable width bin spacing
	Error codes returned by convert_to_units ()
CENTER_CONVERSION	only a subset of the center and band values were converted to units
ALL_OKAY	routine terminated successfully

DESCRIPTION

Center and band values is the IDFS routine that creates the center and/or band width sweep step values for the specified sensor. For any given virtual instrument, there may be one set of sweep step values to be used by all sensors or there may be a set of sweep step values defined for each individual sensor. In either case, this routine should be called once for each sensor that is to be processed by the IDFS routines that return time-averaged data fill discontinuous data), sample-averaged (sweep data (fill data data / sweep discontinuous data) or spin-averaged data (spin data and spin data pixel). These sweep step values are used by the time-averaging, sample-averaging or spinaveraging module when storing the data into the data bins for VARIABLE SWEEP processing (refer to the explanation in the set bin info write-up), but are not used for FIXED SWEEP processing. The data set of interest is referenced through the key value data_key which can be created using the get_data_key module. If the only type of data to be processed for the data set in question is instrument status (mode) data, the user does not need to call this module since the center_and_band_values routine processes sensorspecific data and instrument status data is not sensor-specific.

The sweep step values are created using the information specified by the calls to the **set_bin_info** and **set_scan_info** modules. If the **set_bin_info** module has not been called, an error code is returned to the calling module. If the **set_scan_info** module has not been called, the center and band width values will be calculated in terms of raw units and the IDFS software will set up the system so that only one set of sweep step values are defined for all sensors for the data set selected. When FIXED_SWEEP processing is specified in the call to the **set_bin_info** module, there may be cases when all the center and band values are not converted to the units desired. This situation can occur if the unit conversion is dependent upon calibration data that is stored within the data record. In this case, the

number of center and band values that are converted to units is dependent upon the number of data values contained within the first data record processed. This number is returned in the **num_converted** parameter and is strictly for informational purposes only and this module returns the status code **CENTER_CONVERSION**.

The parameter **version** allows multiple file openings for an IDFS data set. If the data, header and VIDF file for the specified data set need to be opened just once for processing, the same version number should be passed to all IDFS routines. However, for multiple file openings, the version number should be unique and all file manipulations performed by the IDFS routines will use the file descriptors defined for the version number specified. The user should call the **get_version_number** routine to retrieve a unique version number instead of choosing this value themselves. The retrieval of multiple data parameters from a single data source does not constitute the need for multiple version numbers; a single version number will suffice.

The parameter **idf_data_ptr** is a pointer to the structure that is to hold all data pertinent to the data set being processed. The structure is created and the address to this structure is returned when a call to the **create_idf_data_structure** routine is made. The user also has the option of calling the module **create_data_structure**, which determines what type of data structure is needed for the IDFS data set of interest. In most cases, one data structure is sufficient to process any number of distinct data sets. However, if more than one structure is needed, the user may call the **create_idf_data_structure** routine N times to create N instances of the **idf_data** structure. The user must keep track of which pointer to send to the IDFS routines that utilize this structure.

If the **file_open** routine is not to open the default set of IDFS files but a modified set of IDFS files, the two character extension applied to these data files must be supplied to this routine within the string variable **exten**. These files must have the identical name as the IDFS files with the two character identification code appended to the end of the file names (i.e. RTLA19922181432Dxx, RTLA19922181432Hxx, RTLA19922181432Ixx). The files must reside either in the directory specified by the environment variable USER_DATA, which is set by the user, or in the user's home directory if the environment variable USER_DATA is not set. To open the default IDFS data files, **exten** should be set to a null string. The usage of modified data sets is limited to post acquisition data; therefore, it is suggested that the user set **exten** to a null string for real-time scenarios.

The contents of the memory locations returned by this module should **NOT** be altered since the calculated center/band width values are used by the time-averaging, sample-averaging, or spin-averaging routine when processing the data. If the returned values need to be modified, for example, to take the log of the values, the user should allocate space to hold the values, copy the values into this space and modify the values there.

The module returns two possible pointers for the location(s) that hold the lower and upper band width values. In the case where the bands are non-contiguous, both the **low_ptr** and **high_ptr** will reference memory locations that hold the band width values. In the case where the bands are contiguous, there is no need to hold separate upper and lower values –

the upper limit of the current band is the lower limit of the next band. In this case, one extra memory location is allocated, the **high_ptr** pointer is set to nil or 0 and **low_ptr** is set to reference the location that holds the band width values.

An instrument may be classified as a vector instrument or as a scalar instrument. A vector instrument is an instrument whose sensors represent multi-value data sets as opposed to a scalar instrument whose sensors represent a set of singular data values. If the data set to be processed is a vector instrument, the user **should not** call the routine **select_sensor** for this data set; otherwise, erroneous center sweep and/or band width values may be computed.

ERRORS

All errors within this routine are returned through the status variable. The include file **ret_codes.h**, which includes all possible return values, should be included so that the mnemonics for the return codes can be referenced. The **ret_codes.h** file is described in section 1H of the IDFS Programmers Manual.

SEE ALSO

file_open	1 R
convert_to_units	1 R
fill_data	2R
fill_discontinuous_data	2R
sweep_data	2R
sweep_discontinuous_data	2R
spin_data	2R
spin_data_pixel	2R
get_data_key	1 R
set_bin_info	2R
set_scan_info	2R
get_version_number	1 R
select_sensor	1 R
create_data_structure	1 R
create_idf_data_structure	1 R
ret_codes	1H
libtrec_idfs	2H

BUGS

None

EXAMPLES

Create the center and band width sweep values for sensor zero for the RTLA virtual instrument, which is part of the RETE instrument/experiment, which is part of the TSS-1 mission, which is identified with the TSS project.

#include "libbase_idfs.h"
#include "ret_codes.h"

```
SDDAS_ULONG data_key;
SDDAS USHORT vnum;
SDDAS_SHORT sensor, status, num_bins, num_converted, bin;
SDDAS_FLOAT *center_ptr, *low_ptr, *high_ptr;
void *idf data ptr;
status = get_data_key ("TSS", "TSS-1", "RETE", "RETE", "RTLA", &data_key);
if (status != ALL OKAY)
{
 printf ("\n Error %d returned by get data key routine.\n", status);
 exit (-1);
 }
get_version_number (&vnum);
status = create_idf_data_structure (&idf_data_ptr);
if (status != ALL OKAY)
{
 printf ("\n Error %d returned by create idf data structure routine.\n",
         status);
 exit (-1);
 }
sensor = 0;
status = center_and_band_values (data_key, "", vnum, idf_data_ptr, sensor, 1, 1,
                                 &center_ptr, &low_ptr, &high_ptr, &num_bins,
                                 &num_converted);
if (status != ALL_OKAY && status != CENTER_CONVERSION)
 printf ("\n Error returned by center and band values.\n");
 exit (-1);
 }
/* Bands are contiguous?
                                                     */
if (high_ptr == NULL)
 for (bin = 0; bin < num_bins; ++bin)
  printf ("low_{ptr} + bin, *(low_{ptr} + bin), *(low_{ptr} + bin + 1));
/* Bands are non-contiguous.
                                                       */
else
 for (bin = 0; bin < num_bins; ++bin)
  printf ("\nlow = %f high = %f", *(low_ptr + bin), *(high_ptr + bin));
```

COLLAPSE_DIMENSIONS

function - collapses data over the requested dimensions for a single data level (unit)

SYNOPSIS

#include "libtrec_idfs.h"
#include "ret_codes.h"
#include "user_defs.h"

SDDAS_SHORT collapse_dimensions (SDDAS_ULONG data_key,

SDDAS_CHAR *exten, SDDAS_USHORT version, SDDAS_SHORT sensor, SDDAS_CHAR *dimen, SDDAS_FLOAT *s_range, SDDAS_FLOAT *e_range, SDDAS_CHAR avg_type, SDDAS_CHAR int_type, SDDAS_FLOAT **ret_data, SDDAS_CHAR cyclic, SDDAS_SHORT order, SDDAS_LONG need_filled, SDDAS_FLOAT tension, SDDAS_CHAR norm_res, SDDAS_CHAR bin_project, SDDAS_CHAR norm_res, SDDAS_CHAR last_plot, SDDAS_CHAR dlevel, SDDAS_CHAR cur_buf)

ARGUMENTS

data_key	-	unique va	lue which indicates the data set of interest
exten	-	two chara	cter extension to be added to IDFS file names when
		default fil	es are not to be used, otherwise a null string
version	-	IDFS data	a set identification number which allows for multiple
		openings	of the same data set
sensor	-	sensor ide	entification number
dimen	-	status flag	g indicator for each possible dimension
s_range	-	-	g range value for each possible dimension
e_range	-		g range value for each possible dimension
avg_type	-		he to use in order to reduce the dimensionality
0 11		of the data	
		1 -	no reduction is to be performed (NO_AVG)
		2 -	a straight average is to be performed
			(STRAIGHT_AVG)
		3 -	a straight integration is to be performed
			(STRAIGHT_INT)
		4 -	a spherical integration is to be performed
			(SPHERICAL_INT)
		5 -	a straight average is to be performed assuming
			the data represents azimuthal angle values
			(STRAIGHT_AVG_AZ)
		6 -	a flux integration is to be performed
			(FLUX_INT)
		7 -	moments computation is to be performed
			(MOMENTS_INT)

int_type	-	 integration scheme to use for calculations 1 - a trapezoidal integration (POINT_INT) 2 - a block integration (BAND_INT)
ret_data	-	pointer to the resultant matrix or value
cyclic	-	flag indicating if the data is cyclic
		0 - data is not cyclic
		1 - data is cyclic
order	-	the order of the fit, i.e. 1, 2, 3, etc.
		- this parameter is used if the bin fill method
		chosen in the call to the set_bin_info
		routine is any value other than NO_BIN_FILL.
need_filled	-	the number of filled bins needed in order to fill in the missing
		data bins
tension	-	the weighting of the data
norm_res	-	flag indicating if the result is to be normalized
		0 - do not normalize the result
		1 - normalize the result
bin_project	-	flag indicating if the data is to be projected into empty bins
		beyond the first or last data bin which contains data
		0 - do not project the data
		1 - project the data
unit_index	-	index value specifying which sub-buffer returned from the
		fill_data / fill_discontinuous_data / sweep_data /
		sweep_discontinuous_data / spin_data / spin_data_pixel
		routine is to be processed
last_plot	-	flag indicating if this call to collapse_dimensions is the last
		call to be made for the combination being processed
		(necessary for reset purposes)
		0 - not the last call for the combination being
		processed
		1 - the last call for the combination being
		processed
dlevel	-	flag indicating if data is to be reduced to a single value or to
		an array of values.
		1 - data to be reduced to a single value.
		2 - data to be reduced to an array of values (sweep
1 0		of values)
cur_buf	-	the current buffer being processed (number between 0 and
collonge dimensione		NUM_BUFFERS-1)
collapse_dimensions	-	routine status (see TABLE 1)

STATUS_CODE	EXPLANATION OF STATUS
CDIMEN_NOT_FOUND	the requested data_key, exten, version combination has no memory allocated
	for processing (user did not call file_open for this combination)
COMPUTE_MOMENTS	the routine moments_computations () must be called when requesting the
	moments integration averaging method
CDIMEN_COLLAPSE	no memory has been allocated to hold the collapsing information (user did not
	call set_collapse_info for this combination)
CDIMEN_MANY_SCAN	the requested data set has more than one scan range defined
CHRG_PA_ERROR	the Straight Average Azimuthal averaging option for the Charge dimension is
	not a valid averaging method
MASS_PA_ERROR	the Straight Average Azimuthal averaging option for the Mass dimension is
	not a valid averaging method
NEG_BIN_STAT	the base buffer has a bin status value that is negative
TRANS_3D_BINNED_MALLOC	no memory has been allocated to hold the normalization factors needed to
	combine those sensors that are mounted at the same theta angles
ALL_OKAY	routine terminated successfully

TABLE 1. Status Codes Returned for COLLAPSE_DIMENSIONS

DESCRIPTION

Collapse_dimensions is the IDFS routine that reduces the dimensionality of the data returned by the time-averaging routine (**fill_data / fill_discontinuous_data**), the sample-averaging routine (**sweep_data / sweep_discontinuous_data**) or the spin-averaging routine (**spin_data_pixel**). The user should process only those buffers that are flagged with the status value BUFFER_READY. The data set of interest is referenced through the key value **data_key** which can be created using the **get_data_key** module. This module **can not** be used in conjunction with the **fill_mode_data / sweep_mode_data** module since dimensionality is associated with sensor-specific data and instrument status data is not sensor-specific.

The parameter **version** allows multiple file openings for an IDFS data set. If the data, header and VIDF file for the specified data set need to be opened just once for processing, the same version number should be passed to all IDFS routines. However, for multiple file openings, the version number should be unique and all file manipulations performed by the IDFS routines will use the file descriptors defined for the version number specified. The user should call the **get_version_number** routine to retrieve a unique version number instead of choosing this value themselves. The retrieval of multiple data parameters from a single data source does not constitute the need for multiple version numbers; a single version number will suffice.

If the **file_open** routine is not to open the default set of IDFS files but a modified set of IDFS files, the two character extension applied to these data files must be supplied to this routine within the string variable **exten**. These files must have the identical name as the IDFS files with the two character identification code appended to the end of the file names (i.e. RTLA19922181432Dxx, RTLA19922181432Hxx, RTLA19922181432Ixx). The files must reside either in the directory specified by the environment variable USER_DATA, which is set by the user, or in the user's home directory if the environment variable USER_DATA is not set. To open the default IDFS data files, **exten** should be set to a null

string. The usage of modified data sets is limited to post acquisition data; therefore, it is suggested that the user set **exten** to a null string for real-time scenarios.

This routine will work on one data level or "unit". If there are many data levels to be processed, there should be multiple calls to this routine, all made after the time-averaging, sample-averaging, or spin-averaging module has been called. The address of the space that holds the result is passed back to the user. This may be a single value or may be an array of values, as indicated by the **dlevel** parameter. The value for the parameter **unit_index** can be retrieved by calling the module **units_index**, with the third argument from the end holding the value to be passed to this module. If no data is present in the data buffer being processed, the module will return the data value(s) -3.4e38 (OUTSIDE_MIN).

The dimensions that are to be collapsed over are specified in the array **dimen**. The **s_range** and **e_range** parameters are arrays that hold the starting and ending ranges to use to reduce the data at each possible dimension. All three arrays are order dependent, with the order as follows:

element 0	range for the scan dimension
element 1	range for the theta dimension
element 2	range for the phi dimension
element 3	range for the mass dimension
element 4	range for the charge dimension
element 5	range for scalar averaging (sensors to be averaged together)

If a given dimension is to be collapsed over, the value within the **dimen** array corresponding to that dimension should be set to one. If the dimension is not be collapsed over, with no impact on the result, the value within the **dimen** array corresponding to the dimension should be set to zero. If the hemisphere assumption factor is to be utilized for a given dimension, the value within the **dimen** array corresponding to that dimension should be set to two. The hemisphere assumption factor is dependent upon the dimension being processed and the scheme (method) selected in order to reduce the dimensionality of the data. The hemisphere assumption factor is not selectable by the user. The hemisphere assumption factors were obtained for each method assuming angular isotropy. The table below summarizes the values used for assumption factors during processing:

TABLE 2.	Hemisphere Assumption Factors	
	1 1	

DIMENSION	STRAIGHT INTEGRATION	SPHERICAL INTEGRATION	FLUX INTEGRATION
CHARGE	n / a	n / a	n /a
MASS	n / a	n / a	n / a
PHI	n / a	2^pi^	2^pi^
THETA	n / a	1	0.5
SCAN	n / a	n / a	n / a

The scalar average selection should be set when an average of the sensor data values for scalar instruments is desired. If the virtual instrument is designed such that there is more

than one scan range defined for all sensors, the error code **CDIMEN_MANY_SCAN** will be returned if any dimension other than the scan dimension is selected.

Before the actual collapsing is performed, the missing bins are filled in according to the method specified with the call to the module **set_bin_info**. The actual reduction of the data can be performed in one of three ways: straight average, straight integration and spherical integration. The straight average is the simplest of the three schemes - a simple average of the data between the start and stop range specified. A special straight average algorithm is provided for azimuthal angle data. This algorithm takes into account the roll over to a minimum value (0°) when the maximum threshold (360°) has been reached or to a maximum value when the minimum threshold has been reached. If a straight average is not appropriate, the data can be reduced by integrating over the range specified. The distinction between a straight and spherical integration is the integration over the sensors. The spherical integration method may be appropriate when the sensors represent discrete theta angular ranges. With the integration reduction, the user may also select the integration using the center of each bin as the integration parameter. For band integration, the bin widths of each bin are used as the integration widths in a rectangular or block integration.

Since missing bins are filled in prior to data reduction, the data matrices must be reset to their original contents prior to the next call to the time-averaging, sample-averaging, or spin-averaging routine in order to utilize the interleave option. In order for the module to know when the data is to be reset, the module examines the contents of the **last_plot** parameter. When the contents is set to a one, the data matrices are restored. This parameter should be set once the last data level is being processed for the data set being requested; otherwise, erroneous calculations will result.

The parameter **avg_type** specifies the method that is to be used to reduce the dimensionality of the data. The range of possible values for the **avg_type** parameter has been expanded since the ability to compute moments has been added to the IDFS data access capabilities. In order to compute the moments value(s), the dimensionality of the data may need to be reduced. However, the data reduction can not be performed by the **collapse_dimensions** routine and is trapped as an error if this function is called. At the present time, the IDFS Programmers Manual does not contain any information regarding the moments computations; however, this information will be added once testing of the moments computation software has been completed.

ERRORS

All errors within this routine are returned through the status variable. The include file **ret_codes.h**, which includes all possible return values, should be included so that the mnemonics for the return codes can be referenced. The **ret_codes.h** file is described in section 1H of the IDFS Programmers Manual.

SEE ALSO

file_open	1 R
fill_data	2R

fill_discontinuous_data	2R
sweep_data	2R
sweep_discontinuous_data	2R
spin_data	2 R
spin_data_pixel	2 R
set_collapse_info	2 R
set_bin_info	2 R
units_index	2 R
get_data_key	1 R
get_version_number	1 R
ret_codes	1H
user_defs	1H
libtrec_idfs	2H

BUGS

None

EXAMPLES

Collapse the data returned for sensor 1 for the virtual instrument RTLA, which is part of the RETE instrument/experiment, which is part of the TSS-1 mission, which is identified with the TSS project. The data is collapsed over the frequency range 0.16 to 0.9 kilohertz using a straight average. Assume that only one data level or unit is returned by the time-averaging, sample-averaging, or spin-averaging routine (default mode) and that **buf_stat** had been set.

#include "libtrec_idfs.h"
#include "ret_codes.h"
#include "user_defs.h"
#define DUMMY_VAL 0

```
SDDAS_ULONG data_key;
SDDAS_USHORT vnum;
SDDAS_SHORT status;
SDDAS_FLOAT *data_ptr, start[6], stop[6];
SDDAS_CHAR dimen[6], cur_buf, buf_num, *buf_stat;
static SDDAS_CHAR which_buf = 0;
```

```
status = get_data_key ("TSS", "TSS-1", "RETE", "RETE", "RTLA", &data_key);
if (status != ALL_OKAY)
{
    printf ("\n Error %d returned by get_data_key routine.\n", status);
    exit (-1);
    get_version_number (&vnum);
```

dimen[0] = 1;

```
start[0] = 0.16;
stop[0] = 0.9;
dimen[1] = dimen[2] = dimen[3] = dimen[4] = dimen[5] = 0;
start[1] = start[2] = start[3] = start[4] = start[5] = 0.0;
stop[1] = stop[2] = stop[3] = stop[4] = stop[5] = 0.0;
cur buf = which buf;
for (buf num = 0; buf num < NUM BUFFERS; ++buf num)
{
 if (*(buf stat + cur buf) == BUFFER READY)
   {
     status = collapse_dimensions (data_key, "", vnum, 1, dimen, start, stop,
                              STRAIGHT_AVG, DUMMY_VAL, &data_ptr, 0, 1, 3,
                              0.0, 1, 1, 0, 1, 1, cur buf);
     if (status != ALL_OKAY)
      {
       printf ("\n Error %d returned by collapse_dimensions routine.\n", status);
       exit (-1);
      }
      which_buf = (cur_buf + 1) % NUM_BUFFERS;
    }
   cur_buf = (cur_buf + 1) % NUM_BUFFERS;
  }
```

FILL_DATA

function - returns time-averaged data buffers for data sets that do not roll over when the minimum/maximum threshold has been reached

SYNOPSIS

#include "libtrec_idfs.h"
#include "ret_codes.h"
#include "user_defs.h"

SDDAS_SHORT fill_data (SDDAS_ULONG data_key, SDDAS_CHAR *exten,
SDDAS_USHORT version, void *idf_data_ptr,
SDDAS_SHORT **ret_sensors, SDDAS_FLOAT **ret_data,
SDDAS_FLOAT **ret_frac, SDDAS_CHAR **bin_stat,
SDDAS_LONG **bpix, SDDAS_LONG **epix,
SDDAS_CHAR **ret_stat, SDDAS_SHORT *num_sen,
SDDAS_SHORT **num_units, SDDAS_SHORT *block_size,
SDDAS_SHORT **stime_yr, SDDAS_SHORT **stime_day,
SDDAS_LONG **stime_sec, SDDAS_LONG **stime_nano,
SDDAS_SHORT **etime_yr, SDDAS_SHORT **etime_day,
SDDAS_LONG **etime_sec, SDDAS_LONG **etime_nano,
SDDAS_CHAR *hdr_change,
SDDAS_UCHAR exclude_dqual)

ARGUMENTS

data_key exten	-	unique value which indicates the data set of interest two character extension to be added to IDFS file names when
exten	-	default files are not to be used, otherwise a null string
version	-	IDFS data set identification number which allows for multiple openings of the same data set
idf_data_ptr	-	pointer to the idf_data structure that temporarily holds
		sensor data and pertinent ancillary data for the data set of
		interest
ret_sensors	-	an array which holds the sensor number(s) for which data is
		returned
		- the array is initialized to -1 in all elements;
		valid sensor numbers start with 0
ret_data	-	pointer to the data being returned (data for all sensors
		processed)
ret_frac	-	pointer to the normalization factors for the data being returned
bin_stat	-	pointer to status flags which are associated with each data bin
		returned
		0 - no data has been placed into the data bin being processed
		1
		1 - data has been placed into the data bin being processed

bpix	-	pointer to the starting pixel location for the data buffers returned		
epix	-	pointer to the ending pixel location for the data buffers returned		
ret_stat	-	pointer to the status of each of the data buffers being returned UNTOUCHED_BUFFER - no data has ever been placed into the buffer		
		FREE_BUFFER - no data has been placed into the buffer being processed (ready for re- use)		
		PARTIAL_WORKING - data is being acquired into the buffer but is not ready for processing		
		BUFFER_READY data has been acquired into the buffer and is ready for processing		
num_sen	-	the number of elements in the ret_sensors array		
num_units	-	an array holding the number of data sets to bypass in order to		
		get to the data for the sensor being processed		
block_size	-	the number of data values returned in a data buffer		
stime_yr	-	pointer to the start time year values for the data buffers returned		
stime_day	-	pointer to the start time day of year values for the data buffers returned		
stime_sec	-	pointer to the start time of day values (in seconds) for the data buffers returned		
stime_nano	-	pointer to the start time of day residuals (in nanoseconds) for the data buffers returned		
etime_yr	-	pointer to the end time year values for the data buffers returned		
etime_day	-	pointer to the end time day of year values for the data buffers returned		
etime_sec	-	pointer to the end time of day values (in seconds) for the data buffers returned		
etime_nano	-	pointer to the end time of day residuals (in nanoseconds) for the data buffers returned		
hdr_change	-	flag which indicates a header change occurred while processing the data		
		0 - a header change was not encountered during the processing of the data		
		1 - a header change was encountered		
1 1 1 1		during the processing of the data		
exclude_dqual	-	data is to be excluded if the d_qual flag associated with the data is set to the value specified		
fill_data	-	routine status (see TABLE 1)		
		D 1 20 2012		

TABLE 1.	Status Codes Returned for FILL_DATA	

STATUS CODE	EXPLANATION OF STATUS
FILL_NOT_FOUND	the requested data_key, exten, version combination has no memory allocated for
	processing (user did not call file_open for this combination)
FILL_ARRAY_MALLOC	no memory for structure which hold information pertinent to the time-averaged
	data
FILL_BASE_TIME_MISSING	the time interval information has not been set (user did not call set_time_values
	for this combination)
FILL_BIN_MISSING	the data binning information has not been allocated (user did not call
	set_bin_info for this combination)
FILL_CENTER_BAND_MISSING	the routine center_and_band_values has not been called prior to calling the
	fill_data routine
FILL_INFO_MALLOC	no memory for data buffer information
FILL_UNITS_MALLOC	no memory to hold the various data levels for the data buffers
FILL_UNITS_REALLOC	no memory for expansion of space to hold the various data levels for the data
	buffers
FILL_SWP_MALLOC	no memory for
FILL_SWP_REALLOC	no memory for expansion of sweep values in specified units
FILL_DATA_MALLOC	no memory for data buffers
FILL_WITH_SWEEP	the modules fill_data and sweep_data cannot be used interchangeably for the
	same data key, extension, version combination
BAD_VFMT	bad format character for variable width bin spacing
NO_EMPTY_BUFFERS	no spare buffers for data accumulation
PHI_DIFF_UNITS	the sensors being processed do not process the same number of data levels
	(units)
FILL_PHI_FIRST	the starting azimuthal angle was not contained within any of the defined phi bins
FILL_PHI_LAST	the ending azimuthal angle was not contained within any of the defined phi bins
	Error codes returned by read_drec ()
	Error codes returned by convert_to_units ()
	Error codes returned by fill_sensor_info ()
ALL_OKAY	routine terminated successfully

DESCRIPTION

Fill_data is the IDFS time-averaging data read routine, retrieving data for all sensors that return data for the time duration being processed. The data set of interest is referenced through the key value **data_key** which can be created using the **get_data_key** module. Fill data processes sensor-specific data only, that is, it processes sensor, sweep step, calibration, data quality, pitch angle, azimuthal angle, spacecraft potential and background data. If the instrument status (mode) data is desired, the user should use the fill mode data routine. Fill data assumes that the data set of interest does not roll over to a minimum value when the maximum threshold has been reached or to a maximum value when the minimum threshold has been reached. This assumption is crucial since multiple samples may be averaged together in a single buffer. If the data set does roll over at the thresholds, the averaging of these samples will probably result in incorrect data values. An example of a roll over data set is longitude data, which resets values to the minimum threshold (-180) when the maximum threshold (180) has been reached. If the data set does roll over, the user should use the **fill discontinuous data** routine. If the data set of interest is a combination of roll over and non-roll over data, for example, longitude data being returned along with science data, the user may use the fill_discontinuous_data module in

December 28, 2012

conjunction with the **fill_data** routine, using the **fill_data** routine to return the non-roll over data values and using the **fill_discontinuous_data** routine to return the roll over data values. In order to do this correctly, the user must make use of multiple version numbers so that the same data files can be opened more than once. That is, use one version number for the non-roll over data and another version number for the roll over data. All IDFS routines that utilize a version number must be called once for each unique version number.

The parameter **version** allows multiple file openings for an IDFS data set. If the data, header and VIDF file for the specified data set need to be opened just once for processing, the same version number should be passed to all IDFS routines. However, for multiple file openings, the version number should be unique and all file manipulations performed by the IDFS routines will use the file descriptors defined for the version number specified. The user should call the **get_version_number** routine to retrieve a unique version number instead of choosing this value themselves. The retrieval of multiple data parameters from a single data source does not constitute the need for multiple version numbers; a single version number will suffice.

The parameter **idf_data_ptr** is a pointer to the structure that is to hold all data pertinent to the data set being processed. The structure is created and the address to this structure is returned when a call to the **create_idf_data_structure** routine is made. The user also has the option of calling the module **create_data_structure**, which determines what type of data structure is needed for the IDFS data set of interest. In most cases, one data structure is sufficient to process any number of distinct data sets. However, if more than one structure is needed, the user may call the **create_idf_data_structure** routine N times to create N instances of the **idf_data** structure. The user must keep track of which pointer to send to the IDFS routines that utilize this structure.

If the **file_open** routine is not to open the default set of IDFS files but a modified set of IDFS files, the two character extension applied to these data files must be supplied to this routine within the string variable **exten**. These files must have the identical name as the IDFS files with the two character identification code appended to the end of the file names (i.e. RTLA19922181432Dxx, RTLA19922181432Hxx, RTLA19922181432Ixx). The files must reside either in the directory specified by the environment variable USER_DATA, which is set by the user, or in the user's home directory if the environment variable USER_DATA is not set. To open the default IDFS data files, **exten** should be set to a null string. The usage of modified data sets is limited to post acquisition data; therefore, it is suggested that the user set **exten** to a null string for real-time scenarios.

This routine will process data one sweep at a time, placing the data into buffers which hold data that is accumulated over a specified time interval. Once the time interval has been processed, the routine will return the data buffers and a status value for each buffer which indicates when the buffer is ready for the user to retrieve. The user **must** call the module **set_time_values** before the **fill_data** module can be called since the **set_time_values** module is used to specify the base time value and reference location and the time interval (delta) to use to accumulate the data. If the **fill_data** routine determines that the **set_time_values** module has not been called, an error code is returned to the user.

Along with the data being returned, there is a starting location and an ending location that is returned for each of the data buffers. The user may use these values as references to the base location specified in the call to the **set_time_values** module. That is, given a base time value, a time interval and a reference location, the **fill_data** routine will return the location of data with respect to time. The user may chose to ignore these values or may use these locations to plot data along an axis that is scaled with respect to time.

There are a constant number of data buffers that are used by the **fill data** module. This number is defined as NUM_BUFFERS in the user_defs.h file. This file is described in section 1H of the IDFS Programmers Manual. These data buffers are utilized in a cyclic nature, with buffer 0 being re-used once buffer NUM_BUFFERS-1 has been filled. The data buffers that are ready to be processed are flagged with the status value BUFFER_READY. For each buffer, there are N many sub-buffers which hold the data in each of the requested data levels or units. The user must process the data contained within these buffers before the next call to the **fill data** module is made since the module will clear out these buffers for re-use. This holds true even when an LOS STATUS or NEXT_FILE_STATUS status code is returned. The data values must be normalized using the normalization factors returned along with the data. Since the buffers are cyclic, the user may wish to keep a variable indicating the last buffer number processed so that the user can start at the time sample left off from the previous call to the fill data module at the next call. It is important to note that there is one status flag per data buffer that is used by all sensors. If the sensors rotate or alternate when data is returned, the result may be that a buffer is flagged as BUFFER_READY but may not contain any data since the data buffers are reset or cleared out upon each call to the **fill_data** module. The user is advised to check the value or values in the **bin_stat** array. If all values are 0, no data was placed into the buffers.

The size and spacing of the data buffers are either defined by the user or by elements contained within the virtual instrument definition document. The user must call the **set_bin_info** module before calling the **fill_data** routine in order to specify how the binning of the data is to occur. In addition, the user must call the **center_and_band_values** module before calling the **fill_data** module. If the **fill_data** routine determines that no binning scheme has been selected, an error code is returned to the user.

The user should be aware that the data buffers that come back from the **fill_data** module are NOT modified as far as missing bins is concerned. If the user wishes to fill in the missing bins according to the method specified in the call to the **set_bin_info** module, the user must call the **buffer_bin_fill** module. If the data are collapsed over specified dimensions, the **buffer_bin_fill** module need not be called.

The default mode for the **fill_data** routine is to return sensor data in raw units (no tables applied) for each of the sensors processed, with data cutoff values set at -3.0e38 (VALID_MIN) and 3.0e38 (VALID_MAX). The user may select the type of data, the units to be returned and the data cutoff values to be applied by calling the **fill_sensor_info** module prior to calling the **fill_data** module. The user should make one call to the

fill_sensor_info module for each sensor that is to be retrieved for each data type/units/data cutoff combination selected.

If the virtual instrument acquires data over the PHI dimension and the user wishes to average the data over a specified phi range, the **fill_data** routine must be used to acquire the phi data matrix. The user must call the module **set_collapse_info** prior to calling the **fill_data** module in order to specify the resolution of the phi bins and to specify if the interleave option is to be utilized when building the phi matrix.

The parameter **exclude_dqual** holds a single value that is compared against the d_qual value found in the header record for the sensor being processed. If the user wishes to exclude data that is flagged with a specific d_qual value, the user should set the **exclude_dqual** value to this specific value. If the user wishes to include all data encountered, the user should set the **exclude_dqual** value to 255.

ERRORS

All errors within this routine are returned through the status variable. The include file **ret_codes.h**, which includes all possible return values, should be included so that the mnemonics for the return codes can be referenced. The **ret_codes.h** file is described in section 1H of the IDFS Programmers Manual.

SEE ALSO

file_open	1R
read_drec	1 R
convert_to_units	1R
set_time_values	2R
fill_discontinuous_data	2R
fill_mode_data	2R
set_bin_info	2R
center_and_band_values	2R
fill_sensor_info	2R
set_collapse_info	2R
buffer_bin_fill	2R
get_data_key	1R
get_version_number	1R
create_data_structure	1 R
create_idf_data_structure	1R
ret_codes	1H
user_defs	1H
libtrec_idfs	2H

BUGS

None

EXAMPLES

Obtain time-averaged data from the virtual instrument RTLA, which is part of the RETE instrument/experiment, which is part of the TSS-1 mission, which is identified with the TSS project.

#include "libtrec_idfs.h"
#include "ret_codes.h"

```
SDDAS_ULONG data_key;
SDDAS_USHORT vnum;
SDDAS_FLOAT *ret_data, *ret_frac;
SDDAS LONG *start time sec, *start time nano, *end time sec, *end time nano;
SDDAS_LONG *bpix, *epix;
SDDAS_SHORT *start_time_yr, *start_time_day, *end_time_yr, *end_time_day;
SDDAS_SHORT status, *sen_numbers, num_sen, *num_units, data_block;
SDDAS_CHAR *ret_bin, hdr_change, *buf_stat;
void *idf_data_ptr;
status = get_data_key ("TSS", "TSS-1", "RETE", "RETE", "RTLA", &data_key);
if (status != ALL OKAY)
{
  printf ("\n Error %d returned by get data key routine.\n", status);
  exit (-1);
ł
get_version_number (&vnum);
status = create_idf_data_structure (&idf_data_ptr);
if (status != ALL OKAY)
{
  printf ("\n Error %d returned by create idf data structure routine.\n", status);
  exit (-1);
}
status = fill_data (data_key, '''', vnum, idf_data_ptr, &sen_numbers, &ret_data,
                &ret_frac, &ret_bin, &bpix, &epix, &buf_stat, &num_sen,
                &num_units, &data_block, &start_time_yr, &start_time_day,
                &start time sec, &start time nano, &end time yr, &end time day,
                &end_time_sec, &end_time_nano, &hdr_change, 255);
if (status != ALL_OKAY)
ł
  printf ("\n Error %d returned by fill_data routine.\n", status);
  exit (-1);
}
```

fill_data (2R)

FILL_DATA_ENVELOPE

function - returns the data envelope (minimum and maximum values) for the time interval being processed

SYNOPSIS

#include "libtrec_idfs.h"
#include "ret_codes.h"
#include "user_defs.h"

SDDAS_SHORT fill_data_envelope (SDDAS_ULONG data_key, SDDAS_CHAR *exten,
SDDAS_USHORT version, void *idf_data_ptr,
SDDAS_SHORT **ret_sensors, SDDAS_FLOAT **ret_min,
SDDAS_FLOAT **ret_max, SDDAS_CHAR **bin_stat,
SDDAS_LONG **bpix, SDDAS_LONG **epix,
SDDAS_CHAR **buf_stat, SDDAS_SHORT *num_sen,
SDDAS_SHORT **num_units, SDDAS_SHORT *block_size,
SDDAS_SHORT **stime_yr, SDDAS_SHORT **stime_day,
SDDAS_LONG **stime_sec, SDDAS_LONG **stime_nano,
SDDAS_SHORT **etime_yr, SDDAS_SHORT **etime_day,
SDDAS_LONG **etime_sec, SDDAS_LONG **etime_nano,
SDDAS_CHAR *hdr_change,
SDDAS_UCHAR exclude_dqual)

ARGUMENTS

-	unique value which indicates the data set of interest two character extension to be added to IDFS file names when default files are not to be used, otherwise a null string
-	IDFS data set identification number which allows for multiple openings of the same data set
-	pointer to the idf_data structure that temporarily holds sensor data and pertinent ancillary data for the data set of interest
-	an array which holds the sensor number(s) for which data is returned
	- the array is initialized to -1 in all elements; valid sensor numbers start with 0
-	pointer to the minimum data value encountered for the buffer(s) returned
-	pointer to the maximum data value encountered for the buffer(s) returned
-	pointer to status flags which are associated with each data bin returned
	0 - no data has been placed into the data bin being processed
	1 - data has been placed into the data bin being processed
	-

bpix	-	pointer to the starting pixel location returned	for the data buffers
epix	-	pointer to the ending pixel location f returned	or the data buffers
buf_stat	-	pointer to the status of each of the da UNTOUCHED_BUFFER -	no data has ever been placed into the buffer
		FREE_BUFFER -	no data has been placed into the buffer being processed (ready for re- use)
		PARTIAL_WORKING -	data is being acquired into the buffer but is not ready for processing
		BUFFER_READY	data has been acquired into the buffer and is
num con		the number of elements in the ret_se	ready for processing
num_sen num_units	-	an array holding the number of data	-
num_umts	-	get to the data for the sensor being p	• •
block_size	_	the number of data values returned in	
stime_yr	_	pointer to the start time year values f	
stime_yr		returned	for the data burlets
stime_day	-	pointer to the start time day of year v returned	values for the data buffers
stime_sec	-	pointer to the start time of day value buffers returned	s (in seconds) for the data
stime_nano	-	pointer to the start time of day residu the data buffers returned	
etime_yr	-	pointer to the end time year values for returned	
etime_day	-	pointer to the end time day of year v returned	
etime_sec	-	pointer to the end time of day values buffers returned	
etime_nano	-	pointer to the end time of day residu the data buffers returned	
hdr_change	-	flag which indicates a header change processing the data	e occurred while
		1 0	not encountered during
		the processing of the	
		1 - a header change was	
		during the processing	
exclude_dqual	-	data is to be excluded if the d_qual f	
		data is set to the value specified	
fill_data_envelope	-	routine status (see TABLE 1)	
		220	December 28, 2012

TABLE 1. Stat	us Codes Returned	l for FILL_DA T	A_ENVELOPE
----------------------	-------------------	------------------------	------------

STATUS CODE	EXPLANATION OF STATUS
FILL_ENV_NOT_FOUND	the requested data_key, exten, version combination has no memory
	allocated for processing (user did not call file_open for this combination)
FILL_ENV_SCALAR	the requested data source is non-scalar
FILL_ARRAY_MALLOC	no memory for structure which hold information pertinent to the time-
	rectified data
FILL_ENV_BASE_TIME_MISSING	the time interval information has not been set (user did not call
	set_time_values for this combination)
FILL_ENV_BIN_MISSING	the data binning information has not been allocated (user did not call
	set_bin_info for this combination)
FILL_ENV_CENTER_BAND_MISSING	the routine center_and_band_values has not been called prior to calling
	the fill_data_envelope routine
FILL_INFO_MALLOC	no memory for data buffer information
FILL_UNITS_MALLOC	no memory to hold the various data levels for the data buffers
FILL_UNITS_REALLOC	no memory for expansion of space to hold the various data levels for the
	data buffers
FILL_SWP_MALLOC	no memory for sweep values in specified units
FILL_SWP_REALLOC	no memory for expansion of sweep values in specified units
FILL_DATA_MALLOC	no memory for data buffers
FILL_ENV_WITH_SWEEP	the modules fill_data_envelope and sweep_data cannot be used
	interchangeably for the same data key, extension, version combination
BAD_VFMT	bad format character for variable width bin spacing
PHI_DIFF_UNITS	the sensors being processed do not process the same number of data levels
	(units)
FILL_PHI_FIRST	the starting azimuthal angle was not contained within any of the defined
	phi bins
FILL_PHI_LAST	the ending azimuthal angle was not contained within any of the defined
	phi bins
NO_EMPTY_BUFFERS	no spare buffers for data accumulation
	Error codes returned by read_drec ()
	Error codes returned by convert_to_units ()
	Error codes returned by fill_sensor_info ()
ALL_OKAY	routine terminated successfully

DESCRIPTION

Fill_data_envelope is the IDFS data read routine which returns the minimum and maximum data values encountered for the time duration being processed. Fill_data_envelope retrieves data for all sensors that return data for the time duration being processed. The data set of interest is referenced through the key value data_key which can be created using the get_data_key module. Fill_data_envelope processes sensor-specific data only, that is, it processes sensor, sweep step, calibration, data quality, pitch angle, azimuthal angle, spacecraft potential and background data. Currently, there is no similar module defined to return the data envelope encountered for instrument status (mode) data.

The parameter **version** allows multiple file openings for an IDFS data set. If the data, header and VIDF file for the specified data set need to be opened just once for processing, the same version number should be passed to all IDFS routines. However, for multiple file openings, the version number should be unique and all file manipulations performed by the

IDFS routines will use the file descriptors defined for the version number specified. The user should call the **get_version_number** routine to retrieve a unique version number instead of choosing this value themselves. The retrieval of multiple data parameters from a single data source does not constitute the need for multiple version numbers; a single version number will suffice.

The parameter **idf_data_ptr** is a pointer to the structure that is to hold all data pertinent to the data set being processed. The structure is created and the address to this structure is returned when a call to the **create_idf_data_structure** routine is made. The user also has the option of calling the module **create_data_structure**, which determines what type of data structure is needed for the IDFS data set of interest. In most cases, one data structure is sufficient to process any number of distinct data sets. However, if more than one structure is needed, the user may call the **create_idf_data_structure** routine N times to create N instances of the **idf_data** structure. The user must keep track of which pointer to send to the IDFS routines that utilize this structure.

If the **file_open** routine is not to open the default set of IDFS files but a modified set of IDFS files, the two character extension applied to these data files must be supplied to this routine within the string variable **exten**. These files must have the identical name as the IDFS files with the two character identification code appended to the end of the file names (i.e. RTLA19922181432Dxx, RTLA19922181432Hxx, RTLA19922181432Ixx). The files must reside either in the directory specified by the environment variable USER_DATA, which is set by the user, or in the user's home directory if the environment variable USER_DATA is not set. To open the default IDFS data files, **exten** should be set to a null string. The usage of modified data sets is limited to post acquisition data; therefore, it is suggested that the user set **exten** to a null string for real-time scenarios.

This routine will process data one sweep at a time, placing the data into buffers which hold data that is accumulated over a specified time interval. Once the time interval has been processed, the routine will return the data buffers and a status value for each buffer which indicates when the buffer is ready for the user to retrieve. The user **must** call the module **set_time_values** before the **fill_data_envelope** module can be called since the **set_time_values** module is used to specify the base time value and reference location and the time interval (delta) to use to accumulate the data. If the **fill_data_envelope** routine determines that the **set_time_values** module has not been called, an error code is returned to the user.

Along with the data envelope being returned, there is a starting location and an ending location that is returned for each of the data buffers. The user may use these values as references to the base location specified in the call to the **set_time_values** module. That is, given a base time value, a time interval and a reference location, the **fill_data_envelope** routine will return the location of data with respect to time. The user may choose to ignore these values or may use these locations to plot data along an axis that is scaled with respect to time.

There are a constant number of data buffers that are used by the **fill data envelope** module. This number is defined as NUM BUFFERS in the user defs.h file. This file is described in section 1H of the IDFS Programmers Manual. These data buffers are utilized in a cyclic nature, with buffer 0 being re-used once buffer NUM_BUFFERS-1 has been filled. The data buffers that are ready to be processed are flagged with the status value BUFFER READY. For each buffer, there are N many sub-buffers which hold the data in each of the requested data levels or units. The user must process the data contained within these buffers before the next call to the fill data envelope routine is made since the module will clear out these buffers for re-use. This holds true even when an LOS_STATUS or NEXT FILE STATUS status code is returned. Since the buffers are cyclic, the user may wish to keep a variable indicating the last buffer number processed so that the user can start at the time sample left off from the previous call to the **fill data envelope** module at the next call. It is important to note that there is one status flag per data buffer that is used by all sensors. If the sensors rotate or alternate when data is returned, the result may be that a buffer is flagged as BUFFER READY but may not contain any data since the data buffers are reset or cleared out upon each call to the fill_data_envelope module. The user is advised to check the value or values in the **bin stat** array. If all values are 0, no data was placed into the buffers.

The size and spacing of the data buffers are either defined by the user or by elements contained within the virtual instrument definition document. The user must call the **set_bin_info** module before calling the **fill_data_envelope** routine in order to specify how the binning of the data is to occur. If the **fill_data_envelope** routine determines that no binning scheme has been selected, an error code is returned to the user.

The default mode for the **fill_data_envelope** routine is to return sensor data in raw units (no tables applied) for each of the sensors processed, with data cutoff values set at -3.0e38 (VALID_MIN) and 3.0e38 (VALID_MAX). The user may select the type of data, the units to be returned and the data cutoff values to be applied by calling the **fill_sensor_info** module prior to calling the **fill_data_envelope** module. The user should make one call to the **fill_sensor_info** module for each sensor that is to be retrieved for each data type/units/data cutoff combination selected.

Unlike the module **fill_data**, **fill_data_envelope** has no provisions for the averaging of the data returned since the data source must be a scalar source. In other words, there is no allowance for the collapsing of the data over data dimensions (refer to **set_collapse_info** if this statement is unclear). In addition, since the data source must be a scalar source, there is only one bin defined per data buffer; therefore, data is either returned or not returned. There are no provisions made to fill in missing bins since there is only one bin defined (refer to **buffer_bin_fill** if this statement is unclear).

The parameter **exclude_dqual** holds a single value that is compared against the d_qual value found in the header record for the sensor being processed. If the user wishes to exclude data that is flagged with a specific d_qual value, the user should set the **exclude_dqual** value to this specific value. If the user wishes to include all data encountered, the user should set the **exclude_dqual** value to 255.

ERRORS

All errors within this routine are returned through the status variable. The include file **ret_codes.h**, which includes all possible return values, should be included so that the mnemonics for the return codes can be referenced. The **ret_codes.h** file is described in section 1H of the IDFS Programmers Manual.

SEE ALSO

file_open	1 R
read_drec	1 R
convert_to_units	1 R
set_time_values	2R
set_bin_info	2R
fill_sensor_info	2R
get_data_key	1 R
get_version_number	1 R
create_data_structure	1 R
create_idf_data_structure	1 R
ret_codes	1H
user_defs	1H
libtrec_idfs	2H

BUGS

None

EXAMPLES

Obtain the data envelope for the virtual instrument RTLA, which is part of the RETE instrument/experiment, which is part of the TSS-1 mission, which is identified with the TSS project.

#include "libtrec_idfs.h"
#include "ret_codes.h"

SDDAS_ULONG data_key; SDDAS_USHORT vnum; SDDAS_FLOAT *ret_min, *ret_max; SDDAS_LONG *start_time_sec, *start_time_nano, *end_time_sec, *end_time_nano; SDDAS_LONG *bpix, *epix; SDDAS_SHORT *start_time_yr, *start_time_day, *end_time_yr, *end_time_day; SDDAS_SHORT status, *sen_numbers, num_sen, *num_units, data_block; SDDAS_CHAR *ret_bin, hdr_change, *buf_stat; void *idf_data_ptr;

status = get_data_key ("TSS", "TSS-1", "RETE", "RETE", "RTLA", &data_key);

```
if (status != ALL_OKAY)
{
  printf ("\n Error %d returned by get_data_key routine.\n", status);
  exit (-1);
 }
get_version_number (&vnum);
status = create idf data structure (&idf data ptr);
if (status != ALL OKAY)
{
  printf ("\n Error %d returned by create_idf_data_structure routine.\n", status);
  exit (-1);
 }
status = fill_data_envelope (data_key, '''', vnum, idf_data_ptr, &sen_numbers,
                &ret_min, &ret_max, &ret_bin, &bpix, &epix, &buf_stat,
                &num_sen, &num_units, &data_block, &start_time_yr,
                &start_time_day, &start_time_sec, &start_time_nano,
                &end_time_yr, &end_time_day, &end_time_sec, &end_time_nano,
                &hdr_change, 255);
if (status != ALL OKAY)
{
   printf ("\n Error %d returned by fill_data_envelope routine.\n", status);
  exit (-1);
 }
```

FILL_DISCONTINUOUS_DATA

function - returns time-averaged data buffers for data sets that roll over to a minimum value when the maximum threshold has been reached

SYNOPSIS

#include "libtrec_idfs.h"
#include "ret_codes.h"
#include "user_defs.h"

SDDAS_SHORT fill_discontinuous_data (SDDAS_ULONG data_key,

SDDAS_CHAR *exten, SDDAS_USHORT version,
<pre>void *idf_data_ptr, SDDAS_SHORT **ret_sensors,</pre>
SDDAS_FLOAT **ret_data, SDDAS_FLOAT **ret_frac,
SDDAS_CHAR **bin_stat, SDDAS_LONG **bpix,
SDDAS_LONG **epix, SDDAS_CHAR **ret_stat,
SDDAS_SHORT *num_sen, SDDAS_SHORT **num_units,
SDDAS_SHORT *block_size, SDDAS_SHORT **stime_yr,
SDDAS_SHORT **stime_day, SDDAS_LONG **stime_sec,
SDDAS_LONG **stime_nano, SDDAS_SHORT **etime_yr,
SDDAS_SHORT **etime_day, SDDAS_LONG **etime_sec,
SDDAS_LONG **etime_nano, SDDAS_CHAR *hdr_change,
SDDAS_UCHAR exclude_dqual)

ARGUMENTS

data_key	-	unique value which indicates the data set of interest
exten	-	two character extension to be added to IDFS file names when default files are not to be used, otherwise a null string
version	-	IDFS data set identification number which allows for multiple openings of the same data set
idf_data_ptr	-	pointer to the idf_data structure that temporarily holds sensor data and pertinent ancillary data for the data set of interest
ret_sensors	-	 an array which holds the sensor number(s) for which data is returned the array is initialized to -1 in all elements; valid sensor numbers start with 0
ret_data	-	pointer to the data being returned (data for all sensors processed)
ret_frac	-	pointer to the normalization factors for the data being returned
bin_stat	-	pointer to status flags which are associated with each data bin returned 0 - no data has been placed into the data bin being processed

		1 - data has been placed into the data bin
bpix	-	being processed pointer to the starting pixel location for the data
epix	-	buffers returned pointer to the ending pixel location for the data buffers
ret_stat	-	returned pointer to the status of each of the data buffers being
		returned
		UNTOUCHED_BUFFER - no data has ever been placed into the buffer
		FREE_BUFFER - no data has been placed into the buffer being processed (ready
		processed (ready for re-use) PARTIAL_WORKING - data is being
		acquired into the buffer but is not ready for
		BUFFER_READY - data has been acquired into the buffer and is
		ready for processing
num_sen	-	the number of elements in the ret_sensors array
num_units	-	an array holding the number of data sets to bypass in
block size		order to get to the data for the sensor being processed the number of data values returned in a data buffer
block_size	-	
stime_yr	-	pointer to the start time year values for the data buffers returned
stime_day	-	pointer to the start time day of year values for the data buffers returned
stime_sec	-	pointer to the start time of day values (in seconds) for the data buffers returned
stime_nano	-	pointer to the start time of day residuals (in nanoseconds) for the data buffers returned
etime_yr	_	pointer to the end time year values for the data buffers
<u>-</u> j-		returned
etime_day	-	pointer to the end time day of year values for the data buffers returned
etime_sec	-	pointer to the end time of day values (in seconds) for the data buffers returned
etime_nano	-	pointer to the end time of day residuals (in nanoseconds) for the data buffers returned
		228 December 28, 2012

hdr_change	-	flag which indicates a header change occurred while
		processing the data
		0 - a header change was not encountered
		during the processing of the data
		1 - a header change was encountered
		during the processing of the data
exclude_dqual	-	data is to be excluded if the d_qual flag associated
		with the data is set to the value specified
fill_discontinuous_data	-	routine status (see TABLE 1)

TABLE 1. Status Code Returned for FILL_DISCONTINUOUS_DATA

STATUS CODE	EXPLANATION OF STATUS
FILL_DISC_NOT_FOUND	the requested data_key, exten, version combination has no memory
	allocated for processing (user did not call file_open for this combination)
FILL_DISC_BASE_TIME_MISSING	the time interval information has not been set (user did not call
	set_time_values for this combination
FILL_DISC_BIN_MISSING	The data binning information has not been allocated (user did not call
	set_bin_info for this combination)
FILL_DISC_CENTER_BAND_MISSING	the routine center_and_band_values has not been called prior to calling
	the fill_discontinuous_data routine
FILL_DISC_NO_PHI	data sets with PHI, MASS and/or CHARGE dimensions are not supported
FILL_ARRAY_MALLOC	no memory for structure which hold information pertinent to the time-
	averaged data
FILL_DISC_MALLOC	no memory for structure which hold information pertinent to
	discontinuous data sets
FILL_INFO_MALLOC	no memory for data buffer information
FILL_UNITS_MALLOC	no memory to hold the various data levels for the data buffers
FILL_UNITS_REALLOC	no memory for expansion of space to hold the various data levels for the
	data buffers
FILL_SWP_MALLOC	no memory for sweep values in specified units
FILL_SWP_REALLOC	no memory for expansion of sweep values in specified units
FILL_DATA_MALLOC	no memory for data buffers
SWEEP_INFO_MALLOC	no memory for data buffer information
SWEEP_UNITS_MALLOC	no memory to hold the various data levels for the data buffer
SWEEP_UNITS_REALLOC	no memory for expansion of space to hold the various data levels for the
	data buffer
SWEEP_SWP_MALLOC	no memory for sweep values in specified units
SWEEP_SWP_REALLOC	no memory for expansion of sweep values in specified units
SWEEP_DATA_MALLOC	no memory for data buffer
DISC_DATA_MALLOC	no memory for the internal data buffers that are pertinent only to
	discontinuous data sets
FILL_WITH_SWEEP_DISC	the modules fill_discontinuous_data and sweep_discontinuous_data
	cannot be used interchangeably for the same data key, extension, version
	combination.
BAD_VFMT	bad format character for variable width bin spacing
DISC_TMP_MALLOC	no memory for scratch space utilized to process discontinuous data sets
NO_EMPTY_BUFFERS	no spare buffers for data accumulation
	Error codes returned by read_drec ()
	Error codes returned by convert_to_units ()
	Error codes returned by fill_sensor_info ()

STATUS CODE	EXPLANATION OF STATUS
ALL_OKAY	routine terminated successfully

DESCRIPTION

Fill discontinuous data is the IDFS time-averaging data read routine, retrieving data for all sensors that return data for the time duration being processed. The data set of interest is referenced through the key value **data key** which can be created using the **get data key** module. Fill_discontinuous_data processes sensor-specific data only, that is, it processes sensor, sweep step, calibration, data quality, pitch angle, azimuthal angle, spacecraft potential and background data. If the instrument status (mode) data is desired, the user should use the fill_mode_data routine. Fill_discontinuous_data assumes that the data set of interest rolls over to a minimum value when the maximum threshold has been reached or to a maximum value when the minimum threshold has been reached. This assumption is crucial since multiple samples may be averaged together in a single buffer. Before each sample is added to the buffer, a check is made to see if a "boundary" or threshold has been crossed. If so, the value is adjusted so that the addition of the values result in a correct averaged value. Currently, these threshold values are preset at -180 (minimum threshold) and 180 (maximum threshold). If the data set **does not** roll over, the user should use the fill data routine. If the data set of interest is a combination of roll over and non-roll over data, for example, longitude data being returned along with science data, the user may use the fill_discontinuous_data module in conjunction with the fill_data routine, using the to return the non-roll over data values fill data routine and using the fill discontinuous data routine to return the roll over data values. In order to do this correctly, the user must make use of multiple version numbers so that the same data files can be opened more than once. That is, use one version number for the non-roll over data and another version number for the roll over data. All IDFS routines that utilize a version number must be called once for each unique version number.

The parameter **version** allows multiple file openings for an IDFS data set. If the data, header and VIDF file for the specified data set need to be opened just once for processing, the same version number should be passed to all IDFS routines. However, for multiple file openings, the version number should be unique and all file manipulations performed by the IDFS routines will use the file descriptors defined for the version number specified. The user should call the **get_version_number** routine to retrieve a unique version number instead of choosing this value themselves. The retrieval of multiple data parameters from a single data source does not constitute the need for multiple version numbers; a single version number will suffice.

The parameter **idf_data_ptr** is a pointer to the structure that is to hold all data pertinent to the data set being processed. The structure is created and the address to this structure is returned when a call to the **create_idf_data_structure** routine is made. The user also has the option of calling the module **create_data_structure**, which determines what type of data structure is needed for the IDFS data set of interest. In most cases, one data structure is sufficient to process any number of distinct data sets. However, if more than one structure is needed, the user may call the **create_idf_data_structure** routine N times to create N

instances of the **idf_data** structure. The user must keep track of which pointer to send to the IDFS routines that utilize this structure.

If the **file_open** routine is not to open the default set of IDFS files but a modified set of IDFS files, the two character extension applied to these data files must be supplied to this routine within the string variable **exten**. These files must have the identical name as the IDFS files with the two character identification code appended to the end of the file names (i.e. RTLA19922181432Dxx, RTLA19922181432Hxx, RTLA19922181432Ixx). The files must reside either in the directory specified by the environment variable USER_DATA, which is set by the user, or in the user's home directory if the environment variable USER_DATA is not set. To open the default IDFS data files, **exten** should be set to a null string. The usage of modified data sets is limited to post acquisition data; therefore, it is suggested that the user set **exten** to a null string for real-time scenarios.

This routine will process data one sweep at a time, placing the data into buffers which hold data that is accumulated over a specified time interval. Once the time interval has been processed, the routine will return the data buffers and a status value for each buffer which indicates when the buffer is ready for the user to retrieve. The user **must** call the module **set_time_values** before the **fill_discontinuous_data** module can be called since the **set_time_values** module is used to specify the base time value and reference location and the time interval (delta) to use to accumulate the data. If the **fill_discontinuous_data** routine determines that the **set_time_values** module has not been called, an error code is returned to the user.

Along with the data being returned, there is a starting location and an ending location that is returned for each of the data buffers. The user may use these values as references to the base location specified in the call to the **set_time_values** module. That is, given a base time value, a time interval and a reference location, the **fill_discontinuous_data** routine will return the location of data with respect to time. The user may chose to ignore these values or may use these locations to plot data along an axis that is scaled with respect to time.

There are a constant number of data buffers that are used by the **fill_discontinuous_data** module. This number is defined as NUM_BUFFERS in the **user_defs.h** file. This file is described in section 1H of the IDFS Programmers Manual. These data buffers are utilized in a cyclic nature, with buffer 0 being re-used once buffer NUM_BUFFERS-1 has been filled. The data buffers that are ready to be processed are flagged with the status value BUFFER_READY. For each buffer, there are N many sub-buffers which hold the data in each of the requested data levels or units. The user must process the data contained within these buffers before the next call to the **fill_discontinuous_data** routine is made since the module will clear out these buffers for re-use. This holds true even when an LOS_STATUS or NEXT_FILE_STATUS status code is returned. The data values must be normalized using the normalization factors returned along with the data. Since the buffers are cyclic, the user may wish to keep a variable indicating the last buffer number processed so that the user can start at the time sample left off from the previous call to the **fill_discontinuous_data** routine that there is one status flag per data buffer that is used by all sensors. If the sensors rotate or alternate when

December 28, 2012

data is returned, the result may be that a buffer is flagged as BUFFER_READY but may not contain any data since the data buffers are reset or cleared out upon each call to the **fill_discontinuous_data** module. The user is advised to check the value or values in the **bin_stat** array. If all values are 0, no data was placed into the buffers.

The size and spacing of the data buffers are either defined by the user or by elements contained within the virtual instrument definition document. The user must call the **set_bin_info** module before calling the **fill_discontinuous_data** routine in order to specify how the binning of the data is to occur. In addition, the user must call the **center_and_band_values** module before calling the **fill_discontinuous_data** module. If the **fill_discontinuous_data** routine determines that no binning scheme has been selected, an error code is returned to the user.

The user should be aware that the data buffers that come back from the **fill_discontinuous_data** module are NOT modified as far as missing bins is concerned. If the user wishes to fill in the missing bins according to the method specified in the call to the **set_bin_info** routine, the user must call the module **buffer_bin_fill**. If the data are collapsed over specified dimensions, the **buffer_bin_fill** module need not be called. The user should be advised that the **fill_discontinuous_data** routine can not process data sets with a PHI, MASS and/or CHARGE dimensionality.

The default mode for the **fill_discontinuous_data** routine is to return sensor data in raw units (no tables applied) for each of the sensors processed, with data cutoff values set at -3.0e38 (VALID_MIN) and 3.0e38 (VALID_MAX). The user may select the type of data, the units to be returned and the data cutoff values to be applied by calling the **fill_sensor_info** module prior to calling the **fill_discontinuous_data** module. The user should make one call to the **fill_sensor_info** module for each sensor that is to be retrieved for each data type/units/data cutoff combination selected.

The parameter **exclude_dqual** holds a single value that is compared against the d_qual value found in the header record for the sensor being processed. If the user wishes to exclude data that is flagged with a specific d_qual value, the user should set the **exclude_dqual** value to this specific value. If the user wishes to include all data encountered, the user should set the **exclude_dqual** value to 255.

ERRORS

All errors within this routine are returned through the status variable. The include file **ret_codes.h**, which includes all possible return values, should be included so that the mnemonics for the return codes can be referenced. The **ret_codes.h** file is described in section 1H of the IDFS Programmers Manual.

SEE ALSO

1 R
1R
1 R
2R

fill_data	2R
fill_mode_data	2R
set_bin_info	2R
center_and_band_values	2R
fill_sensor_info	2R
buffer_bin_fill	2R
get_data_key	1 R
get_version_number	1 R
create_data_structure	1 R
create_idf_data_structure	1 R
ret_codes	1H
user_defs	1H
libtrec_idfs	2H

BUGS

None

EXAMPLES

Obtain time-averaged data from the virtual instrument RTLA, which is part of the RETE instrument/experiment, which is part of the TSS-1 mission, which is identified with the TSS project.

#include "libtrec_idfs.h"
#include "ret_codes.h"

SDDAS_ULONG data_key; SDDAS_USHORT vnum; SDDAS_FLOAT *ret_data, *ret_frac; SDDAS_LONG *start_time_sec, *start_time_nano, *end_time_sec, *end_time_nano; SDDAS_LONG *bpix, *epix; SDDAS_SHORT *start_time_yr, *start_time_day, *end_time_yr, *end_time_day; SDDAS_SHORT *start_time_yr, *start_time_day, *end_time_yr, *end_time_day; SDDAS_SHORT *status, *sen_numbers, num_sen, *num_units, data_block; SDDAS_CHAR *ret_bin, hdr_change, *buf_stat; void *idf_data_ptr;

```
status = get_data_key ("TSS", "TSS-1", "RETE", "RETE", "RTLA", &data_key);
if (status != ALL_OKAY)
{
    printf ("\n Error %d returned by get_data_key routine.\n", status);
    exit (-1);
    get_version_number (&vnum);
```

```
status = create_idf_data_structure (&idf_data_ptr);
if (status != ALL OKAY)
{
 printf ("\n Error %d returned by create_idf_data_structure routine.\n",
       status);
 exit (-1);
 }
status = fill_discontinuous_data (data_key, '''', vnum, idf_data_ptr, &sen_numbers,
                &ret_data, &ret_frac, &ret_bin, &bpix, &epix, &buf_stat,
                &num_sen, &num_units, &data_block, &start_time_yr,
                &start_time_day,&start_time_sec, &start_time_nano, &end_time_yr,
                &end_time_day,&end_time_sec, &end_time_nano, &hdr_change,
                255);
if (status != ALL_OKAY)
{
 printf ("\n Error %d returned by fill_discontinuous_data routine.\n", status);
 exit (-1);
 }
```

FILL_MODE_DATA

function - returns time-averaged buffers for instrument status (mode) data

SYNOPSIS

#include "libtrec_idfs.h"
#include "ret_codes.h"
#include "user_defs.h"

S	SDDAS_SHORT fill	SD voi SD SD SD SD SD SD SD	_data (SDDAS_ULONG data_key, DAS_CHAR *exten, SDDAS_USHORT version, id *idf_data_ptr, SDDAS_SHORT **ret_modes, DAS_FLOAT **ret_data, SDDAS_FLOAT **ret_frac, DAS_CHAR **bin_stat, SDDAS_LONG **bpix, DAS_LONG **epix, SDDAS_CHAR **ret_stat, DAS_SHORT *num_modes, SDDAS_SHORT **num_units, DAS_SHORT *block_size, SDDAS_SHORT **stime_yr, DAS_SHORT *stime_day, SDDAS_LONG **stime_sec, DAS_LONG **stime_nano, SDDAS_SHORT **etime_yr, DAS_LONG **stime_nano, SDDAS_LONG **etime_sec, DAS_LONG **stime_nano, SDDAS_LONG **etime_sec, DAS_LONG **etime_nano, SDDAS_CHAR *hdr_change, DAS_UCHAR exclude_dqual)
ARGUN	MENTS		
	lata_key	-	unique value which indicates the data set of interest
	exten	-	two character extension to be added to IDFS file names when
			default files are not to be used, otherwise a null string
۲	version	-	IDFS data set identification number which allows for
			multiple openings of the same data set
i	.df_data_ptr	-	pointer to the idf_data structure that temporarily holds
			sensor data and pertinent ancillary data for the data set of
	_		interest
r	ret_modes	-	an array which holds the instrument status (mode) bytes for
			which data is returned
			- the array is initialized to -1 in all elements; valid mode numbers start with 0
r	et_data		pointer to the data being returned (data for all modes
1	et_uata	-	processed)
r	ret_frac	_	pointer to the normalization factors for the data being returned
	oin_stat	-	pointer to status flags which are associated with each data bin
			returned
			0 - no data has been placed into the data bin being
			processed
			1 - data has been placed into the data bin being
-			processed
ł	opix	-	pointer to the starting pixel location for the data buffers
			returned

epix	-	pointer to the ending pixel location for the data buffers returned
ret_stat	-	pointer to the status of each of the data buffers being returned UNTOUCHED_BUFFER - no data has ever been placed into the buffer FREE_BUFFER - no data has been placed
		into the buffer being processed (ready for re- use)
		PARTIAL_WORKING - data is being acquired into the buffer but is not ready for processing
		BUFFER_READY data has been acquired into the buffer and is ready for processing
num_modes	-	the number of elements in the ret_modes array
num_units	-	an array holding the number of data sets to bypass in order to get to the data for the instrument status (mode) value being processed
block_size	-	the number of data values returned in a data buffer
stime_yr	-	pointer to the start time year values for the data buffers returned
stime_day	-	pointer to the start time day of year values for the data buffers returned
stime_sec	-	pointer to the start time of day values (in seconds) for the data buffers returned
stime_nano	-	pointer to the start time of day residuals (in nanoseconds) for the data buffers returned
etime_yr	-	pointer to the end time year values for the data buffers returned
etime_day	-	pointer to the end time day of year values for the data buffers returned
etime_sec	-	pointer to the end time of day values (in seconds) for the data buffers returned
etime_nano	-	pointer to the end time of day residuals (in nanoseconds) for the data buffers returned
hdr_change	-	flag which indicates a header change occurred while processing the data
		0 - a header change was not encountered during the processing of the data
		1 - a header change was encountered
		during the processing of the data
exclude_dqual	-	data is to be excluded if the d_qual flag associated with the data is set to the value specified
fill_mode_data	-	routine status (see TABLE 1)

STATUS CODE	EXPLANATION OF STATUS
FILL_MODE_NOT_FOUND	the requested data_key, exten, version combination has no memory
	allocated for processing (user did not call file_open for this combination)
FILL_MODE_FILE_OPEN	the user did not request mode data processing when file_open was called
FILL_MODE_INFO_DUP	the requested data_key, exten, version combination has no memory
	allocated for the instrument status information
MODES_NOT_REQUESTED	the user did not call fill_mode_info for this combination
FILL_MODE_BASE_TIME_MISSING	the time interval information has not been set (user did not call
	set_time_values for this combination)
FILL_MODE_ARRAY_MALLOC	no memory for structure which hold information pertinent to the time-
	averaged data
ALLOC_MODE_INFO_MALLOC	no memory for data buffer information
MODE_UNITS_MALLOC	no memory to hold the various data levels for the data buffers
MODE_UNITS_REALLOC	no memory for expansion of space to hold the various data levels for the
	data buffers
MODE_DATA_MALLOC	no memory for data buffers
FILL_WITH_SWEEP_MODE	The modules fill_mode_data and sweep_mode_data cannot be used
	interchangeably for the same data key, extension, version combination
NO_EMPTY_BUFFERS	no spare buffers for data accumulation
	Error codes returned by read_drec ()
	Error codes returned by convert_to_units ()
ALL_OKAY	routine terminated successfully

TABLE 1. Status Codes Returned for FILL_MODE_DATA

DESCRIPTION

Fill_mode_data is the IDFS time-averaging data read routine, retrieving instrument status (mode) data for the time duration being processed. The data set of interest is referenced through the key value data_key which can be created using the get_data_key module. Fill_mode_data processes instrument status data only. If sensor-specific data is desired, that is, sensor, sweep step, calibration, data quality, pitch angle, azimuthal angle, spacecraft potential data and / or background data, the user should use the fill_data / fill_discontinuous_data routine(s).

The parameter **version** allows multiple file openings for an IDFS data set. If the data, header and VIDF file for the specified data set need to be opened just once for processing, the same version number should be passed to all IDFS routines. However, for multiple file openings, the version number should be unique and all file manipulations performed by the IDFS routines will use the file descriptors defined for the version number specified. The user should call the **get_version_number** routine to retrieve a unique version number instead of choosing this value themselves. The retrieval of multiple data parameters from a single data source does not constitute the need for multiple version numbers; a single version number will suffice.

The parameter **idf_data_ptr** is a pointer to the structure that is to hold all data pertinent to the data set being processed. The structure is created and the address to this structure is returned when a call to the **create_idf_data_structure** routine is made. The user also has the option of calling the module **create_data_structure**, which determines what type of data structure is needed for the IDFS data set of interest. In most cases, one data structure is

December 28, 2012

sufficient to process any number of distinct data sets. However, if more than one structure is needed, the user may call the **create_idf_data_structure** routine N times to create N instances of the **idf_data** structure. The user must keep track of which pointer to send to the IDFS routines that utilize this structure.

If the **file_open** routine is not to open the default set of IDFS files but a modified set of IDFS files, the two character extension applied to these data files must be supplied to this routine within the string variable **exten**. These files must have the identical name as the IDFS files with the two character identification code appended to the end of the file names (i.e. RTLA19922181432Dxx, RTLA19922181432Hxx, RTLA19922181432Ixx). The files must reside either in the directory specified by the environment variable SER_DATA, which is set by the user, or in the user's home directory if the environment variable USER_DATA is not set. To open the default IDFS data files, **exten** should be set to a null string. The usage of modified data sets is limited to post acquisition data; therefore, it is suggested that the user set **exten** to a null string for real-time scenarios.

This routine will process data one sweep at a time, placing the data into buffers which hold data that is accumulated over a specified time interval. Once the time interval has been processed, the routine will return the data buffers and a status value for each buffer which indicates when the buffer is ready for the user to retrieve. The user **must** call the module **set_time_values** before the **fill_mode_data** module can be called since the **set_time_values** module is used to specify the base time value and reference location and the time interval (delta) to use to accumulate the data. If the **fill_mode_data** routine determines that the **set_time_values** module has not been called, an error code is returned to the user.

Along with the data being returned, there is a starting location and an ending location that is returned for each of the data buffers. The user may use these values as references to the base location specified in the call to the **set_time_values** module. That is, given a base time value, a time interval and a reference location, the **fill_mode_data** routine will return the location of data with respect to time. The user may chose to ignore these values or may use these locations to plot data along an axis that is scaled with respect to time.

There are a constant number of data buffers that are used by the **fill_mode_data** module. This number is defined as NUM_BUFFERS in the **user_defs.h** file. This file is described in section 1H of the IDFS Programmers Manual. These data buffers are utilized in a cyclic nature, with buffer 0 being re-used once buffer NUM_BUFFERS-1 has been filled. The data buffers that are ready to be processed are flagged with the status value BUFFER_READY. For each buffer, there are N many sub-buffers which hold the data in each of the requested data levels or units. The user must process the data contained within these buffers before the next call to the **fill_mode_data** routine is made since the module will clear out these buffers for re-use. This holds true even when an LOS_STATUS or NEXT_FILE_STATUS status code is returned. The data values must be normalized using the normalization factors returned along with the data. Since the buffers are cyclic, the user may wish to keep a variable indicating the last buffer number processed so that the user can start at the time sample left off from the previous call to the **fill_mode_data** routine at the

next call. It is important to note that there is one status flag per data buffer that is used by all instrument status values.

In order to utilize the **fill_mode_data** routine, the user must select the units to be returned and the data cutoff values to be applied by calling the **fill_mode_info** module prior to calling the **fill_mode_data** module. The user should make one call to the **fill_mode_info** module for each instrument status byte that is to be retrieved for each units/data cutoff combination selected. If the **fill_mode_data** routine determines that the **fill_mode_info** module was never called, an error code is returned.

ERRORS

All errors within this routine are returned through the status variable. The include file **ret_codes.h**, which includes all possible return values, should be included so that the mnemonics for the return codes can be referenced. The **ret_codes.h** file is described in section 1H of the IDFS Programmers Manual.

SEE ALSO

file_open	1 R
read_drec	1 R
convert_to_units	1 R
set_time_values	2R
fill_data	2R
fill_discontinuous_data	2R
fill_mode_info	2R
get_data_key	1 R
get_version_number	1 R
mode_units_index	1 R
create_data_structure	1 R
create_idf_data_structure	1 R
ret_codes	1H
user_defs	1H
libtrec_idfs	2H

BUGS

None

EXAMPLES

Obtain time-averaged instrument status values from the virtual instrument RTLA, which is part of the RETE instrument/experiment, which is part of the TSS-1 mission, which is identified with the TSS project.

#include "libtrec_idfs.h"
#include "ret_codes.h"

```
SDDAS ULONG data key:
SDDAS USHORT vnum;
SDDAS_FLOAT *ret_data, *ret_frac;
SDDAS_LONG *start_time_sec, *start_time_nano, *end_time_sec, *end_time_nano;
SDDAS LONG *bpix, *epix;
SDDAS SHORT *start time vr, *start time day, *end time vr, *end time day;
SDDAS_SHORT status, *mode_numbers, num_modes, *num_units, data_block;
SDDAS CHAR *ret bin, hdr change, *buf stat;
void *idf_data_ptr;
status = get_data_key ("TSS", "TSS-1", "RETE", "RETE", "RTLA", &data_key);
if (status != ALL OKAY)
{
 printf ("\n Error %d returned by get data key routine.\n", status);
 exit (-1);
}
get_version_number (&vnum);
status = create_idf_data_structure (&idf_data_ptr);
if (status != ALL OKAY)
{
 printf ("\n Error %d returned by create idf data structure routine.\n", status);
 exit (-1);
}
status = fill_mode_data (data_key, '''', vnum, idf_data_ptr, &mode_numbers,
               &ret data, &ret frac, &ret bin, &bpix, &epix, &buf stat,
               &num modes, &num units, &data block, &start time vr,
               &start_time_day, &start_time_sec, &start_time_nano,
               &end_time_yr, &end_time_day,&end_time_sec, &end_time_nano,
               &hdr_change, 255);
if (status != ALL OKAY)
ł
```

```
printf ("\n Error %d returned by fill_mode_data routine.\n", status);
exit (-1);
```

```
}
```

FILL_MODE_INFO

function - specifies the data cutoff values and units to be returned for the specified instrument status (mode) value

SYNOPSIS

#include "libtrec_idfs.h"
#include "ret_codes.h"

SDDAS_SHORT fill_mode_info (SDDAS_ULONG data_key, SDDAS_CHAR *exten,
SDDAS_USHORT version, SDDAS_SHORT mode_val,
SDDAS_FLOAT min, SDDAS_FLOAT max,
SDDAS_CHAR num_tbls,
SDDAS_CHAR *tbls_to_apply,
SDDAS_LONG *tbl_oper)

ARGUMENTS

data_key	-	unique value which indicates the data set of interest
exten	-	two character extension to be added to IDFS file names when default files are not to be used, otherwise a null string
version	-	IDFS data set identification number which allows for multiple openings of the same data set
mode_val	-	the instrument status (mode) value of interest
min	-	the lower cutoff value for data that are to be put into the data
		buffers, specified in terms of the units desired
max	-	the upper cutoff value for data that are to be put into the data
		buffers, specified in terms of the units desired
num_tbls	-	the number of elements specified in the tbls_to_apply and
		tbl_oper parameters
tbls_to_apply	-	the tables that are to be applied in order to derive the desired units
tbl_oper	-	the operations that are to be applied to the specified tables in order to derive the desired units
fill_mode_info	-	routine status (see TABLE 1)

TABLE 1. Status Codes Returned for FILL_MODE_INFO

STATUS CODE	EXPLANATION OF STATUS
MODE_INFO_NOT_FOUND	the requested data_key, exten, version combination has no memory allocated for
	processing (user did not call file_open for this combination)
MODE_FILE_OPEN	the user did not request mode data processing when file_open was called
MODE_INFO_DUP	the requested data_key, exten, version combination has no memory allocated for
	the instrument status information
MODE_INFO_NO_MODES	there are no instrument status (mode) values defined for the data set
MODE_INFO_MALLOC	no memory for structures which hold mode specific information
MODE_INFO_REALLOC	no memory for expansion of structures which hold mode specific information
MODE_INFO_BASE_MALLOC	no memory for expansion of the min/max values for the modes being processed
MODE_INFO_TBL_MALLOC	no memory for table number / table operation information
MODE_INFO_BASE_REALLOC	no memory for expansion of the min/max values for the modes being processed

STATUS CODE	EXPLANATION OF STATUS
ALL_OKAY	routine terminated successfully

DESCRIPTION

Fill_mode_info is the IDFS routine that specifies which instrument status (mode) values are being returned by the **fill_mode_data / sweep_mode_data** module. The data set of interest is referenced through the key value **data_key** which can be created using the **get_data_key** module. The instrument status (mode) values are not sensor-specific, that is, they pertain to all sensors within the sensor set. If sensor-specific data is to be retrieved, the user should use the **fill_sensor_info** routine to specify the data that is to be returned by the **fill_data / fill_discontinuous_data / sweep_data / sweep_discontinuous_data / spin_data / spin_data / spin_data / spin_data / sweep_mode_data** routine; otherwise, an error code will be returned. The user should make one call to the **fill_mode_info** module for each instrument status value that is to be processed for each units/data cutoff combination selected.

The parameter **version** allows multiple file openings for an IDFS data set. If the data, header and VIDF file for the specified data set need to be opened just once for processing, the same version number should be passed to all IDFS routines. However, for multiple file openings, the version number should be unique and all file manipulations performed by the IDFS routines will use the file descriptors defined for the version number specified. The user should call the **get_version_number** routine to retrieve a unique version number instead of choosing this value themselves. The retrieval of multiple data parameters from a single data source does not constitute the need for multiple version numbers; a single version number will suffice.

If the **file_open** routine is not to open the default set of IDFS files but a modified set of IDFS files, the two character extension applied to these data files must be supplied to this routine within the string variable **exten**. These files must have the identical name as the IDFS files with the two character identification code appended to the end of the file names (i.e. RTLA19922181432Dxx, RTLA19922181432Hxx, RTLA19922181432Ixx). The files must reside either in the directory specified by the environment variable USER_DATA, which is set by the user, or in the user's home directory if the environment variable USER_DATA is not set. To open the default IDFS data files, **exten** should be set to a null string. The usage of modified data sets is limited to post acquisition data; therefore, it is suggested that the user set **exten** to a null string for real-time scenarios.

ERRORS

All errors within this routine are returned through the status variable. The include file **ret_codes.h**, which includes all possible return values, should be included so that the mnemonics for the return codes can be referenced. The **ret_codes.h** file is described in section 1H of the IDFS Programmers Manual.

SEE ALSO

file_open	1 R
fill_mode_data	2R

sweep_mode_data	2R
fill_sensor_info	2R
get_data_key	1R
get_version_number	1R
ret_codes	1H
libtrec_idfs	2H

BUGS

None

EXAMPLES

Specify raw units, with cutoff values of 0 and 5 for instrument status byte 1 from the virtual instrument RTLA, which is part of the RETE instrument/experiment, which is part of the TSS-1 mission, which is identified with the TSS project.

#include "libtrec_idfs.h"
#include "ret_codes.h"

```
SDDAS_ULONG data_key;
SDDAS USHORT vnum;
SDDAS_FLOAT mode_min, mode_max;
SDDAS LONG *tbl oper = NULL;
SDDAS SHORT status, mode val;
SDDAS_CHAR num_tbls, *tbls_to_apply = NULL;
mode_val = 1;
mode \min = 0;
mode max = 5;
num_tbls = 0;
status = get_data_key ("TSS", "TSS-1", "RETE", "RETE", "RTLA", &data_key);
if (status != ALL_OKAY)
{
 printf ("\n Error %d returned by get_data_key routine.\n", status);
 exit (-1);
}
get_version_number (&vnum);
status = fill_mode_info (data_key, '''', vnum, mode_val, mode_min, mode_max,
                       num_tbls, tbls_to_apply, tbl_oper);
if (status != ALL OKAY)
 printf ("\n Error %d from fill mode info routine.\n", status);
 exit (-1);
```

}

FILL_SENSOR_INFO

function - specifies the data cutoff values, data type and units to be returned for the specified sensor

SYNOPSIS

#include "libtrec_idfs.h"
#include "ret_codes.h"
#include "user_defs.h"

SDDAS_SHORT fill_sensor_info (SDDAS_ULONG data_key, SDDAS_CHAR *exten,
SDDAS_USHORT version, SDDAS_SHORT sensor,
SDDAS_FLOAT min, SDDAS_FLOAT max,
SDDAS_CHAR num_tbls, SDDAS_CHAR *tbls_to_apply,
SDDAS_LONG *tbl_oper, SDDAS_CHAR data_type,
SDDAS_CHAR cal_set)

ARGUMENTS

data_key	-	unique value	which	indicates the data set of interest		
exten	-	two character extension to be added to IDFS file names when				
		default files a	are not t	to be used, otherwise a null string		
version	-	IDFS data se	t identif	fication number which allows for multiple		
		openings of t	he same	e data set		
sensor	-	sensor identi				
min	-	the lower cutoff value for data that are to be put into the data				
		buffers, specified in terms of the units desired				
max	-	-		ue for data that are to be put into the data		
		buffers, specified in terms of the units desired				
num_tbls	-	the number of elements specified in the tbls_to_apply and				
		tbl_oper parameters				
tbls_to_apply	-	tables that ar	e to be a	applied in order to derive the desired units		
tbl_oper	-	the operations that are to be applied to the specified tables in				
-		order to deriv	ve the d	esired units		
data_type	-	the type of da	ata bein	g requested		
		1	-	sensor data (SENSOR)		
		2	-	sweep step data (SWEEP_STEP)		
		3	-	calibration data (CAL_DATA)		
		5	-	data quality data (D_QUAL)		
		6	-	pitch angle data PITCH_ANGLE)		
		7	-	start azimuthal angle data		
				(START_AZ_ANGLE)		
		8	-	stop azimuthal angle data		
				(STOP_AZ_ANGLE)		
		9	-	spacecraft potential data		
				(SC_POTENTIAL)		
		10	-	background data		
				(BACKGROUND)		
		~	~	D 1 00 0010		

cal_set	-	the calibration set from which requested calibration data
		(CAL_DATA) is to be retrieved
		- If calibration data is not being requested, this
		parameter is not utilized and it is suggested that the
		user pass a value of zero for this parameter.
fill_sensor_info	-	routine status (see TABLE 1)

STATUS CODE	EXPLANATION OF STATUS
FILL_SEN_NOT_FOUND	the requested data_key, exten, version combination has no memory allocated for
	processing (user did not call file_open for this combination)
FILL_SEN_MODE_TYPE	instrument status (mode) data is not supported by the fill_sensor_info routine
FILL_SEN_MALLOC	no memory for structures which hold sensor specific information
FILL_SEN_REALLOC	no memory for expansion of structures which hold sensor specific information
FILL_SEN_BASE_MALLOC	no memory for min/max values for the sensors being processed
FILL_SEN_BASE_REALLOC	no memory for expansion of the min/max values for the sensor being processed
FILL_SEN_TBL_MALLOC	no memory for table number / table operation information
ALL_OKAY	routine terminated successfully

TABLE 1. Status Codes Returned for FILL_SENSOR_INFO

DESCRIPTION

Fill_sensor_info is the IDFS routine that specifies what data is being returned by the IDFS routines that return time-averaged data (fill_data / fill_discontinuous_data), sample-averaged data (sweep_data / sweep_discontinuous_data) or spin-averaged data (spin_data_pixel). The data set of interest is referenced through the key value data_key which can be created using the get_data_key module. The fill_sensor_info module should be used for sensor-specific data only, that is, for sensor, sweep step, calibration, data quality, pitch angle, azimuthal angle, spacecraft potential and background data. If the instrument status (mode) data is to be retrieved, the user should use the fill_mode_info routine to specify which status bytes are to be returned by the fill_mode_data module.

The parameter **version** allows multiple file openings for an IDFS data set. If the data, header and VIDF file for the specified data set need to be opened just once for processing, the same version number should be passed to all IDFS routines. However, for multiple file openings, the version number should be unique and all file manipulations performed by the IDFS routines will use the file descriptors defined for the version number specified. The user should call the **get_version_number** routine to retrieve a unique version number instead of choosing this value themselves. The retrieval of multiple data parameters from a single data source does not constitute the need for multiple version numbers; a single version number will suffice.

If the **file_open** routine is not to open the default set of IDFS files but a modified set of IDFS files, the two character extension applied to these data files must be supplied to this routine within the string variable **exten**. These files must have the identical name as the IDFS files with the two character identification code appended to the end of the file names (i.e. RTLA19922181432Dxx, RTLA19922181432Hxx, RTLA19922181432Ixx). The files

must reside either in the directory specified by the environment variable USER_DATA, which is set by the user, or in the user's home directory if the environment variable USER_DATA is not set. To open the default IDFS data files, **exten** should be set to a null string. The usage of modified data sets is limited to post acquisition data; therefore, it is suggested that the user set **exten** to a null string for real-time scenarios.

If it has been determined that the **fill_sensor_info** module has not been called, the default mode for the time-averaging, sample-averaging, and spin-averaging routines is to return sensor data in raw units (no tables applied) for each of the sensors processed, with data cutoff values set at -3.0e38 (VALID_MIN) and 3.0e38 (VALID_MAX). The user may specify the type of data, the units to be returned and the data cutoff values to be applied by calling the **fill_sensor_info** module prior to calling the time-averaging, sample-averaging, or spin-averaging module. The user should make one call to the **fill_sensor_info** module for each sensor that is to be processed for each data type/units/data cutoff combination selected.

ERRORS

All errors within this routine are returned through the status variable. The include file **ret_codes.h**, which includes all possible return values, should be included so that the mnemonics for the return codes can be referenced. The **ret_codes.h** file is described in section 1H of the IDFS Programmers Manual.

SEE ALSO

file_open	1 R
fill_mode_info	2R
fill_data	2R
fill_discontinuous_data	2R
sweep_data	2R
sweep_discontinuous_data	2R
spin_data	2R
spin_data_pixel	2R
get_data_key	1R
get_version_number	1R
ret_codes	1H
user_defs	1H
libtrec_idfs	2H

BUGS

None

EXAMPLES

Specify raw units, with cutoff values of 10 and 25 for SENSOR data for all defined sensors from the virtual instrument RTLA, which is part of the RETE instrument/experiment, which is part of the TSS-1 mission, which is identified with the TSS project. Assume that there are 3 sensors applicable to this virtual instrument.

```
#include "libtrec idfs.h"
#include "ret_codes.h"
#include "user_defs.h"
SDDAS_ULONG data_key;
SDDAS_USHORT vnum;
register SDDAS_SHORT sensor;
SDDAS_FLOAT sen_min, sen_max;
SDDAS LONG *tbl oper = NULL;
SDDAS_SHORT status;
SDDAS_CHAR data_type, num_tbls, *tbls_to_apply = NULL;
data_type = SENSOR;
sen_min = 10.0;
sen_max = 25.0;
num_tbls = 0;
status = get_data_key ("TSS", "TSS-1", "RETE", "RETE", "RTLA", &data_key);
if (status != ALL_OKAY)
{
 printf ("\n Error %d returned by get data key routine.\n", status);
 exit (-1);
}
get_version_number (&vnum);
for (sensor = 0; sensor < 3; ++sensor)
{
 status = fill_sensor_info (data_key, '''', vnum, sensor, sen_min, sen_max,
                          num_tbls, tbls_to_apply, tbl_oper, data_type, 0);
 if (status != ALL_OKAY)
  ł
   printf ("\n Error %d from fill_sensor_info routine.\n", status);
   exit (-1);
  }
}
```

FILL_THETA_MATRIX

function - fills in the data matrix that is used to collapse over the theta and scan dimensions

SYNOPSIS

#include "libtrec_idfs.h"
#include "ret_codes.h"
#include "user_defs.h"

ARGUMENTS

data_key	-	unique value which indicates the data set of interest
exten	-	two character extension to be added to IDFS file names when default files are not to be used, otherwise a null string
version	-	IDFS data set identification number which allows for multiple openings of the same data set
num_sen	-	the number of elements in the ret_sensors array
ret_sensors	-	an array which holds the sensor number(s) for which data is returned
		- the array is initialized to -1 in all elements; valid
		sensor numbers start with 0
ret_data	-	pointer to the data being returned (data for all sensors processed)
ret_frac	-	pointer to the normalization factors for the data being returned
bin_stat	-	pointer to status flags which are associated with each data bin returned
		0 - no data has been placed into the data bin being processed
		 data has been placed into the data bin being processed
num_units	-	an array holding the number of data sets to bypass in order to get to the data for the sensor being processed
cur_buf	-	the current buffer being processed (number between 0 and NUM_BUFFERS-1)
sen_units	-	the number of units or data levels defined for the sensor in question
fill_theta_matrix	-	routine status (see TABLE 1)

STATUS CODE	EXPLANATION OF STATUS	
FILL_THETA_NOT_FOUND	the requested data_key, exten, version combination has no memory allocated for	
	processing (user did not call file_open for this combination)	
FILL_THETA_COLLAPSE	no memory has been allocated to hold the collapsing information (user did not call	
	set_collapse_info for this combination)	
THETA_DIFF_UNITS	the sensor do not process the same number of data levels	
ALL_OKAY	routine terminated successfully	

TABLE 1. Status Code Returned for **FILL_THETA_MATRIX**

DESCRIPTION

Fill_theta_matrix is the IDFS routine which assembles a data matrix when data is to be reduced in either the theta and/or scan dimensions. If the user is also collapsing the data over the charge, mass and/or phi dimensions, there is no need to call this module. The data matrix for data reduction will be acquired within the call to the time-averaging module (fill_data / fill_discontinuous_data), the sample-averaging module (sweep_data / sweep_discontinuous_data) or the spin-averaging module (spin_data / spin_data_pixel). The data set of interest is referenced through the key value data_key which can be created using the get_data_key module. This module can not be used in conjunction with the fill_mode_data / sweep_mode_data module since dimensionality is associated with sensor-specific data and instrument status data is not sensor-specific.

The parameter **version** allows multiple file openings for an IDFS data set. If the data, header and VIDF file for the specified data set need to be opened just once for processing, the same version number should be passed to all IDFS routines. However, for multiple file openings, the version number should be unique and all file manipulations performed by the IDFS routines will use the file descriptors defined for the version number specified. The user should call the **get_version_number** routine to retrieve a unique version number instead of choosing this value themselves. The retrieval of multiple data parameters from a single data source does not constitute the need for multiple version numbers; a single version number will suffice.

If the **file_open** routine is not to open the default set of IDFS files but a modified set of IDFS files, the two character extension applied to these data files must be supplied to this routine within the string variable **exten**. These files must have the identical name as the IDFS files with the two character identification code appended to the end of the file names (i.e. RTLA19922181432Dxx, RTLA19922181432Hxx, RTLA19922181432Ixx). The files must reside either in the directory specified by the environment variable USER_DATA, which is set by the user, or in the user's home directory if the environment variable USER_DATA is not set. To open the default IDFS data files, **exten** should be set to a null string. The usage of modified data sets is limited to post acquisition data; therefore, it is suggested that the user set **exten** to a null string for real-time scenarios.

The time-averaging or sample-averaging routine will return a constant number of data buffers. This number is defined as NUM_BUFFERS in the **user_defs.h** file. This file is described in section 1H of the IDFS Programmers Manual. These data buffers are utilized in a cyclic nature, with buffer 0 being re-used once buffer NUM_BUFFERS-1 has been

filled. If the user is collapsing the data over the theta or scan dimension, the user must call this module in conjunction with the **collapse_dimensions** module, processing one buffer at a time. The user should process only those buffers that are flagged with the status value BUFFER_READY. All sensors that contain data in the specified buffer are processed, as well as each different data level or unit. Since the buffers are cyclic, the user may wish to keep a variable indicating the last buffer number processed so that the user can start at the time sample left off from the previous call to the time-averaging or sample-averaging routine at the next call.

The spin-averaging routine will return a single data buffer. If the user is collapsing the data over the theta or scan dimension, the user must call this module in conjunction with the **collapse_dimensions** module. All sensors that contain data in the specified buffer are processed, as well as each different data level or unit.

The call to the **fill_theta_matrix** routine should be called once for each buffer processed. The user may wish to collapse the data over different dimensions and ranges, in which case, there would be multiple calls to the **collapse_dimensions** module but there should be just one call to the **fill_theta_matrix** routine.

The parameter **sen_units** holds the number of units or data levels defined for the sensors. This value is used as an index to get to the first buffer returned by the time-averaging, sample-averaging, or spin-averaging routine for each sensor. The value for this parameter can be retrieved by calling the module **units_index**, with the next to the last argument from the end holding the value to be passed to this module. The parameters **num_sen**, **ret_sensors**, **ret_data**, **ret_frac**, **bin_stat** and **num_units** are returned from the call to the time-averaging, sample-averaging, or spin-averaging routine.

ERRORS

All errors within this routine are returned through the status variable. The include file **ret_codes.h**, which includes all possible return values, should be included so that the mnemonics for the return codes can be referenced. The **ret_codes.h** file is described in section 1H of the IDFS Programmers Manual.

SEE ALSO

file_open	1 R
fill_data	2R
fill_discontinuous_data	2R
sweep_data	2R
sweep_discontinuous_data	2R
spin_data	2R
spin_data_pixel	2R
collapse_dimensions	2R
set_collapse_info	2R
units_index	2R
get_data_key	1 R
get_version_number	1 R

ret_codes	1H
user_defs	1H
libtrec_idfs	2H

BUGS

None

EXAMPLES

In order to produce a line plot from the RTLA virtual instrument, data must be collapsed over a frequency range. Assuming that a single data level (raw units) is being returned, fill the data matrix used for data reduction and collapse the data over the two ranges for each buffer that is ready to be processed. The virtual instrument RTLA is part of the RETE instrument/experiment, which is part of the TSS-1 mission, which is identified with the TSS project.

#include "libtrec_idfs.h"
#include "ret_codes.h"
#include "user_defs.h"
#define DUMMY_VAL 0

```
SDDAS_ULONG data_key;
SDDAS USHORT vnum;
SDDAS_FLOAT *ret_data, *ret_frac, *data_ptr, start[6], stop[6];
SDDAS_LONG *start_time_sec, *start_time_nano, *end_time_sec, *end_time_nano;
SDDAS_LONG *bpix, *epix;
SDDAS_SHORT *start_time_yr, *start_time_day, *end_time_yr, *end_time_day;
SDDAS SHORT status, *sen numbers, num sen, *num units, data block;
SDDAS CHAR *ret bin, hdr change, *buf stat, cur buf, buf num, dimen[6];
static SDDAS_CHAR which_buf = 0;
void *idf data ptr;
dimen[0] = DIMEN ON;
start[0] = 0.16;
stop[0] = 0.9;
start[1] = stop[1] = 0.0;
start[2] = stop[2] = 0.0;
start[3] = stop[3] = 0.0;
start[4] = stop[4] = 0.0;
start[5] = stop[5] = 0.0;
dimen[1] = dimen[2] = dimen[3] = dimen[4] = dimen[5] = DIMEN OFF;
status = get_data_key ("TSS", "TSS-1", "RETE", "RETE", "RTLA", &data_key);
if (status != ALL_OKAY)
{
 printf ("\n Error %d returned by get data key routine.\n", status);
 exit (-1);
```

}

{

}

ł

```
get version number (&vnum);
status = create_idf_data_structure (&idf_data_ptr);
if (status != ALL OKAY)
 printf ("\n Error %d returned by create idf data structure routine.\n", status);
 exit (-1);
status = fill_data (data_key, "", vnum, idf_data_ptr, &sen_numbers, &ret_data, &ret_frac,
                &ret bin, &bpix, &epix, &buf stat, &num sen, &num units,
                &data_block, &start_time_yr, &start_time_day, &start_time_sec,
                &start time nano, &end time vr, &end time day, &end time sec,
                &end time nano, &hdr change, 255);
if (status \geq 0)
 cur buf = which buf:
 for (buf_num = 0; buf_num < NUM_BUFFERS; ++buf_num)
  {
   if (*(buf_stat + cur_buf) == BUFFER_READY)
    {
     status = fill_theta_matrix (data_key, "", vnum, num_sen, sen_numbers, ret_data,
                                ret frac, ret bin, num units, cur buf, 1);
     if (status != ALL OKAY)
       printf ("\n Error %d from fill theta matrix routine.\n", status);
       exit (-1);
      }
     status = collapse_dimensions (data_key, "", vnum, 1, dimen, start, stop,
                                  STRAIGHT AVG, DUMMY VAL, &data ptr, 0, 1, 3,
                                  0.0, 1, 1, 0, 0, 1, cur_buf);
     if (status != ALL_OKAY)
      {
       printf ("\n Error %d from collapse_dimensions routine.\n", status);
       exit (-1);
     printf ("\n data value = % f", *data_ptr);
     start[0] = 0.3;
     stop[0] = 0.6;
     status = collapse_dimensions (data_key, "", vnum, 1, dimen, start, stop,
                                  STRAIGHT_AVG, DUMMY_VAL, &data_ptr, 0, 1,
                                  3, 0.0, 1, 1, 0, 1, 1, cur_buf);
     if (status != ALL_OKAY)
```

}

```
{
    frintf ("\n Error %d from collapse_dimensions routine.\n", status);
    exit (-1);
    printf ("\n data value = %f", *data_ptr);
    which_buf = (cur_buf + 1) % NUM_BUFFERS;
    cur_buf = (cur_buf + 1) % NUM_BUFFERS;
}
```

MODE_UNITS_INDEX

function - returns index values to access the data returned by the **fill_mode_data** / **sweep_mode_data** module for the cutoff / units combination specified

SYNOPSIS

#include "libtrec_idfs.h"
#include "ret_codes.h"

SDDAS_SHORT mode_units_index (SDDAS_ULONG data_key, SDDAS_CHAR *exten,
SDDAS_USHORT version, SDDAS_SHORT mode_val,
SDDAS_FLOAT min, SDDAS_FLOAT max,
SDDAS_CHAR num_tbls, SDDAS_CHAR *tbls_to_apply,
SDDAS_LONG *tbl_oper, SDDAS_SHORT *units_ind,
SDDAS_SHORT *num_units)

ARGUMENTS

data_key	-	unique value which indicates the data set of interest
exten	-	two character extension to be added to IDFS file names when
		default files are not to be used, otherwise a null string
version	-	IDFS data set identification number which allows for multiple
		openings of the same data set
mode_val	-	the instrument status (mode) value of interest
min	-	the lower cutoff value for data that are to be put into the data
		buffers, specified in terms of the units desired.
max	-	the upper cutoff value for data that are to be put into the data
		buffers, specified in terms of the units desired.
num_tbls	-	the number of elements specified in the tbls_to_apply and
		tbl_oper parameters
tbls_to_apply	-	the tables that are to be applied in order to derive the desired
		units
tbl_oper	-	the operations that are to be applied to the specified tables in
		order to derive the desired units
units_ind	-	index value returned to access the correct sub-buffer returned
		from the fill_mode_data / sweep_mode_data routine for the
		cutoff/units combination requested
num_units	-	the number of units or data levels defined for the instrument
		status (mode) value in question (used as an index to get to the
		first buffer returned by the fill_mode_data /
		<pre>sweep_mode_data routine for the mode in question)</pre>
mode_units_index	-	routine status (see TABLE 1)

STATUS CODE	EXPLANATION OF STATUS
MODE_UNITS_IND_NOT_FOUND	the requested data_key, exten, version combination has no memory
	allocated for processing (user did not call file_open for this combination)
MODE_UNITS_FILE_OPEN	the user did not request mode data processing when file_open was called
MODE_UNITS_INFO_DUP	the requested data_key, exten, version combination has no memory
	allocated for the instrument status information
MODE_UNITS_NO_MODE	the requested instrument status (mode) value was not found amongst the
	defined cutoff/units combinations (user did not call fill_mode_info for this
	combination
MODE_UNITS_NO_MATCH	the cutoff/units combination requested was not found for the specified
	instrument status (mode) value
ALL_OKAY	routine terminated successfully

TABLE 1. Status Codes Returned for MODE_UNITS_INDEX

DESCRIPTION

Mode_units_index is the IDFS routine that returns index values that are used to access the data buffers returned by the **fill_mode_data / sweep_mode_data** routine to retrieve the data for the instrument status (mode) value, cutoff/units combination specified. The data set of interest is referenced through the key value **data_key** which can be created using the **get_data_key** module. The instrument status (mode) values are not sensor-specific, that is, they pertain to all sensors within the sensor set. If sensor-specific data is also being processed, the user should use the **units_index** routine to retrieve index values to access the data buffers returned by the **fill_data / fill_discontinuous_data / sweep_data / sweep_data / spin_data_pixel** routines.

The parameter **version** allows multiple file openings for an IDFS data set. If the data, header and VIDF file for the specified data set need to be opened just once for processing, the same version number should be passed to all IDFS routines. However, for multiple file openings, the version number should be unique and all file manipulations performed by the IDFS routines will use the file descriptors defined for the version number specified. The user should call the **get_version_number** routine to retrieve a unique version number instead of choosing this value themselves. The retrieval of multiple data parameters from a single data source does not constitute the need for multiple version numbers; a single version number will suffice.

If the **file_open** routine is not to open the default set of IDFS files but a modified set of IDFS files, the two character extension applied to these data files must be supplied to this routine within the string variable **exten**. These files must have the identical name as the IDFS files with the two character identification code appended to the end of the file names (i.e. RTLA19922181432Dxx, RTLA19922181432Hxx, RTLA19922181432Ixx). The files must reside either in the directory specified by the environment variable USER_DATA, which is set by the user, or in the user's home directory if the environment variable USER_DATA is not set. To open the default IDFS data files, **exten** should be set to a null string. The usage of modified data sets is limited to post acquisition data; therefore, it is suggested that the user set **exten** to a null string for real-time scenarios.

The user may elect to call the **mode_units_index** routine every time a return from the **fill_mode_data / sweep_mode_data** routine is made or may call the **mode_units_index** routine once for each instrument status (mode) value, cutoff/units combination requested and save the index values into variables for later usage. In either case, the call(s) to the **mode_units_index** routine must be made after ALL calls to the **fill_mode_info** routine have been made.

ERRORS

All errors within this routine are returned through the status variable. The include file **ret_codes.h**, which includes all possible return values, should be included so that the mnemonics for the return codes can be referenced. The **ret_codes.h** file is described in section 1H of the IDFS Programmers Manual.

SEE ALSO

file_open	1R
fill_mode_data	2R
sweep_mode_data	2R
fill_mode_info	2R
units_index	2R
get_data_key	1 R
get_version_number	1 R
ret_codes	1H
libtrec_idfs	2H

BUGS

None

EXAMPLES

Retrieve the index values to access data that is returned for instrument status byte 1 from the virtual instrument RTLA, which is part of the RETE instrument/experiment, which is part of the TSS-1 mission, which is identified with the TSS project. Assume that there is one table applicable and the cutoff values of 0 and 5 are to be used.

#include "libtrec_idfs.h"
#include "ret_codes.h"

SDDAS_ULONG data_key; SDDAS_USHORT vnum; SDDAS_FLOAT mode_min, mode_max; SDDAS_LONG tbl_oper[1]; SDDAS_SHORT uind_base, status, mode_units, mode_val; SDDAS_CHAR tbls_to_apply[1], num_tbls;

 $mode_min = 0.0;$ $mode_max = 5.0;$ $mode_val = 1;$

```
num_tbls = 1;
tbls_to_apply[0] = 0;
tbl_oper[0] = 0; /* look-up operation */
status = get_data_key ("TSS", "TSS-1", "RETE", "RETE", "RTLA", &data_key);
if (status != ALL_OKAY)
{
 printf ("\n Error %d returned by get_data_key routine.\n", status);
 exit (-1);
 }
get_version_number (&vnum);
status = mode_units_index (data_key, "", vnum, mode_val, mode_min, mode_max,
                           num_tbls, tbls_to_apply, tbl_oper, &uind_base,
                           &mode_units);
if (status != ALL_OKAY)
{
 printf ("\n Error %d returned by mode_units_index routine.\n", status);
```

exit (-1);
}

NUMBER_OF_DATA_BINS

function - returns the number of data bins created for the data set of interest

SYNOPSIS

#include "libtrec_idfs.h"
#include "ret_codes.h"

SDDAS_SHORT number_of_data_bins (SDDAS_ULONG data_key,
SDDAS_CHAR *exten, SDDAS_USHORT version,
SDDAS_SHORT *num_bins)

ARGUMENTS

data_key	- unique value which indicates the data set of interest	
exten	- two character extension to be added to IDFS file	
	names when default files are not to be used, otherwise	e,
	a null string	
version	- IDFS data set identification number which allows for	•
	multiple openings of the same data set	
num_bins	- the number of data bins created for the data set	
number_of_data_bins	- routine status (see TABLE 1)	

TABLE 1.	Status Codes R	Returned for NUM	BER_OF	DATA_BINS
----------	----------------	------------------	---------------	-----------

STATUS CODE	EXPLANATION OF STATUS	
NBINS_NOT_FOUND	the requested data_key, exten, version combination has no memory allocated for	
	processing (user did not call file_open for this combination)	
NBINS_NO_BINS	no memory has been allocated to hold the binning information (user did not call	
	set_bin_info for this combination)	
ALL_OKAY	routine terminated successfully	

DESCRIPTION

Number_of_data_bins is the IDFS routine that returns the number of data bins that are utilized by the IDFS routines that return time-averaged data (fill_data and fill_discontinuous_data), sample-averaged data (sweep_data and sweep_discontinuous_data), or spin-averaged data (spin_data and spin_data_pixel). The creation of the data bins is handled by the call to the set_bin_info module. If the set_bin_info module has not been called, an error code is returned to the calling module. The data set of interest is referenced through the key value data_key which can be created using the get_data_key module.

The parameter **version** allows multiple file openings for an IDFS data set. If the data, header and VIDF file for the specified data set need to be opened just once for processing, the same version number should be passed to all IDFS routines. However, for multiple file openings, the version number should be unique and all file manipulations performed by the IDFS routines will use the file descriptors defined for the version number specified. The user should call the **get_version_number** routine to retrieve a unique version number instead of choosing this value themselves. The retrieval of multiple data parameters from a

single data source does not constitute the need for multiple version numbers; a single version number will suffice.

If the **file_open** routine is not to open the default set of IDFS files but a modified set of IDFS files, the two character extension applied to these data files must be supplied to this routine within the string variable **exten**. These files must have the identical name as the IDFS files with the two character identification code appended to the end of the file names (i.e. RTLA19922181432Dxx, RTLA19922181432Hxx, RTLA19922181432Ixx). The files must reside either in the directory specified by the environment variable USER_DATA, which is set by the user, or in the user's home directory if the environment variable USER_DATA is not set. To open the default IDFS data files, **exten** should be set to a null string. The usage of modified data sets is limited to post acquisition data; therefore, it is suggested that the user set **exten** to a null string for real-time scenarios.

ERRORS

All errors within this routine are returned through the status variable. The include file **ret_codes.h**, which includes all possible return values, should be included so that the mnemonics for the return codes can be referenced. The **ret_codes.h** file is described in section 1H of the IDFS Programmers Manual.

SEE ALSO

file_open	1 R
fill_data	2R
fill_discontinuous_data	2R
sweep_data	2R
sweep_discontinuous_data	2R
spin_data	2R
spin_data_pixel	2R
set_bin_info	2R
get_data_key	1 R
get_version_number	1 R
ret_codes	1H
libtrec_idfs	2H

BUGS

None

EXAMPLES

Determine the number of data bins created for the SPIA virtual instrument, which is part of the SPREE instrument/experiment, which is part of the TSS-1 mission, which is identified with the TSS project. For this example, assume that the module **set_bin_info** has previously been called.

```
#include "libtrec_idfs.h"
#include "ret_codes.h"
SDDAS_ULONG data_key;
SDDAS_USHORT vnum;
SDDAS_SHORT status, num_bins;
status = get_data_key ("TSS", "TSS-1", "SPREE", "SPREE", "SPIA", &data_key);
if (status != ALL_OKAY)
{
 printf ("\n Error %d returned by get_data_key routine.\n", status);
 exit (-1);
 }
get_version_number (&vnum);
status = number_of_data_bins (data_key, '''', vnum, &num_bins);
if (status != ALL_OKAY)
{
  printf ("\n Error %d from number_of_data_bins routine.\n", status);
  exit (-1);
```

}

NUMBER_OF_PHI_BINS

function - returns the number of phi bins created for the data set of interest

SYNOPSIS

#include "libtrec_idfs.h"
#include "ret_codes.h"

ARGUMENTS

data_key	- unique	value which indicates the data set of interest
exten	- two cha	racter extension to be added to IDFS file
		when default files are not to be used, otherwise,
	a null st	tring
version	- IDFS da	ata set identification number which allows for
	multiple	e openings of the same data set
num_phi_bins	- the num	ber of phi bins created for the data set
number_of_phi_bins	- routine	status (see TABLE 1)

TABLE 1.	Status Codes Returned	for NUMBER	_OF_PHI_BINS
----------	-----------------------	------------	--------------

STATUS CODE	EXPLANATION OF STATUS
NPHI_NOT_FOUND	the requested data_key, exten, version combination has no memory allocated for
	processing (user did not call file_open for this combination)
NPHI_NO_BINS	no memory has been allocated to hold the collapsing information (user did not call
	set_collapse_info for this combination)
ALL_OKAY	routine terminated successfully

DESCRIPTION

Number_of_phi_bins is the IDFS routine that returns the number of phi bins that are utilized by the IDFS routines that return time-averaged data (fill_data and fill_discontinuous_data), sample-averaged data (sweep_data and sweep_discontinuous_data) or spin-averaged data (spin_data and spin_data_pixel). The creation of the phi bins is handled by the call to the set_collapse_info routine. If the set_collapse_info module has not been called, an error code is returned to the calling module. The data set of interest is referenced through the key value data_key which can be created using the get_data_key module.

The parameter **version** allows multiple file openings for an IDFS data set. If the data, header and VIDF file for the specified data set need to be opened just once for processing, the same version number should be passed to all IDFS routines. However, for multiple file openings, the version number should be unique and all file manipulations performed by the IDFS routines will use the file descriptors defined for the version number specified. The user should call the **get_version_number** routine to retrieve a unique version number instead of choosing this value themselves. The retrieval of multiple data parameters from a

single data source does not constitute the need for multiple version numbers; a single version number will suffice.

If the **file_open** routine is not to open the default set of IDFS files but a modified set of IDFS files, the two character extension applied to these data files must be supplied to this routine within the string variable **exten**. These files must have the identical name as the IDFS files with the two character identification code appended to the end of the file names (i.e. RTLA19922181432Dxx, RTLA19922181432Hxx, RTLA19922181432Ixx). The files must reside either in the directory specified by the environment variable USER_DATA, which is set by the user, or in the user's home directory if the environment variable USER_DATA is not set. To open the default IDFS data files, **exten** should be set to a null string. The usage of modified data sets is limited to post acquisition data; therefore, it is suggested that the user set **exten** to a null string for real-time scenarios.

ERRORS

All errors within this routine are returned through the status variable. The include file **ret_codes.h**, which includes all possible return values, should be included so that the mnemonics for the return codes can be referenced. The **ret_codes.h** file is described in section 1H of the IDFS Programmers Manual.

SEE ALSO

file_open	1 R
fill_data	2R
fill_discontinuous_data	2R
sweep_data	2R
sweep_discontinuous_data	2R
spin_data	2R
spin_data_pixel	2R
set_collapse_info	2R
get_data_key	1R
get_version_number	1R
ret_codes	1H
libtrec_idfs	2H

BUGS

None

EXAMPLES

Determine the number of phi bins created for the SPIA virtual instrument, which is part of the SPREE instrument/experiment, which is part of the TSS-1 mission, which is identified with the TSS project. For this example, assume that the module **set_collapse_info** has previously been called.

```
#include "libtrec_idfs.h"
#include "ret_codes.h"
SDDAS_ULONG data_key;
SDDAS_USHORT vnum;
SDDAS_SHORT status, num_phi_bins;
status = get_data_key ("TSS", "TSS-1", "SPREE", "SPREE", "SPIA", &data_key);
if (status != ALL_OKAY)
{
 printf ("\n Error %d returned by get_data_key routine.\n", status);
 exit (-1);
 }
get_version_number (&vnum);
status = number_of_phi_bins (data_key, '''', vnum, &num_phi_bins);
if (status != ALL_OKAY)
{
  printf ("\n Error %d from number_of_phi_bins routine.\n", status);
  exit (-1);
 }
```

RETURN_CENTER_AND_BAND_PTRS

function - returns the address of the center sweep and band width values associated with the data bins for the specified sensor

SYNOPSIS

#include "libtrec_idfs.h"
#include "ret_codes.h"

SDDAS_SHORT return_center_and_band_ptrs (SDDAS_ULONG data_key,
SDDAS_CHAR *exten, SDDAS_USHORT version,
SDDAS_SHORT sensor, SDDAS_FLOAT **center_ptr,
SDDAS_FLOAT **low_ptr, SDDAS_FLOAT **high_ptr)

ARGUMENTS

data_key	-	unique value which indicates the data set of interest
exten	-	two character extension to be added to IDFS file names when default files are not to be used, otherwise a null string
version	-	IDFS data set identification number which allows for multiple openings of the same data set
sensor	-	sensor identification number
center_ptr	-	pointer to the location that holds the center sweep values
low_ptr	-	pointer to the location that holds the lower bands for non-contiguous bands or all band widths for contiguous bands
high_ptr	-	pointer to the location that holds the upper bands for non-contiguous bands
return_center_and_band_	ptrs -	routine status (see TABLE 1)

STATUS CODE	EXPLANATION OF STATUS
RET_CENTER_NOT_FOUND	the requested data_key, exten, version combination has no memory allocated for
	processing (user did not call file_open for this combination)
RET_CBPTR_NOT_FOUND	no memory has been allocated to hold the binning information (user did not call
	set_bin_info for this combination)
RET_CBPTR_NO_SENSOR	the specified sensor is not flagged as a sensor to be process for this data set
ALL_OKAY	routine terminated successfully

DESCRIPTION

Return_center_and_band_ptrs is the IDFS routine that returns pointers to the center and band width sweep step values for the specified sensor, which have been created by a call to the **center_and_band_values** module. For any given virtual instrument, there may be one set of sweep step values to be used by all sensors or there may be a set of sweep step values defined for each individual sensor. The sweep step values are used by the IDFS routines that return time-averaged data (**fill_data** / **fill_discontinuous_data**), sample-averaged data

(sweep_data / sweep_discontinuous_data) or spin-averaged data (spin_data / spin_data_pixel). The data set of interest is referenced through the key value data_key which can be created using the get_data_key module.

The parameter **version** allows multiple file openings for an IDFS data set. If the data, header and VIDF file for the specified data set need to be opened just once for processing, the same version number should be passed to all IDFS routines. However, for multiple file openings, the version number should be unique and all file manipulations performed by the IDFS routines will use the file descriptors defined for the version number specified. The user should call the **get_version_number** routine to retrieve a unique version number instead of choosing this value themselves. The retrieval of multiple data parameters from a single data source does not constitute the need for multiple version numbers; a single version number will suffice.

If the **file_open** routine is not to open the default set of IDFS files but a modified set of IDFS files, the two character extension applied to these data files must be supplied to this routine within the string variable **exten**. These files must have the identical name as the IDFS files with the two character identification code appended to the end of the file names (i.e. RTLA19922181432Dxx, RTLA19922181432Hxx, RTLA19922181432Ixx). The files must reside either in the directory specified by the environment variable USER_DATA, which is set by the user, or in the user's home directory if the environment variable USER_DATA is not set. To open the default IDFS data files, **exten** should be set to a null string. The usage of modified data sets is limited to post acquisition data; therefore, it is suggested that the user set **exten** to a null string for real-time scenarios.

The contents of the memory locations returned by this module should **NOT** be altered since the calculated center/band width values are used by the time-averaging, sample-averaging, or spin-averaging routine when processing the data. If the returned values need to be modified, for example, to take the log of the values, the user should allocate space to hold the values, copy the values into this space and modify the values there.

The module returns two possible pointers for the location(s) that hold the lower and upper band width values. In the case where the bands are non-contiguous, both the **low_ptr** and **high_ptr** will reference memory locations that hold the band width values. In the case where the bands are contiguous, there is no need to hold separate upper and lower values – the upper limit of the current band is the lower limit of the next band. In this case, one extra memory location is allocated, the **high_ptr** pointer is set to nil or 0 and **low_ptr** is set to reference the location that holds the band width values.

ERRORS

All errors within this routine are returned through the status variable. The include file **ret_codes.h**, which includes all possible return values, should be included so that the mnemonics for the return codes can be referenced. The **ret_codes.h** file is described in section 1H of the IDFS Programmers Manual.

SEE ALSO

file_open	1R
fill_data	2R
fill_discontinuous_data	2R
sweep_data	2R
sweep_discontinuous_data	2R
spin_data	2R
spin_data_pixel	2R
set_bin_info	2R
center_and_band_values	2R
get_data_key	1R
get_version_number	1R
ret_codes	1H
libtrec_idfs	2H

BUGS

None

EXAMPLES

Print out the center sweep values used for binning the data for sensor 0 for the SPIA virtual instrument, which is part of the SPREE instrument/experiment, which is part of the TSS-1 mission, which is identified with the TSS project. This code segment assumes that calls to **set_bin_info** and **center_and_band_values** modules have been made.

#include "libtrec_idfs.h"
#include "ret_codes.h"

```
SDDAS_ULONG data_key;
SDDAS_USHORT vnum;
register SDDAS_SHORT bins, num_bins;
SDDAS_FLOAT *center_ptr, *low_ptr, *high_ptr;
SDDAS_SHORT status;
```

```
status = get_data_key ("TSS", "TSS-1", "SPREE", "SPREE", "SPIA", &data_key);
if (status != ALL_OKAY)
{
    printf ("\n Error %d returned by get_data_key routine.\n", status);
    exit (-1);
    get_version_number (&vnum);
.
    status = number_of_data_bins (data_key, "", vnum, &num_bins);
if (status != ALL_OKAY)
{
```

```
printf ("\n Error %d from number_of_data_bins routine.\n", status);
exit (-1);
```

}


```
if (status != ALL_OKAY)
{
    printf ("\n Error %d from return_center_and_band_ptrs routine.\n", status);
    exit (-1);
}
```

```
for (bins = 0; bins < num_bins; ++bins)
printf ("center sweep value [%d] = %.2f\n", bins, *(center_ptr + bins));</pre>
```

RETURN_PHI_PTRS

function - returns the phi bins and the data from the phi data matrix for the specified sensor for the specified buffer

SYNOPSIS

#include "libtrec_idfs.h"
#include "ret_codes.h"

ARGUMENTS

data_key	-	unique value which indicates the data set of interest
exten	-	two character extension to be added to IDFS file names when
		default files are not to be used, otherwise a null string
version	-	IDFS data set identification number which allows for multiple
		openings of the same data set
sensor	-	sensor identification number
ret_data	-	pointer to the data being returned
cyclic	-	flag indicating if the data is cyclic
		0 - data is not cyclic
		1 - data is cyclic
order	-	the order of the fit, i.e. 1, 2, 3, etc.
		- This parameter is used if the bin fill method chosen in the
		call to the set_bin_info routine is any value other than
		NO_BIN_FILL.
need_filled	-	the number of filled bins needed in order to fill in the missing
		data bins
tension	-	the weighting of the data
bin_project	-	flag indicating if the data is to be projected into empty bins
		beyond the first or last data bin which contains data
		0 - do not project the data
		1 - project the data
unit_index	-	index value specifying which data level or unit is to be
		returned for the sensor in question
num_phi	-	the number of phi bins that are being returned
phi_bins	-	pointer to the location that holds the phi bin values
data_size	-	the number of data values returned per phi bin
cur_buf	-	the current buffer being processed (number between 0 and
		NUM_BUFFERS-1)

return_phi_ptrs - routine status (see TABLE 1)

TABLE 1.	Status Codes Returned for RETURN_PHI_PTRS
----------	--

STATUS CODE	EXPLANATION OF STATUS
RET_PHI_NOT_FOUND	the requested data_key, exten, version combination has no memory allocated for
	processing (user did not call file_open for this combination)
CPTR_RET_PHI	no memory has been allocated to hold the collapsing information (user did not call
	set_collapse_info for this combination)
NO_RET_PHI	the phi bins were disabled by the call to set_collapse_info
ALL_OKAY	routine terminated successfully

DESCRIPTION

Return_phi_ptrs is the IDFS routine that returns both the phi band limits and the corresponding sensor data for a given sensor. The sensor data is acquired by the IDFS routines that return time-averaged data (**fill_data**), sample-averaged data (**sweep_data**), or spin-averaged data (**spin_data / spin_data_pixel**). The width of the phi bins was created using the information specified by the call to the **set_collapse_info** module. If the **set_collapse_info** module has not been called or if the phi bins were disabled by the call to the **set_collapse_info** module, an error code is returned to the calling module. The data set of interest is referenced through the key value **data_key** which can be created using the **get_data_key** module.

The parameter **version** allows multiple file openings for an IDFS data set. If the data, header and VIDF file for the specified data set need to be opened just once for processing, the same version number should be passed to all IDFS routines. However, for multiple file openings, the version number should be unique and all file manipulations performed by the IDFS routines will use the file descriptors defined for the version number specified. The user should call the **get_version_number** routine to retrieve a unique version number instead of choosing this value themselves. The retrieval of multiple data parameters from a single data source does not constitute the need for multiple version numbers; a single version number will suffice.

If the **file_open** routine is not to open the default set of IDFS files but a modified set of IDFS files, the two character extension applied to these data files must be supplied to this routine within the string variable **exten**. These files must have the identical name as the IDFS files with the two character identification code appended to the end of the file names (i.e. RTLA19922181432Dxx, RTLA19922181432Hxx, RTLA19922181432Ixx). The files must reside either in the directory specified by the environment variable USER_DATA, which is set by the user, or in the user's home directory if the environment variable USER_DATA is not set. To open the default IDFS data files, **exten** should be set to a null string. The usage of modified data sets is limited to post acquisition data; therefore, it is suggested that the user set **exten** to a null string for real-time scenarios.

The pointer **ret_data** references the data for the sensor requested. The data is laid down by phi bin, with **data_size** elements being returned per phi bin. The data returned can be thought of as a 2-dimensional matrix, with **data_size** rows and **num_phi** columns. This

module must be called after a call to the **fill_data / sweep_data / spin_data / spin_data_pixel** routine, which fills in the phi data matrix, has been made. This module can not be utilized in conjunction with the **fill_discontinuous_data / sweep_discontinuous** module since the module can not process data sets with a PHI, MASS and/or CHARGE dimensionality. The user should process only those buffers that are flagged with the status value BUFFER_READY.

ERRORS

All errors within this routine are returned through the status variable. The include file **ret_codes.h**, which includes all possible return values, should be included so that the mnemonics for the return codes can be referenced. The **ret_codes.h** file is described in section 1H of the IDFS Programmers Manual.

SEE ALSO

file_open	1 R
fill_data	2R
sweep_data	2R
spin_data	2R
spin_data_pixel	2R
set_collapse_info	2R
get_data_key	1 R
get_version_number	1 R
ret_codes	1H
libtrec_idfs	2H

BUGS

None

EXAMPLES

Print out each phi band and associated data values for sensor 0 for the SPIA virtual instrument, which is part of the SPREE instrument/experiment, which is part of the TSS-1 mission, which is identified with the TSS project. For this example, assume that only one data level or unit is returned by the **fill_data** module (default mode) and that **buf_stat** had been set.

#include "libtrec_idfs.h"
#include "ret_codes.h"

SDDAS_ULONG data_key; SDDAS_USHORT vnum; register SDDAS_SHORT phi, sample; SDDAS_FLOAT *data_ptr, *phi_bands, *data; SDDAS_SHORT status, phi_bins, data_block; SDDAS_CHAR cur_buf, buf_num, *buf_stat; static SDDAS_CHAR which_buf = 0;

```
status = get_data_key ("TSS", "TSS-1", "SPREE", "SPREE", "SPIA", &data_key);
if (status != ALL OKAY)
{
 printf ("\n Error %d returned by get_data_key routine.\n", status);
 exit (-1);
}
get version number (&vnum);
cur_buf = which_buf;
for (buf num = 0; buf num < NUM BUFFERS; ++buf num)
{
 if (*(buf stat + cur buf) == BUFFER READY)
  {
     status = return_phi_ptrs (data_key, "", vnum, 0, &data_ptr, 0, 0, 2, 0.0,
                          0, 0, &phi_bins, &phi_bands, &data_block, cur buf);
     if (status != ALL_OKAY)
      {
       printf ("\n Error %d returned by return phi ptrs routine.\n", status);
       exit (-1);
      }
     for (phi = 0; phi < phi bins; ++phi)
      {
       printf ("phi bin is from %.2f to %.2f\n", *(phi_bands + phi),
                                             (phi_bands + phi + 1));
      data = data_ptr + phi * data_block;
      for (sample = 0; sample < data block; ++sample)
         printf ("data[%d] = \%.2e\n", sample, *(data + sample));
      }
      which_buf = (cur_buf + 1) % NUM_BUFFERS;
    }
   cur_buf = (cur_buf + 1) % NUM_BUFFERS;
  }
```

SET_BIN_INFO

function - specifies how time-averaged, sample-averaged, or spin-averaged data is to be binned

SYNOPSIS

#include "libtrec_idfs.h"
#include "ret_codes.h"
#include "user_defs.h"

SDDAS_SHORT set_bin_info (SDDAS_ULONG data_key, SDDAS_CHAR *exten,
SDDAS_USHORT version, SDDAS_CHAR swp_type,
SDDAS_FLOAT start, SDDAS_FLOAT stop,
SDDAS_FLOAT delta, SDDAS_SHORT num_bins,
SDDAS_CHAR swp_fmt, SDDAS_CHAR num_center,
SDDAS_CHAR *center_tbls, SDDAS_LONG *center_opers,
SDDAS_CHAR num_band, SDDAS_CHAR *band_tbls,
SDDAS_LONG *band_opers,
SDDAS_CHAR num_upper_band,
SDDAS_CHAR *upper_band_tbls,
SDDAS_LONG *upper_band_opers,
SDDAS_CHAR var_fmt, SDDAS_CHAR input_fmt,
SDDAS_CHAR bin_fill)

ARGUMENTS

data_key	-	unique value which indicates the data set of interest
exten	-	two character extension to be added to IDFS file names when
		default files are not to be used, otherwise a null string
version	-	IDFS data set identification number which allows for multiple
		openings of the same data set
swp_type	-	the format used to determine the number of data bins
		1 - use swp_len number of bins (FIXED_SWEEP)
		2 - user will specify the number of bin
start	-	
stop	-	-
delta	-	
num_bins	-	
swp_fmt	-	the spacing for the bins
		0 - use zero spacing (ZERO_SPACING)
		1 0 0
		3 - use variable width spacing
		(VARIABLE_SPACING)
		275 December 28, 2012
stop delta num_bins	-	(VARIABLE_SWEEP) the center value associated with the first bin for variable sweep processing the center value associated with the last bin for variable sweep processing the skip increment (delta) to use to create the bins for variable sweep processing the number of bins to create for variable sweep processing the number of bins to create for variable sweep processing the spacing for the bins 0 - use zero spacing (ZERO_SPACING) 1 - use linear spacing (LIN_SPACING) 2 - use logarithmic spacing (LOG_SPACING) 3 - use variable width spacing (VARIABLE_SPACING)

num_center	-	the number of elements in the center_tbls and center_opers
		parameters
center_tbls	-	the tables that are to be applied to derive the units for the
		center sweep step values for variable width spaced bins
center_opers	-	the operations that are to be applied to the specified tables to
		derive the units for the center sweep step values for variable
		width spaced bins
num_band	-	the number of elements in the band_tbls and band_opers
		parameters
band_tbls	-	the tables that are to be applied to derive the units for the band
—		width sweep step values for variable width spaced bins or the
		actual lower edge band width sweep step values for variable
		width spaced bins that use the 'A' format flag
band_opers	_	the operations that are to be applied to the specified tables to
band_opers	-	derive the units for the band width sweep step values for
		variable width spaced bins or the actual lower edge band
		1 0
		width sweep step values for variable width spaced bins that
1 1		use the 'A' format flag
num_upper_band	-	the number of elements in the upper_band_tbls and
1 1 1 1		upper_band_opers parameters
upper_band_tbls	-	the tables that are to be applied to derive the units for the
		actual upper edge band width sweep step values for variable
		width spaced bins that use the 'A' format flag
upper_band_opers	-	the operations that are to be applied to the specified tables to
		derive the units for the actual upper edge band width sweep
		step values for variable width spaced bins that use the 'A'
		format flag
var_fmt	-	the format flag for variable width spacing
		L or l - the center sweep values are used as the lower
		edge of the band width values
		C or c - the center sweep values are used as the
		midpoints of the band width values
		U or u - the center sweep values are used as the upper
		edge of the band width values
		E or e - the center sweep values are used as the lower
		edge of the band width values and the scan
		widths specified are the actual upper edge of
		the band width values, not delta values
		A or a - the actual center, lower edge band width and
		upper edge band width values are defined
		in the VIDF file (no computations off the
		center values are necessary)
input_fmt	-	the storage scheme for the binning of the data for variable
		sweep processing
		1 - data is placed in the bin which encompasses the
		sweep value associated with the data
		276 December 28, 2012

	 (POINT_STORAGE) 2 - data is placed in all bins which fully or partially contain the sweep range associated with the data (BAND_STORAGE)
bin_fill	- method used to fill in any empty data bins
	1 - leave the bins as is (NO_BIN_FILL)
	2 - linearly interpolate across the row and then down
	the column of data (LIN_ROW_COL)
	3 - linearly interpolate down the column and then
	across the row of data (LIN_COL_ROW)
	4 - project data inward across the row and then down
	the column of data (CON_ROW_COL)
	5 - project data inward down the column and then
	across the row of data (CON_COL_ROW)
	6 - apply a two-d least squares fit to the data
	(LEAST_SQ_FIT)
set_bin_info	- routine status (see TABLE 1)

TABLE 1. Status	Codes Returned for	SET_BIN_INFO
-----------------	--------------------	--------------

STATUS CODE	EXPLANATION OF STATUS
SET_BIN_NOT_FOUND	the requested data_key, exten, version combination has no memory
	allocated for processing (user did not call file_open for this
	combination)
SET_BIN_BAD_FMT	ZERO_SPACING or VARIABLE_SPACING can only be requested in
	conjunction with FIXED SWEEP processing
SET_BIN_MALLOC	no memory for data binning information
SET_BIN_INDEX_MALLOC	no memory for index values for the sensors
SET_VWIDTH_CENTER_MALLOC	no memory to hold center tables and operations for variable width
	spacing
SET_VWIDTH_BAND_MALLOC	no memory to hold band width tables and operations for variable width
	spacing
SET_VWIDTH_UPPER_BAND_MALLOC	no memory to hold upper band width tables and operations for variable
	width spacing
	Error codes returned by set_collapse_info ()
ALL_OKAY	routine terminated successfully

DESCRIPTION

Set_bin_info is the IDFS routine that is utilized to define the size and spacing of the data buffers that will be filled by the IDFS routines that return time-averaged data (fill_data / fill_discontinuous_data), sample-averaged data (sweep_data / sweep_discontinuous_data), or spin-averaged data (spin_data / spin_data_pixel). The data set of interest is referenced through the key value data_key which can be created using the get_data_key module. The first call to the set_bin_info routine for the data set specified will be used to generate the binning information. All subsequent calls with the identical data_key, exten and version parameters will be ignored. This module must be called prior to calling the time-averaging, sample-averaging, or spin-averaging routine; otherwise, an error code will be returned. If the only type of data to be processed for the

data set in question is instrument status (mode) data, the user does not need to call this module since the **fill_mode_data / sweep_mode_data** routine determines the size and spacing of the data buffers.

The parameter **version** allows multiple file openings for an IDFS data set. If the data, header and VIDF file for the specified data set need to be opened just once for processing, the same version number should be passed to all IDFS routines. However, for multiple file openings, the version number should be unique and all file manipulations performed by the IDFS routines will use the file descriptors defined for the version number specified. The user should call the **get_version_number** routine to retrieve a unique version number instead of choosing this value themselves. The retrieval of multiple data parameters from a single data source does not constitute the need for multiple version numbers; a single version number will suffice.

If the **file_open** routine is not to open the default set of IDFS files but a modified set of IDFS files, the two character extension applied to these data files must be supplied to this routine within the string variable **exten**. These files must have the identical name as the IDFS files with the two character identification code appended to the end of the file names (i.e. RTLA19922181432Dxx, RTLA19922181432Hxx, RTLA19922181432Ixx). The files must reside either in the directory specified by the environment variable USER_DATA, which is set by the user, or in the user's home directory if the environment variable USER_DATA is not set. To open the default IDFS data files, **exten** should be set to a null string. The usage of modified data sets is limited to post acquisition data; therefore, it is suggested that the user set **exten** to a null string for real-time scenarios.

There are two formats that can be used to bin the data, FIXED SWEEP and VARIABLE SWEEP. With a FIXED_SWEEP format, the bins are set up according to the information found in the VIDF file. The element **swp_len** is used to determine the number of bins. The data is stored into the bins by using the values found in the **scan_index** array as index values into the data bins. The **scan_index** array is contained in the header record. When specifying a FIXED sweep format, the values for the parameters **start**, **stop**, **delta**, **num_bins** and **input_fmt** are ignored. If the virtual instrument selected is a scalar instrument, the **set_bin_info** module will default to the FIXED SWEEP format with LINEAR SPACED bins, regardless of the setting of the parameters.

If the user selects a VARIABLE SWEEP format, the user must specify the number of bins to create (**num_bins**), the spacing of the bins (**swp_fmt**), the center value associated with the first bin (**start**), the center value associated with the last bin (**stop**), the skip increment between bins (**delta**) and the scheme to use for storing the data (**input_fmt**). The data in a vector data set are taken as a function of a variable M. If M is allowed to vary over the individual measurement period or if M actually represents a band width, then each element in the vector can be considered to have been accumulated with the interval M - $\delta 1$ to M + $\delta 2$. Vector data is binned (along the rows) by M. If the user selects the POINT STORAGE scheme, the data is stored by the center variable M. If the center variable M is located between the upper and lower edge values of a given bin, the data value is placed only in this bin. If the user selects the BAND STORAGE scheme, the data is placed in all bins which

December 28, 2012

are fully or partially contained within the range M - $\delta 1$ to M + $\delta 2$. The data is multiplied by the percentage of the bin covered by the range before the data is placed into the bin.

The **bin_fill** parameter defines the method that is to be used to fill in bins that have not been filled in with data. If the data bins are to be left as is, with the unfilled bins left unfilled, the user should set this parameter to NO_BIN_FILL. When selecting a fill method, the user must be aware that for some of the virtual instruments, the binning of the data occurs within a two-dimensional set of bins. In this 2-D binning matrix, the columns represent the data bins and the rows represent phi or azimuthal bins. If the sensor measurements are independent of phi, the binning of the data is only one-dimensional; otherwise, the binning is two-dimensional. In both 1-D and 2-D binning, missing or unfilled bins can be filled by linearly interpolating across the holes using values defined at adjacent bins (LINEAR) or the data in the adjacent bins can be projected inward across the area of missing bins meeting in the center of the gap (CONSTANT). For 2-D binning, such filling can either occur first along the columns (ROW/COL). The 2-D LEAST SQUARES FIT fill method is selectable only for the 2-D data binning. If the user selects this fill method for 1-D data binning, the **set_bin_info** module will change the option to LINEAR COL/ROW (LIN_COL_ROW).

The user should be aware that the data buffers that come back from the time-averaged, sample-averaged, and spin-averaged routines are NOT modified as far as missing bins is concerned. If the user wishes to fill in the missing bins according to the **bin_fill** parameter, the user must call the module **buffer_bin_fill**. If the data are collapsed over specified dimensions, the **buffer_bin_fill** module need not be called.

Some of the error codes returned by this module are the error codes returned by the module **set_collapse_info**. With regards to calling sequences, if the **set_bin_info** module is to be utilized, it should be called before the **set_collapse_info** module is called since the **set_collapse_info** module allocates space based upon the number of bins for the data buffers. If it is determined that the **set_collapse_info** module was called prior to calling the **set_bin_info** routine, the **set_collapse_info** routine will be recalled from within the **set_bin_info** module in order to allocate space for the correct number of bins.

The parameter **swp_fmt** specifies how the band width values are to be calculated using the center sweep step values. Two of the options, zero spacing (ZERO_SPACING) and variable width spacing (VARIABLE_SPACING) are applicable only for FIXED_SWEEP processing. If the user tries to specify these values for VARIABLE_SWEEP processing, an error code is returned. Zero spacing defines a scheme where the lower edge of the band is the same as the upper edge of the band; that is, the band width values are the same as the center values. Linear spacing defines a scheme where the lower (upper) edge of the band is determined by subtracting (adding) one-half of the difference between two successive center values from (to) the center value. The same algorithm is used for log spacing, with the log of the center values being utilized. Variable width spacing defines a scheme which makes use of tables defined in the VIDF file to create the center and band width values. The parameters **num_center, center_tbls** and **center_opers** define the tables and table operations that are to be utilized to calculate the center sweep step values. The parameters

December 28, 2012

num_band, **band_tbls** and **band_opers** define the tables and table operations that are to be utilized to calculate correction values that are to be applied to the center values in order to calculate the band width values. The variable var_fmt specifies how the correction values are to be applied. If the **var_fmt** value is 'L' or 'l', the lower edge of the band is set to the center value and the upper edge of the band is calculated by adding the correction value to the center value. If the **var fmt** value is 'C' or 'c', the lower edge of the band is calculated by subtracting one-half of the correction value from the center value and the upper edge of the band is calculated by adding one-half of the correction value to the center value. If the var_fmt value is 'U' or 'u', the lower edge of the band is calculated by subtracting the correction value from the center value and the upper edge of the band is set to the center value. If the **var_fmt** value is 'E' or 'e', the lower edge of the band is set to the center value and the upper edge of the band is set to the correction value; therefore, the correction value is not really a delta value, it is the actual value to be used as the upper edge of the band. If this format is selected, please take note that the center values and the lower edge values will be identical. If the **var_fmt** value is 'A' or 'a', there is no need to perform a computation using the center values in order to derive the lower and upper edges of the band. The "actual" values for the centers, lower edges and upper edges of the scan band are defined within the VIDF. The parameters num center, center tbls, and center opers define the tables and table operations that are to be utilized to calculate the center sweep step values. The parameters num_band, band_tbls, and band_opers define the tables and table operations that are to be utilized to calculate the lower edges of the band. The parameters num upper band, upper band tbls, and upper band opers define the tables and table operations that are to be utilized to calculate the upper edges of the band. The user is referred to the center and band values write-up for more information concerning center and band width values.

ERRORS

All errors within this routine are returned through the status variable. The include file **ret_codes.h**, which includes all possible return values, should be included so that the mnemonics for the return codes can be referenced. The **ret_codes.h** file is described in section 1H of the IDFS Programmers Manual.

SEE ALSO

file_open	1 R
fill_data	2R
fill_discontinuous_data	2R
fill_mode_data	2R
sweep_data	2R
sweep_discontinuous_data	2R
sweep_mode_data	2R
spin_data	2R
spin_data_pixel	2R
set_scan_info	2R
buffer_bin_fill	2R
get_data_key	1 R
set_collapse_info	2R

center_and_band_values	2R
get_version_number	1 R
ret_codes	1H
user_defs	1H
libtrec_idfs	2H

BUGS

None

EXAMPLES

Create the data bins using the FIXED SWEEP/LINEAR SPACED binning scheme and leave empty bins unprocessed for the virtual instrument RTLA, which is part of the RETE instrument/experiment, which is part of the TSS-1 mission, which is identified with the TSS project.

#include "libtrec_idfs.h"
#include "ret_codes.h"
#include "user_defs.h"
#define DUMMY_VAL 0

```
SDDAS_ULONG data_key;
SDDAS_USHORT vnum;
SDDAS_LONG *no_opers = NULL;
SDDAS_SHORT status;
SDDAS_CHAR *no_tbls = NULL;
```

```
status = get_data_key ("TSS", "TSS-1", "RETE", "RETE", "RTLA", &data_key);
if (status != ALL_OKAY)
{
    printf ("\n Error %d returned by get_data_key routine.\n", status);
    exit (-1);
    get_version_number (&vnum);
```

Create sixteen bins, starting at 5ev, stopping at 155ev, using a delta of 10ev per bin, with log spacing and the data is to be stored using BAND STORAGE. Empty bins are be left alone.

#include "libtrec_idfs.h"
#include "ret_codes.h"

```
SDDAS_ULONG data_key;
SDDAS_USHORT vnum;
SDDAS_LONG *no_opers = NULL;
SDDAS_SHORT status;
SDDAS_CHAR *no_tbls = NULL;
```

```
status = get_data_key ("TSS", "TSS-1", "RETE", "RETE", "RTLA", &data_key);
if (status != ALL_OKAY)
{
    printf ("\n Error %d returned by get_data_key routine.\n", status);
    exit (-1);
}
```

```
get_version_number (&vnum);
```

```
status = set_bin_info (data_key, "", vnum, VARIABLE_SWEEP, 5.0, 155.0, 10.0, 16,
	LOG_SPACING, 0, no_tbls, no_opers, 0, no_tbls,
	no_opers, 0, no_tbls, no_opers, '\0', BAND_STORAGE,
	NO_BIN_FILL);
if (status != ALL_OKAY)
{
	printf ("\n Error %d returned by set_bin_info routine.\n", status);
	exit (-1);
}
```

Create the data bins using the FIXED SWEEP/VARIABLE WIDTH SPACED binning scheme and fill in the empty bins using a constant row/column approach for the virtual instrument RTLA, which is part of the RETE instrument/experiment, which is part of the TSS-1 mission, which is identified with the TSS project.

```
#include "libtrec_idfs.h"
#include "ret_codes.h"
SDDAS_ULONG data_key;
SDDAS_USHORT vnum;
SDDAS_SHORT status;
SDDAS_LONG center_opers[1], lower_band_opers[2], upper_band_opers[2];
SDDAS_CHAR center_tbls[1], lower_band_tbls[2], upper_band_tbls[2];
```

```
SDDAS_CHAR num_center, num_lower_band, num_upper_band;
```

```
status = get_data_key ("TSS", "TSS-1", "RETE", "RETE", "RTLA", &data_key);
if (status != ALL OKAY)
{
 printf ("\n Error %d returned by get_data_key routine.\n", status);
 exit (-1);
ł
get_version_number (&vnum);
num_center = 1;
center tbls[0] = 5;
center_opers[0] = 0;
num lower band = 2;
lower_band_tbls[0] = 7;
lower_band_tbls[1] = 8;
lower_band_opers[0] = 0;
lower_band_opers[1] = 3;
num upper band = 2;
upper_band_tbls[0] = 9;
upper_band_tbls[1] = 10;
upper_band_opers[0] = 0;
upper band opers[1] = 3;
status = set_bin_info (data_key, "", vnum, FIXED_SWEEP, DUMMY_VAL,
                    DUMMY_VAL, DUMMY_VAL, DUMMY_VAL,
                    VARIABLE_SPACING, num_center, center_tbls, center_opers,
                    num lower band, lower band tbls, lower band opers,
                    num_upper_band, upper_band_tbls, upper_band_opers,
                    'A', POINT_STORAGE, CON_ROW_COL);
if (status != ALL OKAY)
{
 printf ("\n Error %d returned by set bin info routine.\n", status);
 exit (-1);
}
```

set_bin_info (2R)

SET_COLLAPSE_INFO

function - sets up information that is pertinent to the collapsing of the data over multiple dimensions

SYNOPSIS

#include "libtrec_idfs.h"
#include "ret_codes.h"

SDDAS_SHORT set_collapse_info (SDDAS_ULONG data_key, SDDAS_CHAR *exten,
SDDAS_USHORT version, SDDAS_SHORT num_units,
SDDAS_FLOAT delta_phi, SDDAS_FLOAT *actual_phi,
SDDAS_CHAR interleave)

ARGUMENTS

data_key	-	unique value which indicates the data set of interest
exten	-	two character extension to be added to IDFS file names when default files are not to be used, otherwise a null string
version	-	IDFS data set identification number which allows for multiple openings of the same data set
num_units	-	the total number of units or data levels to be returned for all
		sensors (must be the same for all sensors)
delta_phi	-	the requested resolution of the phi bins
actual_phi	-	the actual resolution used for the phi bins
interleave	-	flag indicating if the data is to be interleaved (data not cleared
		out if missing on next sweep)
		0 - clear out data matrices and buffers upon each
		call to the fill_data / fill_discontinuous_data /
		sweep_data / sweep_discontinuous_data /
		<pre>spin_data / spin_data_pixel routine</pre>
		1 - leave the data matrices and buffers preserved
		(do not clear)
set_collapse_info	-	routine status (see TABLE 1)

TABLE 1. Status Codes Returned for SET_COLLAPSE_INFO

STATUS CODE	EXPLANATION OF STATUS
COLLAPSE_NOT_FOUND	the requested data_key, exten, version combination has no memory allocated for
	processing (user did not call file_open for this combination)
COLLAPSE_MALLOC	no memory to hold the data collapsing structures
COLLAPSE_SEN_MALLOC	no memory to hold sensor specific collapsing information
THETA_CHK_MALLOC	no memory for temporary array
THETA_BIN_MALLOC	no memory for theta angle values
ORDER_THETA_MALLOC	no memory for theta bin order indexes
COLLAPSE_DATA_MALLOC	no memory for matrices that hold data gathered over specific dimensions
COLLAPSE_DATA_ADDRESS	no memory to hold the array of addresses of the pointers to the data and
	normalization factors for the phi matrices
ALL_OKAY	routine terminated successfully

DESCRIPTION

Set_collapse_info is the IDFS routine which sets up the data matrices and other information that is pertinent to collapse data over the charge, mass, phi, theta and/or scan dimensions. The data set of interest is referenced through the key value data_key which can be created using the get_data_key module. The first call to the set_collapse_info module for the data set specified will be used to generate the dimension collapsing information. All subsequent calls specifying the same data set will be ignored. In addition, if the module set_bin_info is to be utilized, it should be called prior to calling this module since this module allocates space based upon the number of bins per data buffer. If the only type of data to be processed for the data set in question is instrument status (mode) data, the user does not need to call this module since dimensionality is associated with sensor-specific data and instrument status data is not sensor-specific.

The parameter **version** allows multiple file openings for an IDFS data set. If the data, header and VIDF file for the specified data set need to be opened just once for processing, the same version number should be passed to all IDFS routines. However, for multiple file openings, the version number should be unique and all file manipulations performed by the IDFS routines will use the file descriptors defined for the version number specified. The user should call the **get_version_number** routine to retrieve a unique version number instead of choosing this value themselves. The retrieval of multiple data parameters from a single data source does not constitute the need for multiple version numbers; a single version number will suffice.

If the **file_open** routine is not to open the default set of IDFS files but a modified set of IDFS files, the two character extension applied to these data files must be supplied to this routine within the string variable **exten**. These files must have the identical name as the IDFS files with the two character identification code appended to the end of the file names (i.e. RTLA19922181432Dxx, RTLA19922181432Hxx, RTLA19922181432Ixx). The files must reside either in the directory specified by the environment variable USER_DATA, which is set by the user, or in the user's home directory if the environment variable USER_DATA is not set. To open the default IDFS data files, **exten** should be set to a null string. The usage of modified data sets is limited to post acquisition data; therefore, it is suggested that the user set **exten** to a null string for real-time scenarios.

If the virtual instrument acquires data as a function of phi and the user wishes to average the data over a specified phi range, the **fill_data** / **sweep_data** / **spin_data** / **spin_data_pixel** routine must be used to acquire the phi data matrix. The user must call the **set_collapse_info** module before any data is gathered in order to specify the resolution of the phi bins and to specify if the interleave option is to be utilized when building the phi matrix. If the phi data matrix is not needed, the user should pass 360.0 for the **delta_phi** parameter. The **fill_discontinuous_data** / **sweep_discontinuous_data** routine does not support any data sets with a PHI dimension; therefore, the user should pass 360.0 for the **delta_phi** parameter if the **fill_discontinuous_data** / **sweep_discontinuous_data** routine is to be utilized. The parameter **actual_phi** returns the true resolution used for the phi bins. An internal calculation (360.0 / **delta_phi**) is performed to ensure that an integer number of phi bins results; therefore, in some cases, the resolution actually used may deviate from the

December 28, 2012

resolution specified. The interleave option will be utilized for all data matrices that are associated with a specific dimension.

The default mode for the fill_data / fill_discontinuous_data / sweep_data / sweep_discontinuous_data / spin_data_pixel routines is to return sensor data in one data level (raw units) for each of the sensors processed. If the default mode is preserved, the value for the parameter num_units should be set to one. If the user made any calls to the fill_sensor_info module to add/modify the data level(s) being returned, the value for the parameter num_units can be retrieved by calling the module units_index.

ERRORS

All errors within this routine are returned through the status variable. The include file **ret_codes.h**, which includes all possible return values, should be included so that the mnemonics for the return codes can be referenced. The **ret_codes.h** file is described in section 1H of the IDFS Programmers Manual.

SEE ALSO

file_open	1R
fill_data	2R
fill_discontinuous_data	2R
sweep_data	2R
sweep_discontinuous_data	2R
spin_data	2R
spin_data_pixel	2R
fill_sensor_info	2R
units_index	2R
set_bin_info	2R
get_data_key	1R
get_version_number	1 R
ret_codes	1H
libtrec_idfs	2H

BUGS

None

EXAMPLES

In order to produce a line plot from the RTLA virtual instrument, data must be collapsed over a frequency range. Assuming that a single data level (raw units) is being returned, make a call to disable phi information and the interleave option. The virtual instrument RTLA is part of the RETE instrument/experiment, which is part of the TSS-1 mission, which is identified with the TSS project.

#include "libtrec_idfs.h"
#include "ret_codes.h"

```
SDDAS_ULONG data_key;
SDDAS_USHORT vnum;
SDDAS_FLOAT actual_phi;
SDDAS_SHORT status, num_units;
num_units = 1;
status = get_data_key ("TSS", "TSS-1", "RETE", "RETE", "RTLA", &data_key);
if (status != ALL_OKAY)
{
    printf ("\n Error %d returned by get_data_key routine.\n", status);
    exit (-1);
    get_version_number (&vnum);
status = set_collapse_info (data_key, '''', vnum, num_units, 360.0, &actual_phi, 0);
if (status != ALL_OKAY)
```

```
{
    printf ("\n Error %d returned by set_collapse_info routine.\n", status);
    exit (-1);
}
```

SET_SCAN_INFO

function - specifies the tables/operations to be applied to arrive at the desired units for the sweep step values that are associated with the data bins

SYNOPSIS

#include "libtrec_idfs.h"
#include "ret_codes.h"

	SDDAS_SHORT set	_scan_i	nfo (SDDAS_ULONG data_key, SDDAS_CHAR *exten, SDDAS_USHORT version, SDDAS_CHAR num_tbls, SDDAS_CHAR *tbls_to_apply, SDDAS_LONG *tbl_oper)
ARGU	UMENTS		
	data_key	-	unique value which indicates the data set of interest
	exten	-	two character extension to be added to IDFS file names when
			default files are not to be used, otherwise a null string
	version	-	IDFS data set identification number which allows for multiple
			openings of the same data set
	num_tbls	-	the number of elements specified in the tbls_to_apply and
			tbl_oper parameters
	tbls_to_apply	-	the tables that are to be applied in order to derive the desired
			units for the sweep step values
	tbl_oper	-	the operations that are to be applied to the specified tables in
			order to derive the desired units for the sweep step values

set_scan_info -	routine status ((see TABLE 1)
-----------------	------------------	---------------

STATUS CODE	EXPLANATION OF STATUS
SET_SCAN_NOT_FOUND	the requested data_key, exten, version combination has no memory allocated for
	processing (user did not call file_open for this combination)
SCAN_BIN_MISSING	the data binning information has not been allocated (user did not call set_bin_info
	for this combination)
SCAN_INDEX_MALLOC	no memory to hold table offset values
SET_SCAN_TBL_MALLOC	no memory for table number / table operation information
SCAN_IDF_ELE_NOT_FOUND	the data item being requested was not found in the VIDF file
SCAN_IDF_MANY_BYTES	the number of elements being requested is more than the number of elements
	available for the selected field
SCAN_IDF_TBL_NUM	the table being requested exceeds the number of defined tables
SCAN_IDF_CON_NUM	the constant being requested exceeds the number of defined constants
SCAN_IDF_NO_ENTRY	the field being requested is not defined
ALL_OKAY	routine terminated successfully

TABLE 1. Status Codes Returned for SET_SCAN_INFO

DESCRIPTION

Set_scan_info is the IDFS routine that is utilized to specify the units for the sweep step values that are associated with the data bins defined by the **set_bin_info** module. These sweep step values are used by the IDFS routines that return time-averaged data (**fill_data** / **fill_discontinuous_data**), sample-averaged data (**sweep_data** /

sweep_discontinuous_data), or spin-averaged data (**spin_data** / **spin_data_pixel**) when storing the data into the data bins. This module must be called after the call to the **set_bin_info** module has been made; otherwise, an error code is returned. A call to this routine is optional since the **set_bin_info** module sets up the system to calculate the sweep step values in terms of raw units, with one set of sweep step values defined for all sensors for the selected data source. If the user intends to make use of this module, the call must be made **prior** to calling the **center_and_band_values** routine. If the only type of data to be processed for the data set in question is instrument status (mode) data, the user does not need to call this module since the **fill_mode_data** / **sweep_mode_data** routine determines how the data is to be stored in the data bins.

The data set of interest is referenced through the key value **data_key** which can be created using the **get_data_key** module. The first call to the **set_scan_info** module which indicates non-raw units will be used to specify the units for the sweep step values. All subsequent calls specifying the same data set will be ignored. This routine should be used with FIXED_SWEEP, non-variable width spaced data bins. If the user selected VARIABLE_SWEEP or FIXED_SWEEP with data bins that are created using VARIABLE_SPACING, the information specified by this routine is stored but not utilized when determining the sweep step values that are associated with the data bins; the information specified in the call to the **set_bin_info** routine is utilized.

The parameter **version** allows multiple file openings for an IDFS data set. If the data, header and VIDF file for the specified data set need to be opened just once for processing, the same version number should be passed to all IDFS routines. However, for multiple file openings, the version number should be unique and all file manipulations performed by the IDFS routines will use the file descriptors defined for the version number specified. The user should call the **get_version_number** routine to retrieve a unique version number instead of choosing this value themselves. The retrieval of multiple data parameters from a single data source does not constitute the need for multiple version numbers; a single version number will suffice.

If the **file_open** routine is not to open the default set of IDFS files but a modified set of IDFS files, the two character extension applied to these data files must be supplied to this routine within the string variable **exten**. These files must have the identical name as the IDFS files with the two character identification code appended to the end of the file names (i.e. RTLA19922181432Dxx, RTLA19922181432Hxx, RTLA19922181432Ixx). The files must reside either in the directory specified by the environment variable USER_DATA, which is set by the user, or in the user's home directory if the environment variable USER_DATA is not set. To open the default IDFS data files, **exten** should be set to a null string. The usage of modified data sets is limited to post acquisition data; therefore, it is suggested that the user set **exten** to a null string for real-time scenarios.

The units for the sweep step values associated with the data bins is specified by the user through the parameters **num_tbls**, **tbls_to_apply** and **tbl_oper**. If the user wants raw units, that is, the telemetry data, to be returned, the user should set the **num_tbls** parameter to zero and put a placeholder variable for the **tbls_to_apply** and **tbl_oper** parameters. For

December 28, 2012

other units, the user must specify the tables and the table operations that are to be applied to calculate the desired unit. The order is implied by the contents of the **tbls_to_apply** array.

ERRORS

All errors within this routine are returned through the status variable. The include file **ret_codes.h**, which includes all possible return values, should be included so that the mnemonics for the return codes can be referenced. The **ret_codes.h** file is described in section 1H of the IDFS Programmers Manual.

SEE ALSO

fill_data	2R
fill_discontinuous_data	2R
fill_mode_data	2R
sweep_data	2R
sweep_discontinuous_data	2R
sweep_mode_data	2R
spin_data	2R
spin_data_pixel	2R
set_bin_info	2R
center_and_band_values	2R
file_open	1 R
get_data_key	1 R
get_version_number	1 R
ret_codes	1H
libtrec_idfs	2H

BUGS

None

EXAMPLES

Indicate the tables that are to be applied to derive the sweep step values for the virtual instrument RTLA, which is part of the RETE instrument/experiment, which is part of the TSS-1 mission, which is identified with the TSS project.

#include "libtrec_idfs.h"
#include "ret_codes.h"

SDDAS_ULONG data_key; SDDAS_USHORT vnum; SDDAS_LONG tbl_oper[2]; SDDAS_SHORT status; SDDAS_CHAR num_tbls, tbls_to_apply[2];

```
status = get_data_key ("TSS", "TSS-1", "RETE", "RETE", "RTLA", &data_key);
if (status != ALL_OKAY)
{
    printf ("\n Error %d returned by get_data_key routine.\n", status);
    exit (-1);
    get_version_number (&vnum);
/* There are two tables to be applied to derive sweep step units. */
/* Table 3 is the first table to be applied, followed by table 5. */
num_tbls = 2;
tbls_to_apply[0] = 3:
```

tbls_to_apply[0] = 3; tbls_to_apply[1] = 5; tbl_oper[0] = 0; tbl_oper[1] = 3;

```
status = set_scan_info (data_key, "", vnum, num_tbls, tbls_to_apply, tbl_oper);
if (status != ALL_OKAY)
{
    printf ("\n Error %d returned by set_scan_info routine.\n", status);
    exit (-1);
}
```

SET_TIME_VALUES

function - sets the base reference time, reference location and time duration to be utilized by the fill_data / fill_discontinuous_data / fill_mode_data / spin_data_pixel modules

SYNOPSIS

#include "libtrec_idfs.h"

void set_time_values (SDDAS_USHORT version, SDDAS_SHORT base_year,
SDDAS_SHORT base_day, SDDAS_LONG base_sec,
SDDAS_LONG base_nano, SDDAS_LONG base_pix,
SDDAS_LONG res_sec, SDDAS_LONG res_nano)

ARGUMENTS

version	-	IDFS data set identification number which allows for multiple openings of the same data set
base_year	-	the year time component for the base reference time
base_day	-	the day time component for the base reference time
base_sec	-	the time of day in seconds for the base reference time
base_nano	-	the time of day residual in nanoseconds for the base reference time
base_pix	-	the reference point or location associated with the base reference time
res_sec	-	the time duration (delta) in seconds
res_nano	-	the time duration residual in nanoseconds

DESCRIPTION

Set_time_values is the IDFS routine that sets the base reference time, the reference location and the time duration values to be used by the **fill_data** / **fill_discontinuous_data** / **fill_mode_data** / **spin_data_pixel** routines. This routine should be called once, after all calls to the **file_open** and **file_pos** routines have been made. If the base reference time is not known, as is the case in real-time processing, the user can make a call to the **read_drec** / **read_drec_spin** module in order to retrieve the starting time of the first sweep processed.

The parameter **version** allows multiple file openings for an IDFS data set. If the data, header and VIDF file for the specified data set need to be opened just once for processing, the same version number should be passed to all IDFS routines. However, for multiple file openings, the version number should be unique and all file manipulations performed by the IDFS routines will use the file descriptors defined for the version number specified. The user should call the **get_version_number** routine to retrieve a unique version number instead of choosing this value themselves. The retrieval of multiple data parameters from a single data source does not constitute the need for multiple version numbers; a single version number will suffice.

ERRORS

This routine returns no status or error codes.

SEE ALSO

fill_data	2R
fill_discontinuous_data	2R
fill_mode_data	2R
spin_data_pixel	2R
file_open	1R
file_pos	1R
get_version_number	1 R
read_drec	1R
read_drec_spin	1R
libtrec_idfs	2H

BUGS

None

EXAMPLES

The base reference time to be utilized is 1992, day 23, time 00:25:36 which is equal to 1536 seconds. The resolution to be utilized is 1.500 seconds and the reference location is at zero. Assume that the variable **vnum** has been set by a previous call to the **get_version_number** routine.

set_time_values (vnum, 1992, 23, 1536, 0, 0, 1, 50000000);

SPIN_DATA

function - returns spin-averaged sensor-specific data

SYNOPSIS

#include "libtrec_idfs.h"
#include "ret_codes.h"

SDDAS_SHORT spin_data (SDDAS_ULONG data_key, SDDAS_CHAR *exten,
SDDAS_USHORT version, void *idf_data_ptr,
SDDAS_SHORT **ret_sensors, SDDAS_FLOAT **ret_data,
SDDAS_FLOAT **ret_frac, SDDAS_CHAR **bin_stat,
SDDAS_SHORT *num_sen, SDDAS_SHORT **num_units,
SDDAS_SHORT *block_size, SDDAS_SHORT **stime_yr,
SDDAS_SHORT **stime_day, SDDAS_LONG **stime_sec,
SDDAS_LONG **stime_nano, SDDAS_SHORT **etime_yr,
SDDAS_SHORT **etime_day, SDDAS_LONG **etime_sec,
SDDAS_LONG **etime_nano, SDDAS_CHAR *hdr_change)

ARGUMENTS

data_key	-	unique value which indicates the data set of interest
exten	-	two character extension to be added to IDFS file names when
		default files are not to be used, otherwise a null string
version	-	IDFS data set identification number which allows for multiple
		openings of the same data set
idf_data_ptr	-	pointer to the idf_data structure that temporarily holds
_		sensor data and pertinent ancillary data for the data set of
		interest
ret_sensors	-	an array which holds the sensor number(s) for which data is
		returned
		- the array is initialized to -1 in all elements;
		valid sensor numbers start with 0
ret_data	-	pointer to the data being returned (data for all sensors
		processed)
ret_frac	-	pointer to the normalization factors for the data being returned
bin_stat	-	pointer to status flags which are associated with each data bin
		returned
		0 - no data has been placed into the data
		bin being processed
		1 - data has been placed into the data bin
		being processed
num_sen	-	the number of elements in the ret_sensors array
num_units	-	an array holding the number of data sets to bypass in order to
		get to the data for the sensor being processed
block_size	-	the number of data values returned in a data buffer
stime_yr	-	pointer to the start time year value for the first sweep
		contained within the spin being processed

stime_day	-	pointer to the start time day of year value for the first sweep contained within the spin being processed
stime_sec	-	pointer to the start time of day value (in seconds) for the first sweep contained within the spin being processed
stime_nano	-	pointer to the start time of day residual (in nanoseconds) for the first sweep contained within the spin being processed
etime_yr	-	pointer to the end time year value for the last sweep contained within the spin being processed
etime_day	-	pointer to the end time day of year value for the last sweep contained within the spin being processed
etime_sec	-	pointer to the end time of day value (in seconds) for the last sweep contained within the spin being processed
etime_nano	-	pointer to the end time of day residual (in nanoseconds) for the last sweep contained within the spin being processed
hdr_change	-	flag which indicates a header change occurred while processing the data
		0 - a header change was not encountered during the processing of the data
		1 - a header change was encountered during the processing of the data
spin_data	-	routine status (see TABLE 1)

TABLE 1. Status Codes Returned for SPIN_DATA

STATUS CODE	EXPLANATION OF STATUS
SPIN_DATA_NOT_FOUND	the requested data_key, exten, version combination has no memory
	allocated for processing (user did not call file_open for this
	combination)
SPIN_DATA_NO_SPIN	the requested data set does not spin
FILL_ARRAY_MALLOC	no memory for structure which holds information pertinent to the spin-
	averaged data
SPIN_DATA_BIN_MISSING	the data binning information has not been allocated (user did not call
	set_bin_info for this combination)
SPIN_DATA_CENTER_BAND_MISSING	the routine center_and_band_values has not been called prior to
	calling the spin_data routine
SPIN_INFO_MALLOC	no memory for data buffer information
SPIN_UNITS_MALLOC	no memory to hold the various data levels for the data buffer
SPIN_UNITS_REALLOC	no memory for expansion of space to hold the various data levels for the
	data buffer
SPIN_SWP_MALLOC	no memory for sweep values in specified units
SPIN_SWP_REALLOC	no memory for expansion of sweep values in specified units
SPIN_DATA_MALLOC	no memory for data buffer
SPIN_DATA_WITH_FILL_SWEEP	spin_data cannot be used interchangeably with the fill_data and / or
	sweep_data routines for the same data key, extension, version
	combination
PHI_DIFF_UNITS	the sensors being processed do not process the same number of data
	levels (units)
FILL_PHI_FIRST	the starting azimuthal angle was not contained within any of the defined
	phi bins

STATUS CODE	EXPLANATION OF STATUS
FILL_PHI_LAST	the ending azimuthal angle was not contained within any of the defined
	phi bins
SWP_TIMES_TMP_MALLOC	no memory to hold the time components for each element of the sweep
BAD_VFMT	bad format character for variable width bin spacing
	error codes returned by fill_sensor_info ()
	error codes returned by read_drec_spin ()
	error codes returned by convert_to_units ()
ALL_OKAY	routine terminated successfully

DESCRIPTION

Spin_data is the IDFS spin-averaging data read routine for sensor-specific data, summing the data for all sweeps that pertain to the spin being processed. The data set of interest is referenced through the key value **data_key** which can be created using the **get_data_key** module. **Spin_data** processes sensor-specific data only, that is, it can process sensor, sweep step, calibration, data quality, pitch angle, azimuthal angle, spacecraft potential and background data; however, the type of manipulation being performed by this module is best suited to sensor data. **Spin_data** assumes that the data set of interest does not roll over to a minimum value when the maximum threshold has been reached or to a maximum value when the minimum threshold has been reached. This assumption is crucial since multiple samples are averaged together. If the data set does roll over at the thresholds, the averaging of these samples will probably result in incorrect data values. An example of a roll over data set is longitude data, which resets values to the minimum threshold (-180) when the maximum threshold (180) has been reached.

For the **spin_data** module, data acquisition is based upon a full spin of data, not a given time interval as with the **fill_data** module; however, there is still the need to utilize some form of time control. The sensor that is selected as the controller through the call to the **start_of_spin** module will serve as the time manager and all sensors that have a start of spin time WITHIN the time interval of the controller's spin will be returned as a group.

The parameter **version** allows multiple file openings for an IDFS data set. If the data, header and VIDF file for the specified data set need to be opened just once for processing, the same version number should be passed to all IDFS routines. However, for multiple file openings, the version number should be unique and all file manipulations performed by the IDFS routines will use the file descriptors defined for the version number specified. The user should call the **get_version_number** routine to retrieve a unique version number instead of choosing this value themselves. The retrieval of multiple data parameters from a single data source does not constitute the need for multiple version numbers; a single version number will suffice.

If the **file_open** routine is not to open the default set of IDFS files but a modified set of IDFS files, the two character extension applied to these data files must be supplied to this routine within the string variable **exten**. These files must have the identical name as the IDFS files with the two character identification code appended to the end of the file names (i.e. RTLA19922181432Dxx, RTLA19922181432Hxx, RTLA19922181432Ixx). The files must reside either in the directory specified by the environment variable USER_DATA,

which is set by the user, or in the user's home directory if the environment variable USER_DATA is not set. To open the default IDFS data files, **exten** should be set to a null string. The usage of modified data sets is limited to post acquisition data; therefore, it is suggested that the user set **exten** to a null string for real-time scenarios.

This routine will process data one spin at a time, placing the data into one buffer which holds data that is accumulated over the current spin interval. There are N many sub-buffers which hold the data in each of the requested data levels or units. The user must process the data contained within the data buffer before the next call to the **spin_data** routine is made since the module will clear out this buffer for re-use. The data values must be normalized using the normalization factors returned along with the data. If the sensors rotate or alternate when data is returned, the result may be that the data buffer for a specific sensor may not contain any data since the data buffer is reset or cleared out upon each call to the **spin_data** module. The user is advised to check the value or values in the **bin_stat** array. If all values are 0, no data was placed into the buffer.

The size and spacing of the data buffers are either defined by the user or by elements contained within the virtual instrument definition document. The user must call the **set_bin_info** module before calling the **spin_data** routine in order to specify how the binning of the data is to occur. In addition, the user must call the **center_and_band_values** module before calling the **spin_data** module. If the **spin_data** routine determines that no binning scheme has been selected, an error code is returned to the user.

The user should be aware that the data buffers that come back from the **spin_data** module are NOT modified as far as missing bins are concerned. If the user wishes to fill in the missing bins according to the method specified in the call to the **set_bin_info** module, the user must call the module **buffer_bin_fill**. If the data are collapsed over specified dimensions, the **buffer_bin_fill** module need not be called.

The default mode for the **spin_data** routine is to return sensor data in raw units (no tables applied) for each of the sensors processed, with data cutoff values set at -3.0e38 (VALID_MIN) and 3.0e38 (VALID_MAX). The user may select the type of data, the units to be returned and the data cutoff values to be applied by calling the **fill_sensor_info** module prior to calling the **spin_data** module. The user should make one call to the **fill_sensor_info** module for each sensor that is to be retrieved for each data type/units/data cutoff combination selected.

If the virtual instrument acquires data over the PHI dimension and the user wishes to average the data over a specified phi range, the **spin_data** routine must be used to acquire the phi data matrix. The user must call the module **set_collapse_info** prior to calling the **spin_data** routine in order to specify the resolution of the phi bins and to specify if the interleave option is to be utilized when building the phi matrix.

ERRORS

All errors within this routine are returned through the status variable. The include file **ret_codes.h**, which includes all possible return values, should be included so that the

mnemonics for the return codes can be referenced. The **ret_codes.h** file is described in section 1H of the IDFS Programmers Manual.

SEE ALSO

file_open	1R
file_pos	1R
start_of_spin	1 R
get_data_key	1R
get_version_number	1 R
create_data_structure	1 R
create_idf_data_structure	1 R
set_bin_info	2R
center_and_band_values	2R
set_scan_info	2R
fill_sensor_info	2R
units_index	2R
set_collapse_info	2R
buffer_bin_fill	2R
ret_codes	1H
user_defs	1H
libtrec_idfs	2H

BUGS

None

EXAMPLES

Obtain spin-averaged data from the virtual instrument CP3DRH, which is part of the 3DR instrument, which is part of the PEACE experiment, which is part of the CLUSTER-2 mission, which is identified with the CLUSTERII project.

#include "libtrec_idfs.h"
#include "ret_codes.h"

SDDAS_ULONG data_key; SDDAS_USHORT vnum; SDDAS_FLOAT *ret_data, *ret_frac; SDDAS_LONG *start_time_sec, *start_time_nano, *end_time_sec, *end_time_nano; SDDAS_SHORT *start_time_yr, *start_time_day, *end_time_yr, *end_time_day; SDDAS_SHORT status, *sen_numbers, num_sen, *num_units, data_block; SDDAS_CHAR *ret_bin, hdr_change; void *idf_data_ptr;

status = get_data_key ("CLUSTERII", "CLUSTER-2", "PEACE", "3DR", "CP3DRH", &data_key);

```
if (status != ALL_OKAY)
{
   printf ("\n Error %d returned by get_data_key routine.\n", status);
   exit (-1);
 }
get_version_number (&vnum);
•
.
status = spin_data (data_key, "", vnum, idf_data_ptr, &sen_numbers,
                   &ret_data, &ret_frac, &ret_bin, &num_sen, &num_units,
                   &data_block, &start_time_yr, &start_time_day,
                   &start_time_sec, &start_time_nano, &end_time_yr,
                   &end_time_day, &end_time_sec, &end_time_nano,
                   &hdr_change);
if (status != ALL_OKAY)
{
   printf ("\n Error %d returned by spin_data routine.\n", status);
   exit (-1);
 }
```

SPIN_DATA_PIXEL

function - returns spin-averaged sensor-specific data along with reference indicators with respect to a time-oriented axis

SYNOPSIS

#include "libtrec_idfs.h"
#include "ret_codes.h"

SDDAS_SHORT spin_data_pixel (SDDAS_ULONG data_key, SDDAS_CHAR *exten,	
SDDAS_USHORT version, void *idf_data_ptr,	
SDDAS_SHORT **ret_sensors, SDDAS_FLOAT **ret_data,	
SDDAS_FLOAT **ret_frac, SDDAS_CHAR **bin_stat,	
SDDAS_LONG **bpix, SDDAS_LONG **epix,	
SDDAS_SHORT *num_sen, SDDAS_SHORT **num_units,	
SDDAS_SHORT *block_size, SDDAS_SHORT **stime_yr,	
SDDAS_SHORT **stime_day, SDDAS_LONG **stime_sec,	
SDDAS_LONG **stime_nano, SDDAS_SHORT **etime_yr,	
SDDAS_SHORT **etime_day, SDDAS_LONG **etime_sec,	
SDDAS_LONG **etime_nano, SDDAS_CHAR *hdr_change)	

ARGUMENTS

unique value which indicates the data set of interest
two character extension to be added to IDFS file names when default files are not to be used, otherwise a null string
IDFS data set identification number which allows for multiple openings of the same data set
pointer to the idf_data structure that temporarily holds sensor data and pertinent ancillary data for the data set of interest
an array which holds the sensor number(s) for which data is returned
- the array is initialized to -1 in all elements;
valid sensor numbers start with 0
pointer to the data being returned (data for all sensors
processed)
pointer to the normalization factors for the data being returned
pointer to status flags which are associated with each data bin returned
0 - no data has been placed into the data bin being processed
1 - data has been placed into the data bin being processed
pointer to the starting pixel location for the data buffer returned
pointer to the ending pixel location for the data buffer
returned

num_sen	-	the number of elements in the ret_sensors array			
num_units	-	an array holding the number of data sets to bypass in order to			
		get to the data for the sensor being processed			
block_size	-	the number of data values returned in a data buffer			
stime_yr	-	pointer to the start time year value for the first sweep			
		contained within the spin being processed			
stime_day	-	pointer to the start time day of year value for the first sweep			
		contained within the spin being processed			
stime_sec	-	pointer to the start time of day value (in seconds) for the first			
		sweep contained within the spin being processed			
stime_nano	-	pointer to the start time of day residual (in nanoseconds) for			
		the first sweep contained within the spin being processed			
etime_yr	-	pointer to the end time year value for the last sweep contained			
		within the spin being processed			
etime_day	-	pointer to the end time day of year value for the last sweep			
		contained within the spin being processed			
etime_sec	-	pointer to the end time of day value (in seconds) for the last			
		sweep contained within the spin being processed			
etime_nano	-	pointer to the end time of day residual (in nanoseconds) for			
		the last sweep contained within the spin being processed			
hdr_change	-	flag which indicates a header change occurred while			
		processing the data			
		0 - a header change was not encountered during			
		the processing of the data			
		1 - a header change was encountered			
		during the processing of the data			
spin_data_pixel	-	routine status (see TABLE 1)			

TABLE 1. Status Codes Returned for SPIN_DATA_PIXEL

STATUS CODE	EXPLANATION OF STATUS
SPIN_DATA_PIX_NOT_FOUND	the requested data_key, exten, version combination has no memory
	allocated for processing (user did not call file_open for this
	combination)
SPIN_DATA_PIX_NO_SPIN	the requested data set does not spin
FILL_ARRAY_MALLOC	no memory for structure which holds information pertinent to the
	spin-averaged data
SPIN_DATA_PIX_BIN_MISSING	the data binning information has not been allocated (user did not
	call set_bin_info for this combination)
SPIN_DATA_PIX_CENTER_BAND_MISSING	the routine center_and_band_values has not been called prior to
	calling the spin_data_pix routine
SPIN_INFO_MALLOC	no memory for data buffer information
SPIN_UNITS_MALLOC	no memory to hold the various data levels for the data buffer
SPIN_UNITS_REALLOC	no memory for expansion of space to hold the various data levels
	for the data buffer
SPIN_SWP_MALLOC	no memory for sweep values in specified units
SPIN_SWP_REALLOC	no memory for expansion of sweep values in specified units
SPIN_DATA_MALLOC	no memory for data buffer

STATUS CODE	EXPLANATION OF STATUS
SPIN_DATA_PIX_WITH_FILL_SWEEP	spin_data_pix cannot be used interchangeably with the fill_data
	and / or sweep_data routines for the same data key, extension,
	version combination
BAD_VFMT	bad format character for variable width bin spacing
SWP_TIMES_TMP_MALLOC	no memory to hold the time components for each element of the
	sweep
PHI_DIFF_UNITS	the sensors being processed do not process the same number of
	data levels (units)
FILL_PHI_FIRST	the starting azimuthal angle was not contained within any of the
	defined phi bins
FILL_PHI_LAST	the ending azimuthal angle was not contained within any of the
	defined phi bins
	error codes returned by fill_sensor_info ()
	error codes returned by read_drec_spin ()
	error codes returned by convert_to_units ()
ALL_OKAY	routine terminated successfully

DESCRIPTION

Spin_data_pix is the IDFS spin-averaging data read routine for sensor-specific data, summing the data for all sweeps that pertain to the spin being processed. The data set of interest is referenced through the key value **data_key** which can be created using the **get_data_key** module. **Spin_data_pix** processes sensor-specific data only, that is, it processes sensor, sweep step, calibration, data quality, pitch angle, azimuthal angle, spacecraft potential and background data; however, the type of manipulation being performed by this module is best suited to sensor data. **Spin_data_pix** assumes that the data set of interest does not roll over to a minimum value when the maximum threshold has been reached or to a maximum value when the minimum threshold has been reached. This assumption is crucial since multiple samples may be averaged together in a single buffer. If the data set does roll over at the thresholds, the averaging of these samples will probably result in incorrect data values. An example of a roll over data set is longitude data, which resets values to the minimum threshold (-180) when the maximum threshold (180) has been reached.

For the **spin_data_pix** module, data acquisition is based upon a full spin of data, not a given time interval as with the **fill_data** module; however, there is still the need to utilize some form of time control. The sensor that is selected as the controller through the call to the **start_of_spin** module will serve as the time manager and all sensors that have a start of spin time WITHIN the time interval of the controller's spin will be returned as a group. The difference between the **spin_data** module and this module is the return of a starting location and an ending location that are located along a time-axis, similar to the **fill_data** routine. The user may use these values as references to the base location specified in the call to the **set_time_values** module. That is, given a base time value, a time interval and a reference location, the **spin_data_pix** routine will return the location of the spin with respect to time. The user may chose to ignore these values or may use these locations to plot data along an axis that is scaled with respect to time. The user **must** call the module **set_time_values** before the **spin_data_pix** module can be called. If the **spin_data_pix** routine determines that the **set_time_values** module has not been called, an error code is returned to the user.

The parameter **version** allows multiple file openings for an IDFS data set. If the data, header and VIDF file for the specified data set need to be opened just once for processing, the same version number should be passed to all IDFS routines. However, for multiple file openings, the version number should be unique and all file manipulations performed by the IDFS routines will use the file descriptors defined for the version number specified. The user should call the **get_version_number** routine to retrieve a unique version number instead of choosing this value themselves. The retrieval of multiple data parameters from a single data source does not constitute the need for multiple version numbers; a single version number will suffice.

If the **file_open** routine is not to open the default set of IDFS files but a modified set of IDFS files, the two character extension applied to these data files must be supplied to this routine within the string variable **exten**. These files must have the identical name as the IDFS files with the two character identification code appended to the end of the file names (i.e. RTLA19922181432Dxx, RTLA19922181432Hxx, RTLA19922181432Ixx). The files must reside either in the directory specified by the environment variable USER_DATA, which is set by the user, or in the user's home directory if the environment variable USER_DATA is not set. To open the default IDFS data files, **exten** should be set to a null string. The usage of modified data sets is limited to post acquisition data; therefore, it is suggested that the user set **exten** to a null string for real-time scenarios.

This routine will process data one spin at a time, placing the data into a buffer which holds data that is accumulated over the current spin interval. There are N many sub-buffers which hold the data in each of the requested data levels or units. The user must process the data contained within the data buffer before the next call to the **spin_data_pix** routine is made since the module will clear out this buffer for re-use. The data values must be normalized using the normalization factors returned along with the data. If the sensors rotate or alternate when data is returned, the result may be that the data buffer for a specific sensor may not contain any data since the data buffer is reset or cleared out upon each call to the **spin_data_pix** module. The user is advised to check the value or values in the **bin_stat** array. If all values are 0, no data was placed into the buffer.

The size and spacing of the data buffer is either defined by the user or by elements contained within the virtual instrument definition document. The user must call the **set_bin_info** module before calling the **spin_data_pix** routine in order to specify how the binning of the data is to occur. In addition, the user must call the **center_and_band_values** module before calling the **spin_data_pix** module. If the **spin_data_pix** routine determines that no binning scheme has been selected, an error code is returned to the user.

The user should be aware that the data buffer that comes back from the **spin_data_pix** routine is NOT modified as far as missing bins is concerned. If the user wishes to fill in the missing bins according to the method specified in the call to the **set_bin_info** module, the user must call the module **buffer_bin_fill**. If the data are collapsed over specified dimensions, the **buffer_bin_fill** module need not be called.

The default mode for the **spin_data_pix** routine is to return sensor data in raw units (no tables applied) for each of the sensors processed, with data cutoff values set at -3.0e38 (VALID_MIN) and 3.0e38 (VALID_MAX). The user may select the type of data, the units to be returned and the data cutoff values to be applied by calling the **fill_sensor_info** module prior to calling the **spin_data_pix** module. The user should make one call to the **fill_sensor_info** module for each sensor that is to be retrieved for each data type/units/data cutoff combination selected.

If the virtual instrument acquires data over the PHI dimension and the user wishes to average the data over a specified phi range, the **spin_data_pix** routine must be used to acquire the phi data matrix. The user must call the module **set_collapse_info** prior to calling the **spin_data_pix** module in order to specify the resolution of the phi bins and to specify if the interleave option is to be utilized when building the phi matrix.

ERRORS

All errors within this routine are returned through the status variable. The include file **ret_codes.h**, which includes all possible return values, should be included so that the mnemonics for the return codes can be referenced. The **ret_codes.h** file is described in section 1H of the IDFS Programmers Manual.

SEE ALSO

file_open	1 R
file_pos	1 R
start_of_spin	1 R
get_data_key	1 R
get_version_number	1 R
create_data_structure	1 R
create_idf_data_structure	1 R
set_bin_info	2R
center_and_band_values	2R
set_scan_info	2R
fill_sensor_info	2R
units_index	2R
set_collapse_info	2R
buffer_bin_fill	2R
set_time_values	2R
ret_codes	1H
user_defs	1H
libtrec_idfs	2H

BUGS

None

EXAMPLES

Obtain spin-averaged data from the virtual instrument CP3DRH, which is part of the 3DR instrument, which is part of the PEACE experiment, which is part of the CLUSTER-2 mission, which is identified with the CLUSTERII project.

#include "libtrec_idfs.h"
#include "ret_codes.h"

```
SDDAS_ULONG data_key;
SDDAS_USHORT vnum;
SDDAS_FLOAT *ret_data, *ret_frac;
SDDAS_LONG *start_time_sec, *start_time_nano, *end_time_sec, *end_time_nano;
SDDAS_LONG *bpix, *epix;
SDDAS_SHORT *start_time_yr, *start_time_day, *end_time_yr, *end_time_day;
SDDAS_SHORT status, *sen_numbers, num_sen, *num_units, data_block;
SDDAS_CHAR *ret_bin, hdr_change;
void *idf_data_ptr;
status = get_data_key ("CLUSTERII", "CLUSTER-2", "PEACE", "3DR", "CP3DRH",
&data_key);
```

```
if (status != ALL_OKAY)
{
    printf ("\n Error %d returned by get_data_key routine.\n", status);
    exit (-1);
```

```
}
```

.

```
get_version_number (&vnum);
```

```
{
```

```
printf ("\n Error %d returned by spin_data_pix routine.\n", status);
exit (-1);
```

```
}
```

SWEEP_DATA

function - returns sample-averaged sensor-specific data

SYNOPSIS

#include "libtrec_idfs.h"
#include "ret_codes.h"

SDDAS_SHORT sweep_data (SDDAS_ULONG data_key, SDDAS_CHAR *exten,
SDDAS_USHORT version, void *idf_data_ptr,
SDDAS_LONG num_swps, SDDAS_SHORT **ret_sensors,
SDDAS_FLOAT **ret_data, SDDAS_FLOAT **ret_frac,
SDDAS_CHAR **bin_stat, SDDAS_SHORT *num_sen,
SDDAS_SHORT **num_units, SDDAS_SHORT *block_size,
SDDAS_SHORT *stime_yr, SDDAS_SHORT *stime_day,
SDDAS_LONG *stime_sec, SDDAS_LONG *stime_nano,
SDDAS_SHORT *etime_yr, SDDAS_SHORT *etime_day,
SDDAS_LONG *etime_sec, SDDAS_LONG *etime_nano,
SDDAS_CHAR *hdr_change, SDDAS_UCHAR exclude_dqual,
SDDAS_CHAR *complete_acq)

ARGUMENTS

data_key	-	unique value which indicates the data set of interest				
exten	-	two character extension to be added to IDFS file names when				
		default files are not to be used, otherwise a null string				
version	-	IDFS data set identification number which allows for multiple				
		openings of the same data set				
idf_data_ptr	-	pointer to the idf_data structure that temporarily holds sensor				
-		data and pertinent ancillary data for the data set of interest for				
		a single sweep of data				
num_swps	-	the number of samples (sweeps) to average together				
ret_sensors	-	an array which holds the sensor number(s) for which data is				
		returned				
		- the array is initialized to -1 in all elements;				
		valid sensor numbers start with 0				
ret_data	-	pointer to the data being returned (data for all sensors				
		processed)				
ret_frac	-	pointer to the normalization factors for the data being returned				
bin_stat	-	pointer to status flags which are associated with each data bin				
		returned				
		0 - no data has been placed into the data				
		bin being processed				
		1 - data has been placed into the data bin				
		being processed				
num_sen	-	the number of elements in the ret_sensors array				
num_units	-	an array holding the number of data sets to bypass in order to				
	get to the data for the sensor being processed					

block_size	-	the number of data values returned in a data buffer				
stime_yr	-	the year value for the first sweep processed				
stime_day	-	the day of year value for the first sweep processed				
stime_sec	-	the time of day in seconds for the first sweep processed				
stime_nano	-	the time of day residual in nanoseconds for the first sweep processed				
etime_yr	-	the year value for the last sweep processed				
etime_day	-	the day of year value for the last sweep processed				
etime_sec	-	the time of day in seconds for the last sweep processed				
etime_nano	-	the time of day residual in nanoseconds for the last sweep processed				
hdr_change	-	flag which indicates a header change occurred while processing the data				
		0 - a header change was not encountered during the processing of the data				
		1 - a header change was encountered				
		during the processing of the data				
exclude_dqual	-	data is to be excluded if the d_qual flag associated with the				
_		data is set to the value specified				
complete_acq	-	flag which indicates if all samples (sweeps) were acquired 0 - not all samples were acquired				
		1 - all samples were acquired				
sweep_data	-	routine status (see TABLE 1)				

TABLE 1.	Status C	Codes	Returned	for	SWEEP_DATA	
----------	----------	-------	----------	-----	------------	--

STATUS CODE	EXPLANATION OF STATUS
SWEEP_NOT_FOUND	the requested data_key, exten, version combination has no memory allocated
	for processing (user did not call file_open for this combination)
FILL_ARRAY_MALLOC	no memory for structure which holds information pertinent to the sample- averaged data
SWEEP_BIN_MISSING	the data binning information has not been allocated (user did not call
	set_bin_info for this combination)
SWEEP_CENTER_BAND_MISSING	the routine center_and_band_values has not been called prior to calling the
	sweep_data routine
SWEEP_INFO_MALLOC	no memory for data buffer information
SWEEP_UNITS_MALLOC	no memory to hold the various data levels for the data buffer
SWEEP_UNITS_REALLOC	no memory for expansion of space to hold the various data levels for the data
	buffer
SWEEP_SWP_MALLOC	no memory for sweep values in specified units
SWEEP_SWP_REALLOC	no memory for expansion of sweep values in specified units
SWEEP_DATA_MALLOC	no memory for data buffer
SWEEP_WITH_FILL	the modules sweep_data and fill_data cannot be used interchangeably for the
	same data key, extension, version combination
BAD_VFMT	bad format character for variable width bin spacing
PHI_DIFF_UNITS	the sensors being processed do not process the same number of data levels
	(units)
FILL_PHI_FIRST	the starting azimuthal angle was not contained within any of the defined phi
	bins

STATUS CODE	EXPLANATION OF STATUS
FILL_PHI_LAST	the ending azimuthal angle was not contained within any of the defined phi
	bins
	error codes returned by read_drec ()
	error codes returned by convert_to_units ()
	error codes returned by fill_sensor_info ()
ALL_OKAY	routine terminated successfully

DESCRIPTION

Sweep_data is the IDFS sample-averaging data read routine for sensor-specific data, averaging **num swps** sample sets (sweeps). The data set of interest is referenced through the key value **data key** which can be created using the **get data key** module. Sweep_data processes sensor-specific data only, that is, it processes sensor, sweep step, calibration, data quality, pitch angle, azimuthal angle, spacecraft potential and background (mode) data is desired, the user should use the If the instrument status data. sweep mode data routine. Sweep data assumes that the data set of interest does not roll over to a minimum value when the maximum threshold has been reached or to a maximum value when the minimum threshold has been reached. This assumption is crucial since multiple samples may be averaged together. If the data set does roll over at the thresholds, the averaging of these samples will probably result in incorrect data values. An example of a roll over data set is longitude data, which resets values to the minimum threshold (-180) when the maximum threshold (180) has been reached. If the data set **does** roll over, the user should use the sweep_discontinuous_data routine. If the data set of interest is a combination of roll over and non-roll over data, for example, longitude data being returned along with science data, the user may use the sweep_discontinuous_data module in conjunction with the sweep data routine, using the sweep data routine to return the nonroll over data values and using the sweep_discontinuous_data routine to return the roll over data values. In order to do this correctly, the user must make use of multiple version numbers so that the same data files can be opened more than once. That is, use one version number for the non-roll over data and another version number for the roll over data. All IDFS routines that utilize a version number must be called once for each unique version number.

The data is processed one sweep at a time. Once the requested number of sweeps have been processed, the routine will return the data. If the requested number of sweeps could not be processed due to data acquisition problems (LOS_STATUS, NEXT_FILE_STATUS, EOF_STATUS), the routine will return the data and the normalization factors will reflect the number of sweeps processed so far. If more data is put online, the next call to the **sweep_data** routine will continue to accumulate data and will continue until the remaining sweeps have been acquired.

The parameter **version** allows multiple file openings for an IDFS data set. If the data, header and VIDF file for the specified data set need to be opened just once for processing, the same version number should be passed to all IDFS routines. However, for multiple file openings, the version number should be unique and all file manipulations performed by the IDFS routines will use the file descriptors defined for the version number specified. The user should call the **get_version_number** routine to retrieve a unique version number

instead of choosing this value themselves. The retrieval of multiple data parameters from a single data source does not constitute the need for multiple version numbers; a single version number will suffice.

The parameter **idf_data_ptr** is a pointer to the structure that is to hold all data pertinent to the data set being processed. The structure is created and the address to this structure is returned when a call to the **create_idf_data_structure** routine is made. The user also has the option of calling the module **create_data_structure**, which determines what type of data structure is needed for the IDFS data set of interest. In most cases, one data structure is sufficient to process any number of distinct data sets. However, if more than one structure is needed, the user may call the **create_idf_data_structure** routine N times to create N instances of the **idf_data** structure. The user must keep track of which pointer to send to the IDFS routines that utilize this structure.

If the **file_open** routine is not to open the default set of IDFS files but a modified set of IDFS files, the two character extension applied to these data files must be supplied to this routine within the string variable **exten**. These files must have the identical name as the IDFS files with the two character identification code appended to the end of the file names (i.e. RTLA19922181432Dxx, RTLA19922181432Hxx, RTLA19922181432Ixx). The files must reside either in the directory specified by the environment variable USER_DATA, which is set by the user, or in the user's home directory if the environment variable USER_DATA is not set. To open the default IDFS data files, **exten** should be set to a null string. The usage of modified data sets is limited to post acquisition data; therefore, it is suggested that the user set **exten** to a null string for real-time scenarios.

There are N many sub-buffers which hold the data in each of the requested data levels or units for each sensor. The user must process the data contained within these buffers before the next call to the **sweep_data** routine is made since the module will clear out these buffers for re-use if the requested number of sweeps were processed on the previous call. The data values must be normalized using the normalization factors returned along with the data. The user is advised to check the value or values in the **bin_stat** array. If all values are 0, no data was placed into the buffer. This can happen if the sensors rotate or alternate when data is returned or if the data is excluded based upon d_qual or data cutoff values.

The size and spacing of the data buffer is either defined by the user or by elements contained within the virtual instrument definition document. The user must call the **set_bin_info** module before calling the **sweep_data** routine in order to specify how the binning of the data is to occur. In addition, the user must call the **center_and_band_values** module before calling the **sweep_data** module. If the **sweep_data** routine determines that no binning scheme has been selected, an error code is returned to the user.

The user should be aware that the data buffer that comes back from the **sweep_data** routine are NOT modified as far as missing bins is concerned. If the user wishes to fill in the missing bins according to the method specified in the call to the **set_bin_info** module, the user must call the module **buffer_bin_fill**. If the data are collapsed over specified dimensions, the **buffer_bin_fill** module need not be called.

The default mode for the **sweep_data** routine is to return sensor data in raw units (no tables applied) for each of the sensors processed, with data cutoff values set at -3.0e38 (VALID_MIN) and 3.0e38 (VALID_MAX). The user may select the type of data, the units to be returned and the data cutoff values to be applied by calling the **fill_sensor_info** module prior to calling the **sweep_data** module. The user should make one call to the **fill_sensor_info** module for each sensor that is to be retrieved for each data type/units/data cutoff combination selected.

If the virtual instrument acquires data over the PHI dimension and the user wishes to average the data over a specified phi range, the **sweep_data** routine must be used to acquire the phi data matrix. The user must call the module **set_collapse_info** prior to calling the **sweep_data** module in order to specify the resolution of the phi bins and to specify if the interleave option is to be utilized when building the phi matrix.

The parameter **exclude_dqual** holds a single value that is compared against the d_qual value found in the header record for the sensor being processed. If the user wishes to exclude data that is flagged with a specific d_qual value, the user should set the **exclude_dqual** value to this specific value. If the user wishes to include all data encountered, the user should set the **exclude_dqual** value to 255.

ERRORS

All errors within this routine are returned through the status variable. The include file **ret_codes.h**, which includes all possible return values, should be included so that the mnemonics for the return codes can be referenced. The **ret_codes.h** file is described in section 1H of the IDFS Programmers Manual.

SEE ALSO

file_open	1 R
read_drec	1 R
convert_to_units	1 R
sweep_discontinuous_data	2R
sweep_mode_data	2R
set_bin_info	2R
center_and_band_values	2R
fill_sensor_info	2R
buffer_bin_fill	2R
set_collapse_info	2R
get_data_key	1 R
get_version_number	1 R
create_data_structure	1 R
create_idf_data_structure	1 R
ret_codes	1H
libtrec_idfs	2H

BUGS

None

EXAMPLES

Obtain data one sweep at a time from the virtual instrument RTLA, which is part of the RETE instrument/experiment, which is part of the TSS-1 mission, which is identified with the TSS project.

#include "libtrec_idfs.h"
#include "ret_codes.h"

```
SDDAS_ULONG data_key;
SDDAS USHORT vnum;
SDDAS_FLOAT *ret_data, *ret_frac;
SDDAS LONG start time sec, start time nano, end time sec, end time nano;
SDDAS_SHORT start_time_yr, start_time_day, end_time_yr, end_time_day;
SDDAS SHORT status, *sen numbers, num sen, *num units, data block;
SDDAS CHAR *ret bin, hdr change, complete acq;
void *idf data ptr;
status = get_data_key ("TSS", "TSS-1", "RETE", "RETE", "RTLA", &data_key);
if (status != ALL OKAY)
{
 printf ("\n Error %d returned by get_data_key routine.\n", status);
 exit (-1);
}
get version number (&vnum);
status = create_idf_data_structure (&idf_data_ptr);
if (status != ALL OKAY)
{
 printf ("\n Error %d returned by create_idf_data_structure routine.\n", status);
 exit (-1);
}
status = sweep_data (data_key, "", vnum, idf_data_ptr, 1, &sen_numbers, &ret_data,
                    &ret frac, &ret bin, &num sen, &num units, &data block,
                    &start_time_yr, &start_time_day, &start_time_sec,
                    &start_time_nano, &end_time_yr, &end_time_day,
                    &end time sec, &end time nano, &hdr change, 255,
                    &complete_acq);
if (status != ALL OKAY)
 printf ("\n Error %d returned by sweep data routine.\n", status);
 exit (-1);
}
```

SWEEP_DISCONTINUOUS_DATA

function - returns sample-averaged sensor-specific data for data sets that roll over to a minimum value when the maximum threshold has been reached

SYNOPSIS

#include "libtrec_idfs.h"
#include "ret_codes.h"

SDDAS_SHORT sweep_d	SDDAS void *id SDDAS SDDAS SDDAS SDDAS SDDAS SDDAS SDDAS SDDAS	ous_data (SDDAS_ULONG data_key, S_CHAR *exten, SDDAS_USHORT version, df_data_ptr, SDDAS_LONG num_swps, S_SHORT **ret_sensors, SDDAS_FLOAT **ret_data, S_FLOAT **ret_frac, SDDAS_CHAR **bin_stat, S_SHORT *num_sen, SDDAS_SHORT **num_units, S_SHORT *block_size, SDDAS_SHORT *stime_yr, S_SHORT *block_size, SDDAS_LONG *stime_sec, S_LONG *stime_nano, SDDAS_SHORT *etime_yr, S_SHORT *etime_day, SDDAS_LONG *etime_sec, S_LONG *etime_nano, SDDAS_LONG *etime_sec, S_LONG *etime_nano, SDDAS_CHAR *hdr_change, S_UCHAR exclude_dqual, S_CHAR *complete_acq)
ARGUMENTS		
data_key	-	unique value which indicates the data set of interest
exten	-	two character extension to be added to IDFS file
		names when default files are not to be used, otherwise
		a null string
version	-	IDFS data set identification number which allows for
idf data ptr		multiple openings of the same data set pointer to the idf_data structure that temporarily
idf_data_ptr	-	holds sensor data and pertinent ancillary data for the
		data set of interest for a single sweep of data
num_swps	_	the number of samples (sweeps) to average together
ret_sensors	-	an array which holds the sensor number(s) for which
_		data is returned
		- The array is initialized to -1 in all elements; valid
		sensor numbers start with 0
ret_data	-	pointer to the data being returned (data for all sensors
		processed)
ret_frac	-	pointer to the normalization factors for the data being returned
bin_stat	-	pointer to status flags which are associated with each
		data bin returned
		0 - no data has been placed into the data
		bin being processed

		1 - data has been placed into the data bin being processed
num_sen	_	the number of elements in the ret_sensors array
num_units	-	an array holding the number of data sets to bypass in
		order to get to the data for the sensor being processed
block_size	-	the number of data values returned in a data buffer
stime_yr	-	the year value for the first sweep processed
stime_day	-	the day of year value for the first sweep processed
stime_sec	-	the time of day in seconds for the first sweep
		processed
stime_nano	-	the time of day residual in nanoseconds for the first
		sweep processed
etime_yr	-	the year value for the last sweep processed
etime_day	-	the day of year value for the last sweep processed
etime_sec	-	the time of day in seconds for the last sweep processed
etime_nano	-	the time of day residual in nanoseconds for the last
		sweep processed
hdr_change	-	flag which indicates a header change occurred while
		processing the data
		0 - a header change was not encountered
		during the processing of the data
		1 - a header change was encountered
		during the processing of the data
exclude_dqual	-	data is to be excluded if the d_qual flag associated
— 1		with the data is set to the value specified
complete_acq	-	flag which indicates if all samples (sweeps) were
ri		acquired
		0 - not all samples were acquired
		1 - all samples were acquired
sweep_discontinuous_data	_	routine status (see TABLE 1)
sweep_uiscontinuous_data		

TABLE 1. Status Codes Returned for SWEEP_DISCONTINUOUS_DATA

STATUS CODE	EXPLANATION OF STATUS
SWEEP_DISC_NOT_FOUND	the requested data_key, exten, version combination has no memory
	allocated for processing (user did not call file_open for this
	combination)
SWEEP_DISC_BIN_MISSING	the data binning information has not been allocated (user did not call
	set_bin_info for this combination)
SWEEP_DISC_CENTER_BAND_MISSING	the routine center_and_band_values has not been called prior to
	calling the sweep_discontinuous_data routine
SWEEP_DISC_NO_PHI	data sets with PHI, MASS and/or CHARGE dimensions are not
	supported
FILL_ARRAY_MALLOC	no memory for structure which hold information pertinent to the
	sample-averaged data
FILL_DISC_MALLOC	no memory for fill_discontinuous structure
FILL_INFO_MALLOC	no memory for data buffer information
FILL_UNITS_MALLOC	no memory to hold the various data levels for the data buffers

December 28, 2012

STATUS CODE	EXPLANATION OF STATUS
FILL_UNITS_REALLOC	no memory for expansion of space to hold the various data levels for
	the data buffers
FILL_SWP_MALLOC	no memory for sweep values in specified units
FILL_SWP_REALLOC	no memory for expansion of sweep values in specified units
FILL_DATA_MALLOC	no memory for data buffers
SWEEP_INFO_MALLOC	no memory for data buffer information
SWEEP_DATA_MALLOC	no memory for data buffer
SWEEP_UNITS_MALLOC	no memory to hold the various data levels for the data buffer
SWEEP_UNITS_REALLOC	no memory for expansion of space to hold the various data levels for
	the data buffer
SWEEP_SWP_MALLOC	no memory for sweep values in specified units
SWEEP_SWP_REALLOC	no memory for expansion of sweep values in specified units
DISC_DATA_MALLOC	no memory for the internal data buffers that are pertinent only to
	discontinuous data sets
SWEEP_DISC_WITH_FILL	the modules sweep_discontinuous_data and fill_discontinuous_data
	cannot be used interchangeably for the same data key, extension,
	version combination
BAD_VFMT	bad format character for variable width bin spacing
DISC_TMP_MALLOC	no memory for scratch space utilized to process discontinuous data
	sets
	error codes returned by read_drec ()
	error codes returned by convert_to_units ()
	error codes returned by fill_sensor_info ()
ALL_OKAY	routine terminated successfully

DESCRIPTION

Sweep_discontinuous_data is the IDFS sample-averaging read routine for discontinuous sensor-specific data, averaging **num_swps** sample sets (sweeps). The data set of interest is referenced through the key value **data key** which can be created using the **get data key** Sweep_discontinuous_data processes sensor-specific data only, that is, it module. processes sensor, sweep step, calibration, data quality, pitch angle, azimuthal angle, spacecraft potential and background data. If the instrument status (mode) data is desired, the user should use the sweep_mode_data routine. Sweep_discontinuous_data assumes that the data set of interest rolls over to a minimum value when the maximum threshold has been reached or to a maximum value when the minimum threshold has been reached. This assumption is crucial since multiple samples may be averaged together. Before each sample is added to the buffer, a check is made to see if a "boundary" or threshold has been crossed. If so, the value is adjusted so that the addition of the values result in a correct averaged value. Currently, these threshold values are preset at -180 (minimum threshold) and 180 (maximum threshold). If the data set does not roll over, the user should use the sweep_data routine. If the data set of interest is a combination of roll over and non-roll over data, for example, longitude data being returned along with science data, the user may use the sweep_discontinuous_data module in conjunction with the sweep_data routine, using the sweep data routine to return the non-roll over data values and using the sweep_discontinuous_data routine to return the roll over data values. In order to do this correctly, the user must make use of multiple version numbers so that the same data files can be opened more than once. That is, use one version number for the non-roll over data

and another version number for the roll over data. All IDFS routines that utilize a version number must be called once for each unique version number.

The data is processed one sweep at a time. Once the requested number of sweeps have been processed, the routine will return the data. If the requested number of sweeps could not be processed due to data acquisition problems (LOS_STATUS, NEXT_FILE_STATUS, EOF_STATUS), the routine will return the data and the normalization factors will reflect the number of sweeps processed so far. If more data is put online, the next call to the **sweep_discontinuous_data** routine will continue to accumulate data and will continue until the remaining sweeps have been acquired.

The parameter **version** allows multiple file openings for an IDFS data set. If the data, header and VIDF file for the specified data set need to be opened just once for processing, the same version number should be passed to all IDFS routines. However, for multiple file openings, the version number should be unique and all file manipulations performed by the IDFS routines will use the file descriptors defined for the version number specified. The user should call the **get_version_number** routine to retrieve a unique version number instead of choosing this value themselves. The retrieval of multiple data parameters from a single data source does not constitute the need for multiple version numbers; a single version number will suffice.

The parameter **idf_data_ptr** is a pointer to the structure that is to hold all data pertinent to the data set being processed. The structure is created and the address to this structure is returned when a call to the **create_idf_data_structure** routine is made. The user also has the option of calling the module **create_data_structure**, which determines what type of data structure is needed for the IDFS data set of interest. In most cases, one data structure is sufficient to process any number of distinct data sets. However, if more than one structure is needed, the user may call the **create_idf_data_structure** routine N times to create N instances of the **idf_data** structure. The user must keep track of which pointer to send to the IDFS routines that utilize this structure.

If the **file_open** routine is not to open the default set of IDFS files but a modified set of IDFS files, the two character extension applied to these data files must be supplied to this routine within the string variable **exten**. These files must have the identical name as the IDFS files with the two character identification code appended to the end of the file names (i.e. RTLA19922181432Dxx, RTLA19922181432Hxx, RTLA19922181432Ixx). The files must reside either in the directory specified by the environment variable USER_DATA, which is set by the user, or in the user's home directory if the environment variable USER_DATA is not set. To open the default IDFS data files, **exten** should be set to a null string. The usage of modified data sets is limited to post acquisition data; therefore, it is suggested that the user set **exten** to a null string for real-time scenarios.

There are N many sub-buffers which hold the data in each of the requested data levels or units for each sensor. The user must process the data contained within these buffers before the next call to the **sweep_discontinuous_data** routine is made since the module will clear out these buffers for re-use if the requested number of sweeps were processed on the

December 28, 2012

previous call. The data values must be normalized using the normalization factors returned along with the data. The user is advised to check the value or values in the **bin_stat** array. If all values are 0, no data was placed into the buffer. This can happen if the sensors rotate or alternate when data is returned or if the data is excluded based upon d_qual or data cutoff values.

The size and spacing of the data buffer is either defined by the user or by elements contained within the virtual instrument definition document. The user must call the **set_bin_info** module before calling the **sweep_discontinuous_data** routine in order to specify how the binning of the data is to occur. In addition, the user must call the **center_and_band_values** module before calling the **sweep_discontinuous_data** module. If the **sweep_discontinuous_data** routine determines that no binning scheme has been selected, an error code is returned to the user.

The user should be aware that the data buffer that comes back from the **sweep_discontinuous_data** routine are NOT modified as far as missing bins is concerned. If the user wishes to fill in the missing bins according to the method specified in the call to the **set_bin_info** routine, the user must call the module **buffer_bin_fill**. If the data are collapsed over specified dimensions, the **buffer_bin_fill** module need not be called. The user should be advised that the **sweep_discontinuous_data** routine can not process data sets with a PHI, MASS and/or CHARGE dimensionality.

The default mode for the **sweep_discontinuous_data** routine is to return sensor data in raw units (no tables applied) for each of the sensors processed, with data cutoff values set at -3.0e38 (VALID_MIN) and 3.0e38 (VALID_MAX). The user may select the type of data, the units to be returned and the data cutoff values to be applied by calling the **fill_sensor_info** module prior to calling the **sweep_discontinuous_data** module. The user should make one call to the **fill_sensor_info** module for each sensor that is to be retrieved for each data type/units/data cutoff combination selected.

The parameter **exclude_dqual** holds a single value that is compared against the d_qual value found in the header record for the sensor being processed. If the user wishes to exclude data that is flagged with a specific d_qual value, the user should set the **exclude_dqual** value to this specific value. If the user wishes to include all data encountered, the user should set the **exclude_dqual** value to 255.

ERRORS

All errors within this routine are returned through the status variable. The include file **ret_codes.h**, which includes all possible return values, should be included so that the mnemonics for the return codes can be referenced. The **ret_codes.h** file is described in section 1H of the IDFS Programmers Manual.

SEE ALSO

file_open	1 R
read_drec	1R
convert_to_units	1 R

sweep_data	2 R
sweep_mode_data	2 R
set_bin_info	2 R
center_and_band_values	2 R
fill_sensor_info	2R
buffer_bin_fill	2R
get_data_key	1 R
get_version_number	1 R
create_data_structure	1 R
create_idf_data_structure	1 R
ret_codes	1H
libtrec_idfs	2H

BUGS

None

EXAMPLES

Obtain discontinuous data one sweep at a time from the virtual instrument RTLA, which is part of the RETE instrument/experiment, which is part of the TSS-1 mission, which is identified with the TSS project.

#include "libtrec_idfs.h"
#include "ret_codes.h"

```
SDDAS_ULONG data_key;
SDDAS USHORT vnum;
SDDAS FLOAT *ret data, *ret frac;
SDDAS LONG start time sec, start time nano, end time sec, end time nano;
SDDAS_SHORT start_time_yr, start_time_day, end_time_yr, end_time_day;
SDDAS SHORT status, *sen numbers, num sen, *num units, data block;
SDDAS_CHAR *ret_bin, hdr_change, complete_acq;
void *idf data ptr;
status = get_data_key ("TSS", "TSS-1", "RETE", "RETE", "RTLA", &data_key);
if (status != ALL_OKAY)
{
 printf ("\n Error %d returned by get_data_key routine.\n", status);
 exit (-1);
}
get_version_number (&vnum);
status = create_idf_data_structure (&idf_data_ptr);
if (status != ALL_OKAY)
 printf ("\n Error %d returned by create_idf_data_structure routine.\n",
```

status);

exit (-1);
}

SWEEP_MODE_DATA

function - returns sample-averaged instrument status (mode) data

SYNOPSIS

#include "libtrec_idfs.h"
#include "ret_codes.h"

SDDAS_SHORT sweep_mode_data (SDDAS_ULONG data_key,	
SDDAS_CHAR *exten, SDDAS_USHORT version,	
<pre>void *idf_data_ptr, SDDAS_LONG num_swps,</pre>	
SDDAS_SHORT **ret_modes, SDDAS_FLOAT **ret_dat	a,
SDDAS_FLOAT **ret_frac, SDDAS_CHAR **bin_stat,	
SDDAS_SHORT *num_modes,	
SDDAS_SHORT **num_units, SDDAS_SHORT *block_s	ize,
SDDAS_SHORT *stime_yr, SDDAS_SHORT *stime_day,	
SDDAS_LONG *stime_sec, SDDAS_LONG *stime_nano,	
SDDAS_SHORT *etime_yr, SDDAS_SHORT *etime_day,	
SDDAS_LONG *etime_sec, SDDAS_LONG *etime_nano,	
SDDAS_CHAR *hdr_change, SDDAS_CHAR *complete_	acq)

ARGUMENTS

data_key	- unique value which indicates the data set of	of interest			
exten		two character extension to be added to IDFS file names when default files are not to be used, otherwise a null string			
version		IDFS data set identification number which allows for multiple			
idf_data_ptr	- pointer to the idf_data structure that temp data and pertinent ancillary data for the da a single sweep of data	ta set of interest for			
num_swps	- the number of samples (sweeps) to average	e together			
ret_modes	- an array which holds the instrument status which data is returned	(mode) bytes for			
	- the array is initialized to -1	in all elements;			
	valid mode numbers start w				
ret_data	- pointer to the data being returned (data for processed)				
ret_frac	- pointer to the normalization factors for the	data being returned			
bin_stat	- pointer to status flags which are associated	-			
—	returned				
	0 - no data has been pla bin being processed				
	1 - data has been placed being processed				
num_modes	- the number of elements in the ret_modes	array			

num_units	-	an array holding the number of data sets to bypass in order to get to the data for the instrument status (mode) value being processed
block_size	-	the number of data values returned in a data buffer
stime_yr	-	the year value for the first sweep processed
stime_day	-	the day of year value for the first sweep processed
stime_sec	-	the time of day in seconds for the first sweep processed
stime_nano	-	the time of day residual in nanoseconds for the first sweep processed
etime_yr	-	the year value for the last sweep processed
etime_day	-	the day of year value for the last sweep processed
etime_sec	-	the time of day in seconds for the last sweep processed
etime_nano	-	the time of day residual in nanoseconds for the last sweep processed
hdr_change	-	flag which indicates a header change occurred while processing the data
		0 - a header change was not encountered during the processing of the data
		1 - a header change was encountered during the processing of the data
complete_acq	-	flag which indicates if all samples (sweeps) were acquired 0 - not all samples were acquired 1 - all samples were acquired
sweep_mode_data	-	routine status (see TABLE 1)

TABLE 1.	Status Codes I	Returned for	SWEEP_	_MODE_DATA
----------	----------------	--------------	--------	------------

STATUS CODE	EXPLANATION OF STATUS
SWEEP_MODE_NOT_FOUND	the requested data_key, exten, version combination has no memory
	allocated for processing (user did not call file_open for this combination)
SWEEP_MODE_FILE_OPEN	the user did not request mode data processing when file_open was called
SWEEP_MODE_INFO_DUP	the requested data_key, exten, version combination has no memory
	allocated for the instrument status information
SWEEP_MODES_NOT_REQUESTED	the user did not call fill_mode_info for this combination
FILL_MODE_ARRAY_MALLOC	no memory for structure which hold information pertinent to the sample-
	averaged data
ALLOC_SMODE_INFO_MALLOC	no memory for data buffer information
SMODE_UNITS_MALLOC	no memory to hold the various data levels for the data buffer
SMODE_UNITS_REALLOC	no memory for expansion of space to hold the various data levels for the
	data buffer
SMODE_DATA_MALLOC	no memory for data buffer
SWEEP_MODE_WITH_FILL	the modules sweep_mode_data and fill_mode_data cannot be used
	interchangeably for the same data key, extension, version combination
	error codes returned by read_drec ()
	error codes returned by convert_to_units ()
ALL_OKAY	routine terminated successfully

DESCRIPTION

Sweep_mode_data is the IDFS sample-averaging data read routine for instrument status (mode) values, averaging **num_swps** sample sets (sweeps). The data set of interest is referenced through the key value **data_key** which can be created using the **get_data_key** module. **Sweep_mode_data** processes instrument status data only. If sensor-specific data is desired, that is, sensor, sweep step, calibration, data quality, pitch angle, azimuthal angle spacecraft potential and / or background data, the user should use the **sweep_data** / **sweep_discontinuous_data** routine(s).

The data is processed one sweep at a time. Once the requested number of sweeps have been processed, the routine will return the mode data. If the requested number of sweeps could not be processed due to data acquisition problems (LOS_STATUS, NEXT_FILE_STATUS, EOF_STATUS), the routine will return the data and the normalization factors will reflect the number of sweeps processed so far. If more data is put online, the next call to the **sweep_mode_data** routine will continue to accumulate data and will continue until the remaining sweeps have been acquired.

The parameter **version** allows multiple file openings for an IDFS data set. If the data, header and VIDF file for the specified data set need to be opened just once for processing, the same version number should be passed to all IDFS routines. However, for multiple file openings, the version number should be unique and all file manipulations performed by the IDFS routines will use the file descriptors defined for the version number specified. The user should call the **get_version_number** routine to retrieve a unique version number instead of choosing this value themselves. The retrieval of multiple data parameters from a single data source does not constitute the need for multiple version numbers; a single version number will suffice.

The parameter **idf_data_ptr** is a pointer to the structure that is to hold all data pertinent to the data set being processed. The structure is created and the address to this structure is returned when a call to the **create_idf_data_structure** routine is made. The user also has the option of calling the module **create_data_structure**, which determines what type of data structure is needed for the IDFS data set of interest. In most cases, one data structure is sufficient to process any number of distinct data sets. However, if more than one structure is needed, the user may call the **create_idf_data_structure** routine N times to create N instances of the **idf_data** structure. The user must keep track of which pointer to send to the IDFS routines that utilize this structure.

If the **file_open** routine is not to open the default set of IDFS files but a modified set of IDFS files, the two character extension applied to these data files must be supplied to this routine within the string variable **exten**. These files must have the identical name as the IDFS files with the two character identification code appended to the end of the file names (i.e. RTLA19922181432Dxx, RTLA19922181432Hxx, RTLA19922181432Ixx). The files must reside either in the directory specified by the environment variable USER_DATA, which is set by the user, or in the user's home directory if the environment variable USER_DATA is not set. To open the default IDFS data files, **exten** should be set to a null

string. The usage of modified data sets is limited to post acquisition data; therefore, it is suggested that the user set **exten** to a null string for real-time scenarios.

There are N many sub-buffers which hold the data in each of the requested data levels or units for each mode. The user must process the data contained within these buffers before the next call to the **sweep_mode_data** routine is made since the module will clear out these buffers for re-use if the requested number of sweeps were processed on the previous call. The data values must be normalized using the normalization factors returned along with the data. The user is advised to check the value or values in the **bin_stat** array. If all values are 0, no data was placed into the buffer. This can happen if the status bytes rotate or alternate when data is returned.

In order to utilize the **sweep_mode_data** routine, the user must select the units to be returned and the data cutoff values to be applied by calling the **fill_mode_info** module prior to calling the **sweep_mode_data** module. The user should make one call to the **fill_mode_info** module for each instrument status byte that is to be retrieved for each units/data cutoff combination selected. If the **sweep_mode_data** routine determines that the **fill_mode_info** module was never called, an error code is returned.

ERRORS

All errors within this routine are returned through the status variable. The include file **ret_codes.h**, which includes all possible return values, should be included so that the mnemonics for the return codes can be referenced. The **ret_codes.h** file is described in section 1H of the IDFS Programmers Manual.

SEE ALSO

file_open	1 R
read_drec	1 R
convert_to_units	1R
sweep_data	2R
sweep_discontinuous_data	2R
fill_mode_info	2R
get_data_key	1R
get_version_number	1R
create_data_structure	1 R
create_idf_data_structure	1 R
ret_codes	1H
libtrec_idfs	2H

BUGS

None

EXAMPLES

Obtain instrument status values one sweep at a time from the virtual instrument RTLA, which is part of the RETE instrument/experiment, which is part of the TSS-1 mission, which is identified with the TSS project.

```
#include "libtrec idfs.h"
#include "ret codes.h"
SDDAS ULONG data key:
SDDAS USHORT vnum;
SDDAS FLOAT *ret data, *ret frac;
SDDAS_LONG start_time_sec, start_time_nano, end_time_sec, end_time_nano;
SDDAS SHORT start time yr, start time day, end time yr, end time day;
SDDAS_SHORT status, *mode_numbers, num_modes, *num_units, data_block;
SDDAS CHAR *ret bin, hdr change, complete acq;
void *idf_data_ptr;
status = get_data_key ("TSS", "TSS-1", "RETE", "RETE", "RTLA", &data_key);
if (status != ALL_OKAY)
{
 printf ("\n Error %d returned by get_data_key routine.\n", status);
 exit (-1);
}
get_version_number (&vnum);
status = create_idf_data_structure (&idf_data_ptr);
if (status != ALL OKAY)
{
 printf ("\n Error %d returned by create idf data structure routine.\n", status);
 exit (-1);
}
status = sweep_mode_data (data_key, "", vnum, idf_data_ptr, 1, &mode_numbers,
                &ret_data, &ret_frac, &ret_bin, &num_modes, &num_units,
                &data_block, &start_time_yr, &start_time_day,
                &start_time_sec, &start_time_nano, &end_time_yr, &end_time_day,
                &end time sec, &end time nano, &hdr change, &complete acq);
if (status != ALL OKAY)
{
 printf ("\n Error %d returned by sweep_mode_data routine.\n", status);
 exit (-1);
}
```

UNITS_INDEX

function - returns index values to access the data returned by the time-averaging, sample-averaging, and spin-averaging modules for the data type/cutoff/units combination specified

SYNOPSIS

#include "libtrec_idfs.h"
#include "ret_codes.h"
#include "user_defs.h"

per,
nits,

ARGUMENTS

data_key	-	unique value which indicates the data set of interest
exten	-	two character extension to be added to IDFS file names when
		default files are not to be used, otherwise a null string
version	-	IDFS data set identification number which allows for multiple
		openings of the same data set
sensor	-	sensor identification number
min	-	the lower cutoff value for data that are to be put into the data buffers,
		specified in terms of the units desired.
max	-	the upper cutoff value for data that are to be put into the data buffers,
		specified in terms of the units desired.
tbls_to_apply	/ -	the tables that are to be applied in order to derive the desired units
tbl_oper	-	the operations that are to be applied to the specified tables in order to
		derive the desired units
data_type	-	the type of data being requested
		1 - sensor data (SENSOR)
		2 - sweep step data (SWEEP_STEP)
		3 - calibration data (CAL_DATA)
		5 - data quality data (D_QUAL)
		6 - pitch angle data (PITCH_ANGLE)
		7 - start azimuthal angle data
		(START_AZ_ANGLE)
		8 - stop azimuthal angle data
		(STOP_AZ_ANGLE)
		9 - spacecraft potential data (SC_POTENTIAL)
		10 - background data (BACKGROUND)
cal_set	-	the calibration set from which requested calibration data
		(CAL_DATA) is to be retrieved

		- If calibration data is not being requested, this parameter is
		not utilized and it is suggested that the user pass a value of
		zero for this parameter.
units_ind	-	index value returned to access the correct sub-buffer returned from
		the time-averaging, sample-averaging, or spin-averaging routine for
		the data type/cutoff/units combination requested
num_units	-	the number of units or data levels defined for the sensor in question
		(used as an index to get to the first buffer returned by the time-
		averaging or sample-averaging routine for the sensor in question)
num_tbls	-	the number of elements specified in the tbls_to_apply and tbl_oper
		parameters
units_index	-	routine status (see TABLE 1)

TABLE 1. Status Codes Returned for UNITS_INDEX

STATUS CODE	EXPLANATION OF STATUS
UNITS_IND_NOT_FOUND	the requested data_key, exten, version combination has no memory allocated for
	processing (user did not call file_open for this combination)
UNITS_NO_SENSOR	the requested sensor was not found amongst the defined data type/cutoff/units
	combinations (user did not call fill_sensor_info for this combination)
UNITS_NO_MATCH	the data type/cutoff/units combination requested was not found for the specified
	sensor
UNITS_IND_MODE_TYPE	instrument status (mode) data is not supported by the units_index routine
ALL_OKAY	routine terminated successfully

DESCRIPTION

Units_index is the IDFS routine that returns index values that are used to access the data buffers returned by the IDFS routines that return time-averaged data (fill_data / fill_discontinuous_data), sample-averaged data (sweep_data / sweep_discontinuous_data), or spin-averaged data (spin_data / spin_data_pixel) for the sensor, data type / cutoff / units combination specified. The data set of interest is referenced through the key value data_key which can be created using the get_data_key module. The units_index module should be used for sensor-specific data only, that is, for sensor, sweep step, calibration, data quality, pitch angle, azimuthal angle, spacecraft potential and background data. If instrument status (mode) data is also being processed, the user should use the mode_units_index routine to retrieve index values to access the data buffers returned by the fill_mode_data / sweep_mode_data routine.

The parameter **version** allows multiple file openings for an IDFS data set. If the data, header and VIDF file for the specified data set need to be opened just once for processing, the same version number should be passed to all IDFS routines. However, for multiple file openings, the version number should be unique and all file manipulations performed by the IDFS routines will use the file descriptors defined for the version number specified. The user should call the **get_version_number** routine to retrieve a unique version number instead of choosing this value themselves. The retrieval of multiple data parameters from a single data source does not constitute the need for multiple version numbers; a single version number will suffice.

If the **file_open** routine is not to open the default set of IDFS files but a modified set of IDFS files, the two character extension applied to these data files must be supplied to this routine within the string variable **exten**. These files must have the identical name as the IDFS files with the two character identification code appended to the end of the file names (i.e. RTLA19922181432Dxx, RTLA19922181432Hxx, RTLA19922181432Ixx). The files must reside either in the directory specified by the environment variable USER_DATA, which is set by the user, or in the user's home directory if the environment variable USER_DATA is not set. To open the default IDFS data files, **exten** should be set to a null string. The usage of modified data sets is limited to post acquisition data; therefore, it is suggested that the user set **exten** to a null string for real-time scenarios.

The user may elect to call the **units_index** routine every time a return from the timeaveraging, sample-averaging, or spin-averaging routine is made or may call the **units_index** routine once for each sensor, data type/cutoff/units combination requested and save the index values into variables for later usage. In either case, the call(s) to the **units_index** routine must be made after ALL calls to the **fill_sensor_info** routine have been made. The user may not have called the **fill_sensor_info** module if the default mode for the timeaveraging, sample-averaging, or spin-averaging routine is sufficient. In this case, the user may retrieve the index values from the **units_index** routine only AFTER the first call to the time-averaging, sample-averaging, or spin-averaging routine has been made.

ERRORS

All errors within this routine are returned through the status variable. The include file **ret_codes.h**, which includes all possible return values, should be included so that the mnemonics for the return codes can be referenced. The **ret_codes.h** file is described in section 1H of the IDFS Programmers Manual.

SEE ALSO

file_open	1 R
fill_data	2R
fill_discontinuous_data	2R
fill_mode_data	2R
sweep_data	2 R
sweep_discontinuous_data	2R
sweep_mode_data	2R
spin_data	2R
spin_data_pixel	2R
mode_units_index	2R
fill_sensor_info	2R
get_data_key	1 R
get_version_number	1 R
ret_codes	1H
user_defs	1H
libtrec_idfs	2H

BUGS

None

EXAMPLES

Retrieve the index values to access data that is returned for sensor 1 from the virtual instrument RTLA, which is part of the RETE instrument/experiment, which is part of the TSS-1 mission, which is identified with the TSS project. Assume that there is one table applicable to this virtual instrument.

#include "libtrec_idfs.h"
#include "ret_codes.h"
#include "user defs.h"

SDDAS_ULONG data_key; SDDAS_USHORT vnum; SDDAS_FLOAT sen_min, sen_max; SDDAS_LONG tbl_oper[1]; SDDAS_SHORT uind_base, status, sen_units, sensor; SDDAS_CHAR tbls_to_apply[1], num_tbls;

```
sen_min = VALID_MIN;
sen_max = VALID_MAX;
sensor = 1;
num_tbls = 1;
tbls_to_apply[0] = 0;
tbl_oper[0] = 0; /* look-up operation */
```

```
status = get_data_key ("TSS", "TSS-1", "RETE", "RETE", "RTLA", &data_key);
if (status != ALL_OKAY)
{
    printf ("\n Error %d returned by get_data_key routine.\n", status);
    exit (-1);
    get_version_number (&vnum);
```

```
if (status != ALL_OKAY)
{
    printf ("\n Error %d returned by units_index routine.\n", status);
    exit (-1);
}
```

CREATE_SCF_DATA_STRUCTURE

function - creates an instance of the scf_data structure

SYNOPSIS

#include "libbase_SCF.h"
#include "SCF_codes.h"

SDDAS_SHORT create_scf_data_structure (SDDAS_CHAR *filename,
SDDAS_USHORT scf_version,
void **scf_data_ptr)

ARGUMENTS

-	the name of the SCF file of interest
-	SCF identification number which allows for multiple
	openings of the same SCF file
-	pointer to the newly created scf_data structure
-	routine status (see TABLE 1)
	-

TABLE 1. Status Codes Returned for CREATE_SCF_DATA_STRUCTURE

STATUS CODE	EXPLANATION OF STATUS
LOCATE_SCF_NOT_FOUND	the requested filename, scf_version combination has no memory allocated for
	processing (user did not call scf_open for this combination)
SCF_CREATE_ALL_MALLOC	no memory to hold the address of all allocated scf_data structures
SCF_CREATE_ALL_REALLOC	no memory for expansion of the area that holds the address of all allocated
	scf_data structures
SCF_CREATE_MALLOC	no memory for the scf_data structure
SCF_OUTPUT_MALLOC	no memory for the information pertaining to the values for the output variables
ALL_OKAY	the routine terminated successfully

DESCRIPTION

Create_scf_data_structure creates an instance of the **scf_data** structure that is used by the SCF software to return the results from the execution of the SCF algorithm. With each call to this module, a new **scf_data** structure is created and the address of this structure is returned. In order to access the elements within the **scf_data** structure, the user must explicitly cast the returned void pointer to a pointer of the type **struct scf_data**. Before the call to the **create_scf_data_structure** module can be made, a call to the routine **scf_open** with the identical **filename** and **scf_version** parameters must be made; otherwise, an error code is returned. The **filename** parameter includes the full pathname extension of the SCF file being referenced and must be less than 512 characters in length.

The parameter **scf_version** allows multiple file openings for the same SCF file. If the SCF file needs to be opened just once for processing, the same SCF version number should be passed to all SCF routines. However, for multiple file openings, the SCF version number should be unique and all file manipulations performed by the SCF routines will use the file descriptors defined for the SCF version number specified. The user should call the **scf_version_number** routine to retrieve a unique SCF version number instead of choosing

this value themselves. The retrieval of multiple output values from a single SCF source does not constitute the need for multiple SCF version numbers; a single SCF version number will suffice.

Since the SCF file dictates the number of output variables and the dimensionality of these variables, the user should call the **create_scf_data_structure** routine once for each distinct SCF file being processed. When multiple instances of the **scf_data** pointer are created, it is the responsibility of the user to keep track of which pointer to send to the SCF routines that utilize this structure. The contents of this structure is described in section 3S of the IDFS Programmers Manual.

The address and associated memory of each **scf_data** structure that is created can be freed through the **free_scf_info** routine. The user **must not** free the memory themselves since the SCF software will attempt to free the memory location and the result is uncertain.

ERRORS

All errors within this routine are returned through the status variable. The include file **SCF_codes.h**, which includes all possible return values, should be included so that the mnemonics for the return codes can be referenced. The **SCF_codes.h** file is described in section 3H of the IDFS Programmers Manual.

SEE ALSO

3R
3R
3H
3H
3S

BUGS

None

EXAMPLES

Create one instance of the **scf_data** structure that is to be associated with the SCF file TMMO_EXAMPLE and return the address in the specified parameter. Cast the returned void pointer so that elements of the **scf_data** structure can be referenced.

#include "libbase_SCF.h"
#include "SCF_codes.h"

struct scf_data *SCF_DATA; SDDAS_USHORT scf_vnum; SDDAS_SHORT status; void *scf_data_ptr;

scf_version_number (&scf_vnum);

status = create_scf_data_structure ("TMMO_EXAMPLE", scf_vnum, &scf_data_ptr);

if (status != ALL_OKAY)
{
 printf ("\n Error %d returned by create_scf_data_structure routine.\n", status);
 exit (-1);
}
SCF_DATA = (struct scf_data *) scf_data_ptr;

/* Print the name of the SCF file associated with this scf_data structure. */

printf ("\n SCF filename = %s", SCF_DATA->filename);

FREE_SCF_INFO

function - frees all the memory allocated by the SCF routines

SYNOPSIS

#include "libbase_SCF.h"

void free_scf_info (void)

ARGUMENTS

No arguments for this routine

DESCRIPTION

Free_scf_info frees all memory that has been allocated by the SCF routines. The computer operating system normally takes care of freeing any memory before terminating the program; however, for a clean exit, the user should call this module before exiting from the program. In addition, the user may call this module if a total restart of the SCF software is desired without restarting the program. In the case of a total restart, the user is advised to call the module **init_scf** before any other SCF routine since the **free_scf_info** routine merely frees allocated memory; it does not re-initialize variables used by the SCF software.

If any **scf_data** structures were created using the **create_scf_data_structure** routine, the **free_scf_info** module will free the memory associated with elements contained in the **scf_data** structure and the data structure itself. The user **must not** attempt to free this memory since the SCF software will also attempt to free the memory.

ERRORS

This routine returns no status or error codes.

SEE ALSO

init_scf	3R
create_scf_data_structure	3R
libbase_SCF	3H
scf_data	3S

BUGS

None

EXAMPLES

The usage of this routine is quite simple since no parameters are needed:

#include "libbase_SCF.h"

free_scf_info ();

INIT_SCF

function - initializes the system for SCF processing

SYNOPSIS

#include "libbase_SCF.h"

void init_scf (void)

ARGUMENTS

No arguments for this routine

DESCRIPTION

Init_scf initializes the system prior to the processing of the information contained in the SCF files. A call **must** be made to this routine before any other SCF routines are invoked.

Since the SCF data access software must interface with the database, calls must be made to the **dbInitialize** and **CfgInit** modules when the **init_scf** module is called. The user is referred to the webpages <u>http://cluster/libdbSQL.html</u> and <u>http://cluster/libCfg.html</u> for an explanation of these routines.

ERRORS

This routine returns no status or error codes.

BUGS

None

EXAMPLES

The usage of this routine is quite simple since no parameters are needed:

#include "libbase_SCF.h"

CfgInit (); dbInitialize (); init_scf (); init_scf (3R)

LOAD_SCF

function - loads the contents of the SCF file

SYNOPSIS

#include "libbase_SCF.h"
#include "SCF_codes.h"

SDDAS_SHORT load_scf (SDDAS_CHAR *filename, SDDAS_USHORT scf_version,
SDDAS_SHORT btime_yr, SDDAS_SHORT btime_day,
SDDAS_LONG btime_sec, SDDAS_LONG btime_nano,
SDDAS_SHORT etime_yr, SDDAS_SHORT etime_day,
SDDAS_LONG etime_sec, SDDAS_LONG etime_nano)

ARGUMENTS

TABLE 1. Status Codes Returned for LOAD_SCF

STATUS CODE	EXPLANATION OF STATUS
NO_SCF_FILE	error opening the specified SCF file
LOCATE_SCF_MALLOC	no memory for SCF definition structure
LOCATE_SCF_REALLOC	no memory for expansion of SCF definition structure
SCF_CONTACT_MALLOC	no memory for contact information contained in SCF file
SCF_COMMENTS_MALLOC	no memory for comment information contained in SCF file
SCF_INPUTS_MALLOC	no memory for SCF input variable structure
SCF_INPUT_TBL_MALLOC	no memory for unit conversion information for input variables
SCF_TEMP_MALLOC	no memory for SCF temporary variable structure
SCF_OUTPUT_VAR_MALLOC	no memory for SCF output variable structure
SCF_EQNS_MALLOC	no memory for equations structure
SCF_EQNS_REALLOC	no memory for expansion of equations structure
SCF_ARGS_MALLOC	no memory for the arguments/operands specified in the equations
SCF_INDEX_MALLOC	no memory for index variable information
SCF_MAP_MALLOC	no memory for the map of all defined variables
SCF_VOID	the function specified is a void function – no resultant variable should be specified
SCF_NON_VOID	the function specified is a non-void function – the resultant variable is missing
	from the equation
SCF_NUM_ARGS	incorrect number of arguments specified for function call

STATUS CODE	EXPLANATION OF STATUS
SCF_RES_LENGTH	invalid length for the resultant variable
SCF_ARG_RANK	the dimension of the argument/operand is invalid for the function/operator
	specified
SCF_RES_RANK	the dimension of the resultant variable does not match the dimension returned by
	the function/operator specified
SCF_NO_INDEX	the argument specified must not be an indexed variable
VIDF_OPEN_PTR_MALLOC	no memory for IDFS location pointers
VIDF_OPEN_EX_REALLOC	no memory for experiment definition structure expansion
NO_DATA	there is no VIDF available for the requested time period
SCF_SIZE_MISMATCH	the matrix size for all dimensions must be the same for the resultant and the
	arguments in the equation
SCF_MASK_LENGTHS	invalid dimension sizes for the resultant and arguments in the equation
SCF_SQUARE_ARG	the argument matrix in the equation is not a square matrix
SCF_SQUARE_RES	the resultant matrix in the equation is not a square matrix
SCF_AORDER_MISMATCH	the order values are not compliant for the arguments in the equation
SCF_RORDER_MISMATCH	the order value for the resultant is not compliant with arguments in the equation
SCF_NO_FUNCTION	the function being requested is not a registered function
SCF_DIMEN_MALLOC	no memory for the multi-dimensional data array
SCF_TENSOR_MANY_ARGS	there are more than 10 arguments defined for the tensor function
SCF_TENSOR_SAME_RANK	the resultant and the arguments must be the same rank for the tensor function used
SCF_TSIZE_MISMATCH	the matrix size of the resultant is invalid for the selected matrix operation
ALL_OKAY	the routine terminated successfully

Load_scf utilizes the **file_open** and **get_data_key** IDFS read routines. For a complete listing of the error codes returned by these modules, the user is referred to section 1R of the IDFS Programmers Manual.

DESCRIPTION

Load_scf opens and loads the contents of the SCF file. The SCF file of interest is referenced through the parameter **filename**. The **filename** parameter includes the full pathname extension of the SCF file being referenced and must be less than 512 characters in length. This routine needs a start and stop time in order to retrieve information from the VIDF file for the IDFS data sets utilized as input variables. This routine is used when the user is only concerned with accessing the contents of the SCF, not with the execution of the algorithm contained in the SCF file. If the user intends to execute the algorithm, the user should use the **scf_open** routine which calls the **load_scf** routine in addition to opening the IDFS data sets that are pertinent to the SCF file being processed. In either case, once the contents of the SCF file has been loaded, the user may call the **read_scf** routine to retrieve information from the SCF file.

The parameter **scf_version** allows multiple file openings for the same SCF file. If the SCF file needs to be opened just once for processing, the same SCF version number should be passed to all SCF routines. However, for multiple file openings, the SCF version number should be unique and all file manipulations performed by the SCF routines will use the file descriptors defined for the SCF version number specified. The user should call the **scf_version_number** routine to retrieve a unique SCF version number instead of choosing this value themselves. The retrieval of multiple output values from a single SCF source

does not constitute the need for multiple SCF version numbers; a single SCF version number will suffice.

ERRORS

All errors within this routine are returned through the status variable. The include file **SCF_codes.h**, which includes all possible return values, should be included so that the mnemonics for the return codes can be referenced. The **SCF_codes.h** file is described in section 3H of the IDFS Programmers Manual.

SEE ALSO

scf_open	3R
read_scf	3R
scf_version_number	3R
SCF_codes	3H
libbase_SCF	3H

BUGS

None

EXAMPLES

Retrieve the contents of the SCF file TMMO_EXAMPLE.

#include "libbase_SCF.h"
#include "SCF_codes.h"

SDDAS_LONG btime_sec, btime_nsec, etime_sec, etime_nsec; SDDAS_USHORT scf_vnum; SDDAS_SHORT status, btime_yr, btime_day, etime_yr, etime_day;

```
btime_yr = 1992;
btime_day = 217;
btime_sec = 32340;
btime_nsec = 0;
etime_yr = 1992;
etime_day = 217;
etime_sec = 32342;
etime_nsec = 0;
```

```
scf_version_number (&scf_vnum);
```

 $load_scf\left(3R\right)$

READ_SCF

function - retrieve information from the SCF file

SYNOPSIS

#include "libbase_SCF.h"
#include "SCF_file_defs.h"
#include "SCF_codes.h"

SDDAS_SHORT read_scf (SDDAS_CHAR *filename, SDDAS_USHORT scf_version,
SDDAS_LONG field, SDDAS_LONG which_src,
SDDAS_CHAR *var)

ARGUMENTS

filename	-	the name of the SCF file of interest
scf_version	-	SCF identification number which allows for multiple
		openings of the same SCF file
field	-	specified field in the SCF file
which_src	-	the variable or equation definition from which the
		required field is to be retrieved
var	-	output value(s) associated with the selected field
read_scf	-	routine status (see TABLE 1)

TABLE 1. Status Codes Returned for READ_SCF

STATUS CODE	EXPLANATION OF STATUS
LOCATE_SCF_NOT_FOUND	the requested filename, scf_version combination has no memory allocated for
	processing (user did not call scf_open or load_scf for this combination)
READ_SCF_BAD_INPUT	invalid input variable reference number (bad value for which_src parameter
READ_SCF_BAD_DSRC	error encountered for the IDFS data source specified for the input variable
READ_SCF_BAD_FIELD	the information requested is not relevant for the variable referenced
READ_SCF_BAD_TEMP	invalid temporary variable reference number (bad value for which_src parameter)
READ_SCF_NO_DIMEN	dimension length(s) is not pertinent for scalar quantities
READ_SCF_BAD_OUTPUT	invalid output variable reference number (bad value for which_src parameter)
READ_SCF_BAD_EQNS	invalid equation number (bad value for which_src parameter)
READ_SCF_ELSE_INFO	the information requested is not pertinent to the equation (there is no ELSE
	component for the equation in question)
READ_SCF_BAD_FUNCTION	invalid function used in the equation number referenced
READ_SCF_BAD_INDEX	invalid variable name as index value in the equation referenced
READ_SCF_BAD_TOKEN	invalid variable name in the equation number reference
READ_SCF_NO_TOKEN	the field being requested is not defined
ALL_OKAY	the routine terminated successfully

DESCRIPTION

Read_scf returns data for a selected field within the SCF file. The SCF file of interest is referenced through the parameter **filename**. The **filename** parameter includes the full pathname extension of the SCF file being referenced and must be less than 512 characters in length. The value of interest is indicated through the field number (**field**). A list of field numbers together with a set of built-in acronyms which can be used as input to this routine

are found in the **SCF_file_defs.h** file. This file is described in section 3H of the IDFS Programmers Manual. If the field being requested is associated with an input variable, temporary variable, output variable or equation definition, the variable or equation from which the data is to be retrieved is indicated through the parameter **which_src**. If the field being requested is not associated with a variable or equation definition, this parameter value is ignored by this routine; therefore, any value can be passed in for this parameter (the acronym NOT_USED is suggested).

The parameter **scf_version** allows multiple file openings for the same SCF file. If the SCF file needs to be opened just once for processing, the same SCF version number should be passed to all SCF routines. However, for multiple file openings, the SCF version number should be unique and all file manipulations performed by the SCF routines will use the file descriptors defined for the SCF version number specified. The user should call the **scf_version_number** routine to retrieve a unique SCF version number instead of choosing this value themselves. The retrieval of multiple output values from a single SCF source does not constitute the need for multiple SCF version numbers; a single SCF version number will suffice.

The routine returns data through the variable **var**. The variable **var** should be of the format of the data being requested (e.g., SDDAS_FLOAT, SDDAS_LONG, SDDAS_CHAR, etc.) and is cast as a character pointer when input into the routine. If the field being returned is an array field, **var** must be of sufficient size to hold the entire length of the data requested. The routine does not know internally whether a requested variable is an array or a single variable. This determination and the appropriate action must be taken by the calling routine. Prior to calling the **read_scf** routine, a call to either the **scf_open** or **load_scf** routine must have been made with the same **filename** and **scf_version** designations to open and load the contents of the appropriate SCF file.

ERRORS

All errors within this routine are returned through the status variable. The include file **SCF_codes.h**, which includes all possible return values, should be included so that the mnemonics for the return codes can be referenced. The **SCF_codes.h** file is described in section 3H of the IDFS Programmers Manual.

SEE ALSO

scf_open	3R
load_scf	3R
scf_version_number	3R
SCF_file_defs	3H
SCF_codes	3H
libbase_SCF	3H

BUGS

None

EXAMPLES

Obtain the number of equations defined in the SCF file TMMO_EXAMPLE. The number of equations is returned in the variable **num_of**. Since this field does not pertain to an individual variable or equation, the acronym NOT_USED is passed for the **which_src** parameter. Once that information is known, retrieve the equations, one at a time.

#include "libbase_SCF.h"
#include "SCF_file_defs.h"
#include "SCF_codes.h"

register SDDAS_LONG i; SDDAS_USHORT scf_vnum; SDDAS_LONG btime_sec, btime_nsec, etime_sec, etime_nsec, num_of; SDDAS_SHORT status, btime_yr, btime_day, etime_yr, etime_day; SDDAS_CHAR string[90];

```
btime_yr = 1992;
btime_day = 217;
btime_sec = 32340;
btime_nsec = 0;
etime_yr = 1992;
etime_day = 217;
etime_sec = 32342;
etime_nsec = 0;
```

```
status = read_scf ("TMMO_EXAMPLE", scf_vnum, S_NUM_EQNS, NOT_USED,
(SDDAS_CHAR *) &num_of);
```

December 28, 2012

```
if (status != ALL_OKAY)
{
    printf ("\n Error %d returned by read_scf routine.\n", status);
    exit (-1);
    printf ("Equation %ld : %s\n", i, string);
}
```

SCF_OPEN

function - loads the contents of the SCF file and opens all IDFS data sets identified as input variables

SYNOPSIS

#include "libbase_SCF.h"
#include "SCF_codes.h"

SDDAS_SHORT scf_open (SDDAS_CHAR *filename, SDDAS_USHORT scf_version,
SDDAS_SHORT btime_yr, SDDAS_SHORT btime_day,
SDDAS_LONG btime_sec, SDDAS_LONG btime_nano,
SDDAS_SHORT etime_yr, SDDAS_SHORT etime_day,
SDDAS_LONG etime_sec, SDDAS_LONG etime_nano)

ARGUMENTS

filename	-	the name of the SCF file of interest
scf_version	-	SCF identification number which allows for multiple
		openings of the same SCF file
btime_yr	-	the year at which algorithm execution is to commence
btime_day	-	the day of year at which algorithm execution is to commence
btime_sec	-	the time of day in seconds at which algorithm execution is to
		commence
btime_nano	-	the time of day residual in nanoseconds
etime_yr	-	the year at which algorithm execution is to terminate
etime_day	-	the day of year at which algorithm execution is to terminate
etime_sec	-	the time of day in seconds at which algorithm execution is to
		terminate
etime_nano	-	the time of day residual in nanoseconds
scf_open	-	routine status (see TABLE 1)

 TABLE 1. Status Codes Returned for SCF_OPEN

STATUS CODE	EXPLANATION OF STATUS
SCF_OPEN_RTIME	the SCF software does not support real-time processing
SCF_MATRIX_MALLOC	no memory for the data matrix that holds data for all defined variables
SCF_OPEN_ERROR	error returned from call to file_open for specified input variables
SCF_ALLOC_PLOT_LOC	no memory for structure that holds timing information
SCF_REALLOC_PLOT_LOC	no memory for expansion of structure that holds timing information
SCF_FRAC_MALLOC	no memory for normalization factors for the data for the input variables
	Error codes returned by file_open ()
	Error codes returned by get_data_key ()
	Error codes returned by create_idf_data_structure ()
	Error codes returned by load_scf ()
ALL_OKAY	the routine terminated successfully

Scf_open utilizes the **file_open**, **get_data_key** and **create_idf_data_structure** IDFS read routines. For a complete listing of the error codes returned by these modules, the user is referred to section 1R of the IDFS Programmers Manual.

DESCRIPTION

Scf_open opens and loads the contents of the SCF files and all referenced IDFS data sets. The SCF file of interest is referenced through the parameter **filename**. The **filename** parameter includes the full pathname extension of the SCF file being referenced and must be less than 512 characters in length. Once the contents of the specified SCF file is loaded, an attempt is made to open the IDFS data set(s) that are specified as the sources for the input variables. The SCF file itself has no dependence on time; that is, the algorithm can be applied to data taken at any time. However, the IDFS data files that are opened, the header, data, and VIDF file, are dependent on the time range specified. The appropriate IDFS data files are searched for within the current on-line database. If the files do exist on the local machine, the files are opened. If the files do not exist on the local machine, an error code is returned since this routine does not autopromote needed, but off-line, data. This routine opens the first set of IDFS data files within the time span over which data is to be processed. If there is more than one file set within the requested time interval, the remaining IDFS files will be opened and processed after the currently opened files are processed.

The SCF software does not support real-time processing. In the real-time scenario, the header and data files are incomplete and it is possible to attempt to read from either file prior to the data being received. Therefore, the values for the input variables may not be attainable when the algorithm is being executed and thus, the algorithm cannot be executed correctly. In the playback scenario, the data is always available provided data was collected at the time period being processed.

The parameter **scf_version** allows multiple file openings for the same SCF file. If the SCF file needs to be opened just once for processing, the same SCF version number should be passed to all SCF routines. However, for multiple file openings, the SCF version number should be unique and all file manipulations performed by the SCF routines will use the file descriptors defined for the SCF version number specified. In either case, the specified SCF will only be opened once for each unique parameter set. If additional calls are made to this routine with the same parameter set, the module simply returns the **ALL_OKAY** status code. The user should call the **scf_version_number** routine to retrieve a unique SCF version number instead of choosing this value themselves. The retrieval of multiple output values from a single SCF source does not constitute the need for multiple SCF version numbers; a single SCF version number will suffice.

ERRORS

All errors within this routine are returned through the status variable. The include file **SCF_codes.h**, which includes all possible return values, should be included so that the mnemonics for the return codes can be referenced. The **SCF_codes.h** file is described in section 3H of the IDFS Programmers Manual.

SEE ALSO

load_scf	3R
scf_version_number	3R
SCF_codes	3H
libbase_SCF	3H

BUGS

None

EXAMPLES

Retrieve the contents of the SCF file TMMO_EXAMPLE and open the associated IDFS data sets for the time range specified.

#include "libbase_SCF.h"
#include "SCF_codes.h"

SDDAS_LONG btime_sec, btime_nsec, etime_sec, etime_nsec; SDDAS_USHORT scf_vnum; SDDAS_SHORT status, btime_yr, btime_day, etime_yr, etime_day;

```
btime_yr = 1992;
btime_day = 217;
btime_sec = 32340;
btime_nsec = 0;
```

etime_yr = 1992; etime_day = 217; etime_sec = 32342; etime_nsec = 0;

```
scf_version_number (&scf_vnum);
```

scf_open (3R)

SCF_OUTPUT_DATA

function - execute the algorithm defined in the SCF file and return the values for the output variables in the specified **scf_data** structure

SYNOPSIS

#include "libbase_SCF.h"
#include "SCF_codes.h"

SDDAS_SHORT scf_output_data (SDDAS_CHAR *filename,
SDDAS_USHORT scf_version, void *scf_data_ptr)

ARGUMENTS

ple

TABLE 1. Status Codes Returned for SCF_OUTPUT_DATA

STATUS CODE	EXPLANATION OF STATUS
LOCATE_SCF_NOT_FOUND	the requested filename, scf_version combination has no memory allocated for
	processing (user did not call scf_open for this combination)
SCF_OUTPUT_CALC	the data accumulation rate has not been set (user did not call scf_sample_rate for
	this combination)
SCF_OUTPUT_DATA_STR	the scf_data structure is not associated with the specified SCF file
SCF_INVALID_INDEX	the array index value computed at execution time is invalid
SCF_BAD_LOGICAL_OPER	invalid logical operator specified in the IF-ELSE-ENDIF construct
SCF_FAST_BAD_LOCATE	an error was encountered when trying to access the structure that holds
	information pertinent to one of the IDFS data sets being processed
SCF_PROCESS_BAD_EX	an error was encountered when trying to access the structure that holds
	information pertinent to one of the IDFS data sets being processed
SCF_BAD_FRAC	invalid normalization factor computed
SCF_ACQ_MANY_READS	the acquisition time is incorrect for the vector IDFS source selected as the control
	variable
SCF_TERMINATE	processing must stop due to data not being on-line
SCF_NO_FUNCTION	the function being requested is not a registered function
SCF_NO_LIBRARY	the shared object library which holds the user-defined function can not be opened
SCF_NO_FUNC_IN_LIB	the user-defined function is not found in the specified shared object library
SCF_TDIMEN	invalid value for the dimension argument specified in the tensor summation
	equation
SCF_TSUM_VDIMEN	invalid dimension sizes for resultant row/column vector in the tensor summation
	equation
SCF_TSUM_ROW_DIMEN	cannot collapse over the first dimension since the argument is a row vector in the
	tensor summation equation
SCF_TSUM_COL_DIMEN	cannot collapse over the second dimension since the argument is a column vector
	in the tensor summation equation
SCF_TSUM_RSIZE	the size of the resultant tensor is incorrect for summing over the requested
	dimension in the tensor summation equation

STATUS CODE	EXPLANATION OF STATUS
SCF_TWDIMEN	invalid value for the dimension argument specified in the tensor weighted
	summation equation
SCF_TWSUM_VDIMEN	invalid dimension sizes for resultant row/column vector in the tensor weighted
	summation equation
SCF_TWSUM_ROW_DIMEN	cannot collapse over the first dimension since the argument is a row vector in the
	tensor weighted summation equation
SCF_TWSUM_COL_DIMEN	cannot collapse over the second dimension since the argument is a column vector
	in the tensor weighted summation equation
SCF_TWSUM_RSIZE	the size of the resultant tensor is incorrect for summing over the requested
	dimension in the tensor weighted summation equation
SCF_TW_WLEN	the size of the array of weight factors is incorrect for collapsing over the requested
	dimension in the tensor weighted summation equation
SCF_TSPACE	invalid value for the bin_spacing argument specified in the tensor integral equation
SCF_TINT_CLEN	the size of the array of center values in incorrect for collapsing over the requested
	dimension in the tensor integral equation
SCF_TINSERT_SDIMEN	invalid dimension sizes for the start / stop index arguments in the tensor insertion
	equation
SCF_TINSERT_START	the start index value is greater than the stop index value in the tensor insertion
	equation
SCF_TINSERT_INDEX	invalid start / stop index values specified in the tensor insertion equation
SCF_TINSERT_SIZE	the number of elements to be inserted does not match the size defined by the start /
	stop index values in the tensor insertion equation
SCF_TEXTRACT_SDIMEN	invalid dimension sizes for the start / stop index arguments in the tensor extraction
	equation
SCF_TEXTRACT_START	the start index value is greater than the stop index value in the tensor extraction
	equation
SCF_TEXTRACT_INDEX	invalid start / stop index values specified in the tensor extraction equation
SCF_TEXTRACT_RES_RANK	the dimension (rank) of the resultant is inconsistent with the start / stop index
	values specified in the tensor extraction equation
SCF_TEXTRACT_RES_DIMEN	invalid dimension sizes for the resultant in the tensor extraction equation
SCF_BREAK_STMT	a BREAK statement was specified outside of a FOR loop
SCF_FILL_SZ	the size of the array that holds the data once it has been converted into the
	requested units is not large enough to hold the data that is being processed
SCF_TENSOR_VECTOR_SRC	Multi-dimensional IDFS data source cannot serve as a controller
CUR_TIME_NOT_FOUND	an error was encountered when trying to access the structure that holds
	information pertinent to one of the IDFS data sets being processed
CHK_TDATA_NOT_FOUND	an error was encountered when trying to access the structure that holds
	information pertinent to one of the IDFS data sets being processed
CHK_DATA_NOT_FOUND	an error was encountered when trying to access the structure that holds
	information pertinent to one of the IDFS data sets being processed
	Error codes returned by read_drec ()
	Error codes returned by convert_to_units ()
	Error codes returned by reset_experiment_info ()
	Error codes returned by file_pos ()
	Error codes returned by next_file_start_time ()
	Error codes returned by create_idf_data_structure ()
ALL_OKAY	the routine terminated successfully

Scf_output_data utilizes the **convert_to_units**, **read_drec**, **reset_experiment_info** and **file_pos** IDFS read routines. For a complete listing of the error codes returned by these modules, the user is referred to section 1R of the IDFS Programmers Manual.

DESCRIPTION

Scf output data returns data for all the defined output variables evaluated during the current time step of the algorithm. The SCF file of interest is referenced through the parameter filename. The filename parameter includes the full pathname extension of the SCF file being referenced and must be less than 512 characters in length. Due to the nature of the processing, it is possible that the current time interval may cross a file boundary; that is, the start time of the interval is within one file and the end time of the interval is within the next file. If the next file is not available, the status code SCF_TERMINATE will be Subsequent calls to the scf_output_data routine will continue to return returned. SCF TERMINATE until the calling module terminates. Therefore, if the user does not look for the SCF_TERMINATE status code upon return from this module and terminate processing appropriately, the program will end up in an infinite loop. This status code may be returned when the user-requested end time is located between the start and stop time period for the current iteration of the algorithm. In this case, the data for the controlling data set will be complete, but the acquisition of other sets of data required by the SCF may be incomplete due to data files not being available (online) to complete the acquisition. It is up to the user whether or not to utilize the sample. This status code may also be returned in the midst of processing if the data file became unavailable (off-line) after processing of the data began. If this happens, it is not known whether the controlling data set or the other data sets ran into the problem; therefore, it is best to simply throw away the data and terminate processing. Therefore, appropriate termination must be deciphered by the user program.

The returned data is placed in the **scf_data** structure that is referenced by the argument **scf_data_ptr**. The argument **scf_data_ptr** is a pointer to the structure that is to hold all data pertinent to the SCF file being processed. The structure is created and the address to this structure is returned when a call to the **create_scf_data_structure** routine is made. The contents of this structure is described in section 3S of the IDFS Programmers Manual. Since the SCF file dictates the number of output variables and the dimensionality of these variables, the user should call the **create_scf_data_structure** routine once for each distinct SCF file being processed and this pointer should be passed in conjunction with the named SCF file when the output variable values are being retrieved. If the **scf_output_data** routine determines that the **scf_data** structure being referenced is not associated with the named SCF file, an error code is returned.

The parameter **scf_version** allows multiple file openings for the same SCF file. If the SCF file needs to be opened just once for processing, the same SCF version number should be passed to all SCF routines. However, for multiple file openings, the SCF version number should be unique and all file manipulations performed by the SCF routines will use the file descriptors defined for the SCF version number specified. The user should call the **scf_version_number** routine to retrieve a unique SCF version number instead of choosing this value themselves. The retrieval of multiple output values from a single SCF source does not constitute the need for multiple SCF version numbers; a single SCF version number will suffice.

The number of output variables returned is always indicated in the **scf_data** structure in the **num_output** element. The data that is returned is referenced by the **output_data** element of the **scf_data** structure. This element is a pointer to the memory that holds all values for all output variables. In order to get to the data for a specific output variable, the user must retrieve an index into this memory block. These indexes are returned in the **output_index** element of the **scf_data** structure, which is an array of values, with one value being returned per output variable. Indexing into this array starts at position zero. Once this index value has been retrieved, the user can then reference the data for a particular output variable.

The output variables returned may be of different dimensionalities; that is, the data being returned may be a combination of scalar, vector or tensor quantities since the SCF software multi-dimensional quantities supports output (up 10-D). to e.g. OUTPUT1[n][n][n][n][n][n][n][n][n]]. The number of values returned for each output variable is indicated in the output_length element of the scf_data structure. The output_length element is an array of values, with one value being returned per output variable. Indexing into this array starts at position zero. The user is referred to the EXAMPLE section for a coding example which exemplifies data retrieval for each output variable that is returned by this module.

The amount of time that is processed for each iteration of the algorithm is specified in the call to the **scf_sample_rate** routine. The user must call the **scf_sample_rate** routine once per program before the **scf_output_data** routine is called; otherwise, an error code is returned by this module. If the user specifies that the SCF software is to determine the accumulation rate and if the sample rate for one of the input variables changes while the algorithm is being executed, the software will continue to acquire data for the current accumulation period. If the sample rate changed such that the source is returning data at a rate faster than the current accumulation period, the accumulation period will be re-set at the next iteration of the algorithm.

ERRORS

All errors within this routine are returned through the status variable. The include file **SCF_codes.h**, which includes all possible return values, should be included so that the mnemonics for the return codes can be referenced. The **SCF_codes.h** file is described in section 3H of the IDFS Programmers Manual.

SEE ALSO

scf_open	3R
scf_sample_rate	3R
create_scf_data_structure	3R
scf_version_number	3R
SCF_codes	3H
libbase_SCF	3H
scf_data	3S

BUGS

None

EXAMPLES

Execute the algorithm defined in the SCF file TMMO_EXAMPLE one time. The data is returned in the **scf_data** structure referenced by the pointer **scf_data_ptr**. Print out the values for the output variables returned. The code assumes that the **scf_sample_rate** module has been called.

#include "libbase_SCF.h"
#include "SCF_codes.h"

struct scf_data *SCF_DATA; register SDDAS_LONG i; SDDAS_FLOAT *dptr, *stop_loop; SDDAS_USHORT scf_vnum; SDDAS_SHORT status; void *scf_data_ptr;

```
scf_version_number (&scf_vnum);
status = create_scf_data_structure (&scf_data_ptr);
if (status != ALL_OKAY)
{
    printf ("\n Error %d returned by create_scf_data_structure routine.\n", status);
    exit (-1);
  }
SCF_DATA = (struct scf_data *) scf_data_ptr;
```

```
status = scf_output_data ("TMMO_EXAMPLE", scf_vnum, scf_data_ptr);
if (status != ALL_OKAY)
{
    printf ("\n Error %d returned by scf_output_data routine.\n", status);
    exit (-1);
}
/* Print the output variables returned. */
for (i = 0; i < SCF_DATA->num_output; ++i)
{
    dptr = SCF_DATA->output_data + *(SCF_DATA->output_index + i);
    stop_loop = dptr + *(SCF_DATA->output_length + i);
    for (; dptr < stop_loop; ++dptr)
        printf ("\nOutput Variable %ld = %e", i, *dptr);
}
```

SCF_POSITION

function - positions the IDFS file pointers at the requested time in the files for all defined SCF input variables

SYNOPSIS

#include "libbase_SCF.h"
#include "SCF_codes.h"

SDDAS_SHORT scf_position (SDDAS_CHAR *filename, SDDAS_USHORT scf_version,
SDDAS_SHORT btime_yr, SDDAS_SHORT btime_day,
SDDAS_LONG btime_sec, SDDAS_LONG btime_nano,
SDDAS_SHORT etime_yr, SDDAS_SHORT etime_day,
SDDAS_LONG etime_sec, SDDAS_LONG etime_nano)

ARGUMENTS

filename	-	the name of the SCF file of interest
scf_version	-	SCF identification number which allows for multiple openings of the same SCF file
btime_yr	-	the year at which algorithm execution is to commence
btime_day	-	the day of year at which algorithm execution is to commence
btime_sec	-	the time of day in seconds at which algorithm execution is to commence
btime_nano	-	the time of day residual in nanoseconds
etime_yr	-	the year at which algorithm execution is to terminate
etime_day	-	the day of year at which algorithm execution is to terminate
etime_sec	-	the time of day in seconds at which algorithm execution is to terminate
etime_nano	-	the time of day residual in nanoseconds
scf_position	-	routine status (see TABLE 1)

TABLE 1. Status Code Returned for SCF_POSITION

STATUS CODE	EXPLANATION OF STATUS
LOCATE_SCF_NOT_FOUND	the requested filename, scf_version combination has no memory allocated for
	processing (user did not call scf_open for this combination)
SCF_POS_ERROR	error returned from call to file_pos for specified input variables
CHK_TDATA_NOT_FOUND	an error was encountered when trying to access the structure that holds information
	pertinent to one of the IDFS data sets being processed
CHK_DATA_NOT_FOUND	an error was encountered when trying to access the structure that holds information
	pertinent to one of the IDFS data sets being processed
WRONG_DATA_STRUCTURE	incompatibility between IDFS data set and IDFS data structure used to hold the
	data being returned
	Error codes returned by file_pos ()
ALL_OKAY	the routine terminate successfully

Scf_position utilizes the IDFS read routine **file_pos**. For a complete listing of the error codes returned by this module, the user is referred to section 1R of the IDFS Programmers Manual.

DESCRIPTION

Scf_position positions all of the IDFS data sets at the requested start time. The SCF file of interest is referenced through the parameter **filename**. The **filename** parameter includes the full pathname extension of the SCF file being referenced and must be less than 512 characters in length. This routine uses the currently opened IDFS files that are associated with the defined input variables and sets the current data pointers to the data sample or sweep whose beginning time is closest to the requested start time. If all of the IDFS data sets cannot be positioned, an error code is returned. Before the first call to the **scf_position** routine can be made, a call to the routine **scf_open** with the identical **filename** and **scf_version** parameters must have been made to obtain a set of file descriptors for the appropriate vidf, header and data files.

The parameter **scf_version** allows multiple file openings for the same SCF file. If the SCF file needs to be opened just once for processing, the same SCF version number should be passed to all SCF routines. However, for multiple file openings, the SCF version number should be unique and all file manipulations performed by the SCF routines will use the file descriptors defined for the SCF version number specified. The user should call the **scf_version_number** routine to retrieve a unique SCF version number instead of choosing this value themselves. The retrieval of multiple output values from a single SCF source does not constitute the need for multiple SCF version numbers; a single SCF version number will suffice.

ERRORS

All errors within this routine are returned through the status variable. The include file **SCF_codes.h**, which includes all possible return values, should be included so that the mnemonics for the return codes can be referenced. The **SCF_codes.h** file is described in section 3H of the IDFS Programmers Manual.

SEE ALSO

scf_open	3R
scf_version_number	3R
libbase_SCF	3H
SCF_codes	3H

BUGS

None

EXAMPLES

Position the IDFS data files associated with the input variables defined in the SCF file TMMO_EXAMPLE at the start of the time range specified.

#include "libbase_SCF.h"
#include "SCF_codes.h"

exit (-1);

}

```
SDDAS_LONG btime_sec, btime_nsec, etime_sec, etime_nsec;
SDDAS USHORT scf vnum;
SDDAS_SHORT status, btime_yr, btime_day, etime_yr, etime_day;
btime_yr = 1992;
btime_day = 217;
btime_sec = 32340;
btime nsec = 0;
etime yr = 1992;
etime_day = 217;
etime sec = 32342;
etime_nsec = 0;
scf_version_number (&scf_vnum);
status = scf_open ("TMMO_EXAMPLE", scf_vnum, btime_yr, btime_day, btime_sec,
                 btime_nsec, etime_yr, etime_day, etime_sec, etime_nsec);
if (status != ALL OKAY)
{
 printf ("\n Error %d returned by scf_open routine.\n", status);
 exit (-1);
 }
status = scf_position ("TMMO_EXAMPLE", scf_vnum, btime_yr, btime_day,
                      btime_sec, btime_nsec, etime_yr, etime_day, etime_sec,
                      etime_nsec);
if (status != ALL_OKAY)
{
 printf ("\n Error %d returned by scf_position routine.\n", status);
```

scf_position (3R)

SCF_SAMPLE_RATE

function - determines the amount of time to be processed for each iteration of the algorithm

SYNOPSIS

#include "libbase_SCF.h"
#include "SCF_defs.h"
#include "SCF_codes.h"

SDDAS_SHORT scf_sample_rate (SDDAS_CHAR *filename,

SDDAS_USHORT scf_version, SDDAS_CHAR accum_method,
SDDAS_DOUBLE time_value, SDDAS_CHAR rate_calc)

ARGUMENTS

filename	-	the name of the SCF file of interest	
scf_version	-	SCF identification number which allows for multiple	
		openings of the same SCF file	
accum_method	-	the scheme used to determine the amount of time to be	
		processed for each iteration of the algorithm	
		1 - use the accumulation rate of the fastest	
		input variable, as determined by the	
		SCF software (SCF_DELTA_T)	
		2 - use the accumulation rate of the input	
		variable specified in the time_value	
		parameter (USE_INPUT_VAR)	
		3 - use the accumulation rate specified in	
		the time_value parameter	
		(USE_DELTA_T)	
time_value	-	the input variable number to use for the USE_INPUT_VAR	
		accum_method or the time period to use as accumulation rate	
		for the USE_DELTA_T accum_method	
rate_calc	-	the method to use to calculate the accumulation rate for the	
		IDFS data sets utilized by the input variables	
		1 - use data accumulation values	
		(SCF_MEASURE_TM)	
		2 - use data accumulation plus data latency	
		values (SCF_MEASURE_LAT_TM)	
scf_sample_rate	-	routine status (see TABLE 1)	

TABLE 1.	Status Codes	Returned for	SCF_SA	AMPLE_	RATE
----------	--------------	--------------	--------	--------	------

STATUS CODE	EXPLANATION OF STATUS	
LOCATE_SCF_NOT_FOUND	the requested filename, scf_version combination has no memory allocated for	
	processing (user did not call scf_open for this combination)	
SCF_SAMP_VECTOR_ACCUM	the accumulation scheme selected in the accum_method parameter is not a valid	
	selection for non-scalar inputs variables	
SCF_SAMP_POS	the IDFS data sets have not been positioned at the designated start time (user did	
	not call scf_position for this combination)	

STATUS CODE	EXPLANATION OF STATUS	
SCF_SAMP_SWP_MALLOC	no memory to hold the time period for each element of the sweep	
SCF_SAMP_BAD_ACCUM	invalid value for the accum_method parameter	
SCF_SAMP_BAD_LOCATE	an error was encountered when trying to access information pertinent to one of	
	the IDFS data sets being processed	
SCF_SAMP_BAD_RATE	invalid value for the rate_calc parameter	
SCF_SAMP_BAD_INPUT_NUM invalid value for the time_value parameter; bad input variable number		
SCF_SAMP_VECTOR_SRC	a non-scalar input variable must be selected when the input variables are a	
	combination of scalar and non-scalar (vector) data	
SCF_FAST_BAD_LOCATE	an error was encountered when trying to access the structure that holds	
	information pertinent to one of the IDFS data sets being processed	
CUR_TIME_NOT_FOUND	an error was encountered when trying to access the structure that holds	
	information pertinent to one of the IDFS data sets being processed	
	Error codes returned by create_idf_data_structure ()	
ALL_OKAY	the routine terminated successfully	

DESCRIPTION

Scf_sample_rate determines the amount of time to be processed for each iteration of the algorithm defined by the SCF. The SCF file of interest is referenced through the parameter filename. The filename parameter includes the full pathname extension of the SCF file being referenced and must be less than 512 characters in length. The user must call the scf_position routine before the scf_sample_rate module can be called. If the scf_sample_rate routine determines that the scf_position routine has not been called, an error code is returned to the user. In addition, this module must be called once per program prior to calling the scf_output_data routine; otherwise, the scf_output_data routine will return an error code.

The parameter **scf_version** allows multiple file openings for the same SCF file. If the SCF file needs to be opened just once for processing, the same SCF version number should be passed to all SCF routines. However, for multiple file openings, the SCF version number should be unique and all file manipulations performed by the SCF routines will use the file descriptors defined for the SCF version number specified. The user should call the **scf_version_number** routine to retrieve a unique SCF version number instead of choosing this value themselves. The retrieval of multiple output values from a single SCF source does not constitute the need for multiple SCF version numbers; a single SCF version number will suffice.

The amount of time to be processed for each iteration of the algorithm can be computed in one of three ways. The first method lets the user specify the amount of time to be processed. For this method, the parameter **accum_method** must be set to the value **USE_DELTA_T** and the parameter **time_value** must be set to the number of seconds to use as the accumulation period. Since this parameter is a double precision floating point value, fractions of a second can be specified. Since the amount of time is specified and not computed, the parameter **rate_calc** is not utilized, but it must still be specified. The user cannot select this method if any of the defined input variables are vector IDFS sources; an error code will be returned to the user if this condition is true.

The second method uses the data accumulation rate for a specific input variable as the amount of time to be processed for each iteration of the algorithm. For this method, the parameter **accum_method** must be set to the value **USE_INPUT_VAR** and the parameter **time_value** must be set to the input variable number. A check is made to ensure that the input variable number specified is a valid value. If the data associated with the defined input variables is a mixture of scalar and vector (1-D) data, the user must select a 1-D vector input variable to calculate the accumulation period. If the user specified a scalar input variable, an error code is returned to the user.

The third method should be selected when the SCF software is to determine the amount of time to be processed for each iteration of the algorithm. For this method, the parameter **accum_method** must be set to the value **SCF_DELTA_T**. The parameter **time_value** is not utilized but it must still be specified; a value of 0.0 is suggested. For this method, the software loops over all defined input variables to find the IDFS data set that has the fastest sample rate and that data set controls the rate of data accumulation for each iteration of the algorithm. If the data associated with the defined input variables is a mixture of scalar and vector (1-D) data, the SCF software will only use the vector data to determine the fastest sample rate.

For the second and third method, the **rate_calc** parameter defines the scheme that is to be used to calculate the sample rate for the IDFS data sets utilized by the input variables. For a scalar IDFS data set, if the parameter is set to **SCF_MEASURE_TM**, the sample rate will be determined by comparing the **data_accum** value found in the header record for the IDFS data sets. If the parameter is set to **SCF_MEASURE_LAT_TM**, the sample rate will be determined by combining the **data_accum** and **data_lat** values found in the header record for the IDFS data sets. The **data_accum** value is defined as the time over which the acquisition of a single datum occurs and the **data_lat** value is defined as the dead time between successive data acquisitions. The **data_accum** and the **data_lat** values together give the total time between successive accumulations.

For a vector IDFS data set, the interpretation of the **rate_calc** parameter is somewhat different. If the parameter is set to **SCF_MEASURE_TM**, the sample rate will be determined by comparing the time it takes to acquire the data for the sweep, which is defined as (**data_accum** + **data_lat**) times the number of samples in the sweep. If the parameter is set to **SCF_MEASURE_LAT_TM**, the sample rate will be determined by combining the time it takes to acquire the data for the sweep and the **swp_reset** value found in the header record for the IDFS data sets. The **swp_reset** value is defined as the dead time between successive columns of data, which is equivalent to any data latency which exists in going from the last step in one vector back to the initial step in the next vector.

ERRORS

All errors within this routine are returned through the status variable. The include file **SCF_codes.h**, which includes all possible return values, should be included so that the mnemonics for the return codes can be referenced. The **SCF_codes.h** file is described in section 3H of the IDFS Programmers Manual.

SEE ALSO

scf_version_number	3R
scf_output_data	3R
scf_position	3R
SCF_codes	3H
SCF_defs	3H
libbase_SCF	3H

BUGS

None

EXAMPLES

Determine the fastest sample rate of all input variables defined in the SCF file TMMO_EXAMPLE. The following code segment assumes that **scf_version_number** and **scf_position** modules have been called.

#include "libbase_SCF.h"
#include "SCF_defs.h"
#include "SCF_codes.h"

SDDAS_USHORT scf_vnum; SDDAS_DOUBLE time_value; SDDAS_SHORT status;

SCF_TERMINATE_SOURCES

function – returns the IDFS data key(s) for the input variable(s) that are no longer available for processing and caused the return of the status code SCF_TERMINATE from the **scf_output_data** routine

SYNOPSIS

#include "libbase_SCF.h"
#include "SCF_codes.h"

SDDAS_SHORT scf_terminate_sources (SDDAS_CHAR *filename, SDDAS_USHORT scf_version, SDDAS_LONG *num_sources, SDDAS_ULONG **idfs keys)

ARGUMENTS

filename	-	the name of the SCF file of interest
scf_version	-	SCF identification number which allows for multiple openings of the same SCF file
num_sources	-	the number of elements defined for the idfs_keys
idfs_keys	-	array pointer to the array of data keys for the IDFS data sources that are no longer available for processing
scf terminate sources	_	(duplicates are removed) routine status (see TABLE 1)

TABLE 1. Status Codes Returned for SCF_TERMINATE_SOURCES

STATUS CODE	EXPLANATION OF STATUS	
LOCATE_SCF_NOT_FOUND	the requested filename, scf_version combination has no memory allocated for	
	processing (user did not call scf_open for this combination)	
ALL_OKAY	the routine terminated successfully	

DESCRIPTION

Scf_terminate_sources identifies the IDFS data source(s) that triggered the return value of SCF_TERMINATE from the **scf_output_data** routine. This return code indicates that some of the IDFS data sources are no longer available for processing for the time interval being executed. In other words, all of the data for the time step being processed by the SCF algorithm is not available online. The SCF file of interest is referenced through the parameter **filename**. The **filename** parameter includes the full pathname extension of the SCF file being referenced and must be less than 512 characters in length.

The parameter **scf_version** allows multiple file openings for the same SCF file. If the SCF file needs to be opened just once for processing, the same SCF version number should be passed to all SCF routines. However, for multiple file openings, the SCF version number should be unique and all file manipulations performed by the SCF routines will use the file descriptors defined for the SCF version number specified. The user should call the

scf_version_number routine to retrieve a unique SCF version number instead of choosing this value themselves. The retrieval of multiple output values from a single SCF source does not constitute the need for multiple SCF version numbers; a single SCF version number will suffice.

The data key(s) for the IDFS data source(s) that are no longer available for processing are returned in the **idfs_keys** array and the number of elements contained in the **idfs_keys** array is returned in **num_sources**. The memory for the **idfs_keys** array is allocated by this module and should be freed by the calling module once the information has been processed. The pointer value for the **idfs_keys** argument should be checked for a NULL value, which indicates that the memory allocation attempt failed.

ERRORS

All errors within this routine are returned through the status variable. The include file **SCF_codes.h**, which includes all possible return values, should be included so that the mnemonics for the return codes can be referenced. The **SCF_codes.h** file is described in section 3H of the IDFS Programmers Manual.

SEE ALSO

scf_version_number	3R
scf_output_data	3R
scf_open	3R
SCF_codes	3H
libbase_SCF	3H

BUGS

None

EXAMPLES

Execute the algorithm defined in the SCF file TMMO_EXAMPLE one time by calling the module **scf_output_data**. If the status code SCF_TERMINATE is returned, print out the data key(s) for the IDFS data source(s) that are no longer available for processing.

#include "libbase_SCF.h"
#include "SCF_codes.h"

register SDDAS_LONG i; SDDAS_LONG num_sources; SDDAS_ULONG *data_keys; SDDAS_USHORT scf_vnum; SDDAS_SHORT status; void *scf_data_ptr;

scf_version_number (&scf_vnum);

```
status = create_scf_data_structure (&scf_data_ptr);
 if (status != ALL OKAY)
 {
  printf ("\n Error %d returned by create_scf_data_structure routine.\n", status);
  exit (-1);
 }
status = scf_output_data ("TMMO_EXAMPLE", scf_vnum, scf_data_ptr);
if (status != ALL_OKAY && status != SCF_TERMINATE)
{
  printf ("\n Error %d returned by scf_output_data routine.\n", status);
  exit (-1);
}
if (status == SCF_TERMINATE)
{
 status = scf_terminate_sources ("TMMO_EXAMPLE", scf_vnum, &num_sources,
                                  &data_keys);
 if (status != ALL_OKAY)
 {
   printf ("\n Error %d returned by scf_terminate_sources routine.\n", status);
  exit (-1);
 }
 if (*data_keys != NULL)
  for (i = 0; i < num\_sources; ++i)
   printf ("\nData Key[%ld] = %ld", i, data_keys[i]);
 free (data_keys);
}
```

SCF_VERSION_NUMBER

function - returns a unique SCF identification number

SYNOPSIS

#include "libbase_SCF.h"

void scf_version_number (SDDAS_USHORT *scf_version)

ARGUMENTS

scf_version -

SCF identification number which allows for multiple openings of the same SCF file for concurrent algorithm execution

DESCRIPTION

Scf_version_number returns a unique SCF identification number that is to be used as a parameter to the other SCF routines. This parameter allows multiple file openings for an SCF file. In most cases, the user may open many different SCF files, opening each SCF file once. In this case, the user may pass the same SCF version number for each of the different SCF files; that is, one SCF version number is sufficient. The user should call the **scf_version_number** module to be guaranteed a unique SCF version number. For multiple file openings of the same SCF file, the SCF version number must be unique and all file manipulations performed by the SCF routines will use the file descriptors defined for the SCF version number specified.

ERRORS

This routine returns no status or error codes.

BUGS

None

EXAMPLES

Retrieve a unique SCF version number to be used by the SCF routines.

#include "libbase_SCF.h"

SDDAS_USHORT vnum;

scf_version_number (&vnum);

SCF_ALGORITHM_START

function - returns the start time and the accumulation period (delta-t) for the first iteration of the SCF algorithm

SYNOPSIS

#include "libavg_SCF.h"
#include "SCF_codes.h"

SDDAS_SHORT scf_algorithm_start (SDDAS_CHAR *filename,			
SDDAS_USHORT scf_version, SDDAS_SHORT *start_year,			
SDDAS_SHORT *start_day, SDDAS_LONG *start_sec,			
SDDAS_LONG *start_nano, SDDAS_LONG *res_sec,			
SDDAS_LONG *res_nano)			

ARGUMENTS

filename	-	the name of the SCF file of interest
scf_version	-	SCF identification number which allows for multiple openings of the same SCF file
start_year	-	the year time component for the first iteration of the SCF algorithm
start_day	-	the day of year time component for the first iteration of the SCF algorithm
start_sec	-	the time of day in seconds for the first iteration of the SCF algorithm
start_nano	-	the time of day residual in nanoseconds for the first iteration of the SCF algorithm
res_sec	-	the accumulation period (delta-t) in seconds
res_nano	-	the accumulation period residual in nanoseconds
scf_algorithm_start	-	routine status (see TABLE 1)

TABLE 1. Status Codes Returned for SCF_ALGORITHM_START

STATUS CODE	EXPLANATION OF STATUS	
LOCATE_SCF_NOT_FOUND	the requested filename, scf_version combination has no memory allocated for	
	processing (user did not call scf_open for this combination)	
SCF_ALG_START_NO_SAMPLE	the data accumulation rate has not been set (user did not call scf_sample_rate for	
	this combination)	
ALL_OKAY	the routine terminated successfully	

DESCRIPTION

Scf_algorithm_start returns the start time and the amount of time processed for the first iteration of the algorithm defined by the SCF. The SCF file of interest is referenced through the parameter **filename**. The **filename** parameter includes the full pathname extension of the SCF file being referenced and must be less than 512 characters in length. The user **must** call the **scf_sample_rate** routine before the **scf_algorithm_start** module can be called. If

the **scf_algorithm_start** routine determines that the **scf_sample_rate** routine has not been called, an error code is returned.

The parameter **scf_version** allows multiple file openings for the same SCF file. If the SCF file needs to be opened just once for processing, the same SCF version number should be passed to all SCF routines. However, for multiple file openings, the SCF version number should be unique and all file manipulations performed by the SCF routines will use the file descriptors defined for the SCF version number specified. The user should call the **scf_version_number** routine to retrieve a unique SCF version number instead of choosing this value themselves. The retrieval of multiple output values from a single SCF source does not constitute the need for multiple SCF version numbers; a single SCF version number will suffice.

ERRORS

All errors within this routine are returned through the status variable. The include file **SCF_codes.h**, which includes all possible return values, should be included so that the mnemonics for the return codes can be referenced. The **SCF_codes.h** file is described in section 3H of the IDFS Programmers Manual.

SEE ALSO

scf_open	3R
scf_version_number	3R
scf_sample_rate	3R
SCF_codes	3H
libavg_SCF	4H

BUGS

None

EXAMPLES

Determine the start time and the time accumulation period associated with the first iteration of the SCF file TMMO_EXAMPLE. The following code segment assumes that **scf_version_number** and **scf_sample_rate** modules have been called.

#include "libavg_SCF.h"
#include "SCF_codes.h"

SDDAS_USHORT scf_vnum; SDDAS_SHORT status, base_yr, base_day; SDDAS_LONG base_sec, base_nano, res_sec, res_nano;

```
if (status != ALL_OKAY)
{
    printf ("\n Error %d returned by scf_algorithm_start routine.\n", status);
    exit (-1);
}
```

SCF_BIN_INFO

function - specifies how SCF data is to be binned for time or sample averaging

SYNOPSIS

#include "libavg_SCF.h"
#include "SCF_codes.h"
#include "user_defs.h"

SDD	AS_SHORT scf	binin	fo (SDDAS_CHAR *filename,		
	_		<pre>_mio(SDDAS_CHAR menane, SDDAS_USHORT scf_version, SDDAS_LONG output_var, SDDAS_CHAR swp_type, SDDAS_FLOAT start, SDDAS_FLOAT stop, SDDAS_LONG num_bins, SDDAS_CHAR swp_fmt, SDDAS_LONG center_var, SDDAS_LONG band_var, SDDAS_LONG upper_band_var, SDDAS_CHAR var_fmt, SDDAS_CHAR input_fmt)</pre>		
ARGUMEN	TS				
filena		-	the name of the SCF file of interest		
	ersion	-	SCF identification number which allows for multiple		
_			openings of the same SCF file		
outpu	ıt_var	-	output variable identification number (numbering starts at		
-			zero)		
swp_	type	-	the format used to determine the number of data bins and data		
			storage		
			1 - the number of bins used is equal to the		
			number of values returned for the		
			specified output variable (FIXED_SWEEP)		
			2 - user specifies the number of bins		
			(VARIABLE_SWEEP)		
start		-	the center value associated with the first bin for variable		
			sweep processing		
stop		-	the center value associated with the last bin for variable sweep processing		
num_	_bins	-	the number of bins to create for variable sweep processing		
swp_	fmt	-	the spacing for the bins		
			1 - use linear spacing (LIN_SPACING)		
			2 - use logarithmic spacing		
			(LOG_SPACING)		
			3 - use variable width spacing		
			(VARIABLE_SPACING)		
center	r_var	-	the output variable which holds the center values to be used		
			for the bins (the dependent variable); a value of -1 means no		
			output variable specified since numbering starts at zero		

	the output variable which holds the widths of the bins (used to create the band width values); a value of -1 means no output		
	variable specified since numbering starts at zero		
	the output variable which holds the upper edges of the scan		
	bins when var_fmt is set to 'A' or 'a'; a value of -1 means no output variable specified since numbering starts at zero		
	the format flag for variable width spacing		
_	L or l -	the center bin values are used as the	
		lower edge of the band width values	
	C or c -	the center bin values are used as the	
		midpoints of the band width values	
	U or u -	the center bin values are used as the	
		upper edge of the band width values	
	E or e -	the center bin values are used as the	
		lower edge of the band width values	
		and the scan widths specified are the	
		actual upper edge of the band width	
		values, not delta values	
	A or a -	the actual center, lower edge band	
		width and upper edge band width	
		values are provided (no computations	
		off the center values are necessary)	
		or the binning of the SCF data for	
	variable sweep proces	ssing	
	1 -	data is placed in the bin which	
		encompasses the value for the	
		dependent variable associated with the	
		data (POINT_STORAGE)	
	2 -	data is placed in all bins which fully or	
		partially contain the range for the	
		dependent variable associated with the	
		data (BAND_STORAGE)	
scf_bin_info -	routine status (see TA	ABLE 1)	

STATUS CODE	EXPLANATION OF STATUS
LOCATE_SCF_NOT_FOUND	the requested filename, scf_version combination has no memory allocated for
	processing (user did not call scf_open for this combination)
SCF_BIN_BAD_SWP_FMT	invalid value specified for the swp_fmt argument
SCF_BIN_BAD_FMT	VARIABLE_SPACING can only be requested in conjunction with
	FIXED_SWEEP processing
SCF_BIN_BAD_OVAR_NUM	invalid value specified for the output_var argument
SCF_BIN_MALLOC	no memory for data binning information
SCF_BIN_BAD_CNUM	invalid value specified for the center_var argument
SCF_BIN_BAD_BNUM	invalid value specified for the band_var argument
SCF_BIN_BAD_VFMT	bad format character specified in var_fmt argument

TABLE 1. Status Codes Returned for SCF_BIN_INFO

STATUS CODE	EXPLANATION OF STATUS
SCF_BIN_CLENGTH	the length of the center_var output variable does not equal the number of bins
	defined
SCF_BIN_BLENGTH	the length of the band_var output variable does not equal the number of bins
	defined
ALL_OKAY	routine terminated successfully

DESCRIPTION

Scf_bin_info defines the size and the spacing of the data buffers that will be filled by the scf_time_average or scf_sample_average routine. The SCF file of interest is referenced through the parameter filename. The filename parameter includes the full pathname extension of the SCF file being referenced and must be less than 512 characters in length. Scf_bin_info must be called once for each output variable that is to be returned by the scf_time_average or scf_sample_average routine. This is necessary since the output variables returned by an SCF do not have to be homogeneous; that is, the data can be a mixture of scalar and multi-dimensional data. The first call to the scf_bin_info module for the output variable specified will be used to generate the binning information. All subsequent calls with the identical filename, scf_version and output_var parameters will be ignored. This module must be called prior to calling the scf_time_average / scf_sample_average routine.

The parameter **scf_version** allows multiple file openings for the same SCF file. If the SCF file needs to be opened just once for processing, the same SCF version number should be passed to all SCF routines. However, for multiple file openings, the SCF version number should be unique and all file manipulations performed by the SCF routines will use the file descriptors defined for the SCF version number specified. The user should call the **scf_version_number** routine to retrieve a unique SCF version number instead of choosing this value themselves. The retrieval of multiple output values from a single SCF source does not constitute the need for multiple SCF version numbers; a single SCF version number will suffice.

There are two formats that can be used to bin the data, FIXED_SWEEP and VARIABLE_SWEEP. With a FIXED_SWEEP format, the bins are set up according to the definition of the output variable (**output_var**) in the named SCF file. The number of bins used is equal to the number of values returned for the output variable; therefore, the value for the **num_bins** parameter is ignored. The data is always stored into the bins element by element, starting with element zero and terminating with the last element returned. When specifying a FIXED_SWEEP format, the values for the parameters **start**, **stop** and **input_fmt** are ignored. If the output variable specified is a scalar quantity or a variable with a dimension greater than or equal to 2-D, the **scf_bin_info** module will default to the FIXED_SWEEP format with linear spaced bins with no output variable specified for the **center_var** parameter, regardless of the setting of the parameters. The variable width spacing option (VARIABLE_SPACING) for the **swp_fmt** parameter is applicable only for the FIXED_SWEEP format. If the user tries to specify this option for the VARIABLE_SWEEP format, an error code is returned.

If the user selects a VARIABLE_SWEEP format, the user must specify the number of bins to create (**num_bins**), the center value associated with the first bin (**start**), the center value associated with the last bin (**stop**), the spacing of the bins (**swp_fmt**) and the scheme to use for storing the data (**input_fmt**). The data from an IDFS 1-D vector data set are taken as a function of a variable M. If the 1-D vector data is being returned as an output variable, the dependent variable M must also be returned. This output variable must be specified in the **center_var** parameter. If M is allowed to vary over the individual measurement period or if M actually represents a band width, then each element in the vector can be considered to have been accumulated with the interval M - $\delta 1$ to M + $\delta 2$. Vector data is binned by M. If the center variable M is located between the upper and lower edge values of a given bin, the data value is placed only in this bin. If the user selects the BAND STORAGE scheme, the data is placed in all bins which are fully or partially contained within the range M - $\delta 1$ to M + $\delta 2$. The data is multiplied by the percentage of the bin covered by the range before the data is placed into the bin.

The center and band width values for the bins are calculated once. The calculations are made after the first iteration of the SCF algorithm since data for output variables specified in the **center_var**, **band_var**, and **upper_band_var** parameters may be utilized. The algorithm used to create the center values is based in part upon the format selected (**swp_type**). If the VARIABLE_SWEEP format is selected, the center values are calculated using the **start**, **stop** and **num_bins** values. The difference between the **start** and **stop** value is computed and then divided by the number of bins requested. This value is added to the **start** value to calculate the next center value, with this process continuing until all centers have been calculated. The parameter **swp_fmt** specifies whether the centers are to be linearly or logarithmically spaced. The values for the **center_var**, **band_var**, and **upper_band_var** parameters are ignored.

If the FIXED_SWEEP format is selected, the center values will be computed in one of three ways. If variable width spacing (VARIABLE_SPACING) was selected for the **swp_fmt** parameter, the data returned by the output variable specified in the **center_var** parameter are used as the center values for the bins. If the **swp_fmt** parameter is set to LIN_SPACING or LOG_SPACING and if the **center_var** parameter specifies an output variable, the first and last data value for the output variable are used as the **start** and **stop** values and the computation is the same as described above for VARIABLE_SWEEP. If no output variable is specified for the **center_var** parameter (value set to -1), the center values are created, with values from zero to the number of bins requested minus one.

The algorithm used to compute the band width values for the bins is dependent upon the **swp_fmt** parameter. Linear spacing defines a scheme where the lower (upper) edge of the band is determined by subtracting (adding) one-half of the difference between two successive center values from (to) the center value. The same algorithm is used for log spacing, with the log of the center values being utilized. Variable width spacing defines a scheme where the data returned by the output variable specified in the **band_var** parameter are used as correction values that are to be applied to the center values in order to calculate the band width values. The variable **var_fmt** specifies how the correction values are to be

applied. If the **var_fmt** value is 'L' or 'l', the lower edge of the band is set to the center value and the upper edge of the band is calculated by adding the correction value to the center value. If the **var_fmt** value is 'C' or 'c', the lower edge of the band is calculated by subtracting one-half of the correction value from the center value and the upper edge of the band is calculated by adding one-half of the correction value to the center value. If the var fmt value is 'U' or 'u', the lower edge of the band is calculated by subtracting the correction value from the center value and the upper edge of the band is set to the center value. If the **var fmt** value is 'E' or 'e', the lower edge of the band is set to the center value and the upper edge of the band is set to the correction value; therefore, the correction value is not really a delta value, it is the actual value to be used as the upper edge of the band. If this format is selected, please take note that the center values and the lower edge values will be identical. If the **var fmt** value is 'A' or 'a', there is no need to perform a computation using the center values in order to derive the lower and upper edges of the band. The "actual" values for the centers, lower edges and upper edges of the scan band are returned by the output variables specified in the parameters center_var, band var. and upper_band_var, respectively. The user is referred to the scf_output_center_and_band write-up for more information concerning center and band width values.

ERRORS

All errors within this routine are returned through the status variable. The include file **SCF_codes.h**, which includes all possible return values, should be included so that the mnemonics for the return codes can be referenced. The **SCF_codes.h** file is described in section 3H of the IDFS Programmers Manual.

SEE ALSO

scf_open	3R
scf_version_number	3R
scf_time_average	4R
scf_sample_average	4R
scf_output_center_and_band	4R
user_defs	1H
SCF_codes	3H
libavg SCF	4H

BUGS

None

EXAMPLES

Create the data bins using a FIXED_SWEEP, linear spaced binning scheme for output variable zero defined in the SCF file TMMO_EXAMPLE. The following code segment assumes that the **scf_version_number** module has been called to set the **scf_vnum** parameter.

#include "SCF_codes.h"
#include "user_defs.h"
#include "libavg_SCF.h"

```
SDDAS_USHORT scf_vnum;
SDDAS_LONG dependent_var, output_var;
SDDAS_SHORT status;
output_var = 0;
dependent_var = -1;
status = scf_bin_info (''TMMO_EXAMPLE'', scf_vnum, output_var,
FIXED_SWEEP, 0.0, 0.0, 1, LIN_SPACING, dependent_var,
dependent_var, dependent_var, '\0', POINT_STORAGE);
if (status != ALL_OKAY)
{
printf ("\n Error %d returned by scf_bin_info routine.\n", status);
exit (-1);
}
```

Create sixteen bins, starting at 5ev, stopping at 155ev, with log spacing and the data is to be stored using BAND STORAGE for output variable zero.

#include "SCF_codes.h"
#include "libavg_SCF.h"
#include "user_defs.h"

SDDAS_USHORT scf_vnum; SDDAS_LONG dependent_var, output_var; SDDAS_SHORT status;

Create data bins using a FIXED_SWEEP/variable width spacing binning scheme for output variable zero defined in the SCF file TMMO_EXAMPLE. The center values are returned in output variable two and the band correction values are returned in output variable four.

#include "libavg_SCF.h"
#include "SCF_codes.h"
#include "user_defs.h"

SDDAS_USHORT scf_vnum; SDDAS_SHORT status; SDDAS_LONG center_var, band_var, upper_band_var, output_var;

center_var = 2; band_var = 4; upper_band_var = -1; output_var = 0;

status = scf_bin_info ("TMMO_EXAMPLE", scf_vnum, output_var, FIXED_SWEEP, 0.0, 0.0, 1, VARIABLE_SPACING, center_var, band_var, upper_band_var, 'L', POINT_STORAGE);

```
if (status != ALL_OKAY)
{
    printf ("\n Error %d returned by scf_bin_info routine.\n", status);
    exit (-1);
}
```

scf_bin_info (4R)

SCF_OUTPUT_CENTER_AND_BANDS

function - returns the center and band width values associated with the data bins for the specified output variable

SYNOPSIS

#include "libavg_SCF.h"
#include "SCF_codes.h"

SDDAS_SHORT scf_output_center_and_bands (SDDAS_CHAR *filename, SDDAS_USHORT scf_version, SDDAS_LONG output_var, SDDAS_FLOAT **center_ptr, SDDAS_FLOAT **low_ptr, SDDAS_FLOAT **high_ptr, SDDAS_LONG *num_bands)

ARGUMENTS

filename	-	the name of the SCF file of interest
scf_version	-	SCF identification number which allows for
		multiple openings of the same SCF file
output_var	-	output variable identification number
-		(numbering starts at zero)
center_ptr	-	pointer to the location that holds the center bin
-		values
low_ptr	-	pointer to the location that holds the lower
-		bands for non-contiguous bands or all band
		widths for contiguous bands
high_ptr	-	pointer to the location that holds the upper
		bands for non-contiguous bands
num_bands	-	the number of values returned
scf_output_center_and_bands	-	routine status (see TABLE 1)
-		

TABLE 1. Status Codes Returned for SCF_OUTPUT_CENTER_AND_BANDS

STATUS CODE	EXPLANATION OF STATUS
LOCATE_SCF_NOT_FOUND	the requested filename, scf_version combination has no memory allocated
	for processing (user did not call scf_open for this combination)
SCF_OCENTER_OVAR_NUM	invalid value specified for the output_var argument
SCF_OCENTER_NO_AVG	the data has not been returned for the output variable (user did not call
	<pre>scf_time_average or scf_sample_average)</pre>
SCF_OCENTER_SELECT_MISSING	the output variable was not selected for processing (user did not call
	<pre>scf_output_select for this output variable)</pre>
ALL_OKAY	routine terminated successfully

DESCRIPTION

Scf_output_center_and_bands returns the center and band width values for bins that were created for the output variable **output_var** using the information specified by the call to the **scf_bin_info** routine. These center and band width values are used by the **scf_time_average** / **scf_sample_average** module when storing the data into the data bins for VARIABLE_SWEEP processing (refer to the explanation in the **scf_bin_info** write-up).

This module must be called after a call to the **scf_time_average** / **scf_sample_average** module has been made; otherwise, an error code will be returned. The SCF file of interest is referenced through the parameter **filename**. The **filename** parameter includes the full pathname extension of the SCF file being referenced and must be less than 512 characters in length.

The parameter **scf_version** allows multiple file openings for the same SCF file. If the SCF file needs to be opened just once for processing, the same SCF version number should be passed to all SCF routines. However, for multiple file openings, the SCF version number should be unique and all file manipulations performed by the SCF routines will use the file descriptors defined for the SCF version number specified. The user should call the **scf_version_number** routine to retrieve a unique SCF version number instead of choosing this value themselves. The retrieval of multiple output values from a single SCF source does not constitute the need for multiple SCF version numbers; a single SCF version number will suffice.

The contents of the memory locations returned by this module should **NOT** be altered since the calculated center/band width values are used by the **scf_time_average** / **scf_sample_average** routine when processing the data. If the returned values need to be modified, for example, to take the log of the values, the user should allocate space to hold the values, copy the values into this space and modify the values there.

The module returns two possible pointers for the location(s) that hold the lower and upper band width values. In the case where the bands are non-contiguous, both the **low_ptr** and **high_ptr** will reference memory locations that hold the band width values. In the case where the bands are contiguous, there is no need to hold separate upper and lower values – the upper limit of the current band is the lower limit of the next band. In this case, one extra memory location is allocated, the **high_ptr** pointer is set to nil or 0 and **low_ptr** is set to reference the location that holds the band width values.

ERRORS

All errors within this routine are returned through the status variable. The include file **SCF_codes.h**, which includes all possible return values, should be included so that the mnemonics for the return codes can be referenced. The **SCF_codes.h** file is described in section 3H of the IDFS Programmers Manual.

SEE ALSO

scf_open	3R
scf_version_number	3R
scf_time_average	4 R
scf_sample_average	4 R
scf_bin_info	4 R
<pre>scf_output_select</pre>	4 R
SCF_codes	3H
libavg_SCF	4H

BUGS

None

EXAMPLES

Retrieve the center and band width values for the data bins created for output variable zero which is defined in the SCF file TMMO_EXAMPLE. The following code segment assumes that the **scf_version_number** module has been called to set the **scf_vnum** parameter.

#include "libavg_SCF.h"
#include "SCF_codes.h"

SDDAS_USHORT scf_vnum; register SDDAS_LONG bin; SDDAS_LONG num_bins, output_var; SDDAS_FLOAT *center_bin, *bin_low, *bin_high; SDDAS_SHORT status;

```
output_var = 0;
```

```
if (status != ALL_OKAY)
{
    printf ("\n Error %d from scf_output_center_and_bands routine.\n", status);
    exit (-1);
}
```

/* Bands are contiguous?

if (*bin_high == NULL)
for (bin = 0; bin < num_bins; ++bin)
printf ("\nlow = %f high = %f", *(bin_low + bin), *(bin_low + bin + 1));</pre>

/* Bands are non-contiguous.

*/

*/

else

for (bin = 0; bin < num_bins; ++bin)
printf ("\nlow = %f high = %f", *(bin_low + bin), *(bin_high + bin));</pre>

SCF_OUTPUT_DATA_INDEX

function - returns index values to access the data returned by the scf_time_average / scf_sample_average modules

SYNOPSIS

#include "libavg_SCF.h"
#include "SCF_codes.h"

SDDAS_SHORT scf_output_data_index (SDDAS_CHAR *filename,

SDDAS_USHORT scf_version, SDDAS_LONG output_var, SDDAS_FLOAT min, SDDAS_FLOAT max, SDDAS_LONG dependent_var, SDDAS_LONG *num_select, SDDAS_LONG *output_ind, SDDAS_ULONG *buf_zero_loc)

ARGUMENTS

filename	-	the name of the SCF file of interest
scf_version	-	SCF identification number which allows for multiple openings of the same SCF file
output_var	-	output variable identification number (numbering starts at zero)
min	-	the lower cutoff value for data that are to be put into
		the data buffers
max	-	the upper cutoff value for data that are to be put into
		the data buffers
dependent_var	-	the output variable whose data is to be used for the dependent variable for 1-D vector output (numbering starts at zero); a value of -1 should be used when output_var represents a scalar output variable
num_select	-	the number of data sets returned for the output variable in question
output_ind	-	an index value that is returned in order to access the correct sub-buffer (data set) returned for the output variable in question
buf_zero_loc	-	an index value that is used to get to the beginning of all data returned for the output variable in question
<pre>scf_output_data_index</pre>	-	routine status (see TABLE 1)

TABLE 1. Status Codes Returned for SCF_OUTPUT_DATA_INDEX

STATUS CODE	EXPLANATION OF STATUS		
LOCATE_SCF_NOT_FOUND	the requested filename, scf_version combination has no memory allocated for		
	processing (user did not call scf_open for this combination)		
SCF_OINDEX_OVAR_NUM	invalid value specified for the output_var argument		
SCF_OINDEX_NO_AVG	the data has not been returned for the output variable (user did not call		
	<pre>scf_time_average or scf_sample_average)</pre>		
SCF_OINDEX_NO_OUTPUT	the output variable was not selected for processing (user did not call		
	<pre>scf_output_select for this output variable</pre>		

STATUS CODE	EXPLANATION OF STATUS
SCF_OINDEX_NO_MATCH	the data cutoff/dependent_var combination requested was not found amongst the
	defined combinations for this output variable
ALL_OKAY	routine terminated successfully

DESCRIPTION

Scf_output_data_index returns index values that are used to access the data buffers returned by the **scf_time_average / scf_sample_average** routines. The SCF file of interest is referenced through the parameter **filename**. The **filename** parameter includes the full pathname extension of the SCF file being referenced and must be less than 512 characters in length.

The **scf_time_average** and **scf_sample_average** routines return a single pointer to the data array which holds the data for all output variables that were processed. For each output variable specified through the **scf_output_select** module, the **scf_time_average** routine returns NUM_BUFFERS working buffers, with N many sub-buffers, where N reflects the number of data cutoff/dependent_var combinations defined for the selected output variable. The **scf_sample_average** routine returns one working buffer, with N many sub-buffers for the selected output variable. In both scenarios, the value for N may vary from output variable to output variable. The index values returned by this module are used to access the data for a specific output variable, with specific data cutoff/dependent_var values.

The parameter **scf_version** allows multiple file openings for the same SCF file. If the SCF file needs to be opened just once for processing, the same SCF version number should be passed to all SCF routines. However, for multiple file openings, the SCF version number should be unique and all file manipulations performed by the SCF routines will use the file descriptors defined for the SCF version number specified. The user should call the **scf_version_number** routine to retrieve a unique SCF version number instead of choosing this value themselves. The retrieval of multiple output values from a single SCF source does not constitute the need for multiple SCF version numbers; a single SCF version number will suffice.

The user may elect to call the **scf_output_data_index** routine every time a return from the **scf_time_average** / **scf_sample_average** routine is made or may call the **scf_output_data_index** routine once for each output variable, data cutoff/dependent_var combination requested and save the index values for later usage. In either case, the call to the **scf_output_data_index** routine must be made **after** a call to the **scf_time_average** / **scf_sample_average** routine has been made; otherwise, an error code is returned.

ERRORS

All errors within this routine are returned through the status variable. The include file **SCF_codes.h**, which includes all possible return values, should be included so that the mnemonics for the return codes can be referenced. The **SCF_codes.h** file is described in section 3H of the IDFS Programmers Manual.

SEE ALSO

scf_open	3R
scf_version_number	3R
scf_time_average	4R
scf_sample_average	4R
scf_output_select	4R
SCF_codes	3H
libavg_SCF	4H

BUGS

None

EXAMPLES

Retrieve the index values to access data that is returned for scalar output variable zero which is defined in the SCF file TMMO_EXAMPLE. The data which uses a data cutoff range of 10.0 to 25.0 is to be accessed. The following code segment assumes that **scf_version_number** module has been called to set the **scf_vnum** parameter.

#include "SCF_codes.h"
#include "libavg_SCF.h"

SDDAS_USHORT scf_vnum; SDDAS_ULONG buf_zero_loc; SDDAS_FLOAT data_min, data_max; SDDAS_LONG output_var, dependent_var, num_select, output_ind; SDDAS_SHORT status;

data_min = 10.0; data_max = 25.0; output_var = 0; dependent_var = -1;

if (status != ALL_OKAY)
{
 printf ("\n Error %d returned by scf_output_data_index routine.\n", status);
 exit (-1);
}

SCF_OUTPUT_SELECT

function - specifies which output variable(s) are to be returned by the SCF time / sample average routines

SYNOPSIS

#include "libavg_SCF.h"
#include "SCF_codes.h"

SDDAS_SHORT scf_output_select (SDDAS_CHAR *filename,

SDDAS_USHORT scf_version, SDDAS_LONG output_var, SDDAS_FLOAT min, SDDAS_FLOAT max, SDDAS_LONG dependent_var)

ARGUMENTS

filename	-	the name of the SCF file of interest
scf_version	-	SCF identification number which allows for multiple openings of the same SCF file
output_var	-	output variable identification number (numbering starts at zero)
min	-	the lower cutoff value for data that are to be put into the data buffers
max	-	the upper cutoff value for data that are to be put into the data buffers
dependent_var	-	the output variable whose data is to be used for the dependent variable for 1-D vector output (numbering starts at zero); a value of -1 should be used when output_var represents a scalar output variable
scf_output_select	-	routine status (see TABLE 1)

TABLE 1. Status Codes Returned for SCF_OUTPUT_SELECT

STATUS CODE	EXPLANATION OF STATUS
LOCATE_SCF_NOT_FOUND	the requested filename, scf_version combination has no memory allocated for
	processing (user did not call scf_open for this combination)
SCF_SELECT_OVAR_NUM	invalid value specified for the output_var argument
SCF_SELECT_BIN_MISSING	the data binning information has not been allocated (user did not call
	scf_bin_info for this combination
SCF_SELECT_MALLOC	no memory for structures which hold output variable selection
SCF_SELECT_DEF_MALLOC	no memory for min/max/dependent_var values for the output variable being
	processed
SCF_SELECT_DEF_REALLOC	no memory for expansion of the min/max/dependent_var values for the output
	variable being processed
SCF_SELECT_DVAR_NUM	invalid value specified for the dependent_var argument
SCF_SELECT_DVAR_LENGTH	the length of the dependent_var output variable is not the same as the length
	of the output_var output variable
SCF_SELECT_BAND_MALLOC	no memory for the band width values created from data for the dependent_var
	output variable
ALL_OKAY	routine terminated successfully

DESCRIPTION

Scf_output_select specifies which output variable(s) are to be returned by the **scf_time_average** / **scf_sample_average** routines. The SCF file of interest is referenced through the parameter **filename**. The **filename** parameter includes the full pathname extension of the SCF file being referenced and must be less than 512 characters in length. **Scf_output_select** must be called at least once for each output variable that is to be time or sample averaged and must be called before the **scf_time_average** or **scf_sample_average** routine can be called. In addition, the routine **scf_bin_info** must be called for the same output variable as that specified in **output_var** before this module can be called; otherwise, an error code is returned by the **scf_output_select** routine.

The parameter **scf_version** allows multiple file openings for the same SCF file. If the SCF file needs to be opened just once for processing, the same SCF version number should be passed to all SCF routines. However, for multiple file openings, the SCF version number should be unique and all file manipulations performed by the SCF routines will use the file descriptors defined for the SCF version number specified. The user should call the **scf_version_number** routine to retrieve a unique SCF version number instead of choosing this value themselves. The retrieval of multiple output values from a single SCF source does not constitute the need for multiple SCF version numbers; a single SCF version number will suffice.

The output variable **dependent_var** is utilized when the data bins are processed using a VARIABLE_SWEEP format. When using the VARIABLE_SWEEP format, the data for the output variable **output_var** is assumed to be taken as a function of a variable M, which is termed the dependent variable. The dependent variable M must also be returned as an output variable by the SCF. This output variable must be specified in the **dependent_var** parameter. The variable **output_var** may be associated with multiple dependent variables; that is, the same data can be associated with many dependent parameters as long as those dependent parameters are being returned as output variables in the SCF. When this is the case, multiple calls to the **scf_output_select** routine must be made, using the same **output_var** value with different **dependent_var** values. The user is referred to the **scf_bin_info** write-up for more information concerning data bins and storage.

ERRORS

All errors within this routine are returned through the status variable. The include file **SCF_codes.h**, which includes all possible return values, should be included so that the mnemonics for the return codes can be referenced. The **SCF_codes.h** file is described in section 3H of the IDFS Programmers Manual.

SEE ALSO

scf_open	3R
scf_version_number	3R
scf_bin_info	4R
scf_time_average	4R
scf_sample_average	4R
SCF_codes	3H

libavg_SCF

4H

BUGS

None

EXAMPLES

Specify cutoff values for output variables zero and one, which are defined in the SCF file TMMO_EXAMPLE. Output variable zero is scalar and output variable one is a 1-D vector, with the data for the dependent variable being returned in output variable two. The following code segment assumes that **scf_version_number** module has been called to set the **scf_vnum** parameter.

#include "libavg_SCF.h"
#include "user_defs.h"
#include "SCF_codes.h"

SDDAS_USHORT scf_vnum; SDDAS_LONG output_var, dependent_var; SDDAS_FLOAT data_min, data_max; SDDAS_SHORT status;

```
{
    form scf_output_select routine.\n", status);
    exit (-1);
}
```

output_var = 1; dependent_var = 2; data_min = VALID_MIN; data_max = VALID_MAX;

ret_val = scf_output_select (''TMMO_EXAMPLE'', scf_vnum, output_var, data_min, data_max, dependent_var);

```
if (status != ALL_OKAY)
{
    printf ("\n Error %d from scf_output_select routine.\n", status);
    exit (-1);
}
```

SCF_SAMPLE_AVERAGE

function - returns sample-averaged data buffers for selected SCF output variables

SYNOPSIS

#include "libavg_SCF.h"
#include "SCF_codes.h"

SDDAS_SHORT scf_sample_average (SDDAS_CHAR *filename,
SDDAS USHORT scf version, void *scf data ptr.

SDDAS_USHORT scf_version, void *scf_data_ptr,
SDDAS_LONG num_iterations, SDDAS_FLOAT **ret_data,
SDDAS_FLOAT **ret_frac, SDDAS_CHAR **bin_stat,
SDDAS_SHORT *stime_yr, SDDAS_SHORT *stime_day,
SDDAS_LONG *stime_sec, SDDAS_LONG *stime_nano,
SDDAS_SHORT *etime_yr, SDDAS_SHORT *etime_day,
SDDAS_LONG *etime_sec, SDDAS_LONG *etime_nano,
SDDAS_LONG *num_output, SDDAS_LONG **output_var,
SDDAS_LONG **output_size)

ARGUMENTS

filename	-	the name of the SCF file of interest
scf_version	-	SCF identification number which allows for multiple openings of the same SCF file
scf_data_ptr	-	pointer to the scf_data structure that temporarily holds the data for all output variables that are returned by the SCF algorithm
num_iterations	-	the number of samples (iterations of the SCF algorithm) to average together
ret_data	-	pointer to the data being returned (data for output variables that are processed)
ret_frac	-	pointer to the normalization factors for the data being returned
bin_stat	-	pointer to status flags which are associated with each data bin returned 0 - no data has been placed into the data bin being processed 1 - data has been placed into the data bin being processed
stime_yr	-	the year value for the first iteration of the SCF algorithm
stime_day	-	the day of year value for the first iteration of the SCF algorithm
stime_sec	-	the time of day in seconds for the first iteration of the SCF algorithm
stime_nano	-	the time of day residual in nanoseconds for the first iteration of the SCF algorithm

etime_yr	-	the year value for the last iteration of the SCF algorithm
etime_day	-	the day of year value for the last iteration of the SCF algorithm
etime_sec	-	the time of day in seconds for the last iteration of the SCF algorithm
etime_nano	-	the time of day residual in nanoseconds for the last iteration of the SCF algorithm
num_output	-	the number of output variables processed (number of elements in the output_var and output_size arrays)
output_var	-	an array which holds the output variable number(s) for which data is returned (numbering starts with zero)
output_size	-	an array which holds the number of data values returned in a data buffer for each output variable that is processed
scf_sample_average	-	routine status (see TABLE 1)

TABLE 1. Status Codes Returned for SCF_SAMPLE_AVERAGE

STATUS CODE	EXPLANATION OF STATUS
LOCATE_SCF_NOT_FOUND	the requested filename, scf_version combination has no memory allocated for
	processing (user did not call scf_open for this combination)
SCF_SAVG_BIN_MISSING	the data binning information has not been allocated (user did not call
	scf_bin_info for this combination)
SCF_SAVG_SELECT_MISSING	no output variables have been selected for processing (user did not call
	scf_output_select for any output variable)
SCF_SAMPLE_WITH_TIME	the modules scf_sample_average and scf_time_average cannot be used
	interchangeably for the same filename, scf_version combination
SCF_AVG_STR_MALLOC	no memory for structure which hold information pertinent to the sample-
	averaged data
SCF_SINFO_MALLOC	no memory for data buffer information
SCF_SDATA_MALLOC	no memory for data buffers
SCF_CENTER_MALLOC	no memory for center bin values
SCF_BAND_MALLOC	no memory for bin band width values
SCF_TERMINATE	processing must stop due to data not being on-line
SCF_NO_CENTER_VALUES	no values are available to compute the center bin values for the specified center
	variable
SCF_BAD_START_STOP	the start / stop scan value is outside of the valid data range for the parameter
	specified as the scan parameter
	Error codes returned by scf_output_data ()
ALL_OKAY	routine terminated successfully

DESCRIPTION

Scf_sample_average is the SCF sample-averaged data read routine, averaging iterations of the SCF algorithm for all selected output variables. The SCF file of interest is referenced through the parameter **filename**. The **filename** parameter includes the full pathname extension of the SCF file being referenced and must be less than 512 characters in length. The data that is returned is dictated by the output variables that are selected using the **scf_output_select** routine. If no output variables were selected for the SCF

filename/version combination, an error code is returned; otherwise, the number of output variables processed is returned in the **num_output** parameter, along with the output variable number(s) and the number of elements in the data buffers.

The parameter **scf_version** allows multiple file openings for the same SCF file. If the SCF file needs to be opened just once for processing, the same SCF version number should be passed to all SCF routines. However, for multiple file openings, the SCF version number should be unique and all file manipulations performed by the SCF routines will use the file descriptors defined for the SCF version number specified. The user should call the **scf_version_number** routine to retrieve a unique SCF version number instead of choosing this value themselves. The retrieval of multiple output values from a single SCF source does not constitute the need for multiple SCF version numbers; a single SCF version number will suffice.

The parameter **scf_data_ptr** is a pointer to the structure that is to hold all data pertinent to the SCF file being processed. The structure is created and the address to this structure is returned when a call to the **create_scf_data_structure** routine is made. The contents of this structure is described in section 3S of the IDFS Programmers Manual. Since the SCF file dictates the number of output variables and the dimensionality of these variables, the user should call the **create_scf_data_structure** routine once for each distinct SCF file being processed and this pointer should be passed in conjunction with the named SCF file when the output variable values are being retrieved.

The data is processed one iteration at a time. Once the requested number of iterations have been processed, the routine will return the data. If the requested number of iterations could not be processed due to data acquisition problems, the routine will return the data and the normalization factors will reflect the number of iterations processed so far. If more data is put online, the next call to the **scf_sample_average** routine will continue to accumulate data and will continue until the remaining iterations have been acquired.

There are N many sub-buffers, where N reflects the number of data cutoff/dependent_var combinations defined for the selected output variable. The value for N may vary from output variable to output variable. The user must process the data contained within these buffers before the next call to the **scf_sample_average** routine is made since the module will clear out these buffers for re-use if the requested number of iterations were processed on the previous call. The data values must be normalized using the normalization factors returned along with the data. The user is advised to check the value or values in the **bin_stat** array. If all values are 0, no data was placed into the buffer. This can happen if the data is excluded based upon data cutoff values.

The size and spacing of the data buffers are either defined by the user or by elements contained within the SCF file. The user must call the **scf_bin_info** module for each output variable that is to be returned before calling the **scf_sample_average** routine in order to specify how the binning of the data is to occur. If the **scf_sample_average** routine determines that no binning scheme has been selected, an error code is returned to the user.

ERRORS

All errors within this routine are returned through the status variable. The include file **SCF_codes.h**, which includes all possible return values, should be included so that the mnemonics for the return codes can be referenced. The **SCF_codes.h** file is described in section 3H of the IDFS Programmers Manual.

SEE ALSO

scf_open	3R
scf_output_data	3R
create_scf_data_structure	3R
scf_version_number	3R
scf_time_average	4R
scf_output_select	4R
scf_bin_info	4R
SCF_codes	3H
libavg_SCF	4H

BUGS

None

EXAMPLES

Obtain data one iteration at a time for output variables selected from the SCF file TMMO_EXAMPLE. This code segment assumes all necessary subroutine calls have been made.

#include "libavg_SCF.h"
#include "SCF_codes.h"

SDDAS_USHORT scf_vnum; SDDAS_FLOAT *ret_data, *ret_frac; SDDAS_LONG stime_sec, stime_nano, end_time_sec, end_time_nano; SDDAS_LONG *output_numbers, num_output, *output_size; SDDAS_SHORT stime_yr, stime_day, end_time_yr, end_time_day, status; SDDAS_CHAR *ret_bin; void *scf_data_ptr;

```
{
    printf ("\n Error %d returned by scf_sample_average routine.\n", status);
    exit (-1);
}
```

SCF_TIME_AVERAGE

function - returns time-averaged data buffers for selected SCF output variables

SYNOPSIS

#include "libavg_SCF.h"
#include "SCF_codes.h"
#include "user_defs.h"

SDDAS_SHORT scf_time_	average (SDDAS	CHAR *filename.
	$a, e_{1}a_{5}e_{1}b_{1}b_{5}$	_erm me intentatio,

_average (SDDAS_CHAR mename,	
SDDAS_USHORT scf_version, void *scf_data_ptr,	
SDDAS_FLOAT **ret_data, SDDAS_FLOAT **ret_frac,	
SDDAS_CHAR **bin_stat, SDDAS_LONG **bpix,	
SDDAS_LONG **epix, SDDAS_CHAR **ret_stat,	
SDDAS_SHORT *stime_yr, SDDAS_SHORT *stime_day,	
SDDAS_LONG *stime_sec, SDDAS_LONG *stime_nano,	
SDDAS_SHORT *etime_yr, SDDAS_SHORT *etime_day,	
SDDAS_LONG *etime_sec, SDDAS_LONG *etime_nano,	
SDDAS_LONG *num_output, SDDAS_LONG **output_var,	
SDDAS_LONG **output_size)	
=	

ARGUMENTS

filename	-	the name of the SCF file of interest
scf_version	-	SCF identification number which allows for multiple
		openings of the same SCF file
scf_data_ptr	-	pointer to the scf_data structure that temporarily holds the
		data for all output variables that are returned by the SCF algorithm
ret_data	-	pointer to the data being returned (data for output variables
		that are processed)
ret_frac	-	pointer to the normalization factors for the data being returned
bin_stat	-	pointer to status flags which are associated with each data bin
		returned
		0 - no data has been placed into the data bin being processed
		1 - data has been placed into the data bin being
		processed
bpix	-	pointer to the starting pixel location for the data buffers
•		returned
epix	-	pointer to the ending pixel location for the data buffers
· r		returned
ret_stat	-	pointer to the status of each of the data buffers being returned
		UNTOUCHED_BUFFER - no data has ever been
		placed into the buffer
		FREE_BUFFER - no data has been placed
		into the buffer being
		processed (ready for re-

		PARTIAL_WORKING - use) data is being acquired into the buffer but is not ready for processing
		BUFFER_READY - data has been acquired into the buffer and is ready for processing
stime_yr	-	the year value for the first iteration of the SCF algorithm
stime_day	-	the day of year value for the first iteration of the SCF
_ ,		algorithm
stime_sec	-	the time of day in seconds for the first iteration of the SCF
_		algorithm
stime_nano	-	the time of day residual in nanoseconds for the first iteration
_		of the SCF algorithm
etime_yr	-	the year value for the last iteration of the SCF algorithm
etime_day	-	the day of year value for the last iteration of the SCF
•		algorithm
etime_sec	-	the time of day in seconds for the last iteration of the SCF
		algorithm
etime_nano	-	the time of day residual in nanoseconds for the last iteration
		of the SCF algorithm
num_output	-	the number of output variables processed (the number of
		elements in the output_var and output_size arrays)
output_var	-	an array which holds the output variable number(s) for which
		data is returned (numbering starts with zero)
output_size	-	an array which holds the number of data values returned in a
		data buffer for each output variable that is processed
scf_time_average	-	routine status (see TABLE 1)

TABLE 1. Status Codes Returned for SCF_TIME_AVERAGE

STATUS CODE	EXPLANATION OF STATUS
LOCATE_SCF_NOT_FOUND	the requested filename, scf_version combination has not memory allocated for
	processing (user did not call scf_open for this combination)
SCF_TAVG_NO_BASE_TIME	the time interval information has not been set (user did not call
	scf_time_reference for this combination)
SCF_TAVG_BIN_MISSING	the data binning information has not been allocated (user did not call
	scf_bin_info for this combination)
SCF_TAVG_SELECT_MISSING	no output variable have been selected for processing (user did not call
	<pre>scf_output_select for any output variable)</pre>
SCF_TIME_WITH_SAMPLE	the modules scf_time_average and scf_sample_average cannot be used
	interchangeably for the same filename, scf_version combination
SCF_NO_EMPTY_BUFFERS	no spare buffers for data accumulation
SCF_AVG_STR_MALLOC	no memory for structure which hold information pertinent to the time averaged
	data
SCF_TINFO_MALLOC	no memory for data buffer information
SCF_TDATA_MALLOC	no memory for data buffers
SCF_CENTER_MALLOC	no memory for center bin values

STATUS CODE	EXPLANATION OF STATUS
SCF_BAND_MALLOC	no memory for bin band width values
SCF_TERMINATE	processing must stop due to data not being on-line
SCF_NO_CENTER_VALUES	no values are available to compute the center bin values for the specified center variable
SCF_BAD_START_STOP	the start / stop scan value is outside of the valid data range for the parameter specified as the scan parameter
	Error codes returned by scf_output_data ()
ALL_OKAY	routine terminated successfully

DESCRIPTION

Scf_time_average is the SCF time-averaged data read routine, retrieving data for all selected output variables for the time duration being processed. The SCF file of interest is referenced through the parameter **filename**. The **filename** parameter includes the full pathname extension of the SCF file being referenced and must be less than 512 characters in length. The data that is returned is dictated by the output variables that are selected using the **scf_output_select** routine. If no output variables were selected for the SCF filename/version combination, an error code is returned; otherwise, the number of output variables processed is returned in the **num_output** parameter, along with the output variable number(s) and the number of elements in the data buffers.

The parameter **scf_version** allows multiple file openings for the same SCF file. If the SCF file needs to be opened just once for processing, the same SCF version number should be passed to all SCF routines. However, for multiple file openings, the SCF version number should be unique and all file manipulations performed by the SCF routines will use the file descriptors defined for the SCF version number specified. The user should call the **scf_version_number** routine to retrieve a unique SCF version number instead of choosing this value themselves. The retrieval of multiple output values from a single SCF source does not constitute the need for multiple SCF version numbers; a single SCF version number will suffice.

The parameter **scf_data_ptr** is a pointer to the structure that is to hold all data pertinent to the SCF file being processed. The structure is created and the address to this structure is returned when a call to the **create_scf_data_structure** routine is made. The contents of this structure is described in section 3S of the IDFS Programmers Manual. Since the SCF file dictates the number of output variables and the dimensionality of these variables, the user should call the **create_scf_data_structure** routine once for each distinct SCF file being processed and this pointer should be passed in conjunction with the named SCF file when the output variable values are being retrieved.

This routine will process sequential iterations of the SCF algorithm, placing the data into buffers which hold data that is accumulated over a specified time interval. In doing so, multiple data samples may be averaged together in a single buffer. Once the time interval has been processed, the routine will return the data buffers and a status value for each buffer which indicates when the buffer is ready for the user to retrieve. The user **must** call the module **scf_time_reference** before the **scf_time_average** module can be called since the **scf_time_reference** module is used to specify the base time value and reference location

and the time interval (delta) to use to accumulate the data. If the **scf_time_average** routine determines that the **scf_time_reference** routine has not been called, an error code is returned.

Along with the data being returned, there is a starting location and an ending location that is returned for each of the data buffers. The user may use these values as references to the base location specified in the call to the **scf_time_reference** routine. That is, given a base time value, a time interval and a reference location, the **scf_time_average** routine will return the location of SCF data with respect to time. The user may chose to ignore these values or may use these locations to plot data along an axis that is scaled with respect to time.

There are a constant number of data buffers that are used by the scf_time_average module. This number is defined as NUM BUFFERS in the user defs.h file. This file is described in section 1H of the IDFS Programmers Manual. These data buffers are utilized in a cyclic nature, with buffer 0 being re-used once buffer NUM_BUFFERS-1 has been filled. The data buffers that are ready to be processed are flagged with the status value BUFFER READY. For each buffer, there are N many sub-buffers, where N reflects the number of data cutoff/dependent_var combinations defined for the selected output variable. The value for N may vary from output variable to output variable. The user must process the data contained within these buffers before the next call to the scf time average routine is made since the module will clear out these buffers for re-use. The data values must be normalized using the normalization factors returned along with the data. Since the buffers are cyclic, the user may wish to keep a variable indicating the last buffer number processed so that the user can start at the time sample left off from the previous call to the scf_time_average routine at the next call. It is important to note that there is one status flag per data buffer that is used by all output variables. If no data was placed into the buffer due to the data being out of the specified range, the result will be that a buffer is flagged as BUFFER_READY but will not contain any data. The user is advised to check the value or values in the **bin stat** array. If all values are 0, no data was placed into the buffer.

The size and spacing of the data buffers are either defined by the user or by elements contained within the SCF file. The user must call the **scf_bin_info** module for each output variable that is to be returned before calling the **scf_time_average** routine in order to specify how the binning of the data is to occur. If the **scf_time_average** routine determines that no binning scheme has been selected, an error code is returned to the user.

ERRORS

All errors within this routine are returned through the status variable. The include file **SCF_codes.h**, which includes all possible return values, should be included so that the mnemonics for the return codes can be referenced. The **SCF_codes.h** file is described in section 3H of the IDFS Programmers Manual.

SEE ALSO

scf_open	3R
scf_version_number	3R

scf_output_data	3R
create_scf_data_structure	3R
scf_sample_average	4R
scf_time_reference	4R
scf_output_select	4R
scf_bin_info	4R
user_defs	1H
SCF_codes	3H
libavg_SCF	4H

EXAMPLES

Obtain time-averaged data for output variables selected from the SCF file TMMO_EXAMPLE. This code segment assumes all necessary subroutine calls have been made.

#include "libavg_SCF.h"
#include "SCF_codes.h"

SDDAS_USHORT scf_vnum; SDDAS_FLOAT *ret_data, *ret_frac; SDDAS_LONG stime_sec, stime_nano, end_time_sec, end_time_nano; SDDAS_LONG *output_numbers, num_output, *output_size, *bpix, *epix; SDDAS_SHORT stime_yr, stime_day, end_time_yr, end_time_day, status; SDDAS_CHAR *ret_bin, *buf_stat; void *scf_data_ptr;

```
status = scf_time_average ("TMMO_EXAMPLE", scf_vnum, scf_data_ptr,
&ret_data, &ret_frac, &ret_bin, &bpix, &epix, &buf_stat,
&stime_yr, &stime_day, &stime_sec, &stime_nano,
&end_time_yr, &end_time_day, &end_time_sec,
&end_time_nano, &num_output, &output_numbers,
&output_size);
if (status != ALL_OKAY)
{
    printf ("\n Error %d returned by scf_time_average routine \n"_status);
```

printf ("\n Error %d returned by scf_time_average routine.\n", status);
exit (-1);
}

SCF_TIME_REFERENCE

function - sets the base reference time, reference location and time duration to be utilized by the **scf_time_average** module

SYNOPSIS

#include "libavg_SCF.h"

void scf_time_reference (SDDAS_USHORT scf_version, SDDAS_SHORT base_year,
SDDAS_SHORT base_day, SDDAS_LONG base_sec,
SDDAS_LONG base_nano, SDDAS_LONG base_pix,
SDDAS_LONG res_sec, SDDAS_LONG res_nano)

ARGUMENTS

scf_version	-	SCF identification number which allows for multiple openings of the same SCF file
base_year	-	the year time component for the base reference time
base_day	-	the day of year time component for the base reference time
base_sec	-	the time of day in seconds for the base reference time
base_nano	-	the time of day residual in nanoseconds for the base reference time
base_pix	-	the reference point or location associated with the base reference time
res_sec	-	the time duration (delta-t) in seconds
res_nano	-	the time duration residual in nanoseconds

DESCRIPTION

Scf_time_reference sets the base reference time, the reference location and the time duration values to be used by the **scf_time_average** routine. This routine should be called once, after all calls to the **scf_open** routine have been made. If the base reference time or the time duration is not known, the user can make a call to the **scf_algorithm_start** module in order to retrieve the start time and the accumulation period (delta-t) for the first iteration of the SCF algorithm.

The parameter **scf_version** allows multiple file openings for the same SCF file. If the SCF file needs to be opened just once for processing, the same SCF version number should be passed to all SCF routines. However, for multiple file openings, the SCF version number should be unique and all file manipulations performed by the SCF routines will use the file descriptors defined for the SCF version number specified. The user should call the **scf_version_number** routine to retrieve a unique SCF version number instead of choosing this value themselves. The retrieval of multiple output values from a single SCF source does not constitute the need for multiple SCF version numbers; a single SCF version number will suffice.

ERRORS

This routine returns no status or error codes.

SEE ALSO

4R
4R
3R
3R
4H

BUGS

None

EXAMPLES

The base reference time to be utilized is 1992, day 23, time 00:25:36 which is equal to 1536 seconds. The resolution to be utilized is 1.500 seconds and the reference location is at zero. Assume that the variable **scf_vnum** has been set by a previous call to the **scf_version_number** routine.

scf_time_reference (scf_vnum, 1992, 23, 1536, 0, 0, 1, 50000000);

LIBBASE_IDFS.H

function - contains prototypes for the basic set of IDFS data retrieval routines

SYNOPSIS

#include "libbase_idfs.h"

DESCRIPTION

The **libbase_idfs.h** include file contains the ANSI C prototypes for the basic set of IDFS data retrieval routines that return data one sample set or one spin at a time. These routines can be found in the **1R** section of the IDFS Programmers Manual. This file should be included in the source code wherever an IDFS routine is called from to ensure that the correct number of arguments are used and to ensure that the argument types match.

SEE ALSO

libtrec_idfs

2H

RET_CODES.H

function - defines possible return values and associated mnemonics for the IDFS software

SYNOPSIS

#include "ret_codes.h"

DESCRIPTION

The **ret_codes.h** include file holds all of the defined return values for the IDFS routines. All return values are associated with a mnemonic through a **define** statement. The user of the IDFS routines should include this file and use the mnemonics defined for the return values so that if these return values are changed in the future to some other value, code does not have to be modified.

CONTENTS OF FILE

S OF FILE	
#define ALL_OKAY	1
#define EOF_STATUS	0
#define LOS_STATUS	9
#define NEXT_FILE_STATUS	12
#define READ_SPIN_TERMINATE	15
#define READ_SPIN_DATA_GAP	18
#define CENTER_CONVERSION	4
#define DREC_NO_SENSOR	2
#define DREC_EOF_NO_SENSOR	3
#define DREC_EOF_SENSOR	6
#define TENSOR_NO_SENSOR	2
#define TENSOR_EOF_NO_SENSOR	3
#define TENSOR_EOF_SENSOR	6
#define RESET_CSET_MALLOC	-1
#define BUF_BIN_MALLOC	-2
#define LOCATE_NOT_FOUND	-3
#define LOCATE_PTR_MALLOC	-4
#define LOCATE_EX_REALLOC	-5
#define CP_BAD_FRAC	-6
#define CP_BAD_TIMES	-7
#define OPEN_PTR_MALLOC	-8
#define OPEN_EX_REALLOC	-9
#define RTIME_NO_HEADER	-10
#define RTIME_NO_DATA	-11
#define CUR_TIME_NOT_FOUND	-12
#define ALL_FLAG_MALLOC	-13
#define ALLOC_HDR_READ_ERROR	-14
#define ALLOC_HDR_MALLOC	-15
#define ALLOC_HDR_REALLOC	-16
#define CAL_DATA_MALLOC	-17
#define PARTIAL_READ	-18
#define SEL_SEN_NOT_FOUND	-19

#define TIME_OFF_MALLOC	-20
#define SCOM_TBL_MALLOC	-21
#define SCOM_INDEX_MALLOC	-22
#define SCOM_SEN_PTR_MALLOC	-23
#define SCOM_PTR_MALLOC	-24
#define POT_INFO_IDF_ELE_NOT_FOUND	-25
#define POT_INFO_IDF_MANY_BYTES	-26
#define POT_INFO_IDF_TBL_NUM	-27
#define POT_INFO_IDF_CON_NUM	-28
#define POT_INFO_IDF_NO_ENTRY	-29
#define CCOM_MATCH_MALLOC	-30
#define CCOM_VAL_MALLOC	-31
#define CONV_MODE_MISMATCH	-32
#define GET_ACTION_MALLOC	-33
#define POS_NOT_FOUND	-34
#define FILE_POS_MODE	-35
#define POS_DATA_READ_ERROR	-36
#define POS_HDR_READ_ERROR	-37
#define POS_HDR_MALLOC	-38
#define POS_HDR_REALLOC	-39
#define PBACK_LOS	-40
#define PBACK_NEXT_FILE	-41
#define RHDR_READ_ERROR	-42
#define RHDR_HDR_MALLOC	-43
#define RHDR_HDR_REALLOC	-44
#define FILL_HEADER	-45
#define DREC_NOT_FOUND	-46
#define CONV_CAL_MALLOC	-47
#define DREC_NO_FILES	-48
#define DREC_READ_ERROR	-49
#define DREC_HDR_READ_ERROR	-50
#define DREC_HDR_MALLOC	-51
#define DREC_HDR_REALLOC	-52
#define RESET_EULER_REALLOC	-53
#define RESET_MODE_REALLOC	-54
#define RESET_NOT_FOUND	-55
#define RESET_DATA_MALLOC	-56
#define RESET_DATA_REALLOC	-57
#define RESET_ANGLE_REALLOC	-58
#define FILE_POS_EULER	-59
#define TOO_MANY_EULER	-60
#define ALLOC_EV_REALLOC	-61
#define CRIT_TBL_NOT_FOUND	-62
#define CONST_ANG_MALLOC	-63
#define CONST_TEMP_MALLOC	-64
#define CNVT_NOT_FOUND	-65

#define TBL_MISC_MALLOC	-66
#define TBL_MALLOC	-67
#define TBL_IDF_ELE_NOT_FOUND	-68
#define TBL_IDF_MANY_BYTES	-69
#define TBL_IDF_TBL_NUM	-70
#define TBL_IDF_CON_NUM	-71
#define TBL_IDF_NO_ENTRY	-72
#define UPDATE_IDF_ELE_NOT_FOUND	-73
#define UPDATE_IDF_MANY_BYTES	-74
#define UPDATE_IDF_TBL_NUM	-75
#define UPDATE_IDF_CON_NUM	-76
#define UPDATE_IDF_NO_ENTRY	-77
<pre>#define SEN_IDF_ELE_NOT_FOUND</pre>	-78
#define SEN_IDF_MANY_BYTES	-79
#define SEN_IDF_TBL_NUM	-80
#define SEN_IDF_CON_NUM	-81
#define SEN_IDF_NO_ENTRY	-82
<pre>#define ONCE_IDF_ELE_NOT_FOUND</pre>	-83
#define ONCE_IDF_MANY_BYTES	-84
#define ONCE_IDF_TBL_NUM	-85
#define ONCE_IDF_CON_NUM	-86
#define ONCE_IDF_NO_ENTRY	-87
#define ONCE_DATA_MALLOC	-88
#define ONCE_D_TYPE_MALLOC	-89
#define ONCE_TBL_INFO_MALLOC	-90
#define ONCE_CTARGET_MALLOC	-91
#define ONCE_CLEN_MALLOC	-92
#define ONCE_TDW_LEN_MALLOC	-93
#define ONCE_SEN_STAT_MALLOC	-94
#define BAD_SCPOT_FORMAT	-95
#define BAD_PA_FORMAT	-96
<pre>#define MODE_TBL_SZ_IDF_ELE_NOT_FOUND</pre>	-97
<pre>#define MODE_TBL_SZ_IDF_MANY_BYTES</pre>	-98
<pre>#define MODE_TBL_SZ_IDF_TBL_NUM</pre>	-99
<pre>#define MODE_TBL_SZ_IDF_CON_NUM</pre>	-100
<pre>#define MODE_TBL_SZ_IDF_NO_ENTRY</pre>	-101
<pre>#define EXP_IDF_ELE_NOT_FOUND</pre>	-102
#define EXP_IDF_MANY_BYTES	-103
#define EXP_IDF_TBL_NUM	-104
#define EXP_IDF_CON_NUM	-105
#define EXP_IDF_NO_ENTRY	-106
<pre>#define CRIT_IDF_ELE_NOT_FOUND</pre>	-107
#define CRIT_IDF_MANY_BYTES	-108
#define CRIT_IDF_TBL_NUM	-109
#define CRIT_IDF_CON_NUM	-110
#define CRIT_IDF_NO_ENTRY	-111

#define NEW_IDF_ELE_NOT_FOUND	-112
#define NEW_IDF_MANY_BYTES	-113
#define NEW_IDF_TBL_NUM	-114
#define NEW_IDF_CON_NUM	-115
#define NEW_IDF_NO_ENTRY	-116
#define NEW_SCALE_MALLOC	-117
#define CONV_CAL_VECTOR_MISMATCH	-118
#define TIMING_MALLOC	-119
#define PBACK_NO_HEADER	-120
#define PBACK_NO_DATA	-121
#define CHK_DATA_NOT_FOUND	-122
#define NUM_CAL_REALLOC	-123
#define FILE_POS_DATA_GAP	-124
#define READ_IN_MALLOC	-125
#define READ_IN_IDF_ELE_NOT_FOUND	-126
#define READ_IN_IDF_MANY_BYTES	-127
#define READ_IN_IDF_TBL_NUM	-128
#define READ_IN_IDF_CON_NUM	-129
#define READ_IN_IDF_NO_ENTRY	-130
#define CREATE TBL MALLOC	-131
#define CREATE_IDF_ELE_NOT_FOUND	-132
#define CREATE IDF MANY BYTES	-133
#define CREATE_IDF_TBL_NUM	-134
#define CREATE_IDF_CON_NUM	-135
#define CREATE_IDF_NO_ENTRY	-136
#define CONST IDF ELE NOT FOUND	-137
#define CONST IDF MANY BYTES	-138
#define CONST_IDF_TBL_NUM	-139
#define CONST_IDF_CON_NUM	-140
#define CONST_IDF_NO_ENTRY	-141
#define SET_VWIDTH_BAND_MALLOC	-142
#define SET_VWIDTH_CENTER_MALLOC	-143
#define BAD_VFMT	-144
#define DKEY_PROJECT	-145
#define DKEY_MISSION	-146
#define DKEY EXPERIMENT	-147
#define DKEY INSTRUMENT	-148
#define DKEY_VINST	-149
#define FILL_SEN_NOT_FOUND	-150
#define FILL SEN MALLOC	-151
#define FILL SEN REALLOC	-152
#define FILL_SEN_BASE_MALLOC	-153
#define FILL_SEN_BASE_REALLOC	-154
#define FILL_SEN_TBL_MALLOC	-155
#define FILL_BIN_MISSING	-156
#define FILL_NOT_FOUND	-157

#define FILL_ARRAY_MALLOC	-158
#define FILL_UNITS_MALLOC	-159
#define FILL_UNITS_REALLOC	-160
#define FILL_SWP_MALLOC	-161
#define FILL_SWP_REALLOC	-162
#define FILL_DATA_MALLOC	-163
#define FILL_INFO_MALLOC	-164
#define NO_EMPTY_BUFFERS	-165
#define UNITS_IND_NOT_FOUND	-166
#define UNITS_NO_SENSOR	-167
#define UNITS_NO_MATCH	-168
#define COLLAPSE_NOT_FOUND	-169
#define COLLAPSE_MALLOC	-170
#define COLLAPSE_SEN_MALLOC	-171
#define COLLAPSE_DATA_MALLOC	-172
#define THETA_CHK_MALLOC	-173
#define THETA_BIN_MALLOC	-174
#define ORDER_THETA_MALLOC	-175
#define PHI_DIFF_UNITS	-176
#define FILL_PHI_FIRST	-177
#define FILL_PHI_LAST	-178
#define THETA_DIFF_UNITS	-179
#define CDIMEN_NOT_FOUND	-180
#define CDIMEN_COLLAPSE	-181
#define CDIMEN_MANY_SCAN	-182
#define CENTER_NOT_FOUND	-183
#define CENTER_NO_SENSOR	-184
#define BPTR_NOT_FOUND	-185
#define CENTER_TMP_MALLOC	-186
#define BAND_MALLOC	-187
#define CENTER_MALLOC	-188
#define SET_BIN_NOT_FOUND	-189
#define SET_BIN_MALLOC	-190
#define SET_BIN_INDEX_MALLOC	-191
#define SET_BIN_BAD_FMT	-192
#define CALC_TRES_NOT_FOUND	-193
#define CALC_CENTER_DREC	-194
#define RET_PHI_NOT_FOUND	-195
#define CPTR_RET_PHI	-196
#define NO_RET_PHI	-197
#define FILL_THETA_NOT_FOUND	-198
#define FILL_THETA_COLLAPSE	-199
#define IMAGE_NOT_FOUND	-200
#define IMAGE_READ_ERROR	-201
#define IMAGE_HDR_MALLOC	-202
#define IMAGE_HDR_REALLOC	-203
	December 29

#define NEXT_FILE_TIME_NOT_FOUND	-204
#define NEXT_FILE_TIME_FILE_OPEN	-205
#define NEXT_FILE_TIME_INFO_DUP	-206
#define PA_MAIN_DATA_MISSING	-207
#define SET_SCAN_NOT_FOUND	-208
#define SCAN_BIN_MISSING	-209
#define SET_SCAN_TBL_MALLOC	-210
#define SCAN_INDEX_MALLOC	-211
#define SCAN_IDF_ELE_NOT_FOUND	-212
#define SCAN_IDF_MANY_BYTES	-213
#define SCAN_IDF_TBL_NUM	-214
#define SCAN_IDF_CON_NUM	-215
#define SCAN_IDF_NO_ENTRY	-216
#define BUF_BIN_NOT_FOUND	-217
#define FILL_DISC_NOT_FOUND	-218
#define FILL_DISC_BIN_MISSING	-219
#define FILL_DISC_NO_PHI	-220
#define FILL_DISC_MALLOC	-221
#define DISC_DATA_MALLOC	-222
#define DISC_TMP_MALLOC	-223
#define TBL_VAR_NOT_CAL	-224
#define TBL_VAR_NOT_RAW	-225
#define CNVT_BAD_TBL_OPER	-226
#define CNVT_NO_TMP	-227
#define CNVT_TMP_MALLOC	-228
#define CNVT_BAD_TBL_NUM	-229
#define MODE_PTR_MALLOC	-230
#define MODE_TBL_MISC_MALLOC	-231
#define MODE_TBL_IDF_ELE_NOT_FOUND	-232
#define MODE_TBL_IDF_MANY_BYTES	-233
#define MODE_TBL_IDF_TBL_NUM	-234
#define MODE_TBL_IDF_CON_NUM	-235
#define MODE_TBL_IDF_NO_ENTRY	-236
#define MODE_TBL_VAR_NOT_CAL	-237
#define MODE_TBL_VAR_NOT_RAW	-238
#define MODE_TBL_MALLOC	-239
#define ASCII_AFTER_SENSOR	-240
#define CONV_MODE_BAD_MODE	-241
#define CONV_MODE_BAD_TBL_NUM	-242
#define FILL_SEN_MODE_TYPE	-243
#define UNITS_IND_MODE_TYPE	-244
#define MODE_INFO_NOT_FOUND	-245
#define MODE_INFO_MALLOC	-246
#define MODE_INFO_REALLOC	-247
#define MODE_INFO_BASE_MALLOC	-248
#define MODE_INFO_BASE_REALLOC	-249
111	1 00

#define MODE_INFO_TBL_MALLOC	-250
#define MODE_INFO_NO_MODES	-251
#define MODE_UNITS_IND_NOT_FOUND	-252
#define MODE_UNITS_FILE_OPEN	-253
#define MODE_UNITS_INFO_DUP	-254
#define MODE_UNITS_NO_MODE	-255
#define MODE_UNITS_NO_MATCH	-256
#define FILL_MODE_ARRAY_MALLOC	-257
#define MODE_UNITS_MALLOC	-258
#define MODE_UNITS_REALLOC	-259
#define MODE_DATA_MALLOC	-260
#define FILL_MODE_NOT_FOUND	-261
#define FILL_MODE_FILE_OPEN	-262
#define FILL_MODE_INFO_DUP	-263
#define MODES_NOT_REQUESTED	-264
#define ALLOC_MODE_INFO_MALLOC	-265
#define MODE_FILE_OPEN	-266
#define MODE_INFO_DUP	-267
#define CRIT_ACT_MALLOC	-268
#define FILL_BASE_TIME_MISSING	-269
#define FILL_DISC_BASE_TIME_MISSING	-270
#define FILL_MODE_BASE_TIME_MISSING	-271
#define CREATE_DATA_MALLOC	-272
#define CREATE_DATA_ALL_MALLOC	-273
#define CREATE_DATA_ALL_REALLOC	-274
#define RESET_PITCH_MALLOC	-275
#define RESET_PITCH_REALLOC	-276
#define PITCH_MALLOC	-277
#define PA_TBL_MALLOC	-278
#define SWEEP_TIME_MALLOC	-279
#define PINFO_IDF_ELE_NOT_FOUND	-280
#define PINFO_IDF_MANY_BYTES	-281
#define PINFO_IDF_TBL_NUM	-282
#define PINFO_IDF_CON_NUM	-283
#define PINFO_IDF_NO_ENTRY	-284
#define FILE_POS_PA	-285
#define PA_BAD_SRC	-286
#define PA_BAD_FRAC	-287
#define PA_UNIT_NORMAL	-288
#define PA_UNIT_MALLOC	-289
#define PA_DATA_MALLOC	-290
#define CNVT_BAD_DTYPE	-291
#define PA_BAD_TIMES	-292
#define SWEEP_NOT_FOUND	-293
#define SWEEP_BIN_MISSING	-294
#define SWEEP_UNITS_MALLOC	-295
415	December 28

#define SWEEP_UNITS_REALLOC	-296
#define SWEEP_SWP_MALLOC	-297
#define SWEEP_SWP_REALLOC	-298
#define SWEEP_DATA_MALLOC	-299
#define SWEEP_INFO_MALLOC	-300
#define SWEEP_WITH_FILL	-301
#define FILL_WITH_SWEEP	-302
#define SMODE_UNITS_MALLOC	-303
#define SMODE_UNITS_REALLOC	-304
#define SMODE DATA MALLOC	-305
#define ALLOC SMODE INFO MALLOC	-306
#define SWEEP MODE NOT FOUND	-307
#define SWEEP MODE FILE OPEN	-308
#define SWEEP_MODE_INFO_DUP	-309
#define SWEEP_MODES_NOT_REQUESTED	-310
#define SWEEP MODE WITH FILL	-311
#define FILL WITH SWEEP MODE	-312
#define SWEEP_DISC_NOT_FOUND	-313
#define SWEEP DISC BIN MISSING	-314
#define SWEEP DISC NO PHI	-315
#define SWEEP_DISC_WITH_FILL	-316
#define FILL WITH SWEEP DISC	-317
#define RESET_DCOS_MALLOC	-318
#define RESET_DCOS_VAL_MALLOC	-319
#define RESET_DCOS_VAL_REALLOC	-320
#define MASS PA ERROR	-320
#define CHRG PA ERROR	-321
#define GET_FPTR_NOT_FOUND	-322
#define RET_CBPTR_NOT_FOUND	-323
#define RET_CBPTR_NO_SENSOR	-324 -325
#define RET_CENTER_NOT_FOUND	-325
#define NO PA CONSTANT	-320
#define NPHI_NOT_FOUND	-328
#define NPHI_NO_BINS	-329
#define NBINS_NOT_FOUND	-330
#define NBINS_NO_BINS	-331
#define WRONG_DATA_STRUCTURE	-332
#define VIDF_OPEN_PTR_MALLOC	-333
#define VIDF_OPEN_EX_REALLOC	-334
#define FILL_ENV_NOT_FOUND	-335
#define FILL_ENV_SCALAR	-336
#define FILL_ENV_BASE_TIME_MISSING	-337
#define FILL_ENV_BIN_MISSING	-338
#define FILL_ENV_WITH_SWEEP	-339
#define CP_MAIN_DATA_MISSING	-340
#define CP_BAD_SRC	-341

#define BAD_CP_FORMAT	-342
#define COMPUTE MOMENTS	-343
#define CP_INFO_IDF_ELE_NOT_FOUND	-344
#define CP_INFO_IDF_MANY_BYTES	-345
#define CP_INFO_IDF_TBL_NUM	-346
#define CP_INFO_IDF_CON_NUM	-347
#define CP INFO IDF NO ENTRY	-348
#define ONCE CSCOPE MALLOC	-349
#define SET VWIDTH UPPER BAND MALLOC	-350
#define ONCE_BAD_HEADER_FMT	-351
#define ONCE BAD TENSOR RANK	-352
#define ONCE BAD TENSOR LENGTHS	-353
#define HDR_FMT_ONE_MALLOC	-354
#define HDR_FMT_TWO_MALLOC	-355
#define HDR_FMT_TWO_DQUAL	-356
#define UPDATE IDF BAD PA DEF	-357
#define UPDATE IDF NO FILL	-358
#define CREATE_TENSOR_DATA_ALL_MALLOC	-359
#define CREATE_TENSOR_DATA_ALL_REALLOC	-360
#define CREATE_TENSOR_DATA_MALLOC	-361
#define WRONG HEADER FORMAT	-362
#define TENSOR_NOT_FOUND	-363
#define TENSOR_NO_FILES	-364
#define TENSOR_READ_ERROR	-365
#define TENSOR_DQUAL_MALLOC	-366
#define TENSOR_DQUAL_REALLOC	-367
#define TENSOR HDR READ ERROR	-368
#define TENSOR HDR MALLOC	-369
#define TENSOR_HDR_REALLOC	-370
#define TENSOR_MODE_MALLOC	-371
#define TENSOR_MODE REALLOC	-372
#define TENSOR DATA MALLOC	-373
#define TENSOR_DATA_REALLOC	-374
#define ONCE BAD NUM TBLS	-375
#define ONCE BAD CAL TARGET	-376
#define ONCE BAD MAX NSS	-377
#define ONCE BAD SMP ID	-378
#define ONCE BAD DA METHOD	-379
#define ONCE BAD SWP LEN	-380
#define ONCE_BAD_SEN_MODE	-381
#define TENSOR DATA TDW LEN	-382
#define COLLAPSE DATA ADDRESS	-383
#define CHK_TDATA_NOT_FOUND	-384
#define NEG BIN STAT	-385
#define FIRST_SEN_NOT_FOUND	-386
#define START_SPIN_NOT_FOUND	-387
//////////////////////////////////////	December 28

#define START_SPIN_NO_POS	-388
#define START_SPIN_NO_SPIN	-389
#define START_SPIN_ETIME	-390
#define START_SPIN_MALLOC	-391
#define START SPIN ALL MALLOC	-392
#define ONCE SPIN OFF MALLOC	-393
#define TURN_OFF_PA_NOT_FOUND	-394
#define TURN ON EA NOT FOUND	-395
#define START_ELE_BAD_SENSOR	-396
#define START ELE SPIN NO SENSOR	-397
#define READ SPIN NOT FOUND	-398
#define READ_SPIN_NO_START	-399
#define READ_SPIN_ALL_REALLOC	-400
#define READ_SPIN_PARTIAL	-401
#define SPIN_INFO_MALLOC	-402
#define SPIN_UNITS_MALLOC	-403
#define SPIN_UNITS_REALLOC	-404
#define SPIN_SWP_MALLOC	-405
#define SPIN_SWP_REALLOC	-406
#define SPIN DATA MALLOC	-407
#define SPIN_DATA_PIX_NOT_FOUND	-408
#define SPIN_DATA_PIX_WITH_FILL_SWEEP	-409
#define SPIN_DATA_PIX_BIN_MISSING	-410
#define SPIN_DATA_PIX_CENTER_BAND_MISSING	-411
#define SPIN_DATA_PIX_NO_SPIN	-412
#define SPIN_DATA_NOT_FOUND	-413
#define SPIN_DATA_BIN_MISSING	-414
#define SPIN_DATA_WITH_FILL_SWEEP	-415
#define SPIN_DATA_CENTER_BAND_MISSING	-416
#define SPIN_DATA_NO_SPIN	-417
#define FILL_CENTER_BAND_MISSING	-418
#define FILL_ENV_CENTER_BAND_MISSING	-419
#define FILL_DISC_CENTER_BAND_MISSING	-420
#define SWEEP_CENTER_BAND_MISSING	-421
#define SWEEP_DISC_CENTER_BAND_MISSING	-422
#define NEW_BAD_TBL_OFFSET	-423
#define UPDATE_IDF_BAD_SPIN_DEF	-424
#define SPIN_SRC_MALLOC	-425
#define START_SPIN_TIME_MALLOC	-426
#define SPIN_SRC_BAD_SRC	-427
#define SPIN_SINFO_IDF_ELE_NOT_FOUND	-428
#define SPIN_SINFO_IDF_MANY_BYTES	-429
#define SPIN_SINFO_IDF_TBL_NUM	-430
#define SPIN_SINFO_IDF_CON_NUM	-431
#define SPIN_SINFO_IDF_NO_ENTRY	-432
#define FILE_POS_SPIN	-433

#define SPIN_SRC_MAIN_DATA_MISSING	-434
#define READ_SPIN_DSRC_READ	-435
#define READ_SPIN_DSRC_BACK_SPIN	-436
#define READ_SPIN_SENSOR_NOT_FOUND	-437
#define ONCE_CDTYPE_MALLOC	-438
#define CP_STR_MALLOC	-439
#define CP_DATA_MALLOC	-440
#define FILE_POS_CP	-441
#define CNVT_NO_ADV	-442
#define CNVT_BAD_BUF_NUM	-443
#define CNVT_SAME_BUF_NUM	-444
#define UPDATE_IDF_BAD_POT_DEF	-445
#define POT_TBL_MALLOC	-446
#define POT_BAD_SRC	-447
#define POT_BAD_FRAC	-448
#define POT_MALLOC	-449
#define TURN_ON_CP_NOT_FOUND	-450
#define POT_DATA_MALLOC	-451
#define POT_MAIN_DATA_MISSING	-452
#define FILE_POS_POT	-453
#define POT_BAD_TIMES	-454
#define RESET_POT_REALLOC	-455
#define UPDATE_IDF_BAD_PMI_DEF	-456
#define SWP_TIMES_TMP_MALLOC	-457
#define READ_IN_BAD_TBL_OFFSET	-458
#define CREATE_BAD_TBL_OFFSET`	-459
#define OVERRIDE_NOT_FOUND	-460
#define OVERRIDE_NO_POT	-461
#define OVERRIDE_NO_POT_TBLS	-462
#define OVERRIDE_TOO_MANY_POT_TBLS	-463
#define OVERRIDE_TBL_FMT_MALLOC	-464
#define OVERRIDE_BAD_TBL_FMT_VALUE	-465
#define RESET_CP_REALLOC	-466
#define RESET_TINFO_MALLOC	-467
#define NO_CP_CONSTANT	-468
#define CP_TBL_MALLOC	-469
#define UPDATE_IDF_BAD_CP_DEF	-470
#define CREATE_DSTR_NOT_FOUND	-471
#define EULER_MALLOC	-472
#define EULER_MAIN_DATA_MISSING	-473
#define EULER TBL MALLOC	-474
#define BAD_EULER_FORMAT	-475
#define EULER_AXIS_MALLOC	-476
#define LESS_EULER_CONSTANT_ANGLES	-477
#define LESS_EULER_CONSTANT_AXIS	-478
#define MORE_EULER_CONSTANT_ANGLES	-479

#define MORE_EULER_CONSTANT_AXIS	-480
#define EULER_IDF_DATA_MALLOC	-481
#define EULER_BAD_SRC	-482
#define EULER_BAD_TIMES	-483
#define EULER_BAD_FRAC	-484
#define EULER_INFO_IDF_ELE_NOT_FOUND	-485
#define EULER_INFO_IDF_MANY_BYTES	-486
#define EULER_INFO_IDF_TBL_NUM	-487
#define EULER_INFO_IDF_CON_NUM	-488
#define EULER_INFO_IDF_NO_ENTRY	-489
#define TRANS_3D_BINNED_MALLOC	-490
#define DESTROY_NO_IDF_DATA	-491
#define DESTROY_NO_TENSOR_DATA	-492
#define FILE_POS_INVALID_DATA	-493
#define BKGD_MAIN_DATA_MISSING	-494
#define BKGD_BAD_SRC	-495
#define BAD_BKGD_FORMAT	-496
#define BKGD_TBL_MALLOC	-497
#define BKGD_MALLOC	-498
#define BKGD_DATA_MALLOC	-499
#define BKGD_IDF_DATA_MALLOC	-500
#define BKGD_INFO_IDF_ELE_NOT_FOUND	-501
#define BKGD_INFO_IDF_MANY_BYTES	-502
#define BKGD_INFO_IDF_TBL_NUM	-503
#define BKGD_INFO_IDF_CON_NUM	-504
#define BKGD_INFO_IDF_NO_ENTRY	-505
#define FILE_POS_BKGD	-506
#define BKGD_BAD_TIMES	-507
#define RESET_BKGD_REALLOC	-508
#define BKGD_BAD_FRAC	-509
#define UPDATE_IDF_BAD_BKGD_DEF	-510
#define NO_BKGD_CONSTANT	-511

#define UTIL_START_CODE	-1
#define UTIL_STOP_CODE	-511

USER_DEFS.H

function - defines mnemonics that can be utilized for coding purposes

SYNOPSIS

#include "user_defs.h"

DESCRIPTION

The **user_defs.h** include file holds mnemonics available for use with some of the IDFS routines. All mnemonic are initialized through a **define** statement. The user may include this file and use the mnemonics to help improve the readability of the calling sequence for some of the IDFS routines.

CONTENTS OF FILE	
#define SENSOR	1
#define SWEEP_STEP	2
#define CAL_DATA	3
#define MODE	4
#define D_QUAL	5
#define PITCH_ANGLE	6
#define START_AZ_ANGLE	7
#define STOP_AZ_ANGLE	8
#define SC_POTENTIAL	9
#define BACKGROUND	10
#define MAX_DATA_TYPE	10
#define MAX_UNITS_BUFFERS	9
#define OUTSIDE_MIN	-3.4e38
#define OUTSIDE_MAX	3.4e38
#define VALID_MIN	-3.0e38
#define VALID_MAX	3.0e38
#define UNTOUCHED_BUFFER	-2
#define FREE_BUFFER	-1
#define PARTIAL_WORKING	0
#define BUFFER_READY	1
#define NUM_BUFFERS	5
#define LEADING_EDGE	1
#define TRAILING_EDGE	0
#define MASS_DIMEN	1
#define PHI_DIMEN	2
#define THETA_DIMEN	3
#define SCAN_DIMEN	4
#define DATA_DIMEN	5
#define NO_DIMEN	6
#define CHARGE_DIMEN	7
#define SCAN_INDEX	0
#define THETA_INDEX	1
<pre>#define PHI_INDEX`</pre>	2
	101 D 1 00

#define MASS_INDEX	3
#define CHARGE_INDEX	4
#define SCALAR_INDEX	5
#define DIMEN_OFF	0
#define DIMEN_ON	1
#define DIMEN_CONSTANT	2
#define NO_AVG	1
#define STRAIGHT_AVG	2
#define STRAIGHT_INT	3
#define SPHERICAL_INT	4
#define STRAIGHT_AVG_AZ	5
#define FLUX_INT	6
#define MOMENTS_INT	7
#define POINT_INT	1
#define BAND_INT	2
#define FIXED_SWEEP	1
#define VARIABLE_SWEEP	2
#define ZERO_SPACING	0
#define LIN_SPACING	1
#define LOG_SPACING	2
#define VARIABLE_SPACING	3
#define POINT_STORAGE	1
#define BAND_STORAGE	2
#define NO_BIN_FILL	1
#define LIN_ROW_COL	2
#define LIN_COL_ROW	3
#define CON_ROW_COL	4
#define CON_COL_ROW	5
#define LEAST_SQ_FIT	6
#define TORAD	0.017453292519943
#define PA_NOT_APPLICABLE	0
#define PA_READY	1
#define PA_DB_ERROR	2
#define PA_DATA_MISSING	3
#define PA_IR_ERROR	4
#define SPIN_SRC_NOT_APPLICABLE	0
#define SPIN SRC READY	1
#define SPIN_SRC_DB_ERROR	2
#define SPIN_SRC_DATA_MISSING	3
#define SPIN SRC IR ERROR	4
#define POT_NOT_APPLICABLE	0
#define POT_READY	1
#define POT_DB_ERROR	2
#define POT_DATA_MISSING	3
#define POT_IR_ERROR	4
#define EULER_NOT_APPLICABLE	0
	Ŭ

#define EULER_READY	1
#define EULER_DB_ERROR	2
#define EULER_DATA_MISSING	3
#define EULER_IR_ERROR	4
#define CP_NOT_APPLICABLE	0
#define CP_READY	1
#define CP_DB_ERROR	2
#define CP_DATA_MISSING	2 3
#define CP_IR_ERROR	4
#define BKGD_NOT_APPLICABLE	0
#define BKGD_READY	1
#define BKGD_DB_ERROR	2 3
#define BKGD_DATA_MISSING	
#define BKGD_IR_ERROR	4
#define NO_SPECIFIED_CS	-1
#define SPACECRAFT_CS	0
#define PMI_CS	1
#define GEI_CS	2
#define GEO_CS	3
#define GSE_CS	2 3 4 5
#define GSM_CS	
#define SM_CS	6
#define MAG_CS	7
#define HEE_CS	8
#define HAE_CS	9
#define HEEQ_CS	10

user_defs (1H)

LIBTREC_IDFS.H

function - contains prototypes for the IDFS routines that return time-averaged, sampleaveraged, or spin-averaged data

SYNOPSIS

#include "libtrec_idfs.h"

DESCRIPTION

The **libtrec_idfs.h** include file contains the ANSI C prototypes for the IDFS routines that are used to retrieve data that is time-averaged, sample-averaged or spin-averaged. These routines can be found in the **2R** section of the IDFS Programmers Manual. This file should be included in the source code wherever an IDFS routine is called from to ensure that the correct number of arguments are used and to ensure that the argument types match.

SEE ALSO

libbase_idfs 1H

libtrec_idfs (2H)

SCF_CODES.H

function - defines possible return values and associated mnemonics for the SCF software

SYNOPSIS

#include "SCF_codes.h"

DESCRIPTION

The SCF_codes.h include file holds all of the defined return values for the SCF routines defined in sections **3R** and **4R**. All return values are associated with a mnemonic through a **define** statement. The user of the SCF routines should include this file and use the mnemonics defined for the return values. This allows for the values to be changed in the future with no code modification.

CONTENTS OF FILE

IENIS OF FILE	
#define ALL_OKAY	1
#define SCF_TERMINATE	45
#define NO_SCF_FILE	-3001
#define SCF_CONTACT_MALLOC	-3002
#define SCF_COMMENTS_MALLOC	-3003
#define SCF_INPUT_MALLOC	-3004
#define SCF_INPUT_TBL_MALLOC	-3005
#define SCF_TEMP_MALLOC	-3006
#define SCF_OUTPUT_VAR_MALLOC	-3007
#define SCF_MAP_MALLOC	-3008
#define SCF_EQNS_MALLOC	-3009
#define SCF_EQNS_REALLOC	-3010
#define LOCATE_SCF_NOT_FOUND	-3011
#define LOCATE_SCF_MALLOC	-3012
#define LOCATE_SCF_REALLOC	-3013
#define READ_SCF_NO_TOKEN	-3014
#define READ_SCF_BAD_DSRC	-3015
#define READ_SCF_BAD_INPUT	-3016
#define READ_SCF_BAD_TEMP	-3017
#define READ_SCF_BAD_OUTPUT	-3018
#define READ_SCF_BAD_FIELD	-3019
#define READ_SCF_NO_DIMEN	-3020
#define READ_SCF_BAD_EQNS	-3021
#define READ_SCF_BAD_TOKEN	-3022
#define SCF_NO_FUNCTION	-3023
#define READ_SCF_BAD_FUNCTION	-3024
#define READ_SCF_BAD_INDEX	-3025
#define READ_SCF_ELSE_INFO	-3026
#define SCF_ACQ_MANY_READS	-3027
#define SCF_OUTPUT_DATA_STR	-3028
#define SCF_FRAC_MALLOC	-3029
#define SCF_ARGS_MALLOC	-3030
	-

428	Docomb
#define SCF_TSUM_COL_DIMEN	-3077
#define SCF_TSUM_VDIVIEN	-3076
#define SCF_TSUM_VDIMEN	-3075
#define SCF_TDIMEN	-3074
#define SCF_TENSOR_MANY_ARGS	-3073
#define SCF_SQUARE_RES	-3072
#define SCF_SQUARE_ARG	-3071
#define SCF_KOKDEK_MISMATCH #define SCF_TSIZE_MISMATCH	-3070
#define SCF_AORDER_MISMATCH #define SCF_RORDER_MISMATCH	-3069
#define SCF_SIZE_MISMATCH #define SCF_AORDER_MISMATCH	-3068
#define SCF_DIVIEN_WALLOC #define SCF_SIZE_MISMATCH	-3067
#define SCF_DIMEN_MALLOC	-3066
#define SCF_REAK_STMT	-3065
#define SCF_VOID #define SCF_NO_INDEX	-3064
#define SCF_VOID	-3063
#define SCF_NON_VOID	-3062
#define SCF_SAMP_VECTOR_SRC	-3061
#define SCF_SAMP_VECTOR_ACCUM	-3060
#define SCF_SAMP_SWP_MALLOC	-3059
#define SCF_SAMP_BAD_LOCATE	-3058
#define SCF_SAMP_BAD_ACCUM	-3057
#define SCF_SAMP_BAD_INPUT_NUM	-3056
#define SCF_BAD_LOGICAL_OPER	-3055
#define SCF_INVALID_INDEX	-3054
#define SCF_INDEX_MALLOC	-3053
#define SCF_OPEN_RTIME	-3052
#define SCF_UTPUT_CALC	-3051
#define SCF_NO_FUNC_IN_LIB	-3050
#define SCF_OUTPUT_MALLOC	-3049
#define SCF_CREATE_MALLOC	-3048
#define SCF_CREATE_ALL_REALLOC	-3047
#define SCF_CREATE_ALL_MALLOC	-3046
#define SCF_NUM_ARGS	-3045
#define SCF_RES_RANK	-3044
#define SCF ARG RANK	-3043
#define SCF_RES_LENGTH	-3042
#define SCF BAD FRAC	-3040
#define SCF_PROCESS_BAD_EX	-3039
#define SCF_REALLOC_PLOT_LOC	-3038
#define SCF_ALLOC_PLOT_LOC	-3037
#define SCF_FAST_BAD_LOCATE	-3036
#define SCF_SAMP_BAD_RATE	-3035
#define SCF_SAMP_POS	-3034
#define SCF_POS_ERROR	-3033
#define SCF_OPEN_ERROR	-3032
#define SCF_MATRIX_MALLOC	-3031

#define SCF_TSUM_RSIZE	-3078
#define SCF_TWDIMEN	-3079
#define SCF_TWSUM_VDIMEN	-3080
#define SCF_TWSUM_ROW_DIMEN	-3081
#define SCF_TWSUM_COL_DIMEN	-3082
#define SCF_TWSUM_RSIZE	-3083
#define SCF_TW_WLEN	-3084
#define SCF_TENSOR_SAME_RANK	-3085
#define SCF_MASK_LENGTHS	-3086
#define SCF_TEXTRACT_SDIMEN	-3087
#define SCF_TEXTRACT_START	-3088
#define SCF_TEXTRACT_RES_RANK	-3089
#define SCF_TEXTRACT_RES_DIMEN	-3090
#define SCF_TEXTRACT_INDEX	-3091
#define SCF_TINSERT_SDIMEN	-3092
#define SCF_TINSERT_START	-3093
#define SCF_TINSERT_INDEX	-3094
#define SCF_TINSERT_SIZE	-3095
#define SCF_TINT_CLEN	-3096
#define SCF_TSPACE	-3097
#define SCF_TENSOR_VECTOR_SRC	-3098
#define SCF_FILL_SZ	-3099
#define SCF_NO_LIBRARY	-3100
#define SCF_BIN_BAD_SWP_FMT	-3101
#define SCF_BIN_BAD_FMT	-3102
#define SCF_BIN_BAD_OVAR_NUM	-3103
#define SCF_BIN_MALLOC	-3104
#define SCF_BIN_BAD_CNUM	-3105
#define SCF_BIN_BAD_BNUM	-3106
#define SCF_BIN_CLENGTH	-3107
#define SCF_BIN_BLENGTH	-3108
#define SCF_BIN_BAD_VFMT	-3109
#define SCF_CENTER_MALLOC	-3110
#define SCF_BAND_MALLOC	-3111
#define SCF_SELECT_OVAR_NUM	-3112
#define SCF_SELECT_BIN_MISSING	-3113
#define SCF_SELECT_MALLOC	-3114
#define SCF_SELECT_DEF_MALLOC	-3115
#define SCF_SELECT_DEF_REALLOC	-3116
#define SCF_SELECT_DVAR_NUM	-3117
#define SCF_SELECT_DVAR_LENGTH	-3118
#define SCF_SELECT_BAND_MALLOC	-3119
#define SCF_TAVG_NO_BASE_TIME	-3120
#define SCF_TAVG_BIN_MISSING	-3121
#define SCF_TAVG_SELECT_MISSING	-3122
#define SCF_TIME_WITH_SAMPLE	-3123
120	D 1

#define SCF_AVG_STR_MALLOC	-3124
#define SCF_TINFO_MALLOC	-3125
#define SCF_TDATA_MALLOC	-3126
#define SCF_SINFO_MALLOC	-3127
#define SCF_SDATA_MALLOC	-3128
#define SCF_ALG_START_NO_SAMPLE	-3129
#define SCF_OINDEX_OVAR_NUM	-3130
#define SCF_OINDEX_NO_AVG	-3131
#define SCF_OINDEX_NO_OUTPUT	-3132
#define SCF_OINDEX_NO_MATCH	-3133
#define SCF_OCENTER_OVAR_NUM	-3134
#define SCF_OCENTER_NO_AVG	-3135
#define SCF_OCENTER_SELECT_MISSING	-3136
#define SCF_NO_EMPTY_BUFFERS	-3137
#define SCF_SAVG_BIN_MISSING	-3138
#define SCF_SAVG_SELECT_MISSING	-3139
#define SCF_SAMPLE_WITH_TIME	-3140
#define SCF_NO_CENTER_VALUES	-3141
#define SCF_BAD_START_STOP	-3142

SCF_DEFS.H

function - defines mnemonics that can be utilized for SCF coding purposes

SYNOPSIS

#include "SCF_defs.h"

DESCRIPTION

The **SCF_defs.h** include file holds mnemonics available for use with some of the SCF routines. All mnemonic are initialized through a **define** statement. The user may include this file and use the mnemonics to help improve the readability of the calling sequence for some of the SCF routines. This allows for transparent future modifications in their values.

CONTENTS OF FILE

#define SCF_MEASURE_TM	1
#define SCF_MEASURE_LAT_TM	2
#define SCF_DELTA_T	1
#define USE_INPUT_VAR	2
#define USE_DELTA_T	3
#define S_BEFORE_START	1
#define S_EQUAL_START	2
#define S_AFTER_START	3
#define S_NUM_SPECIAL	15
#define SPIN_RATE	10
#define DATA_ACCUM_MS	11
#define DATA_ACCUM_NS	12
#define DATA_LAT_MS	13
#define DATA_LAT_NS	14
#define SCF_LINEAR_BINS	1
#define SCF_LOG_BINS	2
#define SCF_POINT_STORAGE	1
#define SCF_BAND-STORAGE	2
#define SCF_LESS_THAN_MIN	-1
#define SCF_GREATER_THAN_MAX	-2

SCF_FILE_DEFS.H

function - defines all possible mnemonics used to access elements in the SCF file

SYNOPSIS

#include "SCF_file_defs.h"

DESCRIPTION

The **SCF_file_defs.h** include file holds all of the defined mnemonics that can be utilized to access the data elements found within the SCF file. All mnemonics are assigned a value through a **define** statement. It is recommended that the **read_scf** routine be invoked using the defined mnemonics. This allows for transparent future modifications in their values.

CONTENTS OF FILE

-		
	#define NOT_USED	0
	#define S_TITLE	0
	#define S_NUM_CONTACT	1
	#define S_CONTACT	2
	#define S_NUM_COMMENTS	3
	#define S_COMMENTS	4
	#define S_NUM_INPUT	5
	#define S_INPUT_NAME	6
	#define S_INPUT_PROJ	7
	#define S_INPUT_MISSION	8
	#define S_INPUT_EXP	9
	#define S_INPUT_INST	10
	#define S_INPUT_VINST	11
	#define S_INPUT_KEY	12
	#define S_INPUT_DTYPE	13
	#define S_INPUT_DNUM	14
	#define S_INPUT_CSET	15
	#define S_INPUT_NUM_TBLS	17
	#define S_INPUT_TBLS	18
	#define S_INPUT_OPERS	19
	#define S_INPUT_LOWER_CUT	20
	#define S_INPUT_UPPER_CUT	21
	#define S_INPUT_QUAL_MIN	22
	#define S_INPUT_QUAL_MAX	23
	#define S_NUM_TEMP	24
	#define S_TEMP_NAME	25
	#define S_TEMP_DIMENSION	26
	#define S_TEMP_LENGTHS	27
	#define S_NUM_OUTPUT	28
	#define S_OUTPUT_NAME	29
	#define S_OUTPUT_DIMENSION	30
	#define S_OUTPUT_LENGTHS	31
	#define S_NUM_EQNS	32
	122	December (

#define S_EQUATIONS	33
#define S_EQN_TYPE	34
#define S_EQN_START	35
#define S_EQN_STOP	36
#define S_ELSE_START	37
#define S_ELSE_STOP	38
#define SCF_EQN	0
#define SCF_FN	1
#define SCF_FOR	2
#define SCF_IF	3
#define SCF_IF_ELSE	4
#define SCF_BREAK	5

LIBBASE_SCF.H

function- contains prototypes for the basic set of SCF routines

SYNOPSIS

#include "libbase_SCF.h"

DESCRIPTION

The **libbase_SCF.h** include file contains the ANSI C prototypes for the basic set of SCF routines that interpret the contents of the SCF file, execute the algorithm defined in the SCF file and return the results of the algorithm. These routines can be found in section **3R** of the IDFS Programmers Manual. This include file should be included in the source code wherever an SCF routine is called from to ensure that the correct number of arguments are used and to ensure that the argument types match.

SEE ALSO

libavg_SCF 4H

LIBAVG_SCF.H

function - contains prototypes for the SCF routines that return time-averaged or sample-averaged data

SYNOPSIS

#include "libavg_SCF.h"

DESCRIPTION

The **libavg_SCF.h** include file contains the ANSI C prototypes for the SCF routines that are used to retrieve data for output variables that have been time-averaged or sample-averaged. These routines can be found in the **4R** section of the IDFS Programmers Manual. This include file should be included in the source code wherever an SCF routine is called from to ensure that the correct number of arguments are used and to ensure that the argument types match.

SEE ALSO

libbase_SCF 3H

IDF_DATA

function - IDFS data structure

SYNOPSIS

#include "util_str.h"

struct idf_data

{

SDDAS_ULONG	data_key;
SDDAS_SHORT	header_format;
SDDAS_SHORT	sensor;
SDDAS_SHORT	byear;
SDDAS_SHORT	bday;
SDDAS_LONG	bmilli;
SDDAS_LONG	bnano;
SDDAS_LONG	bsec;
SDDAS_LONG	bnsec;
SDDAS_SHORT	eyear;
SDDAS_SHORT	eday;
SDDAS_LONG	emilli;
SDDAS_LONG	enano;
SDDAS_LONG	esec;
SDDAS_LONG	ensec;
SDDAS_SHORT	mode_byear;
SDDAS_SHORT	mode_bday;
SDDAS_LONG	mode_bmilli;
SDDAS_LONG	mode_bnano;
SDDAS_SHORT	mode_eyear;
SDDAS_SHORT	mode_eday;
SDDAS_LONG	mode_emilli;
SDDAS_LONG	mode_enano;
SDDAS_LONG	data_accum_ms;
SDDAS_LONG	data_accum_ns;
SDDAS_LONG	data_lat_ms;
SDDAS_LONG	data_lat_ns;
SDDAS_LONG	<pre>swp_reset_ms;</pre>
SDDAS_LONG	<pre>swp_reset_ns;</pre>
SDDAS_LONG	sen_reset_ms;
SDDAS_LONG	<pre>sen_reset_ns;</pre>
SDDAS_FLOAT	*start_az;
SDDAS_FLOAT	*stop_az;
SDDAS_FLOAT	start_theta;
SDDAS_FLOAT	stop_theta;
SDDAS_FLOAT	*pitch_angles;
SDDAS_FLOAT	*potential;
SDDAS_FLOAT	*background;

SDDAS_SHORT	num_swp_steps;
SDDAS_USHORT	num_sample;
SDDAS_ULONG	cal_len;
SDDAS_USHORT	num_angle;
SDDAS_USHORT	num_pitch;
SDDAS_USHORT	num_potential;
SDDAS_USHORT	num_background;
SDDAS_LONG	sun_sen;
SDDAS_LONG	spin_rate;
SDDAS_LONG	<pre>*cal_data;</pre>
SDDAS_LONG	*sen_data;
SDDAS_LONG	*swp_data;
SDDAS_LONG	*mode;
SDDAS_LONG	d_qual;
SDDAS_UINT	cal_size;
SDDAS_UINT	data_size;
SDDAS_UINT	swp_size;
SDDAS_UINT	mode_size;
SDDAS_UINT	angle_size;
SDDAS_UINT	pitch_size;
SDDAS_UINT	potential_size;
SDDAS_UINT	background_size;
SDDAS_UCHAR	mode_len;
SDDAS_CHAR	hdr_change;
SDDAS_CHAR	exten[3];
SDDAS_CHAR	filled_data;
SDDAS_USHORT	version;
SDDAS_ULONG	*cset_num;
struct direction_cos	*dir_cosines;
struct transformation_info	*idfs_transformation;
void	*base_cal;
void	*base_data;
void	*base_swp;
void	*base_angle;
void	*base_mode;
void	*base_pitch;
void	*base_cset;
void	*base_dir_cosines;
void	*base_potential;
void	*base_background;
void	*base_transform;

};

ELEMENT DEFINITIONS

VIENT DEFINITION	JNS	
data_key	-	unique value which indicates the data set of interest
header_format	-	used to identify conventional IDFS data from multi-
		dimensional tensor IDFS data
sensor	-	the sensor identification number for the current data
byear	-	the year at the start of the accumulation of the first data value
		in the data sweep
bday	-	the day at the start of the accumulation of the first data value
·		in the data sweep
bmilli	-	the milliseconds of the day at the start of the accumulation of
		the first data value in the data sweep
bnano	-	the remaining nanoseconds of the day at the start of the
		accumulation of the first data value in the data sweep
bsec	-	the start time of the first data value in the data sweep in
		seconds (bmilli + bnano)
bnsec	-	the remaining nanoseconds of the start time of the first data
		value in the data sweeps (bmilli + bnano)
eyear	-	the year at the end of the accumulation period of the last data
5		value in the data sweep
eday	-	the day at the end of the accumulation period of the last data
2		value in the data sweep
emilli	-	the milliseconds of the day at the end of the accumulation
		period (including any latency) of the last data value in the
		data sweep
enano	-	the remaining nanoseconds of the day at the end of the
		accumulation period (including any latency) of the last data
		value in the data sweep
esec	-	the end time of the last data value in the data sweep in
		seconds (emilli + enano)
ensec	-	the remaining nanoseconds of the end time of the last data
		value in the data sweeps (emilli + enano)
mode_byear	-	the year at the start of the accumulation for the instrument
_ ,		status values
mode_bday	-	the day at the start of the accumulation for the instrument
_ ,		status values
mode_bmilli	-	the milliseconds of the day at the start of the accumulation for
—		the instrument status values
mode_bnano	-	the remaining nanoseconds of the day at the start of the
		accumulation for the instrument status values
mode_eyear	-	the year at the end of the accumulation period for the
•		instrument status values
mode_eday	-	the day at the end of the accumulation period for the
_ ,		instrument status values
mode_emilli	-	the milliseconds of the day at the end of the accumulation
		period (including any latency) for the instrument status values

mode_enano	-	the remaining nanoseconds of the day at the end of the accumulation period (including any latency) for the
data_accum_ms	-	instrument status values the amount of time for a single data acquisition, in milliseconds
data_accum_ns	-	the remainder of data_accum_ms, in nanoseconds
data_lat_ms	-	the amount of dead time between successive data acquisitions, in milliseconds
data_lat_ns	-	the remainder of data_lat_ms, in nanoseconds
swp_reset_ms	-	the amount of dead time at the end of an instrument sweep, in milliseconds
swp_reset_ns	-	the remainder of swp_reset_ms, in nanoseconds
sen_reset_ms	-	the amount of dead time between successive sensor sets, in milliseconds
sen_reset_ns	-	the remainder of sen_reset_ms, in nanoseconds
start_az	-	pointer to the first element in the initial azimuthal sample
		angle array, with one value per data sample returned
stop_az	-	pointer to the first element in the final azimuthal sample angle
		array, with one value per data sample returned
start_theta	-	the initial theta angle for the sensor in question
stop_theta	-	the final theta angle for the sensor in question
pitch_angles	-	pointer to the first element in the pitch angle array, with one
		value per data sample returned
potential	-	pointer to the first element in the spacecraft potential array,
		with one value per data sample returned
background	-	pointer to the first element in the background data array,
		with one value per data sample returned
num_swp_steps	-	the number of elements returned in the sweep array
1		*swp_data
num_sample	-	the number of elements returned in the sensor data array
		*sen_data
cal_len	-	the number of elements returned in the calibration array
1		*cal_data
num_angle	-	the number of elements returned in the azimuthal angle arrays
		*start_az and *stop_az
num_pitch	-	the number of elements returned in the pitch angle array
num notantial		*pitch_angles
num_potential	-	the number of elements returned in the spacecraft potential
num hadronound		array * potential
num_background	-	the number of elements returned in the background data
aun		array * background
sun_sen	-	the time of the last 0° crossing the current spin rate of the virtual instrument
spin_rate	-	-
cal_data sen_data	-	pointer to the first element in the calibration array pointer to the first element in the sensor data array
	-	pointer to the first element in the sweep array
swp_data	-	
		442 December 28, 2012

mode d_qual	-	pointer to the first element in the mode flags array value which indicates the quality of the data being returned and also serves as an offset into the qual_names array defined in the VIDF file. The user should refer to the IDFS File System Definition Document for an explanation of qual_names and d_qual . The values returned are dependent upon the data set being processed.
cal_size	-	the number of bytes allocated for the calibration array
data_size	-	the number of bytes allocated for the sensor data array
swp_size	-	the number of bytes allocated for the sweep array
mode_size	-	the number of bytes allocated for the mode flags array
angle_size	-	the number of bytes allocated for both of the azimuthal angle arrays
pitch_size	-	the number of bytes allocated for the pitch angle array
potential_size	-	the number of bytes allocated for the spacecraft potential array
background_size	-	the number of bytes allocated for the background array
mode_len	-	the number of elements returned in the mode flags array *mode
hdr_change	-	flag which indicates a header change occurred
		0 - a header change was not encountered
		during the retrieval of data
		1 - a header change was encountered
		during the retrieval of data
exten	-	two character extension identifying the IDFS data file set
		being utilized (should be a null string "" when using the
		default IDFS data sets)
filled_data	-	flag which indicates if data was placed into the data arrays for
		the sensor in question
		0 - data was not placed into the arrays for
		the sensor in question
		1 - data was placed into the arrays for the
		sensor in question
version	-	IDFS data set identification number which allows for multiple
		openings of the same data set
cset_num	-	pointer to the first element in the calibration set size array
dir_cosines	-	pointer to a structure which holds the direction cosines array
		and ancillary theta start / stop angles and azimuthal start /
· 10 · 0 · · ·		stop angles associated with the pitch angle data source
idfs_transformation	-	pointer to a structure which holds data pertinent to coordinate
		system transformations (currently, this includes euler angle
hasa asl		data and/or celestial position angle data)
base_cal	-	the base address of the allocated memory for the calibration
		array

base_data	-	the base address of the allocated memory for the sensor data array
base_swp	-	the base address of the allocated memory for the sweep array
base_angle	-	the base address of the allocated memory for the azimuthal angle arrays
base_mode	-	the base address of the allocated memory for the mode flags
base_pitch	-	the base address of the allocated memory for the pitch angle array
base_cset	-	the base address of the allocated memory for the calibration set size array
base_dir_cosines	-	the base address of the allocated memory for the direction cosine data structure
base_potential	-	the base address of the allocated memory for the spacecraft potential data
base_background	-	the base address of the allocated memory for the background data
base_transform	-	the base address of the allocated memory for the coordinate system transformation structure

DESCRIPTION

The **idf_data** structure holds all of the currently returned data values, in raw format, from the last call to the **read_drec** routine.

SEE ALSO

read_drec	1R
read_drec_spin	1R
create_data_structure	1R
create_idf_data_structure	1R
direction_cos	1H
transformation_info	1H

DIRECTION_COS

function - data structure which holds the direction cosine information returned within the **idf_data** IDFS data structure

SYNOPSIS

#include "util_str.h"

struct direction_cos
{

SDDAS_FLOAT	*dir_cos123;
SDDAS_FLOAT	*start_az123;
SDDAS_FLOAT	*stop_az123;
SDDAS_FLOAT	*start_theta123;
SDDAS_FLOAT	*stop_theta123;
void	*base_mem;

};

ELEMENT DEFINITIONS

dir_cos123	-	pointer to the first element in the direction cosines array, with the three components being returned for each data sample returned in the idf_data structure
start_az123	-	pointer to the first element in the initial azimuthal sample angle array, with the three components being returned for each data sample returned in the idf_data structure
stop_az123	-	pointer to the first element in the final azimuthal sample angle array, with the three components being returned for each data sample returned in the idf_data structure
start_theta123	-	pointer to the first element in the initial theta angle array, with the three components being returned for each data sample returned in the idf_data structure
stop_theta123	-	pointer to the first element in the final theta angle array, with the three components being returned for each data sample returned in the idf_data structure
base_mem	-	pointer to the memory allocated to hold all of the data elements contained within the structure

DESCRIPTION

The **direction_cos** data structure is an integral part of the **idf_data** structure; that is, it is not returned as a stand-alone data structure by the IDFS data access routines. This structure contains the direction cosine values for each of the three components, along with ancillary angular information pertinent to the IDFS data source utilized as the pitch angle data source. The data is stored as triplets (x, y, z), with the 3 values being laid down sequentially within the arrays ([0,1,2] [3,4,5] ...). There is one triplet for each sample returned within the **idf_data** structure. For example, if **num_sample** were set to 8, there would be 8 triplets returned in the five arrays described above. Each array would contain 24 (8 * 3) values.

SEE ALSO

read_drec	1R
read_drec_spin	1 R
idf_data	1H

TRANSFORMATION_INFO

function - data structure which holds the coordinate system transformation information returned within the **idf_data** IDFS data structure

SYNOPSIS

#include "util_str.h"

struct transformation_info

{

<pre>*euler_angles; *euler_rot_axis; num_euler; euler_size; *base_euler; *declination_angles; *rt_ascension_angles; num_celestial; celestial_size;</pre>
celestial_size; *base_celestial;

};

ELEMENT DEFINITIONS

41.4		5	
	euler_angles	-	pointer to the first element in the euler angle array, with
			<pre>num_euler value(s) being returned for each data sample</pre>
			returned in the idf_data structure
	euler_rot_axis	-	pointer to the first element in the euler rotation axis array,
			with num_euler value(s) returned
	num_euler	-	the number of euler angles defined
	euler_size	-	the number of bytes allocated for the euler angle and euler
			rotation axis arrays
	base_euler	-	the base address of the allocated memory for the euler angle
			and euler rotation axis data
	declination_angles	-	pointer to the first element in the declination angle array, with
	-		one value being returned for each data sample returned in the
			idf_data structure
	rt_ascension_angles	-	pointer to the first element in the right ascension angle array,
	-		with one value being returned for each data sample returned
			in the idf_data structure
	num_celestial	-	the number of elements returned in the celestial position angle
			arrays *declination_angles and *rt_ascension_angles
	celestial_size	-	the number of bytes allocated for the declination angle and
			right ascension angle arrays
	base_celestial	-	the base address of the allocated memory for the declination
	—		angle and right ascension angle data

DESCRIPTION

The **transformation_info** data structure is an integral part of the **idf_data** structure; that is, it is not returned as a stand-alone data structure by the IDFS data access routines. This structure contains the euler angle data and the celestial position angle data (declination and right ascension angles) pertinent to the IDFS data source being returned in the **idf_data** structure.

For the celestial position angle data, there is an angle returned for each sample returned within the **idf_data** structure; therefore, **num_celestial** from the **transformation_info** structure and **num_sample** from the **idf_data** structure are identical. However, the data is stored differently for the euler angle information. For the **euler_angles** data, there are **num_euler** values being laid down sequentially within the array for each sample returned within the **idf_data** structure. For example, if **num_sample** were set to 8 and **num_euler** were set to 2, there would be 16 (8 * 2) values returned, with the first 2 values associated with the first data sample, the next 2 values associated with the second data sample, etc. This is not the case for the **euler_rot_axis** array. Since the euler rotation axis does not change from data sample to data sample, there are **num_euler** elements returned in the **euler_rot_axis** array.

SEE ALSO

read_drec	1R
read_drec_spin	1R
idf_data	1H

EXAMPLES

The following code fragment demonstrates how to access the data within the **transformation_info** structure, if pertinent to the data source being processed. The code fragments assumes that a data structure has already been created and data has been read and is ready to be processed.

#include "libbase_idfs.h"

struct idf_data *EXP_DATA; struct transformation_info *trans_ptr; register SDDAS_USHORT loop, k; SDDAS_USHORT offset; void *idf_data_ptr;

EXP_DATA = (struct idf_data *) idf_data_ptr; trans_ptr = EXP_DATA->idfs_transformation; /* Any coordinate system transformation information defined? */

```
if (trans_ptr != NULL)
{
   /* Print out the euler data and rotation axis for each data sample. */
   offset = 0;
   for (k = 0; k < EXP_DATA->num_sample; ++k)
   {
     for (loop = 0; loop < trans_ptr->num_euler; ++loop, ++offset)
       printf ("%05.2f %d ", *(trans_ptr->euler_angles + offset),
                                *(trans_ptr->euler_rot_axis + loop));
     printf ("\n");
    }
   /* Print out the celestial position angle data. */
   for (loop = 0; loop < trans_ptr->num_celestial; ++loop)
    printf ("%05.2f %05.2f \n", *(trans_ptr->declination_angles + loop),
                                    *(trans_ptr->rt_ascension_angles + loop));
   printf ("\n");
}
```

SCF_DATA

function - data structure that returns information for the output variables defined by the SCF

SYNOPSIS

#include "SCF.h"

struct scf_data

{

SDDAS_SHORT	byear;
SDDAS_SHORT	bday;
SDDAS_LONG	bmilli;
SDDAS_LONG	bnano;
SDDAS_SHORT	eyear;
SDDAS_SHORT	eday;
SDDAS_LONG	emilli;
SDDAS_LONG	enano;
SDDAS_LONG	num_output;
SDDAS_LONG	*output_length;
SDDAS_LONG	*output_index;
SDDAS_FLOAT	*output_data;
void	*base_output;
SDDAS_CHAR	filename[SCF_FILENAME];

};

ELEMENT DEFINITIONS

byear	-	the year at the start of the time period processed
bday	-	the day of year at the start of the time period processed
bmilli	-	the milliseconds of the day at the start of the time period processed
bnano	-	the remaining nanoseconds of the day at the start of the time period processed
eyear	-	the year at the end of the time period processed
eday	-	the day of year at the end of the time period processed
emilli	-	the milliseconds of the day at the end of the time period processed
enano	-	the remaining nanoseconds of the day at the end of the time period processed
num_output	-	the number of output variables being returned
output_length	-	pointer to the first element in an array which specifies the number of data values returned for each output variable
output_index	-	pointer to the first element in an array of index values (offsets) that are used to access the data in the output_data array for each output variable
output_data	-	pointer to the first element in the output data array

base_output	- the base address of the allocated memory for the
	output data information
filename	- the name of the SCF file which this data structure is to
	be associated with

DESCRIPTION

The **scf_data** structure holds the results from the last execution of the algorithm defined for the SCF being processed. The user must call the routine **create_scf_data_structure** once for each distinct SCF file being processed. It is these structures which are expected in any SCF routine where output variable values are being retrieved.

SEE ALSO

scf_output_data	3R
create_scf_data_structure	3R

TENSOR_DATA

function - multi-dimensional IDFS data structure

SYNOPSIS

#include "util_str.h"

struct tensor_data

{

SDDAS_ULONG	data_key;
SDDAS_SHORT	header_format;
SDDAS_SHORT	sensor;
SDDAS_SHORT	byear;
SDDAS_SHORT	bday;
SDDAS_LONG	bmilli;
SDDAS_LONG	bnano;
SDDAS_LONG	bsec;
SDDAS_LONG	bnsec;
SDDAS_SHORT	eyear;
SDDAS_SHORT	eday;
SDDAS_LONG	emilli;
SDDAS_LONG	enano;
SDDAS_LONG	esec;
SDDAS_LONG	ensec;
SDDAS_SHORT	mode_byear;
SDDAS_SHORT	mode_bday;
SDDAS_LONG	mode_bmilli;
SDDAS_LONG	mode_bnano;
SDDAS_SHORT	mode_eyear;
SDDAS_SHORT	mode_eday;
SDDAS_LONG	mode_emilli;
SDDAS_LONG	mode_enano;
SDDAS_LONG	data_accum_ms;
SDDAS_LONG	data_accum_ns;
SDDAS_LONG	data_lat_ms;
SDDAS_LONG	data_lat_ns;
SDDAS_LONG	swp_reset_ms;
SDDAS_LONG	swp_reset_ns;
SDDAS_LONG	sen_reset_ms;
SDDAS_LONG	sen_reset_ns;
SDDAS_SHORT	tensor_rank;
SDDAS_LONG	tensor_sizes[IDFS_MAX_DIMEN];
SDDAS_ULONG	<pre>tnext_dimen[IDFS_MAX_DIMEN];</pre>
SDDAS_ULONG	num_vals;
SDDAS_ULONG	cal_len;
SDDAS_LONG	sun_sen;
SDDAS_LONG	spin_rate;

SDDAS_LONG	*sen_data;
SDDAS_LONG	*mode;
SDDAS_LONG	*d_qual;
SDDAS_LONG	<pre>*cal_data;</pre>
SDDAS_UINT	data_size;
SDDAS_UINT	tensor_bytes;
SDDAS_UINT	mode_size;
SDDAS_UINT	dqual_size;
SDDAS_UINT	cal_size;
SDDAS_ULONG	num_dqual;
SDDAS_UCHAR	mode_len;
SDDAS_CHAR	hdr_change;
SDDAS_CHAR	exten[3];
SDDAS_CHAR	filled_data;
SDDAS_USHORT	version;
SDDAS_FLOAT	*tdata;
SDDAS_FLOAT	*tcaldata;
void	*base_data;
void	*base_tdata;
void	*base_cal;
void	*base_tcaldata;
void	*base_mode;
void	*base_dqual;

};

ELEMENT DEFINITIONS

data_key	-	unique value which indicates the multi-dimensional data set of interest
header_format	-	used to identify conventional IDFS data from multi-
		dimensional tensor IDFS data
sensor	-	the sensor identification number for the current data
byear	-	the year at the start of the accumulation of the first data value
bday	-	the day at the start of the accumulation of the first data value
bmilli	-	the milliseconds of the day at the start of the accumulation of
		the first data value
bnano	-	the remaining nanoseconds of the day at the start of the
		accumulation of the first data value
bsec	-	the start time of the first data value in seconds
		(bmilli + bnano)
bnsec	-	the remaining nanoseconds of the start time of the first data
		value (bmilli + bnano)
eyear	-	the year at the end of the accumulation period of the last data
		value
eday	-	the day at the end of the accumulation period of the last data
-		value

emilli	-	the milliseconds of the day at the end of the accumulation
esec	-	period (including any latency) of the last data value the end time of the last data value in seconds (emilli + enano)
ensec	-	the remaining nanoseconds of the end time of the last data value (emilli + enano)
enano	-	the remaining nanoseconds of the day at the end of the accumulation period (including any latency) of the last data value
mode_byear	-	the year at the start of the accumulation for the instrument status values
mode_bday	-	the day at the start of the accumulation for the instrument status values
mode_bmilli	-	the milliseconds of the day at the start of the accumulation for the instrument status values
mode_bnano	-	the remaining nanoseconds of the day at the start of the accumulation for the instrument status values
mode_eyear	-	the year at the end of the accumulation period for the instrument status values
mode_eday	-	the day at the end of the accumulation period for the instrument status values
mode_emilli	-	the milliseconds of the day at the end of the accumulation period (including any latency) for the instrument status values
mode_enano	-	the remaining nanoseconds of the day at the end of the accumulation period (including any latency) for the instrument status values
data_accum_ms	-	the amount of time for a single data acquisition, in milliseconds
data_accum_ns	-	the remainder of data_accum_ms, in nanoseconds
data_lat_ms	-	the amount of dead time between successive data acquisitions, in milliseconds
data_lat_ns	-	the remainder of data_lat_ms, in nanoseconds
swp_reset_ms	-	the amount of dead time at the end of an instrument sweep, in milliseconds
swp_reset_ns	-	the remainder of swp_reset_ms, in nanoseconds
sen_reset_ms	-	the amount of dead time between successive sensor sets, in milliseconds
sen_reset_ns	-	the remainder of sen_reset_ms, in nanoseconds
tensor_rank	-	the number of dimensions returned in the data tensor
tensor_sizes	-	an array of size tensor_rank that holds the maximum lengths of each of the dimensions defined
tnext_dimen	-	an array of size tensor_rank that holds the number of data values to bypass to get to the next index for a given dimension $([0] = 1^{st}$ dimension or slowest varying dimension)
num_vals	-	the number of elements returned in the sensor data tensor
cal_len	-	the number of elements returned in the calibration data tensor
—		455 December 28, 2012

sun_sen	-	the time of the last 0° crossing
spin_rate	-	the current spin rate of the virtual instrument
sen_data	-	pointer to the first element in the sensor data tensor
mode	-	pointer to the first element in the mode flags array
d_qual	-	pointer to the first element in the data quality tensor whose
		value indicates the quality of the data being returned
		and also serves as an offset into the qual_names array
		defined in the VIDF file. The user should refer to the IDFS
		File System Definition Document for an explanation of
		qual_names and d_qual.
cal_data	-	pointer to the first element in the calibration data tensor
data_size	_	the number of bytes allocated for the sensor data tensor
tensor_bytes	_	the number of bytes allocated to convert the tensor data
		according to d_type specified in the VIDF
mode_size	-	the number of bytes allocated for the mode flags array
dqual_size	_	the number of bytes allocated for data quality tensor
cal_size	_	the number of bytes allocated for the calibration data tensor
num_dqual	-	the number of elements returned in the data quality vector
mode_len	-	the number of elements returned in the data quanty vector the number of elements returned in the mode flags array
liloue_leli	-	*mode
hdr change		
hdr_change	-	flag which indicates a header change occurred 0 - a header change was not encountered during
		0 - a header change was not encountered during the retrieval of data
		1 - a header change was encountered during the
		retrieval of data
exten	-	two character extension identifying the multi-dimensional
		IDFS data file set being utilized (should be a null string ""
(****		when using the default IDFS data sets)
filled_data	-	flag which indicates if data was placed into the data tensor for
		the sensor in question
		0 - data was not placed into the tensor for the
		sensor in question
		1 - data was placed into the tensor for the sensor
		in question
version	-	IDFS data set identification number which allows for multiple
		openings of the same data set
tdata	-	pointer to the first element in the sensor data tensor which has
		been converted according to d_type in the VIDF
tcaldata	-	pointer to the first element in the calibration data tensor which
		has been converted according to d_type in the VIDF
base_data	-	the base address of the allocated memory for the sensor data
		tensor
base_tdata	-	the base address of the allocated memory for the sensor data
		that is converted according to d_type in the VIDF
base_cal	-	the base address of the allocated memory for the calibration
		data tensor

base_tcaldata	-	the base address of the allocated memory for the calibration
		data that is converted according to d_type in the VIDF
base_mode	-	the base address of the allocated memory for the mode flags
base_dqual	-	the base address of the allocated memory for the data quality
		tensor

DESCRIPTION

The **tensor_data** structure holds all of the currently returned data values, in raw format, from the last call to the **read_drec_tensor** routine. The only conversion that is performed on the data is a possible conversion from integer storage to its true floating point value, as defined by **d_type** in the VIDF file.

SEE ALSO

read_drec_tensor	1 R
create_data_structure	1 R
create_tensor_data_structure	1 R